DATS 6450 Final Term Project Report Predicting Air Quality Index

Pranay Bhakthula
Professor : Reza Jafari
The George Washington University
15th December 2021

Table of Contents

Topic	Page Number
Abstract	4
Introduction	5
Description of Dataset	8
Preprocessing Dataset	8
Plot of the dependent variable versus time	10
ACF/PACF of the dependent variable	10
Correlation matrix	12
Splitting of dataset	12
Stationarity	12
Time series decomposition	16
Holt-winters method	17
Features selection	18
Base models	21
ARMA and ARIMA model	23
Summary and conclusions	34
Appendix	34
References	55

Table of figures and tables

Topic	Page Number
Figure 1: null values1	8
Figure 2: null values2	9
Figure:3 Plot of AQI vs Time	9
Figure:4 ACF plot of 'AQI'	10
Figure 5: Autocorrelation and partial correlation	10
Figure 6: Heatmap	11
Figure 7: splitting data code	11
Figure:8 ADF statistic	12
Figure:9 Test Statistic	12
Figure:10 rolling mean vs time	12
Figure 11 : PCA features correlation matrix	13
Figure: 12 ACF plot of 'AQI 1st order'	14
Figure:13 ADF test on 1st order data	14
Figure:14 KPSS test on 1st order data	14
Figure:!5 rolling mean vs time -1st order differencing	15
Figure:16 rolling variance vs time-1st order differencing	16
Figure:17 Time series Decomposition	16
Figure:18 AQI vs time prediction plot	17
Figure:19 Feature selection	18
Figure:20 Feature selection	19

Figure:21 AQI vs time	20
Figure:22 OLS method	20
Figure:23 AQI vs time(Average)	21
Figure:24 AQI vs time(navie)	22
Figure:25 AQI vs time(Drift)	22
Figure: 26 AQI vs time(ses)	23
Figure:27 GPAC table	24
Figure:28 ACF plot of residual error	26
Figure:29 AQI vs time(ARMA(1,1))	27
Figure:30 AQI vs time(ARMA(1,1))	27
Figure:31 ACF plot of residual error(ARMA(4,4))	29
Figure:32 AQI vs time(ARMA(4,4))	31
Figure: 33 AQI vs time(ARMA(4,4))	31
Figure: 34 ACF plot of residual error	33
Figure:35 AQI vs time(ARIMA)	34
Figure:36 AQI vs time(ARIMA)	34

Abstract:

The focus of this project is to find the best time series model and predict the Air quality Index of 'Delhi' using various time series modelling methods. As the Air Quality Index (AQI) increases, it suggests that the pollution of the city is increasing. It is important for the Government to know the predictions of AQI and try to make policies so as to reduce the pollution of the city. In cities like 'Delhi', air pollution is a major concern and forecasts are required to warn residents to stay in homes, to reduce vehicle traffic and avoid the highways in order to curtail the accidents that happen due to smog/ fog in the months December - January.

Introduction:

In order to complete the objectives of this project we need to do data cleaning which includes filling the missing values with the mean of that column, then we find stationarity of the target variable using ACF plots, ADF, KPSS tests and if the target variables is non-stationary we differentiate the variable in order to make it stationary. We use base models like average method, naive method, drift method, SES method and Holt winter methods to model and predict the test values. These base models are like a lower bar set to compare the ARMA/ ARIMA models to say how much better these models are. We also use the OLS regression method to do feature reduction and also predict the test values. We use the GPAC table to find the na, nb values for the ARMA/ ARIMA models. We perform diagnostic tests on the ARMA/ARIMA models in order to check if the model is good enough in order to forecast. We then select the best model based on the mean, variance of residual and forecast error, plot the forecast values along the test values and see the difference between them.

The following are the theories behind the methods we used in this project.

Autocorrelation:

[source: DATS 6450 time series analysis lecture notes]

Auto correlation measures the linear relationship between lagged values of time series. It is the similarity between observations as a function of the time lag between them.

The notation used for the autocorrelation is Tk which gives the relationship between yt and yt-k. Ry(t) is the estimated autocorrelation for stationary time series y(t).

$$\hat{R_y}(\tau) = \frac{\sum_{t=\tau+1}^T (y_t - \overline{y})(y_{t-\tau} - \overline{y})}{\sum_{t=1}^T (y_t - \overline{y})^2}$$

Average method:

[source: DATS 6450 time series analysis lecture notes]

The forecast of all future values are equal to the average of the historical data.

$$\hat{y}_{T+h|T} = \frac{y_1 + y_2 + \dots + y_T}{T}$$

The average method treats all the observations with equal importance. It gives equal weights while forecasting.

Naive method:

[source: DATS 6450 time series analysis lecture notes]

In the naive method the future value is equal to the last value. While forecast all the values are equal to the last value of the train data.

$$y|t+T = yT$$

Drift method:

[source: DATS 6450 time series analysis lecture notes]

In drift method the forecast values is equal to the last value plus the average change seen in the data. The forecast values graphs is just extrapolating the line connecting 1st and the last value of the train dataset.

$$\hat{y}_{T+h|T} = y_T + \frac{h}{T-1} \sum_{t=2}^{T} (y_t - y_{t-1}) = y_T + h(\frac{y_T - y_1}{T-1})$$

Simple exponential smoothing (SES) method:

SES method is calculated using weighted averages, where least weight value is given the oldest observation from the current data.

$$\hat{y}_{T+1|T} = \sum_{j=0}^{T-1} \alpha (1-\alpha)^j y_{T-j} + (1-\alpha)^T \ell_0$$

Holt Winter method:

The Holt winter method uses three smoothing equations for the forecast equation so that it takes in level, trend and seasonality of the data into account while calculating the forecast values.

$$\hat{y}_{t+h|t} = \ell_t + hb_t + s_{t+h-m(k+1)}$$

$$\ell_t = \alpha y_t + (1 - \alpha)(\ell_{t-1} + b_{t-1})$$

$$b_t = \beta^*(\ell_t - \ell_{t-1}) + (1 - \beta^*)b_{t-1}$$

$$s_t = \gamma(y_t - \ell_{t-1} - b_{t-1}) + (1 - \gamma)s_{t-m}$$

Where, It - level, bt - trend, st - seasonality

ARMA model:

[Jiann-Fuh Chen, Wei-Ming Wang, Chao-Ming Huang,

Analysis of an adaptive time-series autoregressive moving-average (ARMA) model for short-term load forecasting,

Electric Power Systems Research,]

Autoregressive—moving-average (ARMA) models provide a description of a stationary stochastic process in terms of two polynomials, one for the autoregression (AR) and the second for the moving average (MA).

Regressing the variable on its own lagged (i.e., past) values is what the AR component entails. The MA portion entails modeling the error term as a linear combination of error terms that occur simultaneously and at different points in time in the past.

General form of ARMA:

$$y(t) + a_1 y(t-1) + a_2 y(t-2) + \ldots + a_{n_a} y(t-n_a) = \epsilon(t) + b_1 \epsilon(t-1) + b_2 \epsilon(t-2) + \ldots + b_{n_b} \epsilon(t-n_b)$$

ARIMA model:

[Schaffer, A.L., Dobbins, T.A. & Pearson, SA. Interrupted time series analysis using autoregressive integrated moving average (ARIMA) models: a guide for evaluating large-scale health interventions. *BMC Med Res Methodol* 21, 58 (2021).

https://doi.org/10.1186/s12874-021-01235-8]

An autoregressive integrated moving average (ARIMA) model is a generalization of an autoregressive moving average (ARMA) model. Both of these models are fitted to time series data either to better understand the data or to predict future points in the series (forecasting). ARIMA models are applied in some cases where data show evidence of non-stationarity in the sense of mean , where an initial differencing step which corresponds to the "integrated" part of the model, can be applied one or more times to eliminate the non-stationarity of the mean function.

General form of ARIMA:

$$(1+a_1q^{-1}+\ldots+a_{n_a}q^{-n_a})(1-q^{-1})^dy(t)=(1+b_1q^{-1}+\ldots+b_{n_b}q^{-n_b})\epsilon(t)$$

Description of the Dataset:

The dataset contains 707,875 observations which contains hourly data of Air quality Index and other pollutants for 26 cities in India in the period 2015-2020.

Out of these cities we have selected observations of 'Delhi' which has 48,192 observations. We are going to analyze and do the modelling on the Air Quality Index of Delhi.

a. Pre-processing dataset:

The columns of this dataset are:

'City', 'Datetime', 'PM2.5', 'PM10', 'NO', 'NO2', 'NOx', 'NH3', 'CO', 'SO2', 'O3', 'Benzene', 'Toluene', 'Xylene', 'AQI', 'AQI Bucket'.

The target variable is 'AQI' which refers to the Air Quality Index.

The missing values in the dataset are given below:

City	0
Datetime	0
PM2.5	375
PM10	2421
NO	298
N02	330
NOx	25
NH3	980
CO	364
S02	2852
03	2201
Benzene	38
Toluene	26
Xylene	18904
AQI	498
AQI_Bucket	498
	•

Figure:1 null values1

Since the missing values of 'Xylene' are too many, we have dropped that column. For the rest of the numeric variables we have filled the missing values with the mean of respective columns.

For the categorical variables we have filled the missing values with the mode of the column. The missing values in the dataset after data cleaning are given below:

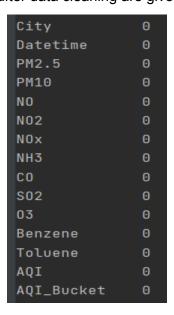


Figure:2 null values2

We have generated the Datetime variable from the date & time 2015-01-01 01:00:00 till 2020-07-01 00:00:00 and added it to the data frame since the given date time column is in string format and was difficult to convert to datatime format.

b. The plot of dependent variable versus the time:

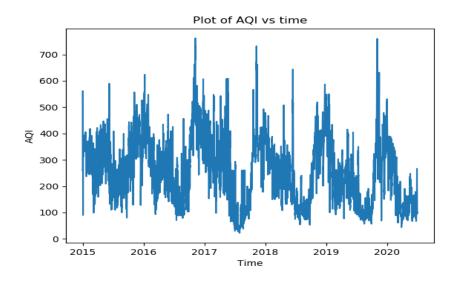


Figure: 3 Plot of AQI vs Time

We can observe from the above graph that the AQI values are distributed within 22 - 762. The mean of AQI is 260.148. The standard deviation of AQI is 120.89. We can observe that AQI values are higher in the months of year ends than in the starting of the year.

c. ACF/PACF of the dependent variable:

The plot of ACF of the dependent variable is shown below:

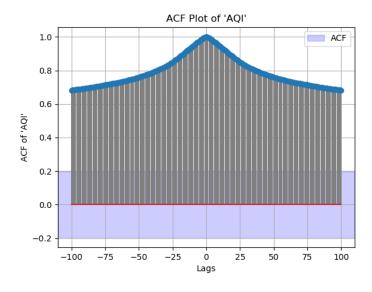


Figure:4 ACF plot of 'AQI'

We can observe that the dependent variable does not tail-off to reach 0 value. So we can say that the variable is non-stationary.

The plot of PACF is shown below:

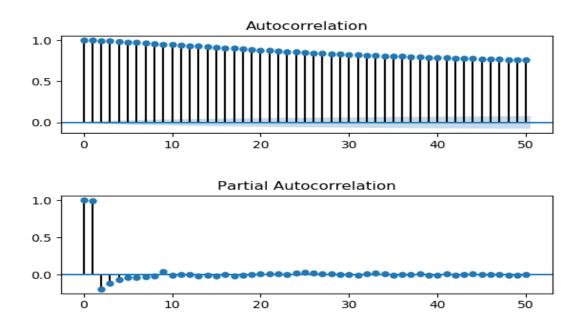


Figure:5 Autocorrelation and partial correlation

We can observe that the dependent variable cuts-off to reach in significant value for lag = 1. So we can say that the nb value we can select as nb = 1.

d. Heatmap of pearson's correlation coefficient:

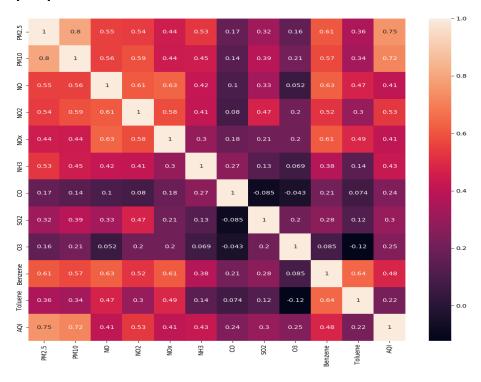


Figure: 6 Heatmap

We can observe that PM10, PM2.5 have high correlation with AQI. All the variables have positive correlation with the target variable.

e. Split the dataset into train and test values:

By using the following code line we can split the dataset into train and test datasets. Notice that shuffle=False since this is a time series dataset.

```
yt_yf = train_test_split(y_shuffle=False_test_size=0.2)
```

Figure:7 splitting data code

Stationarity check:

ADF test:

The results of the ADF tests on the raw data are shown below:

```
ADF Statistic: -8.877810
p-value: 0.000000
Critical Values:
1%: -3.430
5%: -2.862
10%: -2.567
```

Figure:8 ADF statistic

From the ADF test results we can say that the variable is stationary since the p-value is less than 0.05.

KPSS test:

The results of the KPSS tests on the raw data are shown below:

Test Statistic		3.667546
p-value		0.010000
Lags Used		124.000000
Critical Value	(10%)	0.347000
Critical Value	(5%)	0.463000
Critical Value	(2.5%)	0.574000
Critical Value	(1%)	0.739000

Figure:9 Test Statistic

From the KPSS test results we can say that the variable is non - stationary since the p-value is less than 0.05.

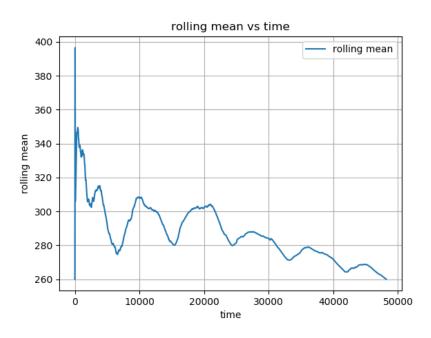


Figure:10 rolling mean vs time

From the rolling mean graph we can see that the trend is decreasing strongly and the values are not constant. So we can say that the variable is non-stationary.

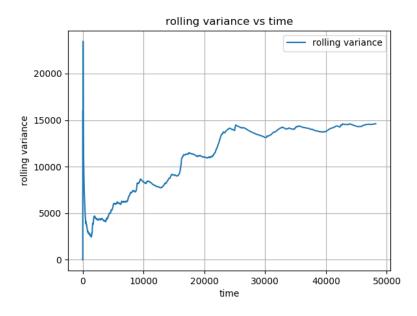


Figure:11 rolling variance vs time

From the rolling variance graph we can see that the value is increasing and the values are not constant. So we can say that the variable is non-stationary.

In order to make our target variable stationary we can use differencing of order 1. This is a commonly used method to make the variable stationary.

ACF plot for 1st order data:

Below is the ACF plot of the 1st order differenced data. We can observe that the variable is stationary since there is a tail off of the ACF values.

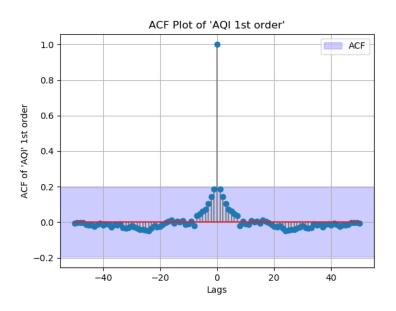


Figure: 12 ACF plot of 'AQI 1st order'

ADF test on 1st order data:

The results of the ADF tests of the 1st order data are shown below:

```
ADF Statistic: -36.101822
p-value: 0.000000
Critical Values:
1%: -3.430
5%: -2.862
10%: -2.567
```

Figure:13 ADF test on 1st order data

From the ADF test results we can say that the variable is stationary, since the p-value is less than 0.05.

KPSS test on 1st order data:

The results of the KPSS tests on the raw data are shown below:

Test Statistic		0.003132
p-value		0.100000
Lags Used		55.000000
Critical Value	(10%)	0.347000
Critical Value	(5%)	0.463000
Critical Value	(2.5%)	0.574000
Critical Value	(1%)	0.739000

Figure:14 KPSS test on 1st order data

From the KPSS test results we can say that the variable is stationary, since the p-value is greater than 0.05.

Rolling mean and variance graphs of 1st order data:

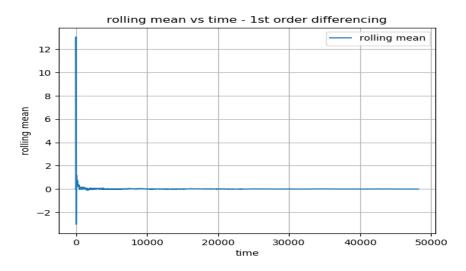


Figure: 15 rolling mean vs time -1st order differencing

From the rolling mean graph we can see that the values are constant and there is no trend. So we can say that the variable is stationary.

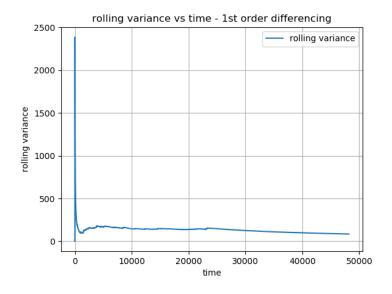


Figure:16 rolling variance vs time-1st order differencing

From the rolling variance graph we can see that the values are constant and there is no major trend. So we can say that the variable is stationary.

Time Series Decomposition:

We performed time series decomposition on the raw data and we get these results:

The strength of trend of the raw data is 0.9944571830068537
The strength of seasonality of the raw data is 0.26967521723997323

Figure: 17 Time series Decomposition

We can observe that there is a very high trend in the raw data since the strength of the trend is very high at around ~ 0.99 and there is low seasonality in the raw data since the strength of the seasonality is low at around ~0.269.

Holt winter method:

We performed holt winter modelling on the raw data and we get these results:

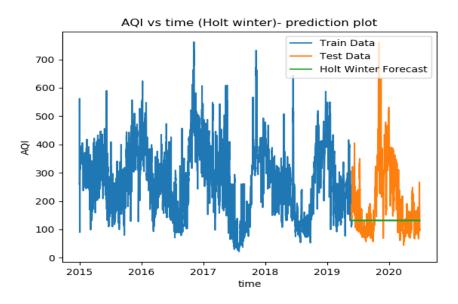


Figure: 18 AQI vs time prediction plot

We can observe that the Holt winter method did not give good predictions as it is not following the test results.

Feature selection:

Shape of H is (12, 12)

Singular Values [8.90020944e+09 2.69478145e+08 1.37153129e+08 1.25948535e+08

5.70047990e+07 3.72612516e+07 2.14860955e+07 1.45793054e+07

1.12590064e+07 3.45208219e+06 3.57062877e+05 1.73365033e+05]

The condition number is 226.5788457225573

Since condition number is greater than 100 and less than 1000, there is moderate degree of collinearity

unknown coefficients:

[0.00876441 0.00661874 0.01115866 -0.02012788 0.00080782 -0.04241885 0.14191928 -0.01810821 0.00537925 -0.0609149 -0.00782991]

We perform feature selection of the dataset using the OLS regression. The results of the OLS regression are shown below:

Omnibus:	19417.069	Durbin-Watson:	1.700
Prob(Omnibus):	0.000	Jarque-Bera (JB):	24352299.775
Skew:	-0.883	Prob(JB):	0.00
Kurtosis:	126.114	Cond. No.	164.
===============			==============

Figure: 19 Feature selection 1

Here we can observe that NOx has a p-value of 0.576, which is high so we can remove this variable and run the regression again.

```
OLS Regression Results
Dep. Variable:
                                       AQI R-squared (uncentered):
                                       OLS Adj. R-squared (uncentered):
Model:
Model: OLS Adj. R-squared (uncentered):

Method: Least Squares F-statistic:

Date: Wed, 15 Dec 2021 Prob (F-statistic):

Time: 15:42:10 Log-Likelihood:

No. Observations: 38552 AIC:

Df Residuals: 38542 BIC:
                                                                                               86.60
                                                                                         1.48e-177
                                                                                          2.867e+05
                                                                                           2.868e+05
Df Model:
Covariance Type: nonrobust

    0.0087
    0.001
    9.668
    0.000
    0.007
    0.011

    0.0066
    0.001
    10.920
    0.000
    0.005
    0.008

    0.0114
    0.001
    8.386
    0.000
    0.009
    0.014

               -0.0197 0.002 -8.053 0.000
                                                                   -0.024
                                                                                 -0.015

    -0.0425
    0.003
    -16.880
    0.000
    -0.047

    0.1431
    0.017
    8.667
    0.000
    0.111

    -0.0185
    0.005
    -3.434
    0.001
    -0.029

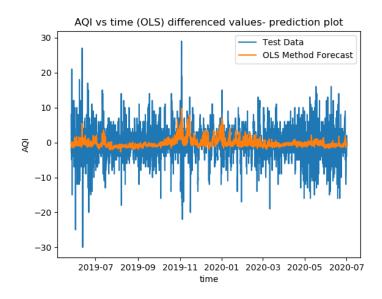
                                                                                   0.176
                                                                                  -0.008
               0.0056 0.001
                                                                                   0.008
Benzene
               -0.0585 0.024
                                                      0.014
                                                                     -0.105
                                                                                  -0.012
Toluene -0.0074 0.004 -2.055 0.040 -0.014 -0.000
```

0	10/01 000	Dunkin Watara	4 700
Omnibus:	19421.890	Durbin-Watson:	1.700
Prob(Omnibus):	0.000	Jarque-Bera (JB):	24353863.777
Skew:	-0.883	Prob(JB):	0.00
Kurtosis:	126.118	Cond. No.	159.
=======================================	========		=======================================

Figure: 20 Feature selection 2

Since none of the variables has a high p-value we don't need to drop any variable any more. We can perform predictions with this.

The predictions of the OLS model is:



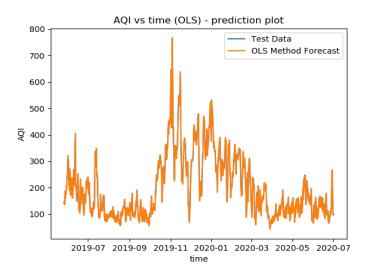


Figure:21 AQI vs time

```
mean of residual error (OLS) method : 0.12969992138649752 variance of residual error (OLS) method : 14.147966213607605
```

Figure:22 OLS method

We can observe that the OLS model is very good at predicting the AQI model. The mean of residual error is low.

Base models:

Average model:

The resultant graph of the average model is shown below:

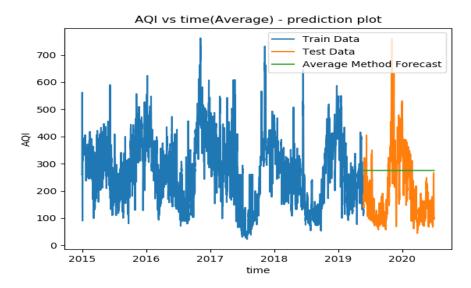


Figure:23 AQI vs time(Average)

From the graph we can see that the forecast of the average method for the length of the test dataset is the average of the train dataset.

Naive model:

The resultant graph of the naive model is shown below:

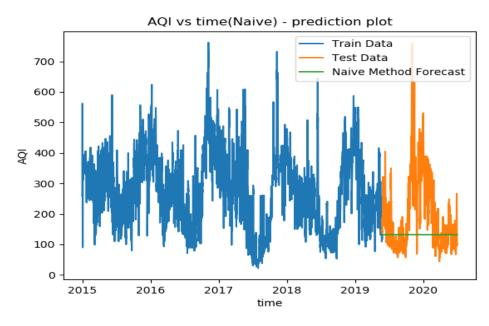


Figure:24 AQI vs time(Naive)

The graph we can see that the forecast of the naive method for the length of the test dataset is the last value of the train dataset.

Drift method:

The resultant graph of the drift model is shown below:

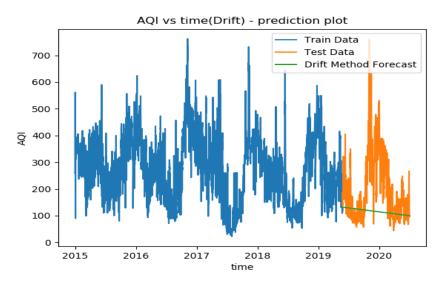


Figure:25 AQI vs time(Drift)

The graph we can see that the forecast of the drift method for the length of the test dataset is the extrapolating the line that connects the 1st and last value of the train dataset.

Simple Exponential Smoothing (SES) method:

The resultant graph of the SES model is shown below:

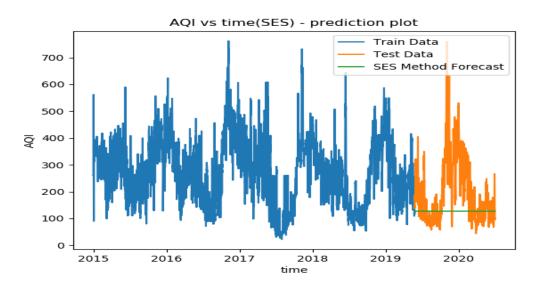


Figure: 26 AQI vs time(ses)

The graph we can see that the forecast of the SES method for the length of the test dataset follows the SES equation. The results are similar to the Holt winter model forecast.

ARMA model:

We perform the GPAC table of the ACF values of the 1st order differenced data. The following is the GPAC table that we obtain from it.

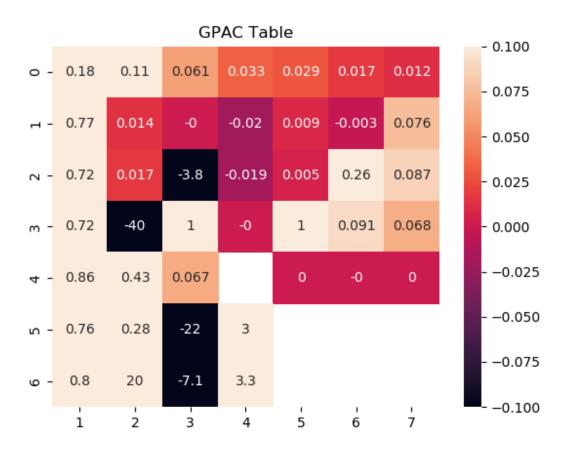


Figure:27 GPAC table

From the above GPAC table we can observe that the 1st column is the column of constants and its 1st row is the row of zeros, since the value of the 1st row is very close to zero.

So we can select the number of AR coefficients, na=1 and the number of MA coefficients, nb=1 for the ARMA and ARIMA models.

We can also select the 4th column as the column of constants and the 4th row is the row of zeros. So we can select the number of AR coefficients, na=4 and the number of MA coefficients nb=4 for the ARMA model.

In this project we performed the 2 ARMA models, each for ARMA(1,1) and ARMA (4,4).

ARMA (1,1) model:

ARMA Model Results

=====

Dep. Variable: AQI No. Observations: 38552

Model: ARMA(1, 1) Log Likelihood -143001.861

Method: css-mle S.D. of innovations 9.879

Date: Wed, 15 Dec 2021 AIC 286009.721

Time: 14:50:05 BIC 286035.401 Sample: 0 HQIC 286017.864

=====

coef std err z P>|z| [0.025 0.975]

ar.L1.AQI 0.7172 0.014 52.598 0.000 0.690 0.744

ma.L1.AQI -0.5756 0.016 -36.161 0.000 -0.607 -0.544

Roots

=====

	Real	Imaginary	Modul	us Frequency
AR.1	1.3944	+0.0000j	1.3944	0.0000
MA.1	1.7373	+0.0000j	1.7373	0.0000

The AR Coefficient : a1 is:, 0.7171753492885212 The MA Coefficient : b1 is:, -0.5755961300211727

The AR coefficient is 0.71 and MA coefficient is -0.57.

The AIC and BIC values are large so we can say that this is a good model.

Diagnostic test:

The ACF plot of residual error is shown below:

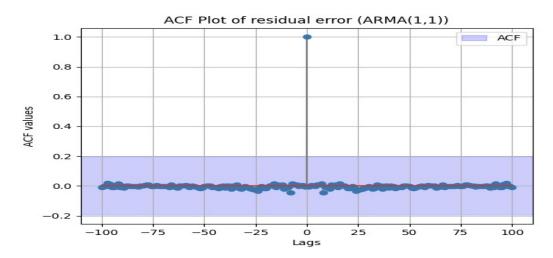


Figure: 28 ACF plot of residual error

Chi Squared test results:

The residuals is white, chi squared value :2.835537718678142

From the above ACF plot we can observe that residual errors is white. We can confirm this by seeing the chi squared test.

confidence intervals of estimated parameters: 0 1

ar.L1.AQI 0.690451 0.743900

ma.L1.AQI -0.606794 -0.544398

zero/cancellation:

zeros : [0.5755961300211727] poles : [-0.7171753492885212]

variance of residual error: 97.59133695867716 variance of forecast error: 16.597283056833152

The variance of residual and forecast are relatively small so this is a good model for forecasting AQI.

The 1-step prediction of 1st 100 samples plot is shown below:

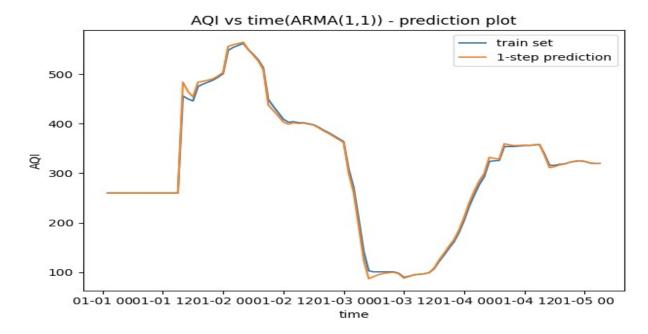


Figure:29 AQI vs time(ARMA(1,1))

The h-step forecast plot is shown below:

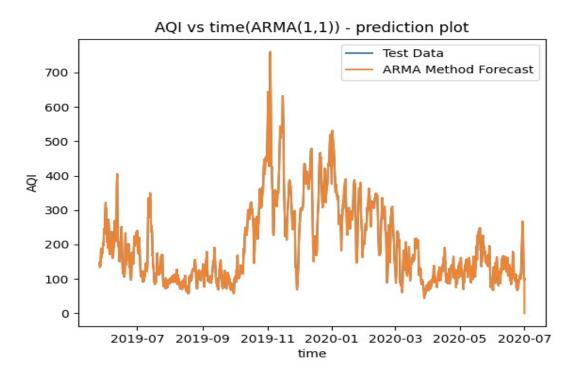


Figure: 30 AQI vs time(ARMA(1,1))

From above 1-step prediction and h-step forecast plots we can see that the model is fitting the predictions very well. So we can say that this is a good model to predict AQI values.

ARMA (4,4) model:

ARMA Model Results

=====

Dep. Variable: AQI No. Observations: 38552

Model: ARMA(4, 4) Log Likelihood -142838.552

Method: css-mle S.D. of innovations 9.837

Date: Wed, 15 Dec 2021 AIC 285695.105

Time: 14:50:39 BIC 285772.142 Sample: 0 HQIC 285719.531

=====

	coef std er	r	z	P> z	[0.025		0.975]		
						•			
ar.L1.AQI	0.1435	0.031	4.624	0.000		0.083		0.204	
ar.L2.AQI	1.1552	0.030	38.202		0.000		1.096		1.215
ar.L3.AQI	0.4000	0.036	10.966		0.000		0.328		0.471
ar.L4.AQI	-0.7201	0.027	-26.590)	0.000	-0.773		-0.667	
ma.L1.AQI	-0.0177	0.032	-0.544		0.586	-0.081		0.046	
ma.L2.AQI	-1.0692	0.028	-38.184	4	0.000	-1.124		-1.014	
ma.L3.AQI	-0.4981	0.036	-13.954	4	0.000	-0.568		-0.428	
ma.L4.AQI	0.5915	0.026	22.701		0.000		0.540		0.643

Roots

=====

	Real	Imaginary	Мо	dulus	Frequency
AR.1	 -0.8673	-0.5638j	1.0344	 -0.40)83
AR.2	-0.8673	+0.5638j	1.0344	0.40	83
AR.3	1.0299	-0.0000j	1.0299	-0.00	000
AR.4	1.2601	-0.0000j	1.2601	-0.00	000
MA.1	-0.8658	-0.5681j	1.0355	-0.40	76
MA.2	-0.8658	+0.5681j	1.0355	0.40	76

MA.3	1.0051	-0.0000j	1.0051	-0.0000
MA.4	1.5685	-0.0000j	1.5685	-0.0000

The AR Coefficient: a1 is:, 0.14351242375438633
The AR Coefficient: a2 is:, 1.1552483558701916
The AR Coefficient: a3 is:, 0.399960107818056
The AR Coefficient: a4 is:, -0.7200561297181469
The MA Coefficient: b1 is:, -0.01767431277600573
The MA Coefficient: b2 is:, -1.0691590548106715
The MA Coefficient: b3 is:, -0.4980845511577915
The MA Coefficient: b4 is:, 0.591488024446287

The AIC and BIC values are large so we can say that this is a good model.

Diagnostic test:

The ACF plot of residual error is shown below:

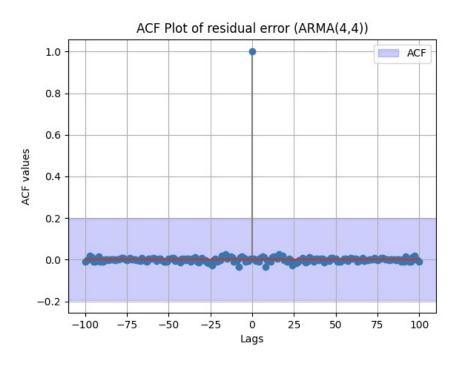


Figure:31 ACF plot of residual error(ARMA(4,4))

Chi Squared test results

The residuals is white, chi squared value :2.288682516508118

From the above ACF plot we can observe that residual errors is white. We can confirm this by seeing the chi squared test.

1

confidence intervals of estimated parameters: 0

ar.L1.AQI 0.082686 0.204339

ar.L2.AQI 1.095978 1.214519

ar.L3.AQI 0.328476 0.471444

ar.L4.AQI -0.773132 -0.666980

ma.L1.AQI -0.081349 0.046000

ma.L2.AQI -1.124038 -1.014280

ma.L3.AQI -0.568043 -0.428126

ma.L4.AQI 0.540420 0.642556

From the confidence intervals we can see that only for one coefficient the interval is crossing 0, which is not good for the model.

zero/cancellation:

zeros: [0.01767431277600573, 1.0691590548106715, 0.4980845511577915,

-0.591488024446287]

poles: [-0.14351242375438633, -1.1552483558701916, -0.399960107818056,

0.7200561297181469]

variance of residual error: 96.77649614930512 variance of forecast error: 16.592978261645367

The 1-step prediction of 1st 100 samples plot is shown below:

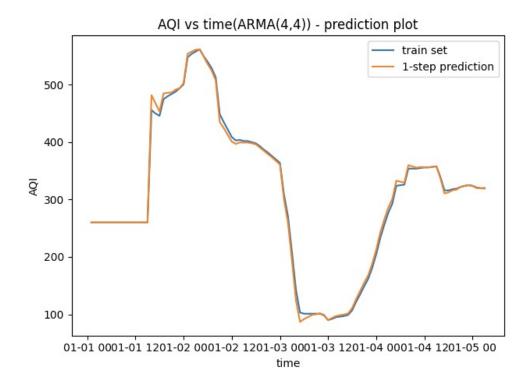


Figure:32 AQI vs time(ARMA(4,4))

The h-step forecast plot is shown below:

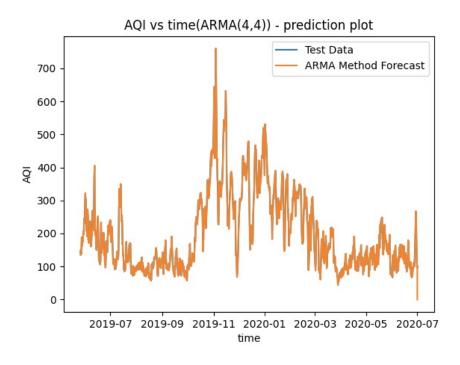


Figure: 33 AQI vs time(ARMA(4,4))

From above 1-step prediction and h-step forecast plots we can see that the model is fitting the predictions very well. So we can say that this is a good model to predict AQI values.

We can observe that the variance of the residual errors is slightly less than the ARMA (1,1). So we can say that the ARMA (4,4) model is better than the ARMA (1,1) model.

ARIMA (1,1,1) model:

ARIMA Model Results

=====

Dep. Variable: D.AQI No. Observations: 38552

Model: ARIMA(1, 1, 1) Log Likelihood -143001.860

Method: css-mle S.D. of innovations 9.879

Date: Wed, 15 Dec 2021 AIC 286011.720

Time: 14:51:01 BIC 286045.959 Sample: 1 HQIC 286022.576

======

coef std err P>|z| [0.025 0.975] Z 0.075 -0.042 -0.0032 0.966 -0.151 0.145 const 0.014 52.598 0.000 ar.L1.D.AQI 0.7172 0.690 0.744 0.016 -36.161 ma.L1.D.AQI -0.5756 0.000 -0.607 -0.544

Roots

=====

	Real	lmaginary	Modul	us Frequency
AR.1	1.3944	+0.0000j	1.3944	0.0000
MA.1	1.7373	+0.0000j	1.7373	0.0000

The AR Coefficient : a1 is:, -0.003177624943659035 The MA Coefficient : b1 is:, 0.7171760560169066 The AIC and BIC values are large so we can say that this is a good model. Diagnostic test:

The ACF plot of residual error is shown below:

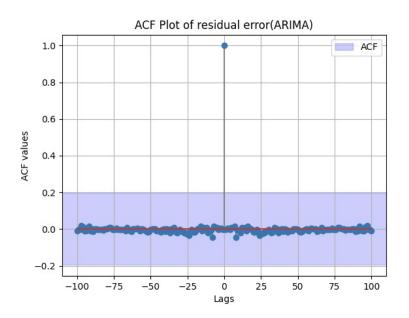


Figure: 34 ACF plot of residual error

Chi Squared test results

The residuals is white, chi squared value :2.8506147859063486

confidence intervals of estimated parameters: 0 1 const -0.151148 0.144793 ar.L1.D.AQI 0.690452 0.743900 ma.L1.D.AQI -0.606795 -0.544399

variance of residual error: 98.04075576373411 variance of forecast error: 13220.248652586179

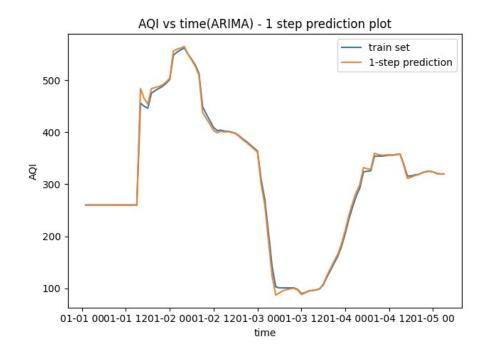


Figure:35 AQI vs time(ARIMA)

The h-step forecast plot is shown below:

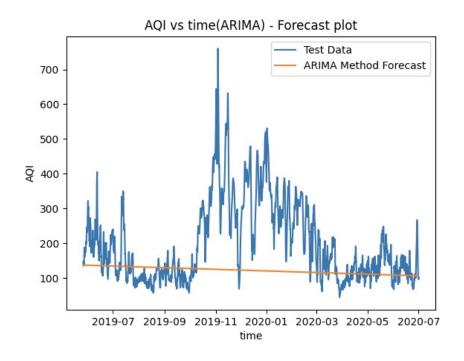


Figure:36 AQI vs time(ARIMA)

We can observe that the ARMA model performed better than the ARIMA model. Even though the 1-step prediction values were good the h-step forecast values are not following the values of test data. We can even observe this from the variance of forecast errors.

So our best model is ARMA (4,4).

Summary and conclusion:

We started off by cleaning the data to remove missing values and performed a stationarity test to check if the raw data is stationary. We found out that the raw data was not stationary so we performed 1st order differencing and checked once again with a stationarity test. We found out that 1st order differenced data is stationary.

We built some base models like average, naive, drift and simple exponential smoothing, Holt winter models to see how they perform for the given data. We have observed that all the base models did not perform exceptionally well.

Then we plotted the GPAC table and found out the auto regressive and moving average orders as na=1 and nb=1, we also found out the 2nd pair of na,nb=4,4.

We built the ARMA (1,1), ARMA(4,4) and ARIMA (1,1,1) models and compared the results of the prediction and forecast and found out that the ARMA(4,4) model is the best model as it has the lowest variance of residual error and variance of forecast error.

We did not perform SARIMA model as we found from the time series decomposition that our dataset did not have much seasonality.

```
Appendix:
import pandas as pd
import matplotlib.pyplot as plt
import numpy as np
from scipy import signal
import statsmodels.api as sm
import math
import seaborn as sns
from statsmodels.graphics.tsaplots import plot acf , plot pacf
from statsmodels.tsa.stattools import adfuller
from statsmodels.tsa.stattools import acf
import TS Helper as helper
import statsmodels.tsa.holtwinters as ets
from sklearn.model selection import train test split
from numpy import linalg as LA
np.random.seed(100)
df = pd.read csv('city hour.csv')
city1 = df['City'].unique()
for i in city1:
z=df[df['City']==i]
print(f'{i} = {len(z)}')
df = df[df['City']=='Delhi']
#======= Data Cleaning
print(df.isnull().sum())
df.drop(['Xylene'],axis=1,inplace=True)
cols = df.columns[2:14]
for i in cols:
df.loc[:,i]=df[i].fillna(np.mean(df[i]))
```

```
df.loc[:,'AQI Bucket'] = df['AQI Bucket'].fillna(df['AQI Bucket'].mode()[0])
print(df.isnull().sum())
df = df.reset index()
start date = '2015-01-01 01:00:00'
date = pd.date range(start=start date, periods=len(df), freq='H')
df['time new'] = date
y = df['AQI']
time= df['time new']
# ======= AQI vs time plot
plt.plot(time,y)
plt.title('Plot of AQI vs time')
plt.xlabel('Time')
# plt.xticks(rotation=90)
plt.ylabel('AQI')
plt.show()
#====== Auto Correlation plot
lags=50
# acf3 = helper.auto correlation cal(y, lags)
acf3 = acf(y, nlags=lags)
plt.stem(np.arange(-lags, lags+1), np.hstack(((acf3[::-1])[:-1],acf3)),
linefmt='grey', markerfmt='o')
m = 1.96 / np.sqrt(100)
plt.axhspan(-m, m, alpha=.2, color='blue')
plt.title("ACF Plot of 'AQI'")
```

```
plt.xlabel("Lags")
plt.ylabel("ACF of 'AQI'")
plt.grid()
plt.legend(["ACF"], loc='upper right')
plt.show()
#====== ACF/PACF plot
helper.ACF PACF Plot(y,50,'AQI')
#====== Correlation plot
plt.figure(figsize=(10,10))
sns.heatmap((df.iloc[:,2:15]).corr(),annot=True)
plt.tight layout()
plt.show()
#====== Stationarity Check
# ADF plot
helper.ADF Cal(y)
# KPSS plot
helper.kpss test(y)
# rolling average
rol m = helper.rolling mean(y)
plt.plot(rol m, label='rolling mean')
plt.title("rolling mean vs time")
plt.xlabel("time")
plt.ylabel("rolling mean")
plt.legend()
plt.grid()
plt.show()
```

```
# rolling variance
rol v = helper.rolling_variance(y)
plt.plot(rol v, label='rolling variance')
plt.title("rolling variance vs time")
plt.xlabel("time")
plt.ylabel("rolling variance")
plt.legend()
plt.grid()
plt.show()
# =========== 1st order differencing ===================
# y1 = helper.diff1(y1)
y1 = y.diff()
lags=50
# acf3 = helper.auto correlation cal(y1, lags)
acf3 = acf(y1[1:], nlags=lags)
linefmt='grey', markerfmt='o')
m = 1.96 / np.sqrt(100)
plt.axhspan(-m, m, alpha=.2, color='blue')
plt.title("ACF Plot of 'AQI 1st order'")
plt.xlabel("Lags")
plt.ylabel("ACF of 'AQI' 1st order")
plt.grid()
plt.legend(["ACF"], loc='upper right')
plt.show()
# rolling average of 1st order differencing
rol m1 = helper.rolling mean(y1[1:])
plt.plot(rol m1, label='rolling mean')
plt.title("rolling mean vs time - 1st order differencing")
plt.xlabel("time")
```

```
plt.ylabel("rolling mean")
plt.legend()
plt.grid()
plt.show()
# rolling variance of 1st order differencing
rol v1 = helper.rolling variance(y1[1:])
plt.plot(rol v1, label='rolling variance')
plt.title("rolling variance vs time - 1st order differencing")
plt.xlabel("time")
plt.ylabel("rolling variance")
plt.legend()
plt.grid()
plt.show()
# ADF test of 1st order differencing
helper.ADF Cal(y1[1:])
# KPSS test of 1st order differencing
helper.kpss test(y1[1:])
-----
from statsmodels.tsa.seasonal import STL
STL=STL(y, period=12)
res = STL.fit()
st = res.seasonal
t = res.trend
rt = res.resid
Ft=1-(np.var(rt)/np.var(t+rt))
print(f'The strength of trend of the raw data is {Ft}')
Fs=1-(np.var(rt)/np.var(st+rt))
print(f'The strength of seasonality of the raw data is {Fs}')
```

```
yt,yf = train test split(y, shuffle=False, test size=0.2)
yt1,yf1 = train test split(y1[1:],shuffle=False,test size=0.2)
dtrain, dtest = train test split(time, shuffle=False, test size=0.2)
holtt=ets.ExponentialSmoothing(yt,trend='mul',damped trend=True,seasonal='mul',
easonal periods=12).fit()
holtf=holtt.forecast(steps=len(yf))
holtf=pd.DataFrame(holtf).set index(yf.index)
plt.plot(dtrain,yt, label='Train Data')
plt.plot(dtest,yf, label='Test Data')
plt.plot(dtest,holtf.values.flatten(), label='Holt Winter Forecast')
plt.title('AQI vs time (Holt winter) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.show()
# ======= Feature Selection
-----
x = df[['PM2.5', 'PM10', 'NO', 'NO2', 'NOx', 'NH3', 'CO',
'SO2', 'O3', 'Benzene', 'Toluene',]]
x = x.iloc[1:,:]
y f = y1[1:]
X train, X test, y train, y test = train test split(x, y f, test size=0.2,
random state=100, shuffle=False)
svd X = df[['PM2.5', 'PM10', 'NO', 'NO2', 'NOx', 'NH3', 'CO',
 'SO2', 'O3', 'Benzene', 'Toluene', 'AQI',]]
```

```
H = np.matmul(svd X.T, svd X)
print(f'Shape of H is {H.shape}')
s, d, v = np.linalg.svd(H)
print(f'Singular Values {d}')
print(f'The condition number is {LA.cond(svd X)}')
print('unknown coefficients :',helper.LSE(X train, y train))
print("==========OLS
MODEL========"")
# X = sm.add constant(X train)
model 1 = sm.OLS(y train, X train)
results 1 = model 1.fit()
print(results 1.summary())
print("=========OLS
-----")
X train new=X train.drop(['NOx'],axis=1)
results 1=sm.OLS(y train,X train new).fit()
print(results 1.summary())
X test new = X test.drop(['NOx'],axis=1)
y pred ols = results 1.predict(X test new)
y pred ols inv =
helper.inverse diff(y[len(yt1)+1:].values,np.array(y pred ols),1)
# def inverse diff forecast(y last,z hat,interval=1):
# y new = np.zeros(len(z hat))
# y new[0] = y last
# for i in range(1,len(z hat)):
# y new[i] = z hat[i-interval] + y new[i-interval]
# # y new = y new[1:]
# return v new
```

```
# y pred ols inv = inverse diff forecast(yt.values[-1],np.array(y pred ols),1)
plt.plot(dtest, y[len(yt1)+1:].values.flatten(), label='Test Data')
plt.plot(dtest[:-1], y pred ols inv, label='OLS Method Forecast')
plt.title('AQI vs time (OLS) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI<u>'</u>)
plt.legend()
plt.show()
print("\n")
plt.plot(dtest, y test.values.flatten(), label='Test Data')
plt.plot(dtest, y pred ols.values.flatten(), label='OLS Method Forecast')
plt.title('AQI vs time (OLS) differenced values- prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.show()
print("\n")
res ols err = y test-y pred ols
lags=100
acf ols err = helper.auto correlation cal(res ols err, lags)
plt.stem(np.arange(-lags+1, lags),
np.hstack(((acf ols err[::-1])[:-1],acf ols err)), linefmt='grey',
markerfmt='o')
m = 1.96 / np.sqrt(100)
plt.axhspan(-m, m, alpha=.2, color='blue')
plt.title("ACF Plot of residual error (OLS)")
plt.xlabel("Lags")
plt.ylabel("ACF values")
plt.grid()
```

```
plt.legend(["ACF"], loc='upper right')
plt.show()
# diagnostic testing
print(f'mean of residual error (OLS) method : {np.mean(res ols err)}')
print(f'variance of residual error (OLS) method : {np.var(res ols err)}')
# ======= Base-Models
# ====== average method
df1 = pd.DataFrame()
y hat=[]
for i in range(len(yt)):
if i==0:
y_hat.append(np.nan)
else:
y hat.append(round((pd.Series(yt)).head(i).mean(),3))
df1['yt']=yt
df1['average']=y_hat
y avg pred = []
for j in yf.index:
y_avg_pred.append(round(df1['yt'].mean(),3))
y avg pred = pd.Series(y avg pred,index=yf.index)
# plt.plot(yt, label='Train Data')
# plt.plot(yf, label='Test Data')
# plt.plot(y avg pred, label='Average Method Forecast')
plt.plot(dtrain,yt, label='Train Data')
plt.plot(dtest,yf, label='Test Data')
```

```
plt.plot(dtest,y avg pred, label='Average Method Forecast')
plt.title('AQI vs time(Average) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.show()
# ======= naive method
y hat1=[]
for i in range(len(df1)):
if i==0:
y hat1.append(np.nan)
else:
y hat1.append(df1.loc[i-1,'yt'])
df1['naive']=y hat1
y naive pred = []
for j in yf.index:
y naive pred.append(round(df1.loc[len(df1)-1,'yt']))
y naive pred = pd.Series(y naive pred, index=yf.index)
# plt.plot(yt, label='Train Data')
# plt.plot(yf, label='Test Data')
# plt.plot(y_naive_pred, label='Naive Method Forecast')
plt.plot(dtrain,yt, label='Train Data')
plt.plot(dtest,yf, label='Test Data')
plt.plot(dtest,y naive pred, label='Naive Method Forecast')
plt.title('AQI vs time(Naive) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.show()
```

```
# ====== drift method
y hat2=[]
for i in range(len(df1)):
if i<=1:</pre>
y hat2.append(np.nan)
else:
y hat2.append(df1.loc[i-1,'yt']+1*((df1.loc[i-1,'yt']-df1.loc[0,'yt'])/((df1.in
dex[i-1]+1)-1) ))
df1['drift']=y hat2
y drift pred = []
h=1
for i in range(len(yf)):
y drift pred.append(df1.loc[len(df1)-1,'yt']+h*((df1.loc[len(df1)-1,'yt']-df1.l
oc[0,'yt'])/(len(df1)-1) ))
h+=1
y drift pred = pd.Series(y drift pred,index=yf.index)
# plt.plot(yt, label='Train Data')
# plt.plot(yf, label='Test Data')
# plt.plot(y drift pred, label='Drift Method Forecast')
plt.plot(dtrain,yt, label='Train Data')
plt.plot(dtest,yf, label='Test Data')
plt.plot(dtest,y drift pred, label='Drift Method Forecast')
plt.title('AQI vs time(Drift) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.show()
# ====== SES method
```

```
y hat3=[]
alpha=0.5
for i in range(len(df1)):
if i==0:
y hat3.append(np.nan)
elif i==1:
y hat3.append(alpha*df1.loc[i-1,'yt']+(1-alpha)*df1.loc[0,'yt']) # since
initial condition is 1st sample
else:
y hat3.append(alpha*df1.loc[i-1,'yt']+(1-alpha)*y hat3[i-1])
df1['ses']=y hat3
y ses pred = []
for i in range(len(yf)):
y ses pred.append(alpha*df1.loc[len(df1)-1,'yt']+(1-alpha)*y hat3[-1])
y ses pred = pd.Series(y ses pred, index=yf.index)
# plt.plot(yt, label='Train Data')
# plt.plot(yf, label='Test Data')
# plt.plot(y ses pred, label='SES Method Forecast')
plt.plot(dtrain,yt, label='Train Data')
plt.plot(dtest,yf, label='Test Data')
plt.plot(dtest, y ses pred, label='SES Method Forecast')
plt.title('AQI vs time(SES) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.show()
# ====== ARMA Process
```

```
acf y2 = acf(y1[1:],100)
helper.Cal GPAC(acf y2,7,7)
na = 1
nb = 1
model = sm.tsa.ARMA(yt1,(na,nb)).fit(trend='nc',disp=0)
print(model.summary())
for i in range(na):
print(f'The AR Coefficient : a{i+1} is:, {model.params[i]}')
for i in range(nb):
print(f'The MA Coefficient : b{i+1} is:, {model.params[i+na]}')
# ======== 1 step prediction ============
def inverse diff(y20,z hat,interval=1):
y \text{ new} = \text{np.zeros(len(y20))}
 for i in range(1,len(z hat)):
y new[i] = z hat[i-interval] + y20[i-interval]
y \text{ new} = y \text{ new}[1:]
return y new
model hat = model.predict(start=0,end=len(yt1)-1)
# res arma error = np.array(yt) - np.array(model hat)
y hat = helper.inverse diff(y[:len(yt1)].values,np.array(model hat),1)
res arma error = y[1:len(yt1)] - y hat
lags=100
helper.ACF PACF Plot(res arma error, lags, 'residual error (ARMA(1,1))')
# acf res = helper.auto correlation cal(res arma error, lags)
acf res = acf(res arma error, nlags= lags)
```

```
plt.stem(np.arange(-lags, lags+1 ), np.hstack(((acf res[::-1])[:-1],acf res)),
linefmt='grey', markerfmt='o')
m = 1.96 / np.sqrt(100)
plt.axhspan(-m, m, alpha=.2, color='blue')
plt.title("ACF Plot of residual error (ARMA(1,1))")
plt.xlabel("Lags")
plt.ylabel("ACF values")
plt.grid()
plt.legend(["ACF"], loc='upper right')
plt.show()
plt.plot(time[:99],y[:99], label = 'train set')
plt.plot(time[:99], y hat[:99], label = '1-step prediction')
plt.title('AQI vs time(ARMA(1,1)) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.tight layout()
plt.show()
# diagnostic testing
from scipy.stats import chi2
print('confidence intervals of estimated parameters:',model.conf int())
poles = []
for i in range(na):
poles.append(-(model.params[i]))
print('zero/cancellation:')
zeros = []
for i in range(nb):
zeros.append(-(model.params[i+na]))
print(f'zeros : {zeros}')
print(f'poles : {poles}')
```

```
Q = len(yt)*np.sum(np.square(acf res[lags:]))
DOF = lags-na-nb
alfa = 0.01
chi critical = chi2.ppf(1-alfa, DOF)
print('Chi Squared test results')
if Q<chi critical:</pre>
print(f'The residuals is white, chi squared value :{Q}')
else:
print(f'The residual is NOT white, chi squared value :{Q}')
# ======= h step prediction ==========
forecast = model.forecast(steps=len(yf1))
y arma pred = pd.Series(forecast[0], index=yf1.index)
y hat fore = inverse diff(y[len(yt1):].values,np.array(y arma pred),1)
# h step prediction
plt.plot(dtest,y[len(yt1)+1:].values.flatten(), label='Test Data')
plt.plot(dtest,y hat fore, label='ARMA Method Forecast')
plt.title('AQI vs time(ARMA(1,1)) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.show()
res arma forecast = y[len(yt1)+1:] - y hat fore
print(f'variance of residual error : {np.var(res arma error)}')
print(f'variance of forecast error : {np.var(res arma forecast)}')
```

```
na = 4
nb = 4
model1 = sm.tsa.ARMA(yt1,(na,nb)).fit(trend='nc',disp=0)
print(model1.summary())
for i in range(na):
print(f'The AR Coefficient : a{i+1} is:, {model1.params[i]}')
for i in range(nb):
print(f'The MA Coefficient : b{i+1} is:, {model1.params[i+na]}')
#=========== 1 step prediction ===============
model hat1 = model1.predict(start=0,end=len(yt1)-1)
# res arma error = np.array(yt) - np.array(model hat)
y hat1 = helper.inverse diff(y[:len(yt1)].values,np.array(model hat1),1)
res arma error1 = y[1:len(yt1)] - y hat1
lags=100
helper.ACF_PACF_Plot(res_arma_error1,lags,'ARMA(4,4) residual_error')
# acf res = helper.auto correlation cal(res arma error, lags)
acf res = acf(res arma error1, nlags= lags)
plt.stem(np.arange(-lags, lags+1), np.hstack(((acf res[::-1])[:-1],acf res)),
linefmt='grey', markerfmt='o')
m = 1.96 / np.sqrt(100)
plt.axhspan(-m, m, alpha=.2, color='blue')
plt.title("ACF Plot of residual error (ARMA(4,4))")
```

```
plt.xlabel("Lags")
plt.ylabel("ACF values")
plt.grid()
plt.legend(["ACF"], loc='upper right')
plt.show()
plt.plot(time[:99],y[:99], label = 'train set')
plt.plot(time[:99],y hat1[:99], label = '1-step prediction')
plt.title('AQI vs time(ARMA(4,4)) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.tight layout()
plt.show()
# diagnostic testing
from scipy.stats import chi2
print('confidence intervals of estimated parameters:',model1.conf int())
poles = []
for i in range(na):
poles.append(-(model1.params[i]))
print('zero/cancellation:')
zeros = []
for i in range(nb):
zeros.append(-(model1.params[i+na]))
print(f'zeros : {zeros}')
print(f'poles : {poles}')
Q = len(yt1)*np.sum(np.square(acf res[lags:]))
DOF = lags-na-nb
alfa = 0.01
```

```
chi critical = chi2.ppf(1-alfa, DOF)
print('Chi Squared test results')
if Q<chi critical:</pre>
print(f'The residuals is white, chi squared value :{Q}')
else:
print(f'The residual is NOT white, chi squared value :{Q}')
# ======= h step prediction ==========
forecast1 = model1.forecast(steps=len(yf1))
y arma pred1 = pd.Series(forecast1[0], index=yf1.index)
y hat fore1 = inverse diff(y[len(yt1):].values,np.array(y arma pred1),1)
# h step prediction
plt.plot(dtest,y[len(yt1)+1:].values.flatten(), label='Test Data')
plt.plot(dtest, y hat fore1, label='ARMA Method Forecast')
plt.title('AQI vs time(ARMA(4,4)) - prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.show()
res arma forecast1 = y[len(yt1)+1:] - y hat fore1
print(f'variance of residual error : {np.var(res arma error1)}')
print(f'variance of forecast error : {np.var(res arma forecast1)}')
# ====== ARIMA Process
-----
```

```
na = 1
d=1
nb = 1
# yt,yf=train test split(y, shuffle=False, test size=0.2)
model2 = sm.tsa.ARIMA(endog=yt,order=(na,d,nb)).fit()
print(model2.summary())
for i in range(na):
 print(f'The AR Coefficient : a{i+1} is:, {model2.params[i]}')
for i in range(nb):
print(f'The MA Coefficient : b{i+1} is:, {model2.params[i+na]}')
print('confidence intervals of estimated parameters:',model2.conf int())
# ============ 1 step prediction ======================
model hat2 = model2.predict(start=1,end=len(yt)-1)
y hat3 = inverse diff(y[:len(yt)].values,np.array(model hat2),1)
res arima error = y[1:len(yt)] - y hat3
lags=100
acf res = acf(res arima error, nlags=lags)
plt.stem(np.arange(-lags, lags+1), np.hstack(((acf res[::-1])[:-1],acf res)),
linefmt='grey', markerfmt='o')
m = 1.96 / np.sqrt(100)
plt.axhspan(-m, m, alpha=.2, color='blue')
plt.title("ACF Plot of residual error(ARIMA)")
plt.xlabel("Lags")
plt.ylabel("ACF values")
plt.grid()
plt.legend(["ACF"], loc='upper right')
```

```
plt.show()
plt.plot(time[:99],y[:99], label = 'train set')
plt.plot(time[:99], y hat3[:99], label = '1-step prediction')
plt.title('AQI vs time(ARIMA) - 1 step prediction plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.tight layout()
plt.show()
# diagnostic testing
from scipy.stats import chi2
print('confidence intervals of estimated parameters:',model2.conf int())
Q = len(yt)*np.sum(np.square(acf res[lags:]))
DOF = lags-na-nb
alfa = 0.01
chi critical = chi2.ppf(1-alfa, DOF)
print('Chi Squared test results')
if Q<chi critical:</pre>
print(f'The residuals is white, chi squared value :{Q}')
else:
 print(f'The residual is NOT white, chi squared value :{Q}')
# ============= h step prediction =====================
forecast2 = model2.forecast(steps=len(yf))
y arima pred = pd.Series(forecast2[0], index=yf.index)
# plt.plot(dtrain,yt, label='Train Data')
plt.plot(dtest,yf.values.flatten(), label='Test Data')
```

```
plt.plot(dtest,y_arima_pred.values.flatten(), label='ARIMA Method Forecast')
plt.title('AQI vs time(ARIMA) - Forecast plot')
plt.xlabel('time')
plt.ylabel('AQI')
plt.legend()
plt.show()

res_arima_forecast = np.array(yf) - forecast[0]

print(f'variance of residual error : {np.var(res_arima_error)}')

print(f'variance of forecast error : {np.var(res_arima_forecast)}')
```

References:

https://www.kaggle.com/rohanrao/air-quality-data-in-india

https://plotly.com/

https://dash.plotly.com/dash-core-components

https://dash.plotly.com/dash-html-components

Class lecture videos and lecture material

Labs and assignment code