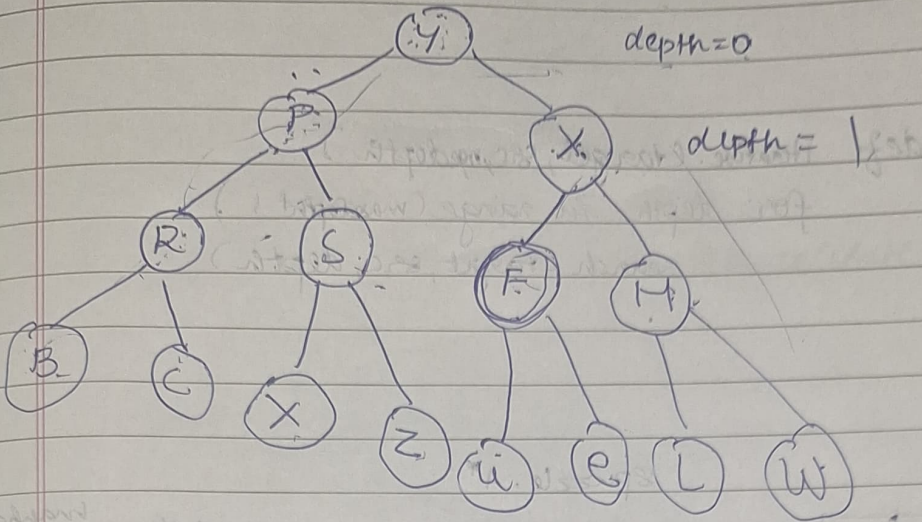


Solving ~~8 puzzle~~ <sup>using</sup> A\* algorithm & Iterative deepening.



The depth is 0 so it will start at Y.  
Y is not goal state.

The depth is incremented to 1. It will the path will be

$Y \rightarrow P \rightarrow X$

It didn't reach goal state.

The depth is incremented by 1. It will traverse up till the end of left node and visit the child node of parent node. It's a combination DFS and BFS.

The path will be

$Y \rightarrow P \rightarrow R \rightarrow S \rightarrow X \rightarrow F$

It reached the goal state.

Algorithm:

depth = 0

def search (target, src, depth)

if node == target

return True

while (depth <= 0)

if for neighbours nodes in nodes:



search(target, neighbours, depth-1)

def iterative(target, src, maxdepth):  
 for depth in range(maxdepth+1):  
 search(target, src, depth)

8puzzle, A\*

cost  
 ↑  
 Manhattan distance  
 $f(n) = g(n) + h(n)$

2	8	1
	4	3
7	6	5

1	2	3
8		4
7	6	5

$g(n) = 1$

$4 + 2 + 1 = 1$

$g(n) = 1$

$h(n) = 8$

$f(n) = 9$

$h(n) = 6$

$f(n) = 7$

$f(n) = 7$   
 $h(n) = 6$

$f(n) = 9$

$g(n) = 2$

$h(n) = 7$

$f(n) = 9$

$f(n) = 9$

$f(n) = 7$

$f(n) = 9$

$g(n) = 3$

$h(n) = 5$

1	3	2
8	4	3
7	6	5

1	2	2
8	4	3
7	6	5

8	1	2
	4	3
7	6	5

1	4	2
8		3
7	6	5

A\* algorithm.

def A\_star (startstate, goalstate):

cost = 0

if (startstate != goalstate):

states = generationmoves (startstate)

for states in generationmoves:

f(n) = cost + manhattan distance (state)

sort(f(n)).

if visited.append (state).

A\_star (state, goalstate).

~~Answer~~

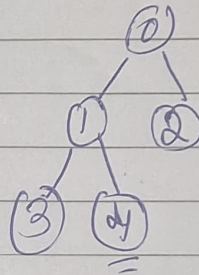
Output for IDS

Iteration 1

0 → 1 → 2.

Iteration 2.

0 → 1 → 3 → 4



~~Ans~~  
10/10