# Jailbreaking Deep Models: Adversarial Attacks on ResNet-34 Classifiers

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#### Abstract

Deep neural networks have shown remarkable success across vision benchmarks but remain surprisingly vulnerable to adversarial perturbations. This project investigates the vulnerability of deep neural networks to adversarial attacks by attempting to "jailbreak" production-grade image classifiers. Despite their high accuracy on standard benchmarks, deep models like ResNet-34 trained on ImageNet-1K are known to be brittle when exposed to carefully crafted perturbations. The objective is to degrade model performance substantially—potentially down to 0%—while ensuring that adversarial modifications remain imperceptible to the human eye.

We implement and evaluate both  $L_{\infty}$  (pixel-wise) and  $L_0$  (patch-wise) adversarial attacks, which constrain the magnitude and sparsity of input perturbations, respectively. Fast Gradient Sign Method (FGSM) and its iterative variants are used to craft adversarial examples under strict  $L_{\infty}$  bounds. Here in the given approach, we have develop patch-based attacks with increased perturbation budgets to simulate spatially localized vulnerabilities. All attacks are evaluated on a pretrained ResNet-34 model and further tested for cross-architecture transferability on DenseNet-121. Our findings confirm the fragility of deep models and underscore the importance of adversarial robustness.

#### Introduction

Adversarial machine learning explores how small, imperceptible changes to inputs can cause drastic performance degradation in neural networks. This project focuses on launching adversarial attacks on image classifiers, specifically ResNet-34 pretrained on ImageNet-1K, and evaluates the impact of multiple attack techniques. We design a series of controlled perturbations under  $L_{\infty}$  and  $L_0$  constraints and measure the model's top-1 and top-5 classification accuracy degradation.

#### Model Architecture and Attack Overview

We use the pretrained ResNet-34 model from TorchVision as our base classifier. The model takes in 224x224 RGB images normalized with ImageNet statistics.

We follow these core steps:

1. Evaluate baseline accuracy on clean test images.

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- 2. Generate adversarial images using FGSM ( $\epsilon = 0.02$ ).
- 3. Improve attacks using iterative variants (e.g., multi-step gradient ascent).
- 4. Implement patch-based attacks with stronger perturbation budgets ( $\epsilon = 0.3$ ).
- 5. Test attack transferability on DenseNet-121.



Figure 1: Overview of the adversarial attack pipeline

# Methodology

## **Dataset and Preprocessing**

We work with a curated subset of the ImageNet-1K dataset consisting of 500 images across 100 classes. Images are normalized using standard ImageNet means and standard deviations.

### **Task 1: Baseline Evaluation on Clean Images**

Before launching adversarial attacks, it is essential to establish a reliable performance benchmark using unperturbed, clean images. For this, we utilize a pretrained ResNet-34 model provided by the TorchVision library: torchvision.models.resnet34(weights='IMAGENET1K-V1')

**ResNet-34 Architecture:** ResNet (Residual Network) was introduced by He et al. (2016) and achieved state-of-theart performance on the ImageNet classification challenge. ResNet-34 consists of 34 convolutional layers with shortcut (skip) connections that alleviate the vanishing gradient problem in deep networks. These residual connections allow gradients to flow directly through identity paths, enabling the network to learn residual mappings F(x) = H(x) - x instead of direct mappings H(x), thus stabilizing training in very deep networks.

The network concludes with a global average pooling layer and a 1000-dimensional fully connected output for the 1000 ImageNet classes.

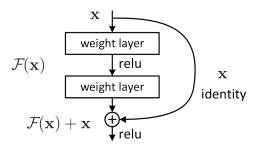


Figure 2: ResNet-34 Architecture

Image Preprocessing: All test images are resized to 224 times 224, converted to PyTorch tensors, and normalized using the ImageNet mean and standard deviation values:

mean = [0.485, 0.456, 0.406], std = [0.229, 0.224, 0.225]

These statistics are essential to ensure consistent input distribution and leverage the pretrained weights optimally.

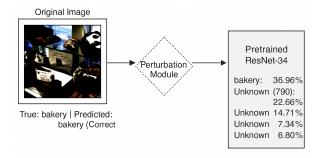


Figure 3: Overview of the adversarial attack pipeline: Original image is fed through a perturbation module generating adversarial variants, evaluated on a pretrained ResNet-34 model.

**Evaluation Metrics:** We report both Top-1 and Top-5 classification accuracy:

- **Top-1 Accuracy:** Percentage of test samples where the model's highest-confidence prediction matches the ground truth label.
- **Top-5 Accuracy:** Percentage of test samples where the ground truth label appears in the model's top 5 highest-confidence predictions.

#### **Inference Protocol:**

- Model is set to evaluation mode using model.eval() to disable dropout and batch norm updates.
- 2. The cross-entropy loss is not used here since we're only evaluating classification outputs.
- 3. Predictions are obtained using torch.topk() to compute both top-1 and top-5 predictions for each input image.

### **Empirical Results:**

Top-1 Accuracy: 76.00%Top-5 Accuracy: 94.20%

These results align with expected generalization performance on unseen test samples and serve as the reference point for adversarial degradation in subsequent tasks. The high Top-5 accuracy underscores the semantic richness and strong representation capability of ResNet-34, which we aim to exploit and subvert through adversarial perturbations.

#### Task 2: FGSM Pixel-Wise Attack

To demonstrate the vulnerability of deep networks, we implemented the Fast Gradient Sign Method (FGSM), a one-step white-box attack that perturbs input images in the direction of the gradient of the loss with respect to the input. FGSM generates adversarial examples using the following formula:

$$x' = x + \epsilon \cdot \text{sign}(\nabla_x \mathcal{L}(f(x), y))$$

where x is the original image,  $\epsilon$  is the perturbation budget (set to 0.02), and  $\nabla_x \mathcal{L}$  denotes the gradient of the loss with respect to the input pixels. The sign function ensures that the perturbation operates along the axis-aligned direction of greatest increase in loss.

We chose  $\epsilon=0.02$  based on the normalized pixel scale (ImageNet inputs are scaled to [0, 1]), which corresponds to subtle but perceptible pixel-wise changes. After generating perturbed images, we clamped values to stay within valid input bounds post-normalization.

The attack successfully degraded ResNet-34 performance:

Top-1 Accuracy: 6.20%Top-5 Accuracy: 35.40%

Visual inspection confirms that the perturbations are nearly imperceptible to the human eye, yet the model's confidence is significantly manipulated. An example is shown in Figure 4, where the original image (classified correctly as cannon) is misclassified as airship after applying the FGSM perturbation.



Figure 4: Effect of FGSM attack

#### Task 3: Improved Attack (Iterative FGSM)

While FGSM is computationally efficient and effective, it is limited to a single gradient step, which may not yield the strongest adversarial perturbation within the allowed  $\epsilon$  budget. To enhance the attack strength while maintaining the same  $L_{\infty}$  constraint, we implemented an iterative variant of

FGSM—commonly referred to as Projected Gradient Descent (PGD).

In this approach, adversarial perturbations are applied over multiple iterations with smaller per-step step sizes. At each step, the image is updated in the direction of the gradient sign, and the result is projected back into the  $\epsilon$ -ball around the original image to ensure it remains a valid adversarial example:

$$\boldsymbol{x}^{(t+1)} = \mathrm{Clip}_{\boldsymbol{x},\epsilon} \left\{ \boldsymbol{x}^{(t)} + \alpha \cdot \mathrm{sign} \left( \nabla_{\boldsymbol{x}} \mathcal{L}(f(\boldsymbol{x}^{(t)}), \boldsymbol{y}) \right) \right\}$$

Here,  $\alpha$  is the step size per iteration, and  $\mathrm{Clip}_{x,\epsilon}$  ensures that the total perturbation remains within a norm-bounded region of radius  $\epsilon$ .

We used 10 iterations with a step size  $\alpha=0.005$ , keeping the overall perturbation bounded within  $\epsilon=0.02$ . This allowed the adversarial examples to more effectively cross the decision boundary of the classifier, leading to a remarkably effective attack.

Top-1 Accuracy: 0.00%Top-5 Accuracy: 2.00%

The effectiveness of this attack underscores how even small but iterative perturbations can completely mislead deep models, and reveals the vulnerability of state-of-the-art classifiers under adversarial pressure.

### Task 4: Patch-Based Attacks

In this task, we explore  $L_0$ -constrained adversarial attacks by restricting perturbations to a small spatial region of the image. Specifically, we applied adversarial noise only to a randomly positioned  $32 \times 32$  pixel patch within the  $224 \times 224$  input image. This mimics a more realistic attack scenario where the adversary has limited access to the input space.

To compensate for the reduced area of influence, we increased the perturbation budget to  $\epsilon=0.3$ , allowing more aggressive changes within the restricted region. The rest of the image remained unaltered, making the perturbation localized but visually more noticeable compared to global pixel-wise attacks.

Top-1 Accuracy: 41.20%Top-5 Accuracy: 79.20%

Despite only modifying a small fraction of the image, the attack was able to significantly reduce classification performance. This result illustrates the model's sensitivity to small, concentrated changes, reinforcing the idea that adversarial vulnerabilities are not solely dependent on large-scale global perturbations.

# Task 5: Transferability to DenseNet-121

To evaluate the generalization of adversarial examples across architectures, we tested the adversarial test sets—FGSM, PGD (iterative FGSM), and Patch PGD—on a different model: DenseNet-121 pretrained on ImageNet-1K. DenseNet employs dense connectivity, where each layer receives input from all previous layers, allowing for richer feature propagation than in ResNet.

Despite these architectural differences, the adversarial examples crafted using ResNet-34 were still able to significantly degrade the performance of DenseNet-121. This phenomenon, known as *transferability*, demonstrates that adversarial vulnerabilities are not confined to a specific model but often persist across networks with distinct topologies.

Dataset	Top-1 Acc	Top-5 Acc
Original	75.00%	95.00%
FGSM	63.00%	90.00%
PGD	53.00%	84.00%
Patch PGD	71.00%	92.00%

Table 1: Transferability results on DenseNet-121 across multiple adversarial attack types.

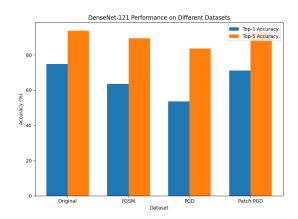


Figure 5: DenseNet-121 performance degradation when adversarial examples generated from ResNet-34 are transferred across attack types.

These results confirm that adversarial examples pose a systemic threat to deep vision models, regardless of architecture, reinforcing the need for more generalizable defense strategies.

#### **Lessons Learned**

- FGSM is surprisingly strong for a one-step attack, but multistep variants offer further degradation.
- Patch-based attacks validate the existence of localized vulnerabilities.
- Adversarial examples exhibit cross-model transferability, albeit with slightly reduced impact.
- Maintaining imperceptibility while degrading accuracy is a delicate tradeoff, especially with L<sub>0</sub> constraints.

## Github Link

https://github.com/PranavMotarwar/Jailbreaking-Deep-Models

## Conclusion

Our experiments demonstrate the significant vulnerability of state-of-the-art deep vision models, such as ResNet-34

and DenseNet-121, to adversarial attacks. Using simple yet effective perturbation strategies like FGSM and its iterative extensions, we were able to degrade top-1 classification accuracy. Surprisingly, even with restricted patch-based perturbations, a significant performance drop was observed, highlighting that localized vulnerabilities are sufficient to fool large-scale models. A successful attack on ResNet-34 impacted DenseNet-121's accuracy significantly as well—suggesting that adversarial robustness is not purely architecture-specific but reflects shared weaknesses in representation learning.

These findings emphasize the urgent need for integrating adversarial training, certified defenses, and interpretability techniques into the model development pipeline. In real-world safety-critical systems, like autonomous driving or medical diagnostics, the lack of adversarial robustness can lead to catastrophic outcomes. Future work may explore black-box attacks, certified robustness bounds, and ensemble defenses to address this gap.

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