(QI)
$$f(x,\lambda) = \frac{1}{2}\pi^{T}Px + q^{T}x + r + \lambda_{1}(x_{1}-1) + \lambda_{2}(-x_{1}-1) + \lambda_{3}(x_{2}-1) + \lambda_{4}(-x_{2}-1) + \lambda_{5}(x_{3}-1) + \lambda_{6}(-x_{3}-1)$$

KKT conditions:

a) Preimal feasibility: $-1 \le \chi_i^* \le 1$ (softisfied at the given χ_i^*)

b) from complementary slackness: $\lambda_3^* = \lambda_3^* = \lambda_2^* = 0$

b) from complementary slackness:
$$3 = 3 = 32$$

c) Dual feasibility: $3 \neq 2/0$
d) $\nabla_x \mathcal{L}(x, A) = 0 \Rightarrow Px^{+} + 9 + \begin{bmatrix} 3 & -32 \\ 2 & -34 \end{bmatrix} = 0$

Thus, we can find it s.t. (it) satisfy KKT condutions, which is sufficient for optimality.

(02) cost function is convex because each |x;+c| is a convex function, (affine function + 1-norm)

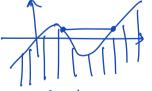
and sum of two convex functions is convex.

Feasibility set is a convex set as if is defined via lineare inequality constraints.

(3) a) convex set as if is epigraph of e^{x_i-1} which is a convex function.

b) not a convex set.

one can easily find two
points whose connecting line
is outside the set.



c) convex set as it is intersection of two convex sets g x2+x2 43 and fx120}

QA) since the function is convex,
$$f(x) > f(y) + \nabla f(y) (x-y)$$
$$f(y) > f(x) + \nabla f(x) (y-x)$$
adding both yields the result.

(Q5) converting to standard form

min
$$x_1 + x_3$$
 $C = [1010]$
 $x \in \mathbb{R}^3$, s
 $g + .$ $x_1 + 2x_2 + s = 5$ $A = [120]$, $s = [5]$
 $x_1 + 2x_3 = 6$ $x_2 + x_3 = 6$ $x_4 + x_5 = 6$

dual of min
$$c^{Tx}$$

s.t. $Ax = b$
 $x > 70$

max b^{Ty}
 $y = y_1, y_2$
 $y_1 + y_2 \le 1$
 $y_1 + y_2 \le 1$
 $y_1 \le 0$
 $y_2 \le 1$

which is equivalent to $\max_{y \in Y_1 + 6y_2} 5y_1 + 6y_2$ s.t. $y_1 + y_2 \le 1$ $y_1 \le 0$ $y_2 \le 1/2$

Strong duality holds.

optimal dual soln: [0, 1], optimal value = 3

Q6)
$$J(x, x) = x^2(1+x) - 6Ax + 1 + 8A$$
 $\nabla_x J(x, x) = 0 \Rightarrow x^* = \frac{3A}{1+x}$ minimizes $J(x, A)$
 $J(x) = J(x^*, A) = -\frac{9A^2}{1+x} + 1 + 8A$

optimal dual solⁿ: max $J(x)$ is attached at $J^* = 2$

And aptimal value = 5

 $J(x, A) = 0 \Rightarrow x^* = \frac{3A}{1+x}$ minimizes $J(x, A)$
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