name Pranav Narayan Pisal
roll no 63 se2

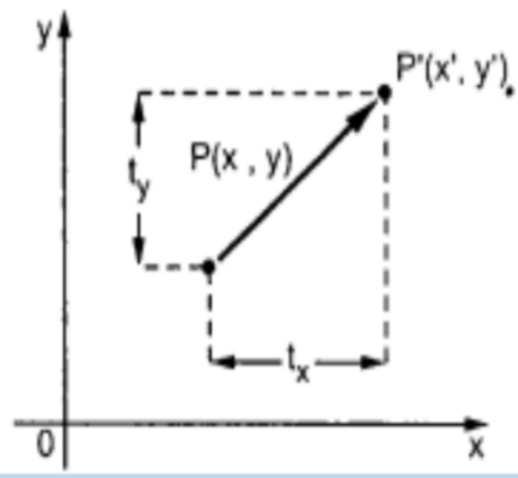
Aim: To implement 2D Transformations: Translation, Scaling, Rotation.

Objective:
To understand the concept of transformation, identify the process of transformation and application of these methods to different object and noting the difference between these transformations.

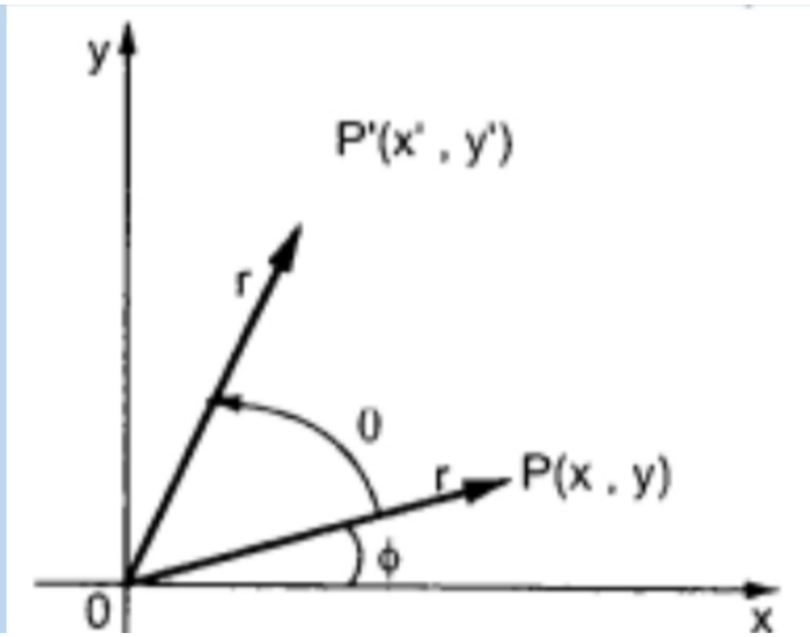
Theory:
1) Translation –
Translation is defined as moving the object from one position to another position along straight line path. We can move the objects based on translation distances along x and y axis. tx denotes translation distance along x-axis and ty denotes translation distance along y axis.

Consider (x,y) are old coordinates of a point. Then the new coordinates of that same point (x’,y’) can be obtained as follows:
x’ = x + tx
y’ = y + ty
We denote translation transformation as P. we express above equations in matrix form as:
P’ = P + T , where

$$P = \begin{bmatrix} x \\ y \end{bmatrix} \quad P' = \begin{bmatrix} x' \\ y' \end{bmatrix} \quad T = \begin{bmatrix} t_x \\ t_y \end{bmatrix}$$



2) Rotation –
A rotation repositions all points in an object along a circular path in the plane centered at the pivot point. We rotate an object by an angle theta. New coordinates after rotation depend on both x and y.



$$x' = x\cos\theta - y\sin\theta$$
$$y' = x\sin\theta + y\cos\theta$$

The above equations can be represented in the matrix form as given below

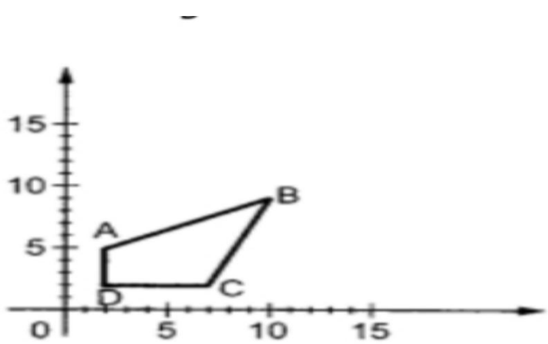
$$[x' \ \ y'] = [x \ \ y]\begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$

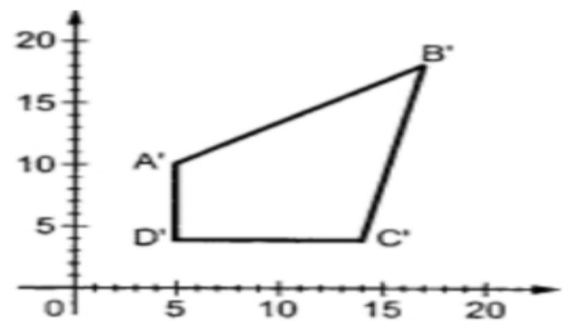
$$P' = P \cdot R$$

where R is the rotation matrix and it is given as

$$R = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$

3) Scaling -
scaling refers to changing the size of the object either by increasing or decreasing. We will increase or decrease the size of the object based on scaling factors along x and y-axis.





If (x, y) are old coordinates of object, then new coordinates of object after applying scaling transformation are obtained as:
x' = x * Sx
y' = y * Sy
Sx and Sy are scaling factors along x-axis and y-axis. we express the above equations in matrix form as:

$$[x' \; y'] = [x \; y] \begin{bmatrix} S_x & 0 \\ 0 & S_y \end{bmatrix}$$
$$= [x \cdot S_x \quad y \cdot Sy]$$
$$= P \cdot S$$

Program

```
#include<stdio.h>
#include<conio.h>
#include<graphics.h>
void main()
{
int gd=DETECT,t,r,gm,ch,sx,sy,tx,ty,nx1,nx2,ny1,ny2;
initgraph(&gd,&gm,"");
line(100,100,200,100);
printf("1.translation,2.rotation,3.scalling:");
printf("enter your ch :");
scanf ("%d",&ch);
switch(ch)
{
case 1:printf("enter transition factor :");
       scanf("%d  %d",&tx,&ty);
       nx1=100+tx;
       nx1=100+ty;
       nx2=200+tx;
       nx2=100+ty;
       line(nx1,ny1,nx2,ny2);
       getch()
case 2:printf("enter angle:");
       scanf("%lf",r);
       t=(3.14*r)/180;
       nx1=(int)(100+(100*cos(t)-(0));
       ny1=(int)(100+(100*sin(t)-(0));
       line(100,100,nx1,ny1);
       getch();
case 3:printf("enter scalling factor :");
       scanf("%d  %d",&sx,&sy);
       nx1=100*sx;
       nx1=100*sy;
       nx2=200*sx;
       nx2=100*sy;
       line(nx1,ny1,nx2,ny2);
       getch();
default:printf("invalid");}
```

```
getch();
closegraph();
      }
```

output: