American Sign Language Prediction

This notebook is in association with the Unified Mentor Machine Learning internship project submission.

The task is to build a system that accepts an ASL input image and detects what the ASL input image represents.

This is an image classification task. We have to classify different ASL hand signs to what they repectively represent. We'll use Transfer Learning for this task, using the EfficientNetB0 model.

Transfer Learning is a machine learning technique where a pretrained model, previously trained on similar data of our own, is used to train a new model for our specific task and accelerate the training process.

Visit Projects' Streamlit App

1. Downloading & Importing Libraries

```
In [1]:
try:
    import kagglehub
except:
    !pip install kagglehub
    import kagglehub
# Download latest version
asl path = kagglehub.dataset download('grassknoted/asl-alphabet')
print('Data source import complete. Dataset path: ', asl path)
Warning: Looks like you're using an outdated `kagglehub` version (installed: 0.3.5), plea
se consider upgrading to the latest version (0.3.6).
Downloading from https://www.kaggle.com/api/v1/datasets/download/grassknoted/asl-alphabet
?dataset version number=1...
     | 1.03G/1.03G [00:33<00:00, 33.1MB/s]
Extracting files...
Data source import complete. Dataset path: /root/.cache/kagglehub/datasets/grassknoted/a
sl-alphabet/versions/1
In [5]:
| ls /root/.cache/kagglehub/datasets/grassknoted/asl-alphabet/versions/1
asl_alphabet_test asl_alphabet_train
In [2]:
# Train images folders.
!ls /root/.cache/kagglehub/datasets/grassknoted/asl-alphabet/versions/1/asl alphabet tra
in/asl alphabet train
A B C D del E F G H I J K L M N nothing O P Q R S space T U V W
X Y Z
In [3]:
# Test images.
! ls /root/.cache/kagglehub/datasets/grassknoted/asl-alphabet/versions/1/asl alphabet tes
```

```
t/asl_alphabet_test
A test.jpg E test.jpg I test.jpg M test.jpg
                                                   P test.jpg
                                                                   S test.jpg W test.jp
B_test.jpg F_test.jpg J_test.jpg nothing_test.jpg Q_test.jpg
                                                                     T_test.jpg X_test.j
pq
C_test.jpg G_test.jpg K_test.jpg N_test.jpg
                                                   R test.jpg
                                                                    U_test.jpg Y_test.jp
D_test.jpg H_test.jpg L_test.jpg O_test.jpg
                                                   space_test.jpg V_test.jpg Z_test.jp
In [4]:
# installing packages.
! pip install icecream dagshub mlflow torchmetrics
Collecting icecream
  Downloading icecream-2.1.3-py2.py3-none-any.whl.metadata (1.4 kB)
Collecting dagshub
  Downloading dagshub-0.4.2-py3-none-any.whl.metadata (11 kB)
Collecting mlflow
  Downloading mlflow-2.19.0-py3-none-any.whl.metadata (30 kB)
Collecting torchmetrics
  Downloading torchmetrics-1.6.1-py3-none-any.whl.metadata (21 kB)
Collecting colorama>=0.3.9 (from icecream)
  Downloading colorama-0.4.6-py2.py3-none-any.whl.metadata (17 kB)
Requirement already satisfied: pygments>=2.2.0 in /usr/local/lib/python3.10/dist-packages
(from icecream) (2.18.0)
Collecting executing>=0.3.1 (from icecream)
  Downloading executing-2.1.0-py2.py3-none-any.whl.metadata (8.9 kB)
Collecting asttokens>=2.0.1 (from icecream)
  Downloading asttokens-3.0.0-py3-none-any.whl.metadata (4.7 kB)
Requirement already satisfied: PyYAML>=5 in /usr/local/lib/python3.10/dist-packages (from
dagshub) (6.0.2)
Collecting appdirs>=1.4.4 (from dagshub)
  Downloading appdirs-1.4.4-py2.py3-none-any.whl.metadata (9.0 kB)
Requirement already satisfied: click>=8.0.4 in /usr/local/lib/python3.10/dist-packages (f
rom dagshub) (8.1.7)
Requirement already satisfied: httpx>=0.23.0 in /usr/local/lib/python3.10/dist-packages (
from dagshub) (0.28.1)
Requirement already satisfied: GitPython>=3.1.29 in /usr/local/lib/python3.10/dist-packag
es (from dagshub) (3.1.43)
Requirement already satisfied: rich>=13.1.0 in /usr/local/lib/python3.10/dist-packages (f
rom dagshub) (13.9.4)
Collecting dacite~=1.6.0 (from dagshub)
  Downloading dacite-1.6.0-py3-none-any.whl.metadata (14 kB)
Requirement already satisfied: tenacity>=8.2.2 in /usr/local/lib/python3.10/dist-packages
(from dagshub) (9.0.0)
Collecting gql[requests] (from dagshub)
  Downloading gql-3.5.0-py2.py3-none-any.whl.metadata (9.2 kB)
Collecting dataclasses-json (from dagshub)
  Downloading dataclasses json-0.6.7-py3-none-any.whl.metadata (25 kB)
Requirement already satisfied: pandas in /usr/local/lib/python3.10/dist-packages (from da
gshub) (2.2.2)
Collecting treelib>=1.6.4 (from dagshub)
  Downloading treelib-1.7.0-py3-none-any.whl.metadata (1.3 kB)
Collecting pathvalidate>=3.0.0 (from dagshub)
  Downloading pathvalidate-3.2.1-py3-none-any.whl.metadata (12 kB)
Requirement already satisfied: python-dateutil in /usr/local/lib/python3.10/dist-packages
(from dagshub) (2.8.2)
Collecting boto3 (from dagshub)
  Downloading boto3-1.35.90-py3-none-any.whl.metadata (6.7 kB)
Collecting dagshub-annotation-converter>=0.1.0 (from dagshub)
  Downloading dagshub_annotation_converter-0.1.2-py3-none-any.whl.metadata (2.5 kB)
Collecting mlflow-skinny==2.19.0 (from mlflow)
  Downloading mlflow skinny-2.19.0-py3-none-any.whl.metadata (31 kB)
Requirement already satisfied: Flask<4 in /usr/local/lib/python3.10/dist-packages (from m
1flow) (3.1.0)
Requirement already satisfied: Jinja2<4,>=2.11 in /usr/local/lib/python3.10/dist-packages
(from mlflow) (3.1.4)
Collecting alembic!=1.10.0,<2 (from mlflow)
  Downloading alembic-1.14.0-py3-none-any.whl.metadata (7.4 kB)
```

```
Collecting docker<8,>=4.0.0 (from mlflow)
  Downloading docker-7.1.0-py3-none-any.whl.metadata (3.8 kB)
Collecting graphene<4 (from mlflow)
  Downloading graphene-3.4.3-py2.py3-none-any.whl.metadata (6.9 kB)
Collecting gunicorn<24 (from mlflow)
  Downloading gunicorn-23.0.0-py3-none-any.whl.metadata (4.4 kB)
Requirement already satisfied: markdown<4,>=3.3 in /usr/local/lib/python3.10/dist-package
s (from mlflow) (3.7)
Requirement already satisfied: matplotlib<4 in /usr/local/lib/python3.10/dist-packages (f
rom mlflow) (3.8.0)
Requirement already satisfied: numpy<3 in /usr/local/lib/python3.10/dist-packages (from m
1flow) (1.26.4)
Requirement already satisfied: pyarrow<19,>=4.0.0 in /usr/local/lib/python3.10/dist-packa
ges (from mlflow) (17.0.0)
Requirement already satisfied: scikit-learn<2 in /usr/local/lib/python3.10/dist-packages
(from mlflow) (1.6.0)
Requirement already satisfied: scipy<2 in /usr/local/lib/python3.10/dist-packages (from m
lflow) (1.13.1)
Requirement already satisfied: sqlalchemy<3,>=1.4.0 in /usr/local/lib/python3.10/dist-pac
kages (from mlflow) (2.0.36)
Requirement already satisfied: cachetools<6,>=5.0.0 in /usr/local/lib/python3.10/dist-pac
kages (from mlflow-skinny==2.19.0->mlflow) (5.5.0)
Requirement already satisfied: cloudpickle<4 in /usr/local/lib/python3.10/dist-packages (
from mlflow-skinny==2.19.0->mlflow) (3.1.0)
Collecting databricks-sdk<1,>=0.20.0 (from mlflow-skinny==2.19.0->mlflow)
  Downloading databricks_sdk-0.40.0-py3-none-any.whl.metadata (38 kB)
Requirement already satisfied: importlib metadata!=4.7.0,<9,>=3.7.0 in /usr/local/lib/pyt
hon3.10/dist-packages (from mlflow-skinny==2.19.0->mlflow) (8.5.0)
Requirement already satisfied: opentelemetry-api<3,>=1.9.0 in /usr/local/lib/python3.10/d
ist-packages (from mlflow-skinny==2.19.0->mlflow) (1.29.0)
Requirement already satisfied: opentelemetry-sdk<3,>=1.9.0 in /usr/local/lib/python3.10/d
ist-packages (from mlflow-skinny==2.19.0->mlflow) (1.29.0)
Requirement already satisfied: packaging<25 in /usr/local/lib/python3.10/dist-packages (f
rom mlflow-skinny==2.19.0->mlflow) (24.2)
Requirement already satisfied: protobuf<6,>=3.12.0 in /usr/local/lib/python3.10/dist-pack
ages (from mlflow-skinny==2.19.0->mlflow) (4.25.5)
Requirement already satisfied: requests < 3, >= 2.17.3 in /usr/local/lib/python <math>3.10/dist-pack
ages (from mlflow-skinny==2.19.0->mlflow) (2.32.3)
Requirement already satisfied: sqlparse<1,>=0.4.0 in /usr/local/lib/python3.10/dist-packa
ges (from mlflow-skinny==2.19.0->mlflow) (0.5.3)
Requirement already satisfied: torch>=2.0.0 in /usr/local/lib/python3.10/dist-packages (f
rom torchmetrics) (2.5.1+cu121)
Collecting lightning-utilities>=0.8.0 (from torchmetrics)
  Downloading lightning utilities-0.11.9-py3-none-any.whl.metadata (5.2 kB)
Collecting Mako (from alembic!=1.10.0,<2->mlflow)
  Downloading Mako-1.3.8-py3-none-any.whl.metadata (2.9 kB)
Requirement already satisfied: typing-extensions>=4 in /usr/local/lib/python3.10/dist-pac
kages (from alembic!=1.10.0,<2->mlflow) (4.12.2)
Requirement already satisfied: lxml in /usr/local/lib/python3.10/dist-packages (from dags
hub-annotation-converter>=0.1.0->dagshub) (5.3.0)
Requirement already satisfied: pillow in /usr/local/lib/python3.10/dist-packages (from da
gshub-annotation-converter>=0.1.0->dagshub) (11.0.0)
Requirement already satisfied: pydantic>=2.0.0 in /usr/local/lib/python3.10/dist-packages
(from dagshub-annotation-converter>=0.1.0->dagshub) (2.10.3)
Requirement already satisfied: urllib3>=1.26.0 in /usr/local/lib/python3.10/dist-packages
(from docker < 8, >= 4.0.0 -> mlflow) (2.2.3)
Requirement already satisfied: Werkzeug>=3.1 in /usr/local/lib/python3.10/dist-packages (
from Flask<4->mlflow) (3.1.3)
Requirement already satisfied: itsdangerous>=2.2 in /usr/local/lib/python3.10/dist-packag
es (from Flask<4->mlflow) (2.2.0)
Requirement already satisfied: blinker>=1.9 in /usr/local/lib/python3.10/dist-packages (f
rom Flask<4->mlflow) (1.9.0)
Requirement already satisfied: gitdb<5,>=4.0.1 in /usr/local/lib/python3.10/dist-packages
(from GitPython>=3.1.29->dagshub) (4.0.11)
Collecting graphql-core<3.3,>=3.1 (from graphene<4->mlflow)
  Downloading graphql core-3.2.5-py3-none-any.whl.metadata (10 kB)
Collecting graphql-relay<3.3,>=3.1 (from graphene<4->mlflow)
  Downloading graphql_relay-3.2.0-py3-none-any.whl.metadata (12 kB)
Requirement already satisfied: anyio in /usr/local/lib/python3.10/dist-packages (from htt
px >= 0.23.0 - dagshub) (3.7.1)
Requirement already satisfied: certifi in /usr/local/lib/python3.10/dist-packages (from h
ttpx>=0.23.0->dagshub) (2024.12.14)
```

```
Requirement already satisfied: httpcore==1.* in /usr/local/lib/python3.10/dist-packages (
from httpx>=0.23.0->dagshub) (1.0.7)
Requirement already satisfied: idna in /usr/local/lib/python3.10/dist-packages (from http
x \ge 0.23.0 - dagshub) (3.10)
Requirement already satisfied: h11<0.15,>=0.13 in /usr/local/lib/python3.10/dist-packages
(from httpcore==1.*->httpx>=0.23.0->dagshub) (0.14.0)
Requirement already satisfied: MarkupSafe>=2.0 in /usr/local/lib/python3.10/dist-packages
(from Jinja2<4,>=2.11->mlflow) (3.0.2)
Requirement already satisfied: setuptools in /usr/local/lib/python3.10/dist-packages (fro
m lightning-utilities>=0.8.0->torchmetrics) (75.1.0)
Requirement already satisfied: contourpy>=1.0.1 in /usr/local/lib/python3.10/dist-package
s (from matplotlib<4->mlflow) (1.3.1)
Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.10/dist-packages (f
rom matplotlib<4->mlflow) (0.12.1)
Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.10/dist-packag
es (from matplotlib<4->mlflow) (4.55.3)
Requirement already satisfied: kiwisolver>=1.0.1 in /usr/local/lib/python3.10/dist-packag
es (from matplotlib<4->mlflow) (1.4.7)
Requirement already satisfied: pyparsing>=2.3.1 in /usr/local/lib/python3.10/dist-package
s (from matplotlib<4->mlflow) (3.2.0)
Requirement already satisfied: pytz>=2020.1 in /usr/local/lib/python3.10/dist-packages (f
rom pandas->dagshub) (2024.2)
Requirement already satisfied: tzdata>=2022.7 in /usr/local/lib/python3.10/dist-packages
(from pandas->dagshub) (2024.2)
Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.10/dist-packages (from
python-dateutil->dagshub) (1.17.0)
Requirement already satisfied: markdown-it-py>=2.2.0 in /usr/local/lib/python3.10/dist-pa
ckages (from rich>=13.1.0->dagshub) (3.0.0)
Requirement already satisfied: joblib>=1.2.0 in /usr/local/lib/python3.10/dist-packages (
from scikit-learn<2->mlflow) (1.4.2)
Requirement already satisfied: threadpoolctl>=3.1.0 in /usr/local/lib/python3.10/dist-pac
kages (from scikit-learn<2->mlflow) (3.5.0)
Requirement already satisfied: greenlet!=0.4.17 in /usr/local/lib/python3.10/dist-package
s (from sqlalchemy<3,>=1.4.0->mlflow) (3.1.1)
Requirement already satisfied: filelock in /usr/local/lib/python3.10/dist-packages (from
torch \ge 2.0.0 - torchmetrics) (3.16.1)
Requirement already satisfied: networkx in /usr/local/lib/python3.10/dist-packages (from
torch >= 2.0.0 -> torchmetrics) (3.4.2)
Requirement already satisfied: fsspec in /usr/local/lib/python3.10/dist-packages (from to
rch>=2.0.0->torchmetrics) (2024.10.0)
Requirement already satisfied: sympy==1.13.1 in /usr/local/lib/python3.10/dist-packages (
from torch>=2.0.0->torchmetrics) (1.13.1)
Requirement already satisfied: mpmath<1.4,>=1.1.0 in /usr/local/lib/python3.10/dist-packa
ges (from sympy==1.13.1->torch>=2.0.0->torchmetrics) (1.3.0)
Collecting botocore<1.36.0,>=1.35.90 (from boto3->dagshub)
  Downloading botocore-1.35.90-py3-none-any.whl.metadata (5.7 kB)
Collecting jmespath<2.0.0,>=0.7.1 (from boto3->dagshub)
  Downloading jmespath-1.0.1-py3-none-any.whl.metadata (7.6 kB)
Collecting s3transfer<0.11.0,>=0.10.0 (from boto3->dagshub)
  Downloading s3transfer-0.10.4-py3-none-any.whl.metadata (1.7 kB)
Collecting marshmallow<4.0.0,>=3.18.0 (from dataclasses-json->dagshub)
  Downloading marshmallow-3.23.2-py3-none-any.whl.metadata (7.1 kB)
Collecting typing-inspect<1,>=0.4.0 (from dataclasses-json->dagshub)
  Downloading typing inspect-0.9.0-py3-none-any.whl.metadata (1.5 kB)
Requirement already satisfied: yarl<2.0,>=1.6 in /usr/local/lib/python3.10/dist-packages
(from gql[requests]->dagshub) (1.18.3)
Collecting backoff<3.0,>=1.11.1 (from gql[requests]->dagshub)
  Downloading backoff-2.2.1-py3-none-any.whl.metadata (14 kB)
Requirement already satisfied: requests-toolbelt<2,>=1.0.0 in /usr/local/lib/python3.10/d
ist-packages (from gql[requests]->dagshub) (1.0.0)
Requirement already satisfied: sniffio>=1.1 in /usr/local/lib/python3.10/dist-packages (f
rom anyio->httpx>=0.23.0->dagshub) (1.3.1)
Requirement already satisfied: exceptiongroup in /usr/local/lib/python3.10/dist-packages
(from anyio->httpx>=0.23.0->dagshub) (1.2.2)
Requirement already satisfied: google-auth~=2.0 in /usr/local/lib/python3.10/dist-package
s (from databricks-sdk<1,>=0.20.0->mlflow-skinny==2.19.0->mlflow) (2.27.0)
Requirement already satisfied: smmap<6,>=3.0.1 in /usr/local/lib/python3.10/dist-packages
(from gitdb<5,>=4.0.1->GitPython>=3.1.29->dagshub) (5.0.1)
Requirement already satisfied: zipp>=3.20 in /usr/local/lib/python3.10/dist-packages (fro
m importlib metadata!=4.7.0, <9, >=3.7.0->mlflow-skinny=2.19.0->mlflow) (3.21.0)
Requirement already satisfied: mdurl~=0.1 in /usr/local/lib/python3.10/dist-packages (fro
m markdown-it-py>=2.2.0->rich>=13.1.0->dagshub) (0.1.2)
```

```
Requirement already satisfied: deprecated>=1.2.6 in /usr/local/lib/python3.10/dist-packag
es (from opentelemetry-api<3,>=1.9.0->mlflow-skinny==2.19.0->mlflow) (1.2.15)
Requirement already satisfied: opentelemetry-semantic-conventions==0.50b0 in /usr/local/l
ib/python3.10/dist-packages (from opentelemetry-sdk<3,>=1.9.0->mlflow-skinny==2.19.0->mlf
low) (0.50b0)
Requirement already satisfied: annotated-types>=0.6.0 in /usr/local/lib/python3.10/dist-p
ackages (from pydantic>=2.0.0->dagshub-annotation-converter>=0.1.0->dagshub) (0.7.0)
Requirement already satisfied: pydantic-core==2.27.1 in /usr/local/lib/python3.10/dist-pa
ckages (from pydantic>=2.0.0->dagshub-annotation-converter>=0.1.0->dagshub) (2.27.1)
Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.10/dist
-packages (from requests<3,>=2.17.3->mlflow-skinny==2.19.0->mlflow) (3.4.0)
Collecting mypy-extensions>=0.3.0 (from typing-inspect<1,>=0.4.0->dataclasses-json->dagsh
  Downloading mypy extensions-1.0.0-py3-none-any.whl.metadata (1.1 kB)
Requirement already satisfied: multidict>=4.0 in /usr/local/lib/python3.10/dist-packages
(from \ yarl < 2.0, >= 1.6 - > gql[requests] - > dagshub) (6.1.0)
Requirement already satisfied: propcache>=0.2.0 in /usr/local/lib/python3.10/dist-package
s (from yar1<2.0, >=1.6->gql[requests]->dagshub) (0.2.1)
Requirement already satisfied: wrapt<2,>=1.10 in /usr/local/lib/python3.10/dist-packages
(from deprecated>=1.2.6->opentelemetry-api<3,>=1.9.0->mlflow-skinny==2.19.0->mlflow) (1.1
Requirement already satisfied: pyasn1-modules>=0.2.1 in /usr/local/lib/python3.10/dist-pa
ckages (from google-auth~=2.0->databricks-sdk<1,>=0.20.0->mlflow-skinny==2.19.0->mlflow)
(0.4.1)
Requirement already satisfied: rsa<5,>=3.1.4 in /usr/local/lib/python3.10/dist-packages (
from google-auth~=2.0->databricks-sdk<1,>=0.20.0->mlflow-skinny==2.19.0->mlflow) (4.9)
Requirement already satisfied: pyasn1<0.7.0,>=0.4.6 in /usr/local/lib/python3.10/dist-pac
kages (from pyasn1-modules>=0.2.1->google-auth~=2.0->databricks-sdk<1,>=0.20.0->mlflow-sk
inny==2.19.0->mlflow) (0.6.1)
Downloading icecream-2.1.3-py2.py3-none-any.whl (8.4 kB)
Downloading dagshub-0.4.2-py3-none-any.whl (255 kB)
                                           - 255.6/255.6 kB 13.0 MB/s eta 0:00:00
Downloading mlflow-2.19.0-py3-none-any.whl (27.4 MB)
                                           - 27.4/27.4 MB 77.6 MB/s eta 0:00:00
Downloading mlflow skinny-2.19.0-py3-none-any.whl (5.9 MB)
                                          - 5.9/5.9 MB 108.0 MB/s eta 0:00:00
Downloading torchmetrics-1.6.1-py3-none-any.whl (927 kB)
                                           - 927.3/927.3 kB 54.7 MB/s eta 0:00:00
Downloading alembic-1.14.0-py3-none-any.whl (233 kB)
                                           - 233.5/233.5 kB 19.0 MB/s eta 0:00:00
Downloading appdirs-1.4.4-py2.py3-none-any.whl (9.6 kB)
Downloading asttokens-3.0.0-py3-none-any.whl (26 kB)
Downloading colorama-0.4.6-py2.py3-none-any.whl (25 kB)
Downloading dacite-1.6.0-py3-none-any.whl (12 kB)
Downloading dagshub annotation converter-0.1.2-py3-none-any.whl (33 kB)
Downloading docker-7.1.0-py3-none-any.whl (147 kB)
                                           - 147.8/147.8 kB 14.2 MB/s eta 0:00:00
Downloading executing-2.1.0-py2.py3-none-any.whl (25 kB)
Downloading graphene-3.4.3-py2.py3-none-any.whl (114 kB)
                                           - 114.9/114.9 kB 10.5 MB/s eta 0:00:00
Downloading gunicorn-23.0.0-py3-none-any.whl (85 kB)
                                           - 85.0/85.0 kB 8.0 MB/s eta 0:00:00
Downloading lightning utilities-0.11.9-py3-none-any.whl (28 kB)
Downloading pathvalidate-3.2.1-py3-none-any.whl (23 kB)
Downloading treelib-1.7.0-py3-none-any.whl (18 kB)
Downloading boto3-1.35.90-py3-none-any.whl (139 kB)
                                           • 139.2/139.2 kB 13.1 MB/s eta 0:00:00
Downloading dataclasses json-0.6.7-py3-none-any.whl (28 kB)
Downloading backoff-2.2.1-py3-none-any.whl (15 kB)
Downloading botocore-1.35.90-py3-none-any.whl (13.3 MB)
                                           - 13.3/13.3 MB 93.5 MB/s eta 0:00:00
Downloading databricks_sdk-0.40.0-py3-none-any.whl (629 kB)
                                          -- 629.7/629.7 kB 44.7 MB/s eta 0:00:00
Downloading graphql core-3.2.5-py3-none-any.whl (203 kB)
                                          - 203.2/203.2 kB 18.9 MB/s eta 0:00:00
Downloading graphql relay-3.2.0-py3-none-any.whl (16 kB)
Downloading jmespath-1.0.1-py3-none-any.whl (20 kB)
Downloading marshmallow-3.23.2-py3-none-any.whl (49 kB)
                                           - 49.3/49.3 kB 4.2 MB/s eta 0:00:00
Downloading s3transfer-0.10.4-py3-none-any.whl (83 kB)
                                          - 83.2/83.2 kB 6.4 MB/s eta 0:00:00
Downloading typing inspect-0.9.0-py3-none-any.whl (8.8 kB)
```

```
Downloading gql-3.5.0-py2.py3-none-any.whl (74 kB)
                                           - 74.0/74.0 kB 7.0 MB/s eta 0:00:00
Downloading Mako-1.3.8-py3-none-any.whl (78 kB)
                                           - 78.6/78.6 kB 7.5 MB/s eta 0:00:00
Downloading mypy extensions-1.0.0-py3-none-any.whl (4.7 kB)
Installing collected packages: appdirs, treelib, pathvalidate, mypy-extensions, marshmall
ow, Mako, lightning-utilities, jmespath, gunicorn, graphql-core, executing, dacite, color
ama, backoff, asttokens, typing-inspect, icecream, graphql-relay, docker, botocore, alemb
ic, torchmetrics, s3transfer, graphene, gql, dataclasses-json, databricks-sdk, dagshub-an
notation-converter, boto3, mlflow-skinny, dagshub, mlflow
Successfully installed Mako-1.3.8 alembic-1.14.0 appdirs-1.4.4 asttokens-3.0.0 backoff-2.
2.1 boto3-1.35.90 botocore-1.35.90 colorama-0.4.6 dacite-1.6.0 dagshub-0.4.2 dagshub-anno
tation-converter-0.1.2 databricks-sdk-0.40.0 dataclasses-json-0.6.7 docker-7.1.0 executin
g-2.1.0 ggl-3.5.0 graphene-3.4.3 graphql-core-3.2.5 graphql-relay-3.2.0 gunicorn-23.0.0 i
cecream-2.1.3 jmespath-1.0.1 lightning-utilities-0.11.9 marshmallow-3.23.2 mlflow-2.19.0
mlflow-skinny-2.19.0 mypy-extensions-1.0.0 pathvalidate-3.2.1 s3transfer-0.10.4 torchmetr
ics-1.6.1 treelib-1.7.0 typing-inspect-0.9.0
```

In [6]:

```
# Importing libraries.
import mlflow
import dagshub
from torchvision import datasets, transforms
from torch.utils.data import Dataset, DataLoader
import torch.nn.functional as F
import torchvision
import torch
import torchmetrics
import torch.nn as nn
from sklearn.metrics import classification report, confusion matrix, precision recall cur
ve, roc curve
from sklearn.model selection import train test split
from sklearn.utils.class weight import compute class weight
from typing import Dict, Any, Optional
from urllib.parse import urlparse
from icecream import ic
from rich.progress import track
import os
import pickle
import plotly
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import plotly.express as px
import plotly.io as pio
# pio.templates.default = "seaborn"
pio.renderers.default = "colab"
```

2. Data Loader Script

This is the data_loader.py script used to load the images, pytorch model, optimizer, and learning rate scheduler.

```
In [7]:
```

```
%%writefile data_loader.py
import os
import torchvision
import torch
import numpy as np
import pandas as pd
import torch.nn as nn
from typing import Dict, List, Optional, Tuple
from dataclasses import dataclass, field
from torchvision import datasets, transforms
from torch.utils.data import DataLoader
from torch.utils.data import WeightedRandomSampler
```

```
from torch.utils.data.distributed import DistributedSampler
from sklearn.utils.class_weight import compute_class_weight
NUM WORKERS = os.cpu count()
def load data objs(
   batch size: int,
   rank: int,
   world size: int,
   epochs: int,
   x train path: str,
   gpu: bool,
    gpu id: int,
   learning rate: float,
   num workers: int,
   lr scheduler: Optional[str] = None,
) -> tuple[DataLoader, DataLoader, nn.Module, nn.CrossEntropyLoss, torch.optim.Optimizer
, Optional[torch.optim.lr_scheduler._LRScheduler]]:
    # Loading DEFAULT = best available weights of EfficientNet B0 model
   weights = torchvision.models.EfficientNet B0 Weights.DEFAULT
    # Loading transform for transforming the images to be compatible with EfficientNet B0
mode1
   auto transforms = weights.transforms()
   torch.save(auto transforms, "effnetb0 transform.pt")
    # Loading EfficientNet B0 model
   model = torchvision.models.efficientnet b0(weights=weights)
    # Use ImageFolder to create dataset(s)
    train data = datasets.ImageFolder(x train path, transform=auto transforms)
    torch.save(train data, "train data.pt")
    # val data = datasets. ImageFolder(x val path, transform=auto transforms)
    # Get class names
    class names = train data.classes
    torch.save(class names, "class names.pt")
    # Freeze all base layers in the "features" section of the model (the feature extracto
r) by setting requires_grad=False
   for param in model.features.parameters():
       param.requires grad = False
    # Recreate the classifier layer
    model.classifier = nn.Sequential(
       nn.Dropout (p=0.2, inplace=True),
       nn.Linear(in features=1280, out features=len(class names), bias=True))
    optimizer = torch.optim.Adam(
       params=model.parameters(), lr=learning rate, weight decay=1e-4)
    criterion = nn.CrossEntropyLoss()
    if gpu:
       dist sampler train = DistributedSampler(
            train_data, num_replicas=world_size, rank=rank, seed=42)
        train_dtl = DataLoader(train_data, batch_size=batch_size, shuffle=False,
                               pin_memory=True, sampler=dist_sampler_train, num workers=
num workers, )
        # dist sampler val = DistributedSampler(val data, num replicas=world size, rank=
rank, seed=42)
        # val dtl = DataLoader(val data, batch size=1, shuffle=False, pin memory=True, sa
mpler=dist sampler val, num workers=num workers, )
   else:
       train dtl = DataLoader(train data, batch size=batch size,
                               shuffle=True, pin memory=True, num workers=num workers, )
        # val dtl = DataLoader(val dts, batch size=1, shuffle=False, pin memory=True, num
workers=num workers, )
```

Writing data loader.py

3. PyTorch Engine Script

This is the <code>pt_engine.py</code> script, used to train the the model and save model checkpoints.

```
In [13]:
```

```
%%writefile pt engine.py
from torch.nn.parallel import DistributedDataParallel as DDP
from torch.utils.data import DataLoader
from typing import List, Dict, Optional
from rich.progress import track
from pathlib import Path
from icecream import ic
import torch.distributed as dist
import torch.nn.functional as F
import torch.nn as nn
import numpy as np
import random
import torchmetrics
import torch
import time
import os
def set seed(seed):
   random.seed(seed)
   np.random.seed(seed)
   torch.manual seed (seed)
   if torch.cuda.is available():
        torch.cuda.manual seed(seed)
        torch.cuda.manual seed all(seed)
def loss metric tensor(array: List[Dict[str, np.ndarray]]) -> torch.Tensor:
    all tensors = [torch.tensor([[array[0][j][k] for k in range(
        len(array[0][j]))]], dtype=torch.float32) for j in array[0].keys()]
   b = torch.cat(all_tensors, dim=0)
    return b.transpose(0, 1)
class CustomTrainer:
   def __init__(
        self,
       model: nn.Module,
        train data: DataLoader,
        # val data: DataLoader,
        criterion: nn.CrossEntropyLoss,
        optimizer: torch.optim.Optimizer,
        gpu id: int,
```

```
save path: str | Path,
        gpu: bool,
        patience: int = 5,
        max epochs: int = 10,
        world size: int = 1,
        scheduler: Optional[torch.optim.lr scheduler. LRScheduler] = None
        ) -> None:
        self.model = model
        self.train data = train data
        # self.val data = val data
        self.criterion = criterion
        self.optimizer = optimizer
        self.gpu id = gpu id
        self.save path = save path
        self.gpu = gpu
        self.patience = patience
        self.max_epochs = max epochs
        self.world size = world size
        self.scheduler = scheduler
        if self.gpu:
            self.model = DDP(self.model.to(self.gpu id), device ids=[self.gpu id])
            self.train_losses_ = [{f'train_losses{i}': np.array([]) for i in range(self.
world size) }]
             # self.val losses = [{f'val losses{i}': np.array([]) for i in range(self.wo
rld size) } ]
            self.train f1s = [{f'train metrics{i}}': np.array([]) for i in range(self.wo
rld size) } ]
            # self.val fls = [{f'val metrics{i}': np.array([]) for i in range(self.worl
d size) }]
            self.train accuracies = [{f'train metrics{i}}': np.array([]) for i in range(
self.world size) } ]
            # self.val accuracies = [{f'val metrics{i}': np.array([]) for i in range(se
lf.world size) } ]
            self.train metric accuracy = torchmetrics.classification.MulticlassAccuracy(
num classes=29, average="micro", sync on compute=False).to(self.gpu id)
            self.train metric flscore = torchmetrics.classification.MulticlassFlScore(nu
m_classes=29, average="macro", sync_on_compute=False).to(self.gpu_id)
            # self.val_metric_accuracy = torchmetrics.classification.BinaryAccuracy(sync
on compute=False).to(self.gpu id)
           # self.val metric flscore = torchmetrics.classification.BinaryFlScore(sync o
n compute=False).to(self.gpu id)
        else:
            self.train losses = [{"losses": np.array([])}]
            # self.val losses = [{"losses": np.array([])}]
            self.train_f1s_ = [{"metrics": np.array([])}]
            # self.val f1s = [{"metrics": np.array([])}]
            self.train_accuracies_ = [{"metrics": np.array([])}]
# self.val_accuracies_ = [{"metrics": np.array([])}]
            self.train metric accuracy = torchmetrics.classification.MulticlassAccuracy(
num classes=29, average="micro")
            self.train metric f1score = torchmetrics.classification.MulticlassF1Score(nu
m classes=29, average="macro")
            # self.val_metric_accuracy = torchmetrics.classification.BinaryAccuracy()
            # self.val metric f1score = torchmetrics.classification.BinaryF1Score()
    def run batch(self, source: torch.Tensor, targets: torch.Tensor, pred labels: np.nd
array) -> tuple[float]:
        source = source.to(self.gpu id)
        targets = targets.to(self.gpu id)
        self.model.train()
        self.optimizer.zero grad()
        y logits = self.model(source)
        preds = torch.softmax(y logits, dim=1)
        preds = torch.argmax(preds, dim=1)
        loss = self.criterion(y_logits, targets)
        loss.backward()
        self.optimizer.step()
        pred labels[0]['preds'].extend(preds.detach().cpu().numpy().tolist())
```

```
pred labels[0]['targets'].extend(targets.cpu().numpy().tolist())
        self.train metric accuracy.update(preds, targets)
        self.train metric f1score.update(preds, targets)
        return loss.item(), pred labels
    def run epoch(self, epoch: int, total epochs: int) -> tuple[float, float, float]:
        total samples = len(self.train data.dataset)
        num batches = len(self.train_data)
        total loss = 0
        total accuracy = 0
        total f1score = 0
        total samples = 0
        if self.qpu:
            self.train data.sampler.set epoch(epoch)
            self.train_metric_accuracy.reset()
            self.train_metric_f1score.reset()
        pred labels = np.array([{'targets': [], 'preds': []}])
        for source, targets in track(self.train data,
                         description=f"""{f"[GPU{self.gpu_id}] " if self.gpu else ""}Epo
ch {epoch + 1}/{total epochs} | Training: {num batches} batches...""", style='red', compl
ete style='cyan', finished style='green'):
            batch size = source.size(0) # Get batch size
            total samples += batch size # Accumulate total samples
            loss, pred labels = self. run batch(source, targets, pred labels)
            total loss += loss * batch size
        avg loss = total_loss / total_samples_
        accuracy = self.train metric accuracy.compute()
        flscore = self.train metric flscore.compute()
        return avg_loss, accuracy.item(), f1score.item(), pred_labels
    def save checkpoint(self, loss: float, accuracy: float, flscore: float, pred labels
: np.ndarray) -> None:
        ckp = self.model.module.state dict()
        ckp path = f"{self.save path}/best model.pt"
        torch.save(ckp, ckp path)
        np.save("loss train.npy", loss, allow pickle=True)
        np.save("accuracy_train.npy", accuracy, allow_pickle=True)
np.save("flscore_train.npy", flscore, allow_pickle=True)
        np.save("pred_labels.npy", pred_labels, allow pickle=True)
        if self.qpu:
            print(f"\t\tNew best model saved at {ckp path} from GPU{self.gpu id}.")
            print(f"\t\tNew best model save at {ckp path}.")
    def gather tensor(self, t: torch.Tensor) -> torch.Tensor:
        gathered_t = [torch.zeros_like(t) for _ in range(self.world_size)]
        torch.distributed.all_gather(gathered_t, t)
        return torch.cat(gathered t, dim=0)
    def train(self) -> None:
        if self.qpu:
            should stop = torch.zeros(1).to(self.gpu id)
            patience count = torch.zeros(1, dtype=torch.int32).to(self.gpu id)
            # Gather losses from all GPUs
            train losses = [torch.zeros(1).to(self.gpu id)
                            for in range(self.world size)]
            # val_losses = [torch.zeros(1).to(self.gpu_id)
```

```
# for in range(self.world size)]
            train fls = [torch.zeros(1).to(self.gpu id)
                        for in range(self.world size)]
            # val f1s = [torch.zeros(1).to(self.gpu id)
                       for _ in range(self.world size)]
            train accuracies = [torch.zeros(1).to(self.gpu id)
                               for in range(self.world size)]
            # val accuracies = [torch.zeros(1).to(self.gpu id)
                               for in range(self.world size)]
            train losses t = torch.empty(0).to(self.gpu id)
            train metrics t = torch.empty(0).to(self.gpu id)
       else:
           should stop = torch.zeros(1)
            patience count = torch.zeros(1, dtype=torch.int32)
           train losses = []
            # val losses = []
           train_fls = []
           \# val_fls = []
           train accuracies = []
            # val_accuracies = []
           train losses t = []
           train metrics t = []
       set seed(42)
       for epoch in range(self.max epochs):
            train loss, train accuracy, train f1, pred labels = self. run epoch(epoch, s
elf.max epochs)
           print(
               f"""\t{f"[GPU{self.gpu id}] | " if self.gpu else ""}Batches: {len(self.t
rain data)} per GPU | train loss: {train loss:.4f} | train accuracy: {train accuracy:.4f}
| train f1: {train f1:.4f} | Learning Rate: {self.optimizer.param groups[0]['lr']:.6f}"""
            if self.scheduler is not None:
                self.scheduler.step(val loss)
            ic(pred labels[0]['targets'][-6:], pred labels[0]['preds'][-6:])
            # Save losses for all GPUs
            if self.gpu:
               try:
                    torch.distributed.all gather(
                       train losses, torch.tensor([train loss]).to(self.gpu id))
                    torch.distributed.all gather(
                       train fls, torch.tensor([train fl]).to(self.gpu id))
                    torch.distributed.all gather(
                       train accuracies, torch.tensor([train accuracy]).to(self.gpu id)
                except RuntimeError as e:
                    print(f"Error gathering losses: {e}")
                    break
                for i in range(self.world size):
                    self.train_losses_[0][f"train_losses{i}"] = np.append(
                        self.train_losses_[0][f"train_losses{i}"], train losses[i].item(
) )
                    self.train f1s [0][f"train metrics{i}"] = np.append(
                        self.train f1s [0][f"train_metrics{i}"], train_f1s[i].item())
                    self.train_accuracies_[0][f"train_metrics{i}"] = np.append(
                        self.train accuracies [0][f"train metrics{i}"], train accuracies
[i].item())
                train losses t = loss metric tensor(self.train losses )
                train metrics t = loss metric tensor(self.train f1s )
                train losses last item = np.min(train losses t[-1:].squeeze().numpy())
                train metrics last item = np.max(train metrics t[-1:].squeeze().numpy())
                bval loss = np.min(train losses t.numpy())
                bval metric = np.max(train metrics t.numpy())
                improved = torch.tensor([False], dtype=torch.bool).to(self.gpu id)
```

```
else:
                self.train_losses_[0]["losses"] = np.append(self.train_losses_[0]["losse
s"], train losses)
                self.train f1s [0]["metrics"] = np.append(self.train f1 s[0]["metrics"],
train fls)
                self.train accuracies [0]["metrics"] = np.append(self.train accuracies [
0]["metrics"], train accuracies)
                train losses last item = self.train losses [0]["losses"][-1]
                train metrics last item = self.train f1s [0]["metrics"][-1]
                bval loss = np.min(self.train losses )
                bval metric = np.max(self.train fls )
                improved = torch.tensor([False], dtype=torch.bool)
            if self.qpu:
                if (len(torch.where(train losses t == train losses last item)[1]) == 1)
and (
                        len(torch.where(train metrics t == train metrics last item)[1])
== 1):
                    train_losses_last_gpu = torch.where(
                        train losses t == train losses last item)[1].item()
                    train_metrics_last_gpu = torch.where(
                        train_metrics_t == train_metrics_last_item)[1].item()
                    train_losses_last_gpu_row = torch.where(
                        train losses t == train losses last item)[0].item()
                    train_metrics_last_gpu_row = torch.where(
                        train metrics t == train metrics last item)[0].item()
                    train losses last metric = train metrics t[train losses last gpu row
, train losses last gpu]
                    train metrics last loss = train losses t[train metrics last gpu row,
train metrics last gpu]
                    if (train losses last item == bval loss) and (train metrics last ite
m == bval metric) and (
                            train losses last gpu == train metrics last gpu) and (self.g
pu id == train losses last gpu):
                        print(f"""\t\t1/1:[GPU{self.gpu_id}] train_loss improved to {
                        train_losses_last_item:.4f} | train_f1score improved to {train_m
etrics last item:.4f}""")
                        self._save_checkpoint(train_loss, train_accuracy, train_f1, pred
labels)
                        improved = torch.tensor([True], dtype=torch.bool).to(self.gpu id
                        time.sleep(2)
                    elif (train losses last item == bval loss) and (train metrics last i
tem == bval metric) and (
                            train losses last gpu != train metrics last gpu) and (self.g
pu id == train losses last gpu):
                        print(f"""\t\t1/2:[GPU{self.gpu id}] train_loss improved to {
                        train losses last item:.4f} | train f1score: {train losses last
metric:.4f}""")
                        self. save checkpoint(train loss, train accuracy, train f1, pred
labels)
                        improved = torch.tensor([True], dtype=torch.bool).to(self.gpu id
                        time.sleep(2)
                    elif (train losses last item == bval loss) and (self.gpu id == train
losses last gpu):
                        print(f"""\t\t1/3:[GPU{self.gpu id}] train loss improved to {
                        train losses last item:.4f} | train f1score: {train losses last
metric:.4f}""")
                        self. save checkpoint(train loss, train accuracy, train f1, pred
labels)
                        improved = torch.tensor([True], dtype=torch.bool).to(self.gpu id
```

```
time.sleep(2)
                    elif (train metrics last item == bval metric) and (self.gpu id == tr
ain metrics last gpu):
                        print(f"""\t\t1/4[GPU{self.gpu_id}] train_loss: {
                        train metrics last loss:.4f} | train flscore improved to {train
metrics_last item:.4f}""")
                        self. save checkpoint(train loss, train accuracy, train f1, pred
labels)
                        improved = torch.tensor([True], dtype=torch.bool).to(self.gpu id
                        time.sleep(2)
                elif (len(torch.where(train losses t == train losses last item)[1]) == 1
) and (
                        len(torch.where(train metrics t == train metrics last item)[1])
> 1):
                    train losses last gpu = torch.where(
                        train_losses_t == train_losses_last_item)[1].item()
                    train_losses_last_gpu_row = torch.where(
                        train losses t == train losses last item)[0].item()
                    train_losses_last_metric = train_metrics_t[train_losses_last_gpu_row
, train_losses_last_gpu]
                    if (train losses last item == bval loss) and (self.gpu id == train l
osses last gpu):
                        print(f"""\t\t3:[GPU{self.gpu id}] train loss improved to {
                        train losses last item:.4f} | train f1score: {train losses last
metric:.4f}""")
                        self. save checkpoint(train loss, train accuracy, train f1, pred
labels)
                        improved = torch.tensor([True], dtype=torch.bool).to(self.gpu id
                        time.sleep(2)
                else:
                    pass
            else:
                if (train losses last item == bval loss) and (train metrics last item ==
bval metric):
                    print(f"""\t\t1:train_loss improved to {
                    train losses last item:.4f} | train flscore improved to {train metri
cs_last item:.4f}""")
                    self. save checkpoint (train loss, train accuracy, train f1, pred lab
els)
                    improved = torch.tensor([True], dtype=torch.bool)
                    time.sleep(2)
                elif train losses last item == bval_loss:
                    print(f"""\t\t2:train loss improved to {
                    train losses last item: .4f} | train f1score: {train metrics last ite
m:.4f}""")
                    self. save checkpoint(train loss, train accuracy, train f1, pred lab
els)
                    improved = torch.tensor([True], dtype=torch.bool)
                    time.sleep(2)
                elif train metrics last item == bval metric:
                    print(f"""\t\t3:train_loss: {
                    train losses last item:.4f} | train f1score improved to {train metri
cs last item:.4f}""")
                    self. save checkpoint (train loss, train accuracy, train f1, pred lab
els)
                    improved = torch.tensor([True], dtype=torch.bool)
                    time.sleep(2)
                else:
                    pass
```

```
if self.gpu:
                # Synchronize patience count across all GPU
                improved state = self.gather tensor(improved)
                # Update patience count
                if self.world size == 1:
                    if improved state:
                       patience count.zero ()
                        patience count += 1
                else:
                    if (improved state[0] and improved state[1]) or (improved state[0] o
r improved state[1]):
                        patience count.zero ()
                    else:
                        patience count += 1
                # Synchronize patience count across all GPUs
                all_patience_counts = self.gather_tensor(patience_count)
                max patience count = torch.max(all patience counts).item()
                patience_count.fill_(max_patience_count)
                if max patience count >= self.patience:
                        f"\n[GPU{self.gpu id}] Patience exceeded. Early stopping...")
                    should stop[0] = 1
                # Synchronize the should stop tensor across all GPUs
                should stop list = [torch.zeros(1).to(
                    self.gpu id) for  in range(self.world size)]
                torch.distributed.all gather(should stop list, should stop)
                # If any GPU wants to stop, all GPUs should stop
                if any( stop.item() for stop in should stop list):
            else:
                if improved:
                   patience_count.zero ()
                else:
                   patience count += 1
                    if patience count >= self.patience:
                        print(f"\nPatience exceeded. Early stopping...")
                        break
            time.sleep(2)
        if self.qpu:
            # Ensure all GPUs exit the training loop together
            dist.barrier()
            if self.gpu id == 0:
                np.save("train_losses.npy", self.train_losses_, allow_pickle=True)
                np.save("train_f1s.npy", self.train_f1s_, allow_pickle=True)
                np.save("train_accuracies.npy", self.train_accuracies_, allow_pickle=Tru
e)
        else:
            np.save("train_losses.npy", self.train_losses_, allow_pickle=True)
            np.save("train_f1s.npy", self.train_f1s_, allow_pickle=True)
            np.save("train accuracies.npy", self.train accuracies, allow pickle=True)
```

Overwriting pt engine.py

4. Train Script

This the pt train.py script, used to accept training arguments and run the pt engine.py script.

```
%%writefile pt train.py
from torch.distributed import init process group, destroy process group
from pt engine import CustomTrainer
from data loader import load data objs
from typing import Optional
from pathlib import Path
import torch.multiprocessing as mp
import torch.distributed as dist
import numpy as np
import argparse
import random
import torch
import time
import os
NUM WORKERS = os.cpu count()
def find free port():
    """Finds a free port."""
   import socket
   with socket.socket(socket.AF INET, socket.SOCK STREAM) as s:
       s.bind(('', 0)) # Bind to port 0 to get a free port
        print("Got free port...")
        return s.getsockname()[1]
def ddp setup(rank: int, world size: int) -> None:
    Aras:
        rank: Unique identifier of each process
        world size: Total number of processes
    os.environ['MASTER ADDR'] = 'localhost'
   os.environ['MASTER PORT'] = '12355'
    print("Init. process group...")
   dist.init process group("nccl", rank=rank, world size=world size)
    torch.cuda.set device(rank)
def cleanup():
    dist.destroy process group()
def set seed(seed):
   random.seed(seed)
   np.random.seed(seed)
    torch.manual seed (seed)
    if torch.cuda.is available():
        torch.cuda.manual seed(seed)
        torch.cuda.manual seed all(seed)
def main(rank: Optional[int], world size: Optional[int], total epochs: int, patience: int
, batch_size: int, save_path: str | Path, xtrain_path: str, learning_rate: float, lr_sch
eduler: str, gpu: bool) -> None:
   if gpu:
        # if rank == 0:
        print(f"{'>' * 10}ASLClassifier Model Training{'<' * 10}\n")
        ddp setup(rank, world size)
        print("Initializing dataset and model...")
        train dtl, model, criterion, optimizer, scheduler = load data objs(
            batch size, rank, world size, total epochs, xtrain path, gpu, rank,
            learning rate, NUM WORKERS, lr scheduler)
        print("Created dataset and initialized model...")
        trainer = CustomTrainer(model=model, train data=train dtl, criterion=criterion,
optimizer-optimizer, gpu id=rank, save path=save path, gpu=gpu, patience=patience, max ep
ochs=total epochs, world size=world size, scheduler=scheduler)
        print("Starting model training...")
        trainer.train()
```

```
# destroy_process_group()
       cleanup()
       print(f"\n<{'=' * 10}Training completed & best model saved{'=' * 10}>\nExiting..
.")
    else:
       print(f"{'>' * 10}ASLClassifier Model Training{'<' * 10}\n")</pre>
        train dtl, val dtl, model, criterion, optimizer, scheduler = load data objs(
            batch size, rank, world size, total epochs, xtrain path, gpu, rank,
            learning rate, NUM WORKERS, lr scheduler)
        trainer = CustomTrainer(model=model, train data=train dtl, criterion=criterion,
optimizer-optimizer, gpu id-rank, save path-save path, gpu-gpu, patience-patience, max ep
ochs=total epochs, world size=world size, scheduler=scheduler)
        trainer.train()
       print(f"\n<{'=' * 10}Training completed & best model saved{'=' * 10}>\nExiting..
.")
def create model path(path str: str) -> Path | None:
       model_path = Path(path str)
       model path.mkdir(parents=True, exist ok=True)
        # Check if the directory is writable
       if not os.access(model path, os.W OK):
            raise PermissionError(f"The directory {model path} is not writable.")
       return model path
    except PermissionError as e:
       print(f"Permission error: {e}")
       return None
    except OSError as e:
       print(f"OS error occurred when creating directory: {e}")
       return None
    except Exception as e:
       print(f"An unexpected error occurred: {e}")
       return None
def exec time(st: float, et: float) -> None:
   hour = int(et-st)//3600
   minute = int((et-st) %3600)//60
   second = int(et-st)%60
   print(f'\nexec time => {hour:02d}hr : {minute:02d}min : {second:02d}sec')
if name == " main ":
    os.environ['NOTEBOOKAPP IOPUB MSG RATE LIMIT'] = '10000.0'
   os.environ['NOTEBOOKAPP RATE LIMIT WINDOW'] = '10.0'
    os.environ["PYTORCH CUDA ALLOC CONF"] = "expandable segments:True"
    parser = argparse.ArgumentParser(description='simple distributed training job')
    parser.add_argument('--total_epochs', default=10, type=int,
                        help='Total epochs to train the model (default: 10)')
   parser.add_argument('--patience', default=5, type=int,
                        help='Patience for increasing val loss (default: 5)')
    parser.add argument('--batch_size', default=32, type=int,
                        help='Input batch size on each device (default: 32)')
    parser.add argument('--model save path', default='./checkpoints', type=str,
                        help='Path to save the best model (default: ./checkpoints)')
   parser.add argument('--xtrain path', default='X train.npy', type=str,
                        help='Path to X train pytorch tensor (default: X train.npy)')
   parser.add argument('--learning rate', default=0.001, type=float,
                        help='Select learning rate (default: 0.001)')
   parser.add argument('--lr scheduler', default=None, type=str,
                        help='Select learning rate scheduler (default: None)')
    parser.add argument('--world size', default=None, type=int,
                       help='Pass the number of GPUs to be used for training (default: N
one(all))')
   parser.add_argument('--gpu', action='store_true', help='Train on GPU (default)')
```

```
parser.add_argument('--no-gpu', dest='gpu', action='store_false', help='Train on CPU
• )
   parser.set defaults(gpu=True)
   args = parser.parse_args()
   MODEL PATH = create model path(args.model save path)
   if MODEL PATH is None:
       print("Failed to create model path. Exiting program.")
       exit(1)
   if args.gpu:
       if args.world size == None:
            world size = torch.cuda.device count()
       else:
            world size = args.world size
        # Set the start method to 'forkserver'
       mp.set start method('forkserver', force=True)
       set seed(42)
       start time = time.time()
       mp.spawn (main,
                 args=(world size, args.total epochs, args.patience, args.batch size, MO
DEL PATH, args.xtrain path,
                      args.learning rate, args.lr scheduler, args.gpu), nprocs=world si
ze, join=True)
       end time = time.time()
       exec time(start time, end time)
   else:
       start time = time.time()
       set seed(42)
       main (None, None, args.total epochs, args.patience, args.batch size, MODEL PATH,
args.xtrain path,
            args.learning rate, args.lr scheduler, args.gpu)
       end time = time.time()
       exec_time(start_time, end_time)
```

Overwriting pt train.py

```
5. Start Training
In [16]:
# Kaggle
# !python pt train.py --total epochs 10 --batch size 64 --gpu --xtrain path /kaggle/input
/asl-alphabet/asl alphabet train/asl alphabet train --learning rate 0.001 --world size 1
# Colab
!python pt_train.py --total_epochs 10 --batch_size 64 --gpu --xtrain path /root/.cache/k
agglehub/datasets/grassknoted/asl-alphabet/versions/1/asl alphabet train/asl alphabet tra
in --learning rate 0.001 --world size 1
>>>>>>ASLClassifier Model Training<
Init. process group...
[W1229 11:08:17.841494482 CUDAAllocatorConfig.h:28] Warning: expandable segments not supp
orted on this platform (function operator())
Initializing dataset and model...
Downloading: "https://download.pytorch.org/models/efficientnet b0 rwightman-7f5810bc.pth"
to /root/.cache/torch/hub/checkpoints/efficientnet b0 rwightman-7f5810bc.pth
100% 20.5M/20.5M [00:00<00:00, 115MB/s]
Created dataset and initialized model...
Starting model training...
[GPU0] Epoch 1/10 | Training: 1360 batches...
0% 0:07:11
 [GPU0] | Batches: 1360 per GPU | train_loss: 0.6293 | train_accuracy: 0.8809 | train_f1:
0.8805 | Learning Rate: 0.001000
ic| pred labels[0]['targets'][-6:]: [7, 16, 27, 10, 12, 13]
```

```
Prod_rancip[0][ Prodo ][ 0.]. [// 10/ 2// 10/ 12/ 10]
 1/1:[GPU0] train loss improved to 0.6293 | train flscore improved to 0.8805
 New best model saved at checkpoints/best model.pt from GPU0.
[GPU0] Epoch 2/10 | Training: 1360 batches...
0% 0:07:06
 [GPU0] | Batches: 1360 per GPU | train loss: 0.2321 | train accuracy: 0.9448 | train f1:
0.9447 | Learning Rate: 0.001000
ic| pred labels[0]['targets'][-6:]: [22, 13, 12, 20, 10, 24]
   pred labels[0]['preds'][-6:]: [22, 13, 12, 20, 10, 24]
  1/1:[GPU0] train loss improved to 0.2321 | train flscore improved to 0.9447
 New best model saved at checkpoints/best model.pt from GPU0.
[GPU0] Epoch 3/10 | Training: 1360 batches...
0% 0:06:56
[GPU0] | Batches: 1360 per GPU | train loss: 0.1800 | train accuracy: 0.9536 | train f1:
0.9535 | Learning Rate: 0.001000
ic| pred_labels[0]['targets'][-6:]: [21, 22, 18, 8, 10, 9]
    pred labels[0]['preds'][-6:]: [21, 22, 18, 8, 10, 9]
  1/1:[GPU0] train loss improved to 0.1800 | train flscore improved to 0.9535
 New best model saved at checkpoints/best model.pt from GPU0.
[GPU0] Epoch 4/10 | Training: 1360 batches...
0% 0:06:54
 [GPU0] | Batches: 1360 per GPU | train loss: 0.1583 | train accuracy: 0.9567 | train f1:
0.9567 | Learning Rate: 0.001000
ic| pred labels[0]['targets'][-6:]: [22, 22, 14, 8, 1, 10]
   pred labels[0]['preds'][-6:]: [22, 22, 14, 8, 1, 10]
 1/1:[GPU0] train loss improved to 0.1583 | train flscore improved to 0.9567
 New best model saved at checkpoints/best model.pt from GPU0.
[GPU0] Epoch 5/10 | Training: 1360 batches...
0% 0:06:53
 [GPU0] | Batches: 1360 per GPU | train loss: 0.1439 | train accuracy: 0.9600 | train f1:
0.9600 | Learning Rate: 0.001000
ic| pred_labels[0]['targets'][-6:]: [17, 12, 19, 2, 19, 16]
   pred labels[0]['preds'][-6:]: [17, 12, 19, 2, 19, 16]
  1/1:[GPU0] train_loss improved to 0.1439 | train_flscore improved to 0.9600
 New best model saved at checkpoints/best model.pt from GPU0.
[GPU0] Epoch 6/10 | Training: 1360 batches...
0% 0:06:50
 [GPU0] | Batches: 1360 per GPU | train loss: 0.1387 | train accuracy: 0.9610 | train f1:
0.9610 | Learning Rate: 0.001000
ic| pred labels[0]['targets'][-6:]: [22, 17, 9, 17, 19, 15]
   pred labels[0]['preds'][-6:]: [22, 17, 9, 20, 19, 15]
  1/1:[GPU0] train loss improved to 0.1387 | train flscore improved to 0.9610
 New best model saved at checkpoints/best model.pt from GPU0.
[GPU0] Epoch 7/10 | Training: 1360 batches...
0% 0:07:10
 [GPU0] | Batches: 1360 per GPU | train loss: 0.1353 | train accuracy: 0.9610 | train f1:
0.9610 | Learning Rate: 0.001000
ic| pred labels[0]['targets'][-6:]: [26, 5, 20, 7, 7, 14]
    pred labels[0]['preds'][-6:]: [26, 5, 20, 7, 6, 14]
  1/3:[GPU0] train loss improved to 0.1353 | train f1score: 0.9610
 New best model saved at checkpoints/best model.pt from GPU0.
[GPU0] Epoch 8/10 | Training: 1360 batches...
0% 0:06:48
 [GPU0] | Batches: 1360 per GPU | train loss: 0.1315 | train accuracy: 0.9625 | train f1:
0.9625 | Learning Rate: 0.001000
ic| pred labels[0]['targets'][-6:]: [13, 10, 0, 10, 21, 15]
    pred labels[0]['preds'][-6:]: [13, 10, 0, 10, 21, 15]
  1/1:[GPU0] train loss improved to 0.1315 | train flscore improved to 0.9625
 New best model saved at checkpoints/best model.pt from GPU0.
[GPU0] Epoch 9/10 | Training: 1360 batches...
0% 0:06:51
 [GPU0] | Batches: 1360 per GPU | train loss: 0.1308 | train accuracy: 0.9623 | train f1:
0.9623 | Learning Rate: 0.001000
ic| pred labels[0]['targets'][-6:]: [11, 6, 12, 25, 18, 1]
    pred labels[0]['preds'][-6:]: [11, 6, 12, 25, 18, 1]
 1/3:[GPU0] train loss improved to 0.1308 | train f1score: 0.9623
 New best model saved at checkpoints/best model.pt from GPU0.
[GPU0] Epoch 10/10 | Training: 1360 batches...
00% 0:06:48
 [GPU0] | Batches: 1360 per GPU | train_loss: 0.1278 | train_accuracy: 0.9634 | train_f1:
0.9634 | Learning Rate: 0.001000
ic| pred labels[0]['targets'][-6:]: [26, 10, 8, 19, 5, 27]
   nred lahels[N]['nreds'][-6.1. [26 10 8 19 5 27]
```

```
1/1:[GPU0] train_loss improved to 0.1278 | train_flscore improved to 0.9634

New best model saved at checkpoints/best_model.pt from GPU0.

<=======Training completed & best model saved=====>

Exiting...

exec time => 01hr : 10min : 37sec
```

6. Model Evaluation

```
In [17]:
```

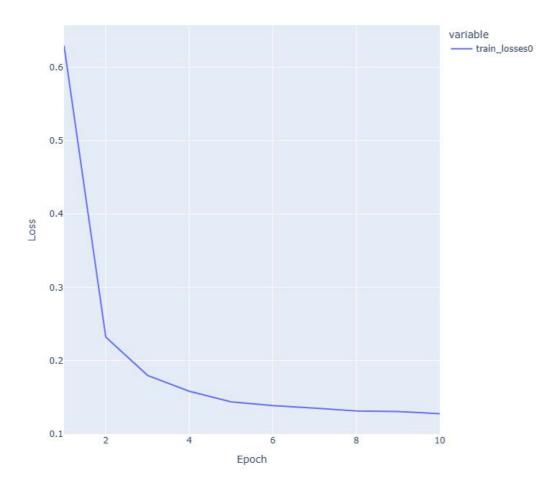
```
# Function for saving plotly plots as html to embed them later
with open('html template.html', 'w') as f:
  f.write("""
  <!doctype html>
 <html>
 <head>
 <meta charset="utf-8" />
 <meta name="viewport" content="width=device-width, initial-scale=1.0" />
 </head>
 <body>
 <!-- <h3>{{ heading }}</h3> -->
  {{ fig }}
 </body>
  </head>
  """)
# Function to save plotly plots as html
def fig to html(fig: plotly.graph objs. figure.Figure,
                # plot heading: str,
                output path: Optional[str]="output.html",
                template path: Optional[str]="html template.html") -> None:
  Convert a plotly figure to an HTML.
  11 11 11
  # Create output directory if it doesn't exist
  output dir = "plotly html"
  os.makedirs(output dir, exist ok=True)
  from jinja2 import Template
  # Convert the figure to HTML
  plotly jinja data = {
      "fig": fig.to html(full html=False, include plotlyjs="cdn"),
      # "heading": plot_heading
  # Load the template
  with open(os.path.join(output dir, output path), "w", encoding="utf-8") as f:
    with open(template path, "r", encoding="utf-8") as template file:
      template = Template(template file.read())
      f.write(template.render(plotly_jinja_data))
```

In [18]:

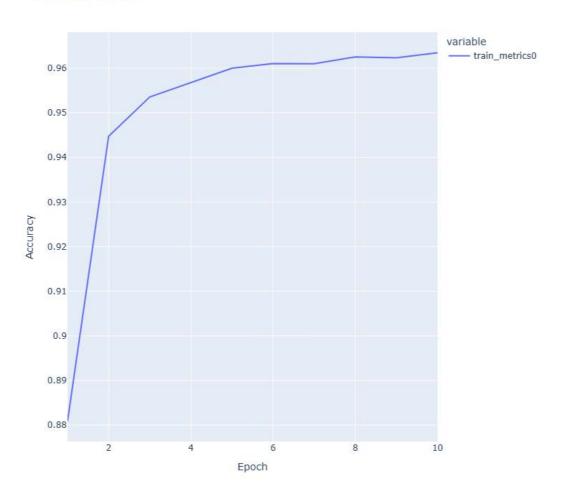
```
# Preparing data for plotting epochs vs metrics curve.
tl_data = pd.DataFrame(np.load('train_losses.npy', allow_pickle=True).item())
ta_data = pd.DataFrame(np.load('train_accuracies.npy', allow_pickle=True).item())
tfl_data = pd.DataFrame(np.load('train_fls.npy', allow_pickle=True).item())
tl_data['epochs'] = np.arange(1, len(tl_data)+1)
ta_data['epochs'] = np.arange(1, len(ta_data)+1)
tfl_data['epochs'] = np.arange(1, len(tfl_data)+1)
# Plotting curve.
```

```
if len(tl data.columns) > 3:
    fig1 = px.line(data_frame=tl_data, x='epochs', y=['train_losses0'], height=750, widt
h=750, title='Loss Curves: GPU0')
    fig1.update xaxes(title text='Epoch',)
    fig1.update yaxes(title text='Loss')
    fig to html(fig1, 'loss curve g0.html')
    fig2 = px.line(data frame=tl data, x='epochs', y=['train losses1'], height=750, widt
h=750, title='Loss Curves: GPU1')
    fig2.update xaxes(title text='Epoch',)
    fig2.update yaxes(title text='Loss')
    fig to html(fig2, 'loss curve g1.html')
    fig2.show()
    fig3 = px.line(data frame=ta data, x='epochs', y=['train metrics0'], height=750, wid
th=750, title='Accuracy Curves: GPU0')
    fig3.update xaxes(title text='Epoch',)
    fig3.update yaxes(title text='Accuracy')
    fig to html(fig3, 'accuracy curve g0.html')
    fig3.show()
    fig4 = px.line(data_frame=ta_data, x='epochs', y=['train_metrics1'], height=750, wid
th=750, title='Accuracy Curves: GPU1')
    fig4.update xaxes(title text='Epoch',)
    fig4.update_yaxes(title_text='Accuracy')
    fig to html(fig4, 'accuracy curve g1.html')
    fig4.show()
    fig5 = px.line(data frame=tf1 data, x='epochs', y=['train metrics0'], height=750, wi
dth=750, title='F1Score Curves: GPU0')
    fig5.update xaxes(title text='Epoch',)
    fig5.update yaxes(title text='F1Score')
    fig to html(fig5, 'f1score curve g0.html')
    fig5.show()
    fig6 = px.line(data frame=tf1 data, x='epochs', y=['train metrics1'], height=750, wi
dth=750, title='F1Score Curves: GPU1')
    fig6.update xaxes(title text='Epoch',)
    fig6.update yaxes(title text='F1Score')
    fig to html(fig6, 'f1score curve g1.html')
    fig6.show()
    # fig1.show(), fig2.show(), fig3.show(), fig4.show(), fig5.show(), fig6.show()
elif len(tl_data.columns == 3) and 'train_losses1' not in tl_data.columns:
    fig1 = px.line(data frame=tl data, x='epochs', y=['train losses0'], height=750, widt
h=750, title='Loss Curves')
    fig1.update xaxes(title text='Epoch',)
    fig1.update yaxes(title text='Loss')
    fig to html(fig1, 'loss curve.html')
    fig2 = px.line(data frame=ta data, x='epochs', y=['train metrics0'], height=750, wid
th=750, title='Accuracy Curves')
    fig2.update xaxes(title text='Epoch',)
    fig2.update yaxes(title text='Accuracy')
    fig to html(fig2, 'accuracy curve.html')
    fig3 = px.line(data frame=tf1 data, x='epochs', y=['train metrics0'], height=750, wi
dth=750, title='F1Score Curves')
    fig3.update xaxes(title text='Epoch',)
    fig3.update_yaxes(title_text='F1Score')
    fig_to_html(fig3, 'f1score curve.html')
    fig1.show(), fig2.show(), fig3.show()
else:
    fig1 = px.line(data_frame=tl_data, x='epochs', y=['train_losses'], height=750, width
=750, title='Loss Curves')
    fig1.update xaxes(title text='Epoch',)
    fig1.update_yaxes(title_text='Loss')
    fig to html(fig1, 'loss curve.html')
    fig2 = px.line(data frame=ta data, x='epochs', y=['train metrics'], height=750, widt
h=750, title='Accuracy Curves')
    fig2.update xaxes(title text='Epoch',)
    fig2.update yaxes(title text='Accuracy')
    fig_to_html(fig2, 'accuracy curve.html')
    fig3 = px.line(data frame=tf1 data, x='epochs', y=['train metrics'], height=750, wid
th=750, title='F1Score Curves')
    fig3.update xaxes(title text='Epoch',)
    fig3.update yaxes(title text='F1Score')
    fig to html(fig3, 'f1score curve.html')
    fig1.show(), fig2.show(), fig3.show()
```

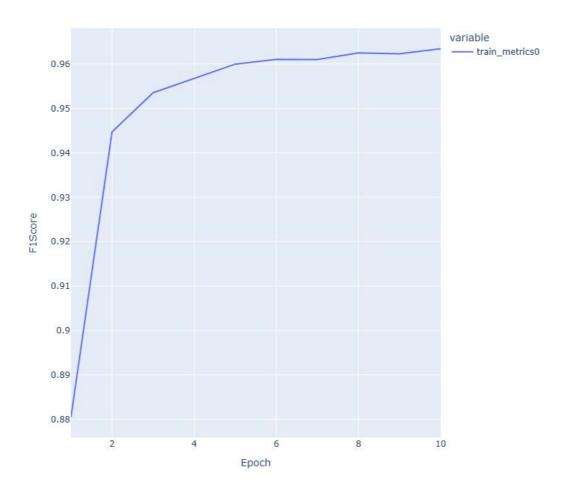
Loss Curves



Accuracy Curves



F1Score Curves



1. Loss Curve: The loss curve for GPU0 rapidly decreases during the initial epochs, this rapid decrease indicates that the model is learning the patterns and relationships in the training data quickly and effectively, indicating quick convergence. The curve starts flattening after epoch 6, indicating that there is little to no improvement happening in model performance. This flattening of the curve suggests that the model has reached a point where further training may not significantly reduce the training error

reaction a point where further training thay not significantly reduce the training error.

- 2. Accuracy Curve: The accuracy increases rapidly, indicating that the model is learning the patterns of the training data well. The accuracy curve almost plateaus around epoch 6, which suggests that the model's performance on the training data has stabilized, consistent with the observation of the loss curve.
- 3. F1 Score Curve: The F1-score curve for GPU0 exhibits a trend similar to the accuracy curve, showing increasing scores rapidly in the initial epochs, and flattening out around epoch 6. This indicates that the model's overall performance, taking into account both precision and recall, is improving initially and the flattening of the F1-score curve suggests that the model's performance on the training data has stabilized and is in line with the observations from the loss and accuracy curves.

In [19]:

In [21]:

wei

```
class_names = torch.load('class_names.pt', weights_only=True)
print(f"Classification Report:\n\n{classification_report(np.array(pred_labels[0]['targets
']), np.array(pred_labels[0]['preds']), target_names=class_names)}")
```

Classification Report:

	precision	ICCAII	II SCOIC	Support
А	0.97	0.97	0.97	3000
В	0.98	0.98	0.98	3000
С	0.99	0.99	0.99	3000
D	0.99	0.99	0.99	3000
E	0.97	0.96	0.97	3000
F	0.99	0.99	0.99	3000
G	0.98	0.97	0.98	3000
Н	0.98	0.99	0.98	3000
I	0.97	0.96	0.96	3000
J	0.97	0.97	0.97	3000
K	0.97	0.97	0.97	3000
L	0.98	0.99	0.99	3000
M	0.95	0.95	0.95	3000
N	0.95	0.96	0.96	3000
Ο	0.98	0.98	0.98	3000
P	0.98	0.97	0.97	3000
Q	0.97	0.98	0.98	3000
R	0.92	0.92	0.92	3000
S	0.93	0.93	0.93	3000
Т	0.94	0.95	0.94	3000
U	0.90	0.90	0.90	3000
V	0.93	0.92	0.92	3000
M	0.95	0.95	0.95	3000
X	0.92	0.92	0.92	3000
Y	0.95	0.96	0.95	3000
Z	0.96	0.96	0.96	3000
del	0.99	0.98	0.99	3000
nothing	1.00	1.00	1.00	3000
space	0.98	0.99	0.99	3000
accuracy			0.96	87000
macro avg	0.96	0.96	0.96	87000
ighted avg	0.96	0.96	0.96	87000

precision recall f1-score support

The classification report provides precision, recall, and F1-score for each individual class.

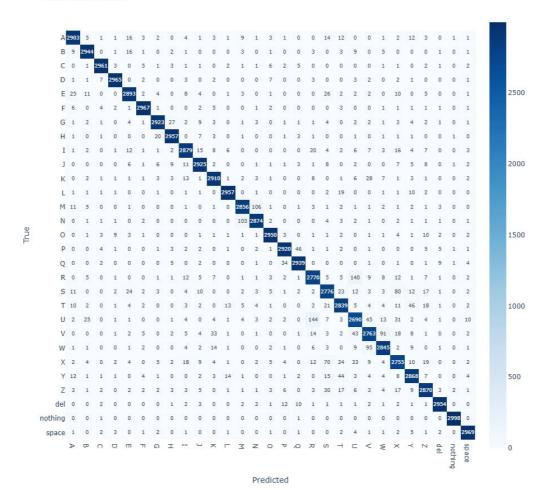
 Precision: Precision is the fraction of correctly classified instances among all instances classified as belonging to a particular class. Higher precision values indicate that the model is making fewer false positive predictions for that class. It can be seen that the values are generally higher than 0.90, indicating good

- performance.
- 2. **Recall:** Recall is the fraction of correctly classified instances among all instances that actually belong to a particular class. Higher recall values indicate that the model is making fewer false negative predictions for that class. These are also above 0.90, indicating good performance.
- 3. **F1-score:** The F1-score is a harmonic mean of precision and recall. It is a good overall measure of the model's performance for a particular class. The F1-scores are above 0.90, indicating good overall performance per class.

Observations: The model performs well on most classes, with high precision, recall, and F1-score values for most classes. This suggests that the model is able to accurately classify those classes in the training dataset. Lower values of precision, recall and F1-score for some classes suggest the need to inspect those classes further, as the model may have some difficulty recognizing patterns related to those classes in the training data. There are a couple of classes for which this is the case in the provided classification report. The results highlight the overall effectiveness of the model in accurately classifying images of sign language letters, with room for potential improvements for certain letter classification using additional training or data augmentation techniques. The high accuracy and relatively balanced scores across classes in the classification report indicate a robust model with good generalization capabilities, making it suitable for detecting different classes of input images.

In [22]:

```
# Plot Confusion Matrix.
def plot confusion matrix(y test: np.ndarray, y preds: np.ndarray, plot name: str) -> No
    """Plot confusion matrix."""
   cm = confusion matrix(y test, y preds)
   fig = px.imshow(
       CM,
       text auto=True, # Display values on the heatmap
       labels=dict(x="Predicted", y="True"), # Set axis labels
       x=class_names, # Update x-axis labels
       y=class names, # Update y-axis labels
       color continuous scale="Blues", # Customize the color scale
       width=920,
       height=920
   fig.update layout(title=f"Confusion Matrix") # Set plot title
   fig to html(fig, f"{plot name}")
   fig.show() # Display plot
plot confusion matrix(np.array(pred labels[0]['targets']), np.array(pred labels[0]['pred
s']), "confusion matrix.html")
```



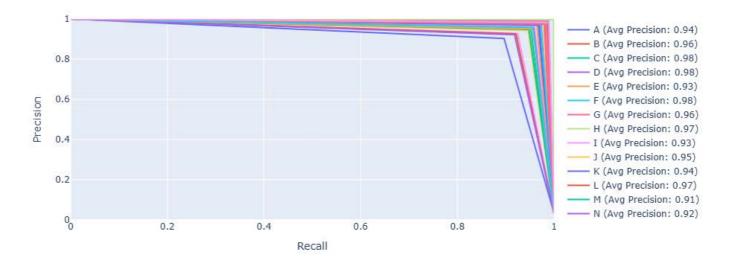
Plotting Precision-Recall Curve

In [24]:

```
def plot precision recall curve (y test: np.ndarray, y preds: np.ndarray, plot name: str)
-> None:
    """Plot precision-recall curve."""
    import plotly.graph objects as go
    from sklearn.metrics import precision recall curve, average precision score
    from sklearn.preprocessing import label binarize
    # Assuming you have 'y test' (true labels) and 'y preds' (predicted labels)
    # 1. Binarize the labels
    n classes = len(class names) # Get the number of classes
    y_test_bin = label_binarize(y_test, classes=range(n_classes))
    y preds bin = label binarize(y preds, classes=range(n classes))
    # 2. Create the Plotly figure
```

```
fig = go.Figure()
    # 3. Calculate and plot precision-recall curves for each class
   for i, cls in enumerate(class names):
       precision, recall, _ = precision_recall_curve(y_test_bin[:, i], y_preds_bin[:, i
])
       avg precision = average precision score(y test bin[:, i], y preds bin[:, i])
       fig.add trace(go.Scatter(
           x=recall,
            y=precision,
            mode='lines',
            name=f"{cls} (Avg Precision: {avg_precision:.2f})"
       ) )
    # 4. Update layout for better visualization
   fig.update layout(
```

Precision-Recall Curve

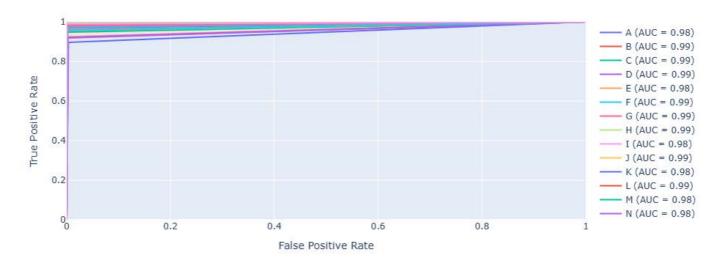


In [25]:

```
# Plotting ROC Curve
def plot_roc_curve(y_test: np.ndarray, y_preds: np.ndarray, plot_name: str) -> None:
    import plotly.graph objects as go
    from sklearn.metrics import roc curve, auc, roc auc score
    from sklearn.preprocessing import label_binarize
    """Plots the ROC curve."""
    # 1. Binarize the labels.
    n classes = len(class names) # Get the number of classes
    y test bin = label binarize(y test, classes=range(n classes))
    y preds bin = label binarize(y preds, classes=range(n classes))
    # 2. Create the figure.
    fig = go.Figure()
    # 3. Calculate the fpr and tpr.
    for i, cls in enumerate(class names):
        fpr, tpr, _ = roc_curve(y_test_bin[:, i], y_preds bin[:, i])
        roc auc = auc(fpr, tpr)
        fig.add trace(go.Scatter(
            x=fpr,
```

```
y=tpr,
            mode='lines',
            name=f"{cls} (AUC = {roc auc:.2f})"
        ) )
    # 4. Update the plot.
    fig.update layout(
        title=f"ROC Curve",
        xaxis title="False Positive Rate",
        yaxis title="True Positive Rate",
        xaxis range=[0, 1],
        yaxis range=[0, 1],
        showlegend=True
    fig to html(fig, f"{plot name}")
    fig.show() # Display
plot_roc_curve(np.array(pred_labels[0]['targets']), np.array(pred_labels[0]['preds']), "
roc curve.html")
```

ROC Curve



7. Logging Experiment to DAGHub mlflow.

In [26]:

!dagshub login

 $\Box\Box\Box$ AUTHORIZATION REQUIRED $\Box\Box\Box$

Open the following link in your browser to authorize the client: https://dagshub.com/login/oauth/authorize?state=5e9f46bf-8f65-477f-9856-39013ba507a0&client_id=32b60ba385aa7cecf24046d8195a71c07dd345d9657977863b52e7748e0f0f28&middleman_request_id=d972e48f304c6d1b9a616dfbeb1090bc3a3234a181f03e06950c0daa17bc3aa6

```
: Waiting for authorization
☐ OAuth token added
In [28]:
from google.colab import userdata
repo_owner_ = userdata.get('REPO OWNER')
repo name = userdata.get('REPO NAME')
tracking uri = userdata.get('MLFLOW TRACKING URI')
# from kaggle secrets import UserSecretsClient
# repo_owner_ = UserSecretsClient().get secret("REPO OWNER")
# repo name = UserSecretsClient().get secret("REPO NAME")
# tracking uri = UserSecretsClient().get secret("MLFLOW TRACKING URI")
os.makedirs('tmp', exist ok=True)
# Creating function to log experiments to mlflow
def create experiment (experiment name: str, run name: str, run metrics: Dict[str, Any], mo
del: nn.Module, model_name: Optional[str] = None, artifact_paths: Dict[str, str] = {}, r
un_params: Optional[Dict[str, Any]] = None, tag_dict: Dict[str, str] = {"tag1":"Binary Cl
assification", "tag2": "Patient Survival Prediction", "tag3": "PyTorch"}):
    try:
        dagshub.init(repo_owner=f"{repo_owner_}", repo_name=f"{repo_name_}", mlflow=True
)
        # You can get your MLlfow tracking uri from your dagshub repo by opening "Remote"
dropdown menu, go to "Experiments" tab and copy the MLflow experiment tracking uri and pa
ste below
        mlflow.set tracking uri(f"{tracking uri}")
        mlflow.set experiment(experiment name)
        with mlflow.start run(run name=run name):
            # log params
            if run params:
                for param in run params:
                    mlflow.log_param(param, run_params[param])
            # log metrics
            for metric, value in run_metrics.items():
                if isinstance(value, list):
                    # If the metric is a list, log each value as a separate step
                    for step, v in enumerate(value):
                        mlflow.log metric(metric, v, step=step)
                elif isinstance(value, str):
                    value = np.load(value, allow pickle=True)
                    mlflow.log metric(metric, value)
                else:
                    # If it's a single value, log it normally
                    mlflow.log metric(metric, value)
            tracking url type store = urlparse(mlflow.get tracking uri()).scheme
            # log artifacts
            for artifact name, path in artifact paths.items():
                if path and os.path.exists(path):
                    if tracking url type store != "file":
                        mlflow.log artifact(
                            path,
                            # artifact name
                        )
```

print(f"Warning: Artifact file not found: {path}")

elif path:

log model

In [42]:

```
import builtins
torch.serialization.add safe globals([torchvision.transforms.presets.ImageClassification
, torchvision.transforms.functional.InterpolationMode, torchvision.datasets.folder.Image
Folder, torchvision.datasets.vision.StandardTransform, torchvision.datasets.folder.defau
lt loader, builtins.set])
class names = torch.load("class names.pt", weights only=True)
transforms = torch.load("effnetb0 transform.pt", weights only=True)
model = torchvision.models.efficientnet b0().to(0)
for param in model.features.parameters():
   param.requires_grad = False
# Recreate the classifier layer
model.classifier = nn.Sequential(
    nn.Dropout (p=0.2, inplace=True),
    nn.Linear(in features=1280, out features=len(class names), bias=True))
model.load state dict(torch.load('checkpoints/best model.pt', weights only=True))
images = datasets.ImageFolder("/root/.cache/kagglehub/datasets/grassknoted/asl-alphabet/v
ersions/1/asl alphabet test", transform=transforms)
# img dtl = DataLoader(images, batch size=1, shuffle=False, pin memory=True, num workers=
os.cpu count())
```

In [36]:

```
# Logging Experiment
from datetime import datetime
experiment name = "asl pytorch transfer learning"
run name = "run "+str(datetime.now().strftime("%d-%m-%y %H:%M:%S"))
run params = {"epochs": 10, "batch size": 64, "learning rate": 0.001, "image size": 224,
"gpu": True, "lr scheduler": None}
run metrics = {"train accuracy": "accuracy train.npy", "train flscore": "flscore train.n
py", "train loss": "loss train.npy"}
# Kaggle
# plotly path = "/kaggle/working/plotly html"
# Colab
plotly path = "/content/plotly html"
artifact paths = {"loss curve": os.path.join(plotly path, "loss curve.html"), "accuracy
curve": os.path.join(plotly_path, "accuracy_curve.html"), "f1score_curve": os.path.join(plotly_path, "f1score_curve.html"), "confusion_matrix": os.path.join(plotly_path, "confu
sion_matrix.html"), "pr_curve": os.path.join(plotly_path, "pr_curve.html"), "roc_curve":
os.path.join(plotly_path, "roc_curve.html"), "transforms": "/content/effnetb0_transform.
pt", "class names": "/content/class names.pt"
create experiment (experiment name, run name, run metrics, model, model name="pytorch mode
1_tl", artifact_paths=artifact_paths, run_params=run_params, tag_dict={"tag1": "Multiclas
s Classification", "tag2": "ASL", "tag3": "PyTorch", "tag4": "Image Classification Trans
fer Learning"})
```

Accessing as pranay.makxenia

Initialized MLflow to track repo "pranay.makxenia/ML Projects"

Repository pranay.makxenia/ML Projects initialized!

2024/12/29 12:32:54 WARNING mlflow.utils.requirements_utils: Found torch version (2.5.1+c u121) contains a local version label (+cu121). MLflow logged a pip requirement for this p ackage as 'torch==2.5.1' without the local version label to make it installable from PyPI. To specify pip requirements containing local version labels, please use `conda_env` or `pip_requirements`.
2024/12/29 12:33:05 WARNING mlflow.utils.requirements_utils: Found torchvision version (0.20.1+cu121) contains a local version label (+cu121). MLflow logged a pip requirement for this package as 'torchvision==0.20.1' without the local version label to make it installable from PyPI. To specify pip requirements containing local version labels, please use `conda_env` or `pip_requirements`.
2024/12/29 12:33:05 WARNING mlflow.models.model: Model logged without a signature and input example. Please set `input_example` parameter when logging the model to auto infer the model signature.

```
model signature.

| View run run_29-12-24_12:32:45 at: https://dagshub.com/pranay.makxenia/ML_Projects.mlfl ow/#/experiments/19/runs/2b11adb5092e4d5888ecf772a1cda105 | View experiment at: https://dagshub.com/pranay.makxenia/ML_Projects.mlflow/#/experiment s/19 | Run - run 29-12-24 12:32:45 is logged to Experiment - asl_pytorch_transfer_learning
```

8. Testing Model on Test Images

```
In [37]:
```

```
from typing import List, Tuple
from PIL import Image
# 1. Take in a trained model, class names, image path, image size, a transform and target
def pred_and_plot_image(model: torch.nn.Module,
                        image path: str,
                        class names: List[str],
                        image\_size: Tuple[int, int] = (224, 224),
                        transform: torchvision.transforms = None,
                        device: torch.device="cuda:0"):
    # 2. Open image
   img = Image.open(image path)
    # 3. Create transformation for image (if one doesn't exist)
   if transform is not None:
       image transform = transform
   else:
       image transform = transforms.Compose([
           transforms.Resize(image size),
            transforms.ToTensor(),
            transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                 std=[0.229, 0.224, 0.225]),
       ])
    ### Predict on image ###
    # 4. Make sure the model is on the target device
   model.to(device)
    # 5. Turn on model evaluation mode and inference mode
   model.eval()
   with torch.inference_mode():
      # 6. Transform and add an extra dimension to image (model requires samples in [batc
h size, color channels, height, width])
     transformed image = image transform(img).unsqueeze(dim=0)
      # 7. Make a prediction on image with an extra dimension and send it to the target d
evice
     target image pred = model(transformed image.to(device))
    # 8. Convert logits -> prediction probabilities (using torch.softmax() for multi-clas
```

```
s classification)
   target_image_pred_probs = torch.softmax(target_image_pred, dim=1)
   # 9. Convert prediction probabilities -> prediction labels
   target image pred label = torch.argmax(target image pred probs, dim=1)
   # 10. Plot image with predicted label and probability
   true class = image path.split("/")[-1][:-9]
   pred class = class_names[target_image_pred_label]
   plt.figure()
   plt.imshow(img)
   if true class == pred class:
       plt.title(f"True: {true_class} | Pred: {pred_class} | Prob: {target_image_pred_p
robs.max():.3f}", c='g')
   else:
       plt.title(f"True: {true class} | Pred: {pred class} | Prob: {target image pred p
robs.max():.3f}", c='r')
   plt.axis(False);
```

In [43]:

True: C | Pred: C | Prob: 0.999



True: G | Pred: G | Prob: 1.000





True: F | Pred: F | Prob: 1.000



The model is able to predict all the images accurately with almost 100% probability.

In [40]:

test_img_sample[0][0]

Out[40]:

 $'/root/.cache/kagglehub/datasets/grassknoted/asl-alphabet/versions/1/asl_alphabet_train/asl_alphabet_train/U/U632.jpg'$

Next

Next we'll deploy the model to a streamlit app.

In []: