MultiLayer

February 17, 2025

1 Acknowledgements

This notebook lab has been taken from the TBMI26 course (Neural networks and learning systems).

Examiner: Magnus Borga

Initial code authors (MATLAB version): UNKNOWN

Conversion to Python and overall refinement: Martin Hultman & David Abramian

1.0.1 Quick introduction to jupyter notebooks

- Each cell in this notebook contains either code or text.
- You can run a cell by pressing Ctrl-Enter, or run and advance to the next cell with Shift-Enter.
- Code cells will print their output, including images, below the cell. Running it again deletes the previous output, so be careful if you want to save some results.
- You don't have to rerun all cells to test changes, just rerun the cell you have made changes to. Some exceptions might apply, for example if you overwrite variables from previous cells, but in general this will work.
- If all else fails, use the "Kernel" menu and select "Restart Kernel and Clear All Output". You can also use this menu to run all cells.
- A useful debug tool is the console. You can right-click anywhere in the notebook and select "New console for notebook". This opens a python console which shares the environment with the notebook, which let's you easily print variables or test commands.

1.0.2 Setup

```
plotResultsDots, plotIsolines, plotConfusionMatrixOCR,
plotResultsDotsGradient
from evalFunctions import calcAccuracy, calcConfusionMatrix

# Configure nice figures
plt.rcParams['figure.facecolor']='white'
plt.rcParams['figure.figsize']=(8, 5)
```

1.0.3 ! IMPORTANT NOTE!

Your implementation should only use the numpy (np) module. The numpy module provides all the functionality you need for this assignment and makes it easier debuging your code. No other modules, e.g. scikit-learn or scipy among others, are allowed. You can find everything you need about numpy in the official documentation.

1.0.4 1. Multi-layer neural network

The implementation of the multi-layer network is a bit beyond the scope of this course, so we will provide it for you. Your task is instead to optimize the training and interpret the results.

Similar to the single-layer network, the multi-layer keep track of weight matrices W1 and W2, and bias vectors B1 and B2. The structure of the code is still the same, with a forward, backward, and update function.

1.1 Implementing the forward pass This implementation will look similar to the single-layer code, but note that it also returns the intemediate variable U, which is the output of the hidden layer after passing throught the activation function. This will be used in the backward pass.

```
[2]: def forward(X, W1, B1, W2, B2, useTanhOutput=False):
         """Forward pass of two layer network
         Args:
             X (array): Input samples.
             W1 (array): First layer neural network weights.
             B1 (array): First layer neural network biases.
             W2 (array): Second layer neural network weights.
             B2 (array): Second layer neural network biases.
         Returns:
             Y (array): Output for each sample and class.
             L (array): Resulting label of each sample.
             U (array): Output of hidden layer.
         ,, ,, ,,
         U = np.tanh(X @ W1 + B1)
         if useTanhOutput:
             Y = np.tanh(U @ W2 + B2)
         else:
```

```
Y = U @ W2 + B2

L = Y.argmax(axis=1)

return Y, L, U
```

1.2 Implementing the backward pass This backward pass implementation uses the so called delta notation. This is very useful when implementing the general case of an N-layer network, since it can easily be implemented in an iterative manner in a loop going over each layer. We will not do that in this assignment, but it is good to know that this is essentially how the popular frameworks for deep learning functions.

```
[3]: def backward(W1, B1, W2, B2, X, U, Y, D, useTanhOutput=False):
         """Compute the gradients for network weights and biases
         Args:
             W1 (array): Current values of the layer 1 network weights.
             B1 (array): Current values of the layer 1 network biases.
             W2 (array): Current values of the layer 2 network weights.
             B2 (array): Current values of the layer 2 network biases.
             X (array): Training samples.
             U (array): Intermediate outputs of the hidden layer.
             Y (array): Predicted outputs.
             D (array): Target outputs.
             useTanhOutput (bool): (optional)
                 True - Network uses tanh activation on output layer
                 False - Network uses linear (no) activation on output layer
         Returns:
             GradW1 (array): Gradients with respect to W1
             GradB1 (array): Gradients with respect to B1
             GradW2 (array): Gradients with respect to W2
             GradB2 (array): Gradients with respect to B2
         11 11 11
         N = Y.shape[0]
         NC = Y.shape[1]
         if useTanhOutput:
             output_error = 2 * (Y - D) * (1 - Y**2)
         else:
             output_error = 2 * (Y - D)
         GradW2 = (U.T @ output_error) / N
         GradB2 = np.sum(output_error, axis=0) / N
         hidden_error = (output_error @ W2.T) * (1 - U**2)
```

```
GradW1 = (X.T @ hidden_error) / N
GradB1 = np.sum(hidden_error, axis=0) / N
return GradW1, GradB1, GradW2, GradB2
```

1.3 Implementing the weight update For this update function we have implemented a more powerful algorithm called momentum gradient descent. This is part of an optional task at the end of the notebook, and you do not have to use it unless you want to.

```
[4]: def update(W1, B1, W2, B2, GradW1, GradB1, GradW2, GradB2, params):
         """Update weights and biases using computed gradients.
         Args:
             W1 (array): Current values of the layer 1 network weights.
             B1 (array): Current values of the layer 1 network biases.
             W2 (array): Current values of the layer 2 network weights.
             B2 (array): Current values of the layer 2 network biases.
             GradW1 (array): Gradients with respect to W1.
             GradB1 (array): Gradients with respect to B1.
             GradW2 (array): Gradients with respect to W2.
             GradB2 (array): Gradients with respect to B2.
             params (dict): Dictionary containing learning rate and momentum.
         Returns:
             W1 (array): Updated layer 1 weights.
             B1 (array): Updated layer 1 biases.
             W2 (array): Updated layer 2 weights.
             B2 (array): Updated layer 2 biases.
         LR = params["learningRate"]
         if "momentum" in params:
             M = params["momentum"]
             PrevGradW1 = params["PrevGradW1"]
             PrevGradB1 = params["PrevGradB1"]
             PrevGradW2 = params["PrevGradW2"]
             PrevGradB2 = params["PrevGradB2"]
             W1 = W1 + M * PrevGradW1 - LR * GradW1
             B1 = B1 + M * PrevGradB1 - LR * GradB1
             W2 = W2 + M * PrevGradW2 - LR * GradW2
             B2 = B2 + M * PrevGradB2 - LR * GradB2
             params["PrevGradW1"] = M * PrevGradW1 - LR * GradW1
             params["PrevGradB1"] = M * PrevGradB1 - LR * GradB1
```

```
params["PrevGradW2"] = M * PrevGradW2 - LR * GradW2
    params["PrevGradB2"] = M * PrevGradB2 - LR * GradB2

else:
    W1 = W1 - LR * GradW1
    B1 = B1 - LR * GradB1
    W2 = W2 - LR * GradW2
    B2 = B2 - LR * GradB2
return W1, B1, W2, B2
```

1.4 The training function

```
[5]: def trainMultiLayer(XTrain, DTrain, XTest, DTest, W1_0, B1_0, W2_0, B2_0,
      →params):
         """Trains a two-layer network
         Args:
             XTrain (array): Training samples.
             DTrain (array): Training network target values.
             XTest (array): Test samples.
             DTest (array): Test network target values.
             W1_0 (array): Initial values of the first layer network weights.
             B1_0 (array): Initial values of the first layer network biases.
             W2_0 (array): Initial values of the second layer network weights.
             B2_0 (array): Initial values of the second layer network biases.
             params (dict): Dictionary containing:
                 epochs (int): Number of training steps.
                 learningRate (float): Size of a training step.
         Returns:
             W1 (array): First layer weights after training.
             B1 (array): Fisrt layer biases after training.
             W2 (array): Second layer weights after training.
             B2 (array): Second layer biases after training.
             metrics (dict): Losses and accuracies for training and test data.
         11 11 11
         # Initialize variables
         metrics = {keys:np.zeros(params["epochs"]+1) for keys in ["lossTrain", __

¬"lossTest", "accTrain", "accTest"]}
         if "useTanhOutput" not in params:
             params["useTanhOutput"] = False
         if "momentum" not in params:
             params["momentum"] = 0
```

```
nTrain = XTrain.shape[0]
  nTest = XTest.shape[0]
  nClasses = DTrain.shape[1]
  # Set initial weights
  W1 = W1_0
  B1 = B1 0
  W2 = W2_0
  B2 = B2 0
  # For optional task on momentum
  params["PrevGradW1"] = np.zeros_like(W1)
  params["PrevGradB1"] = np.zeros_like(B1)
  params["PrevGradW2"] = np.zeros_like(W2)
  params["PrevGradB2"] = np.zeros_like(B2)
  # Get class labels
  LTrain = np.argmax(DTrain, axis=1)
  LTest = np.argmax(DTest , axis=1)
  # Calculate initial metrics
  YTrain, LTrainPred, UTrain = forward(XTrain, W1, B1, W2, B2,
→params["useTanhOutput"])
  YTest , LTestPred , _
                          = forward(XTest , W1, B1, W2, B2, U
⇔params["useTanhOutput"])
  # Including the initial metrics makes the progress plots worse, set nan tout
\rightarrowexclude
  metrics["lossTrain"][0] = np.nan # ((YTrain - DTrain)**2).mean()
  metrics["lossTest"][0] = np.nan # ((YTest - DTest )**2).mean()
  metrics["accTrain"][0] = np.nan # (LTrainPred == LTrain).mean()
  metrics["accTest"][0] = np.nan # (LTestPred == LTest ).mean()
  # Create figure for plotting progress
  fig = plt.figure(figsize=(20,8), tight_layout=True)
  # Training loop
  for n in range(1, params["epochs"]+1):
      # -----
      # === This is the important part ========
      # === where your code is applied ========
      # -----
      # Compute gradients...
      GradW1, GradB1, GradW2, GradB2 = backward(W1, B1, W2, B2, XTrain,
→UTrain, YTrain, DTrain, params["useTanhOutput"])
```

```
# ... and update weights
      W1, B1, W2, B2 = update(W1, B1, W2, B2, GradW1, GradB1, GradW2, GradB2,
→params)
      # Evaluate errors
      YTrain, LTrainPred, UTrain = forward(XTrain, W1, B1, W2, B2,

¬params["useTanhOutput"])
      YTest , LTestPred , _
                                 = forward(XTest , W1, B1, W2, B2,
→params["useTanhOutput"])
      metrics["lossTrain"][n] = ((YTrain - DTrain)**2).mean()
      metrics["lossTest"][n] = ((YTest - DTest )**2).mean()
      metrics["accTrain"][n] = (LTrainPred == LTrain).mean()
      metrics["accTest"][n] = (LTestPred == LTest ).mean()
      # Plot progress
      if (plotProgress and not n % 500) or n == params["epochs"]:
          if W1.shape[0] == 2 and W1.shape[1] <= 8:</pre>
              plotProgressNetworkMulti(fig, W1, B1, W2, B2, metrics, n=n)
          else:
              plotProgress(fig, metrics, n)
  return W1, B1, W2, B2, metrics
```

We also define the same function for normalizing the data, which is even more important now that we have more than one layer.

```
[6]: def normalize(X):
    # Compute mean and std
    m = X.mean(axis=0)
    s = X.std(axis=0)
    # Prevent division by 0 is feature has no variance
    s[s == 0] = 1
    # Return normalized data
    return (X - m) / s
```

Question

1. Explain why large, non-normalized input features might be a problem when using two layers, but not when using a single layer.

Answer: For Large, non-normalized input features causes significant issues in a two layer neural network. This includes gradients becoming excessively larger, which reduces stability in learning and gradients becoming too small. In contrast, single layer network, it is less effected due to direct evaludation of gradients and since there are no hidden layers, so the gradient passes directly from input to outputwhere compounding effects can occur.

1.0.5 2 Optimizing each dataset

Like before, we define a function that performs the boilerplate code for training the networks.

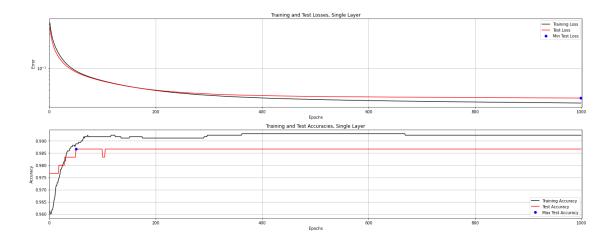
```
[7]: def trainMultiLayerOnDataset(datasetNr, testSplit, W1_0, B1_0, W2_0, B2_0, U
      →params):
         """Train a two layer network on a specific dataset.
         Aqs:
             datasetNr (int): ID of dataset to use
             testSplit (float): Fraction of data reserved for testing.
             W1_0 (array): Initial values of the first layer network weights.
             B1_0 (array): Initial values of the first layer network biases.
             W2_0 (array): Initial values of the second layer network weights.
             B2_0 (array): Initial values of the second layer network biases.
             params (dict): Dictionary containing:
                 nIterations (int): Number of training steps.
                 learningRate (float): Size of a training step.
         11 11 11
         # Load data and split into training and test sets
         X, D, L = loadDataset(datasetNr)
         XTrain, DTrain, LTrain, XTest, DTest, LTest = splitData(X, D, L, testSplit)
         if "normalize" in params and params["normalize"]:
             XTrainNorm = normalize(XTrain)
             XTestNorm = normalize(XTest)
         else.
             XTrainNorm = XTrain
             XTestNorm = XTest
         # Train network
         W1, B1, W2, B2, metrics = trainMultiLayer(XTrainNorm, DTrain, XTestNorm,
      →DTest, W1_0, B1_0, W2_0, B2_0, params)
         # Predict classes on test set
         LPredTrain = forward(XTrainNorm, W1, B1, W2, B2, params["useTanhOutput"])[1]
         LPredTest = forward(XTestNorm , W1, B1, W2, B2, params["useTanhOutput"])[1]
         # Compute metrics
         accTrain = calcAccuracy(LPredTrain, LTrain)
         accTest = calcAccuracy(LPredTest , LTest)
         confMatrix = calcConfusionMatrix(LPredTest, LTest)
         # Display results
         print(f'Train accuracy: {accTrain:.4f}')
```

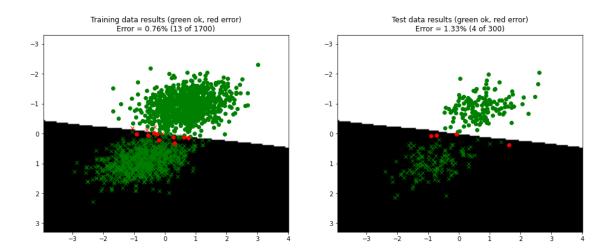
```
print(f'Test accuracy: {accTest:.4f}')
print("Test data confusion matrix:")
print(confMatrix)

if datasetNr < 4:
    # Switch between these two functions to see another way to visualize
the network output.
    plotResultsDots(XTrainNorm, LTrain, LPredTrain, XTestNorm, LTest,
LPredTest, lambda X: forward(X, W1, B1, W2, B2, params["useTanhOutput"])[1])
    #plotResultsDotsGradient(XTrainNorm, LTrain, LPredTrain, XTestNorm,
LTest, LPredTest, lambda X: forward(X, W1, B1, W2, B2,
params["useTanhOutput"])[0])
else:
    plotConfusionMatrixOCR(XTest, LTest, LPredTest)</pre>
```

2.1 Optimizing dataset 1

```
Train accuracy: 0.9924
Test accuracy: 0.9867
Test data confusion matrix:
[[139 4]
[ 0 157]]
```



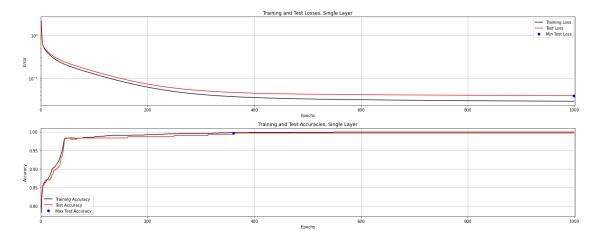


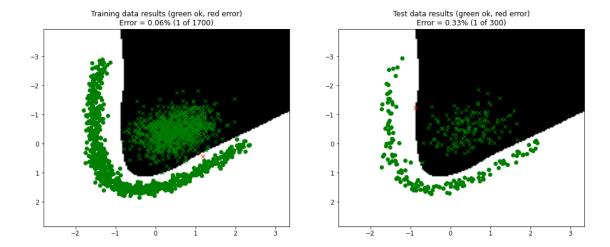
2. Optimize the training until you reach at least 98% test accuracy. Briefly motivate your choice of hyperparameters.

Answer: We kept the initial hyperparameters of epochs = 1000, LR = 0.05, normalize = True, tanh = False and as a rule of thumb chose 10 hidden neurons. We thought of this as the data was not complex and achieving a good accuracy was possible and we got accuracy of 99.67. Hence, the further optimization was not required.

2.2 Optimizing dataset 2

Train accuracy: 0.9994
Test accuracy: 0.9967
Test data confusion matrix:
[[146 0]
 [1 153]]





3. Optimize the training until you reach at least 99% test accuracy. Briefly motivate your choice of hyperparameters.

Answer: As stated in the previous dataset explanation, we set the initial hyperparameters and used 10 neurons as rule of thumb, and it was able to classify the points very easily getting 100% accuracy. But we think this is not ideal as these are signs of overfitting.

2.3 Optimizing dataset 3

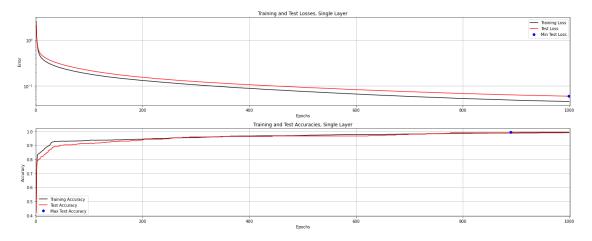
```
[13]: # -
     # === Your code here ===========
     nInputs = 2
     nClasses = 3
     nHidden = 20
     W1_0 = np.random.randn(nInputs, nHidden)
     B1_0 = np.zeros((1, nHidden))
     W2_0 = np.random.randn(nHidden, nClasses)
     B2_0 = np.zeros((1, nClasses))
     params = {"epochs": 1000, "learningRate": 0.03, "normalize": True, U

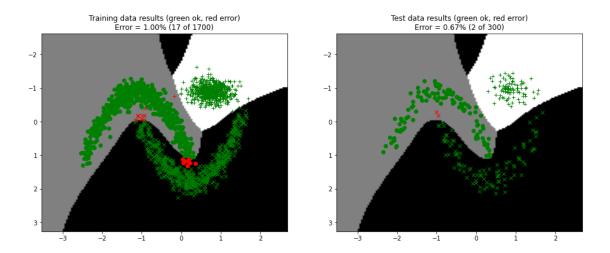
¬"useTanhOutput": False}
     # -----
     trainMultiLayerOnDataset(3, 0.15, W1_0, B1_0, W2_0, B2_0, params)
```

Train accuracy: 0.9900 Test accuracy: 0.9933

Test data confusion matrix:

```
[[ 98  0  0]
[ 2 111  0]
[ 0  0  89]]
```

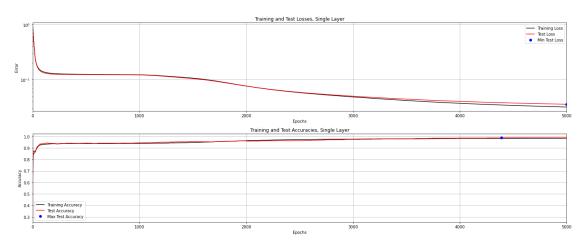


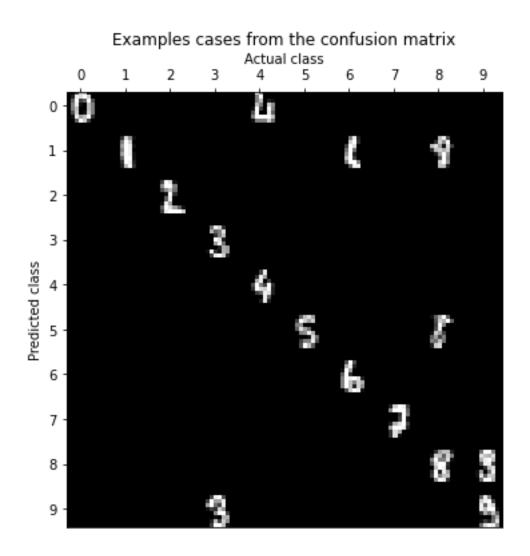


4. Optimize the training until you reach at least 99% test accuracy. Briefly motivate your choice of hyperparameters.

Answer: This data had 3 classes. We started with the same initial hyperparameters and data being separable with approximately 3 decision boundaries, we thought that the number of neurons as 10 should work for this classification. We achieved the accuracy of 99.3% using these hyperparameters, so we did not optimize it further.

2.4 Optimizing dataset 4





5. Optimize the training until you reach at least 96% test accuracy. Briefly motivate your choice of hyperparameters.

Answer: Scaled the initial weights by a small factor 0.01 to reduce to make sure data is not large. As this data had more input features than the previous datasets, we started with 64 neurons but were unable to achieve the desired accuracy. We further increased them to 500 and as the number of features were more to learn from, we set the learning rate = 0.025 and ran it for more time by settingepochs = 5000. We also kept normalize = True so that the data is in the same scale achieving an accuracy of ~96%.

[]: