Smart Drone for Precision Agriculture: A Survey

A. Samuel Sudeep ^a, G. Praneeth Chand ^b

^a Department of Computer Science and Engineering,

Karunya Institute of Technology and Sciences,

Coimbatore- 641114, Tamil Nadu, India.

Abstract

In this work, we propose developing a system that helps to find the disease of the Plant using Image processing and Pattern matching techniques. Training of the model is done with the database of the healthy images and the diseased images contained a different type of distinct classes of combinations. We have performed a survey of some research used deep learning techniques, applied to various images of the plants. We have examined some particular agricultural problems in this study and all the metrics, sources, pre-processed data that have been used and worked under this. To perform the image processing and plant protection operations, an Unmanned Aerial Vehicle (UAV) based automatic control spraying system. UAVs are used to help the farmers in developing the best crops. As UAVs replace manned aircraft and satellites. They have many advantages over some of the traditional remotesensing techniques. UAVs can be easy to use in most of the drone mapping and data collection missions for conducting them autonomously which makes the drone fly itself and capture data and process it to get the desired output which can be easier and cheaper to get.

Keywords: Plant disease, UAV, Image processing.

INTRODUCTION:

Farming in India establishes over 60% of occupation. It serves to be the foundation of the Indian economy. It is fundamental to improve the profitability and proficiency of agribusiness by giving the safe development of the farmer. The different activities like spraying of pesticides and sprinkling fertilizers are significant. Even though spraying of pesticides has become obligatory it moreover ends up being an unsafe technique for the farmers. Farmers particularly when they spray urea, avoid potential risks like wearing suitable outfit veils and gloves. It will dodge any destructive impact on the farmers. Keeping away from the pesticides is additionally not conceivable as the necessary outcome must be met. Thus fore, the utilization of robots in such cases gives the best of the answers for this sort of issue, alongside the necessary profitability and effectiveness of the item [1]. As per review led by WHO (World Health Organization), it is evaluated that consistently around 3 million laborers are influenced by harming from pesticides from which 18000 die. This task means to conquer the evil impact of the pesticides on individuals and use to shower pesticides over the huge zone in short interims of time contrast with ordinary spraying by utilizing

programmed fertilizer sprayer. This gadget is essentially a blend of spraying system on a hexacopter outline [3]. This model is utilized to shower the pesticide substance to the zones that can only with significant effort open by people. The general sprayer framework uses to splash fluid just as strong substance which are finished by the inclusive nozzle.

LITERATURE SURVEY:

Prof. P. P. Mone, Chavhan, et al.,[1] gave an issue explanation of the World Health Organization where it appraises that there are 3 million instances of pesticide poisons in every year and up to 220,000 passings, fundamentally in creating nations. They have also clarified what insurances the farmer ought to need to use to stay away from destructive impacts of pesticides and preparing impacts just as practical innovation utilizing parts, for example, PIC microcontroller for the control of farming robots.

Bruno S. Faiçal et al., [2] proposed that airborne models use airplanes with a joined showering framework to fly over the territory of development and splash the pesticide on the estate. An option normally received for controlling the development and the conditions required for crop development is the utilization of nurseries. These structures can give a controlled domain whose conditions are nearer to the ideal required for generation. Subsequently, this movement gets helpless to human mistakes and can prompt an unequal affidavit of pesticide. Also, despite the utilization of security equipment, the laborers are presented to the showered items.

K. B. Korlahalli et al.,[3] published a paper that says the wireless drone system which is made using parts like flight control board (FCB), GPS, Brushless DC motor, electronic speed control (ESC), wireless transceiver, frame, propellers, and battery, etc. Flight Control which is programmed in their project is used for handling different sensors such as GPS, Barometer, Accelerometer, Gyroscope, etc. and motors. This drone can be worked in two modes that are manual mode and autonomous mode.

Anandarup Mukherjee et al.,[4] proposed that In the present occasions, nations with cutting edge flying frameworks have an unmistakable high ground in mechanical, logical, just as military issues when contrasted with nations coming up short on this innovation.

L. Minh Dang et al., [5] proposed that these kinds of diseases can be found out using some of the Image processing techniques and classifying data using deep learning algorithms. The steps that are done for processing the data will be Image Acquisition, Image pre-processing, Image feature Extraction, Classification.

Amarendra Goap et al., [6] proposed the detection of plant leaf illness requires shut observation. The proposed gadget entails various steps, which include-dataset creation, image pre-processing, and deep learning-based training and classification. Finally, a device is developed that extracts the features from pictures and classifies the ailments is the usage of deep learning Algorithms. Image processing strategies are employed to decorate the fine of images. Besides, the proposed work uses deep learning techniques and image processing to classify the plant ailments which are cited above.

Jirapond Muangprathub et al.,[7] proposed the data analysis algorithm for optimization of agriculture, installing a Wireless Sensor Network (WSN) in the field has improved the effectiveness and efficiency of the farmers. Farmers have always needed accurate and up-to-date information on the health of their crops and the environmental condition of the land. Agricultural aircraft have been in use since the 1920s, while agricultural experts increasingly use satellites to assess crop health from the sky. UAVs are a natural progression from macro to micro, from large-scale to small scale farms.

Srdjan Sladojevic et al., [8] Executing the proper administration systems like fungicide applications, illness explicit synthetic applications, and vector control through pesticide applications could lead to early data on crop wellbeing and illness location. This could encourage the control of infections and improve profitability. In [12], creators present, audit, and perceive the interest for building up a fast, savvy, and solid wellbeing observing sensor that encourages headways in horticulture. They depicted the as of now utilized advances that incorporate spectroscopic and imaging-based and unstable profiling-based plant illness location strategies to create a ground-based sensor framework to aid observing wellbeing and ailments in plants under field conditions.

Xinyu Xue et al., [9] proposed that Aerial spraying by unmanned aerial vehicles (UAVs) has large application potential in many areas in Asia, including Korea and Japan, where most fields are small-scale or fragmented. By the end of 2012, the application area for UAV spraying in agriculture and forestry was a hundred thousand hectares in Japan. However, the export of Yamaha helicopters was banned in 2007 to protect their technology from being used by others. China has systematically researched rice, maize, and wheat diseases and insect prevention using UAV spraying technology under the support of National Science and Technology projects.

Konstantinos P. Ferentinos et al., [10] proposed the Plant disease diagnosis through optical observation of the symptoms on plant leaves, incorporates a significantly high degree of complexity. Due to this complexity and to a large number of cultivated plants and their existing pathological problems, even experienced agronomists and plant pathologists often fail to successfully diagnose specific diseases and are consequently led to mistaken conclusions and treatments. The existence of an automated computational system for the detection and diagnosis of plant diseases would offer valuable assistance to the agronomist who is asked to perform such diagnoses through optical observation of leaves of infected plants.

Andreas Kamilaris et al., [11] proposed work to where DL extends classical ML by adding more "depth" (complexity) into the model as well as transforming the data using various functions that hierarchically allow data representation, through several levels of abstraction. A strong advantage of DL is feature learning, i.e. the automatic feature extraction from raw data, with features from higher levels of the hierarchy being formed by the composition of lower-level features. DL can solve more complex problems particularly well and fast, because of more complex models used, which allow massive parallelization. These complex models employed in DL can increase classification accuracy or reduce error in regression problems, provided there are adequately large datasets available describing the problem.

Rajashree Patil et al., [12] proposed to use neural networks in Image processing by making a computational model that works in a manner like the human mind 's neurons. Every neuron takes info, does certain activities, and passes the yield to the following neuron. The fundamental target of any neural system is to dispose of the need to plan highlight vectors by hand. The neural system endeavors to imitate the working of a cerebrum, where we just present the "crude" input - the picture and get the yield legitimately. The different applications in picture handling could be the grouping of pictures, programmed comments of pictures, and so on. There are two regular approaches to do picture preparing in the neural system for example utilizing dim scale furthermore, utilizing RGB values.

Using gray Scale: Firstly the image is converted into a grayscale (range of gray pixels from white to black) and each pixel is given the values based on how dark the pixel is. All pixels are placed in an array.

Yallappa D et al., [13] proposed This sprayer is extremely valuable where human mediations are impractical for the splashing of synthetic concoctions on crops including rice fields and plantation crops just as harvests under landscape lands. This innovation was significantly supportive of the little cultivating network in lessening the cost of pesticide application and ecological contamination yet additionally natural viability of use innovation.

S.R.Kurkute et al., [14] published a paper which explains an embedded system which will intently screen and control the microclimatic parameters of a nursery all the time nonstop for development of harvests or explicit plant species which could amplify their creation over the entire yield development season and to dispense with the challenges associated with the framework by decreasing human mediation to the best conceivable degree. The framework includes sensors, Analog to Digital Converter, microcontroller, and actuators. At the point when any of the previously mentioned climatic parameters cross a wellbeing edge which must be kept up to ensure the yields, the sensors sense the change and the microcontroller peruses this from the information at its information ports after being changed over to a computerized structure by the ADC. The microcontroller then plays out the required activities by utilizing transfers until the wandered-out pa presents a hypothetically extremely basic yet productive multiresolution

Timo Ojala et al., [15] proposed a way to deal with dark scale and turn invariant surface grouping dependent on nearby twofold examples and nonparametric separation of test and model circulations. The technique is because of perceiving that specific nearby double examples named 'uniform' are key properties of the neighborhood picture surface, and their event histogram ends up being an exceptionally amazing surface component. We determine a summed up dim scale and revolution invariant administrator introduction that takes into consideration identifying the 'uniform' designs for any quantization of the rakish space and any spatial goals and present a strategy for joining numerous administrators for multiresolution examination.

Monishanker Halder et al., [16] To advance reasonable improvement, the keen city suggests a worldwide vision that combines computerized reasoning, huge information, dynamic, data and correspondence innovation (ICT), and the Internet-of-Things (IoT). These procedures

above are connected to taking care of genuine issues. Nourishment is one of the fundamental necessities of an individual. The total populace is expanding step by step. So, it has gotten imperative to develop an adequate measure of harvests to take care of such an immense populace. In any case, with the time cruising by, plants are influenced by different sorts of ailments, which cause incredible damage to the horticultural plant creations. Close to that numerous nations economy extraordinarily relies upon horticultural profitability and it's additionally a requirement for a coun attempt to achieve farming efficiency of the fundamental farming item for the individuals of that specific nation. Identification of plant sickness through some programmed strategy is valuable as it requires an enormous measure of work of checking in the large ranch of harvests, also, at the beginning period itself, it distinguishes side effects of infections that imply where they show up on plant leaves. In this paper overviews on various ailment order procedures that can be utilized for plant leaf illness recognition.

Guiling Sun et al., [17] proposed that the avoidance and control of plant sickness have consistently been broadly talked about because plants are presented to external conditions and are profoundly inclined to sicknesses. Regularly, the precise and quick determination of sickness plays a significant job in controlling plant infection, since helpful assurance measures are often actualized after the right diagnosis. This framework depends on picture preparing innovation and utilizes MATLAB as the primary handling device. Besides, advanced picture handling, numerical insights, plant pathology, what's more, other relative fields are additionally considered. Contrasting with the conventional picture acknowledgment, there are a lot of developments in picture division and framework development. To reinforce the division of the sore, clients have different imaginative intelligent alternatives to address their issues. In the meantime, a straight relapse model can be utilized in different sorts of plant infection.

Sachin D. Khirade et al.,[18] published a paper which says Identification of the plant illnesses is the way to forestalling the misfortunes in the yield and amount of the agrarian item. Sickness discovery includes means like picture securing, picture pre-preparing, picture division, highlight extraction, and order. This paper talked about the techniques utilized for the identification of plant ailments utilizing their leaves pictures. This paper additionally examined some division and highlight extraction calculations utilized in the plant infection location.

Sujatha R et al., [19] published a paper that says recognizable proof of plant illness is extremely troublesome in the farming field. If distinguishing proof is wrong, at that point, there is a colossal misfortune on the creation of harvest and conservative estimation of the market. Leaf infection recognition requires the colossal sum of work, information in the plant maladies, and requires the additional handling time. So, we can utilize picture handling for distinguishing proof of leaf infection in MATLAB. Distinguishing proof of infection follows the means like stacking the picture, differentiate upgrade, changing over RGB to HSI, extracting of highlights, and SVM.

Vijai Singh, A.K. Misra et al., [20] Agriculture productivity is something on which the Economy exceptionally depends. This is one of the reasons that illness identification in plants

assumes a significant job in the farming field, as having illness in plants are very common. On the off chance that appropriate consideration isn't taken right now, it causes genuine impacts on plants and because of which separate item quality, amount, or profitability is influenced. For example, an ailment named little leaf sickness is a perilous illness found in pine trees in the US. Location of plant ailment through some programmed system is valuable as it decreases an enormous work of checking in large homesteads of harvests, and at the beginning time itself, it distinguishes the side effects of maladies for example at the point when they show up on plant leaves. This paper presents a calculation for picture division strategy which is utilized for programmed recognition and characterization of plant leaf sicknesses. It additionally covers the study on various illnesses arrangement strategies that can be utilized for plant leaf infection recognition. Picture division, which is a significant angle for infection recognition in plant leaf sickness, is finished by utilizing hereditary calculation.

Jirapond Muangprathub et al., [21] says building up a framework ideally watering farming yields dependent on a remote sensor organize. This work meant to structure and build up a control framework utilizing hub sensors in the harvest field with information the executives through cell phones and a web application. The three parts are equipment, web application, and versatile application. The principal part was structured and executed in charge of box equipment associated with gathering information on the harvests.

UM. Rao Mogili et al.,[22] explains that there is an excessive number of improvements in accuracy farming for expanding the harvest profitability. Particularly, in creating nations like India, over 70% of the country individuals rely on the horticulture fields. The WHO (World Health Organization) assessed as one million instances of not well affected when splashing the pesticides in the harvest documented physically. Unmanned aerial vehicle (UAV) — airplanes are utilized to shower the pesticides to dodge the medical issues of people when they splash physically. UAVs can be utilized effectively, where the hardware and works trouble work.

G. J. Grenzdörffer et al., [23] has proposed a paper which says Micro UAVs (Unmanned-Aerial-Vehicles or automatons) with a complete load underneath 5 kg are fascinating other option transporters for horticultural and ranger service applications. Contrasted with standard airborne flying studies UAVs are considerably more adaptable and climate free. Subsequently, small-scale UAV studies will make ready for reasonable, current, and exact geo-data. Down to earth tests with two unique frameworks at a few areas uncovered that the two frameworks were fit for securing pictures in a precise way.

Nathan Stein et al., [24] has published a paper that says The Modern farming industry is at a turning point. With the improvement of the further developed ranch the executive's procedures, such as accuracy horticulture, industry experts currently have more apparatuses than at any other time to improve the precision and effectiveness of procedures. Creative innovations, for example, unmanned aeronautical vehicle (UAV) arrangements, additionally have a developing nearness right now, as the advantages become progressively obvious and access to equipment, what's more, programming improves.

Vikram Puri et al., [25] has given a paper that says about drones generally alluded, as UAVs are for the most part connected with the military, industry and other particular tasks however with ongoing improvements in the territory of sensors and Information Innovation in most recent two decades the extent of automatons has been broadened to different territories like Agribusiness. The automatons produced nowadays are getting more astute by coordinating open source innovation, brilliant sensors, better reconciliation, more flight time, following down hoodlums, identifying backwoods, and other hazardous situations. The point of this examination paper is to feature the significance of automatons in agribusiness and expand top automatons accessible in advertising for Agriculture checking and perception for yielding better harvest quality and keeping fields from any kind of harm.

H.S. Abdullahi et al., [26] has proposed about to say that In a quickly evolving world, with the possibility of diminishing arable land because of urbanization and industrialization, rural yield requires a 70 % expansion underway levels and effective development in the collecting, circulation, and utilization of the assets, to satisfy a need. There are advancements in Information and Communications Innovation that can be applied to the rural division in regions of exactness cultivating, utilization of ranch the executives programming, remote sensors, and utilization of agricultural hardware. Remote detecting innovation is assuming a key job through precision horticulture. This paper features manners by which exactness agribusiness is affecting on horticulture with the utilization of unmanned elevated vehicles for picture catching, preparing, and investigation.

Crystal Kyle et al., [27] has proposed a method about another area of consideration is the utilization of automatons in farming. Even though automatons might be utilized by anybody, they may have uncommon ramifications for those with physical challenges on ranches. As the normal populace of America's farmer's increment, so does the probability that these farmers and farmers will confront physical wounds or ailments that have the potential to hinder creation and increment wellbeing concerns. The automaton possibly an approach to address a portion of these issues. This asset direct is intended to be a prologue to rambles. Right now, we will talk about various kinds of automatons and the manners by which they are commonly used.

Pasquale Daponte et al., [28] has told that Cultivating is confronting numerous financial difficulties as far as profitability and cost-adequacy, and the expanding work deficiency somewhat because of the termination of rustic zones, too. Among such worldwide difficulties, it ought to be viewed as the populace increment, the urbanization, a progressively corrupted condition, an expanding pattern toward utilization of creature proteins changing in nourishment inclinations through maturing populace and movement, and, obviously, the atmosphere change.

George IPATE et al., [29] have published a paper that says Mechanical advancement made in checking, supervision, the board, and control frameworks have opened another period in which numerous conventional rural rehearses are obsolete. Their supplanting with new advancements falls into the "precision farming" class, which converts into applying the agronomic factors in the correct spot, at the perfect time and with exact command over the measure of material sources of info or harvest creation. Unmanned airplanes end up being

one of those procedures that permit quick and nondestructive investigation of air quality, physical properties of the segments of soil, or harvest development.

Ioanna Simelli et al., [30] has proposed a paper which says Unmanned Aerial Systems (UAS) are airborne vehicles, which come in wide assortments, shapes, and measures and can be remotely controlled or can fly self-governing through programming-controlled flight designs in their inserted frameworks chipping away at the premise of GPS. A portion of the advances of the utilization of UAS is that they are lightweight and simple to transport, they catch high goals and ease pictures, they can fly at an assortment of heights relying upon information assortment needs, they can travel territories which are most certainly not open employing vehicle, vessel, and so on., they are broadly utilized in salvage activities, making a difference in conveying drugs and nourishment, giving the live status of the influenced territory, conveying in an emergency, and so forth, fast accessibility of crude information.

Petkovics et al., [31] have proposed a paper that says Modern horticulture requires consistent plant, creature, and machine observing to guarantee ideal working. In the present time of agrarian robotization, it is important to mastermind an appropriate robotized information assortment framework, principally for plant and creature status which can give the necessary information inside a brief timeframe period. There are commonly two choices for this reason: a system of IoT (Internet of Things) gadgets, and automatons (transcendently for plants) with various, primarily varying media, sensors that gather information when making a trip over the harvests or creature living space. The two options fulfill the ranchers' need for expanded achievement, while they moreover guarantee abatement of expenses. This part depicts the attributes of these two options for information assortment, featuring the points of interest and impediments of both arrangements found in their usage.

UM. Rao Mogili et al.,[32] has proposed a paper that says that In the current period, there are such a large number of advancements in accuracy agribusiness for expanding the yield efficiency. Particularly, in creating nations like India, over 70% of the country individuals rely on the agribusiness fields. The WHO (World Health Organization) assessed as one million instances of poorly affected when showering the pesticides in the harvest documented physically. The Unmanned Aerial Vehicle (UAV) – airplanes are utilized to splash the pesticides to maintain a strategic distance from the medical issues of people when they shower physically. UAVs can be utilized effectively, where the hardware and works trouble work. This paper surveys quickly the usage of UAVs for crop observing and pesticide splashing.

Wouter H. Maes et al., [33] has published a paper that says Remote detecting with unmanned airborne vehicles (UAVs) is a distinct advantage inaccuracy horticulture. It offers uncommon ghostly, spatial, and worldly goals, however, it can likewise give nitty gritty vegetation stature information and multiangular perceptions. Right now, audit the advancement of remote detecting with UAVs in dry season worry, in weed and pathogen recognition, in supplement status what's more, development power evaluation, and in yield forecast. To move this information to the regular act of exactness farming, future research should center on abusing the complementarity of hyperspectral or multispectral information with warm information, on coordinating perceptions into a powerful exchange or development models as

opposed to direct relapse models, and on joining UAV items with other spatially unequivocal data.

Marek Kulbacki et al.,[34] have published a paper that says Ranchers investigate the abilities for applications of Robotic Process Automation (RPA) with picture handling, design acknowledgment, and AI, so it's coherent to ask where best to apply this innovation for most extreme impact. Great remote detecting with ghastly imaging utilizing rambles makes them intriguing for ordinary use in Precision Agriculture (PA). Automatons are regularly utilized in horticulture in manners that were profoundly questionable just a brief timeframe before even there is no brought together enactment on rambles utilization in horticulture. Right now, address the issue of Remote Sensing (RS) innovations joined with Unmanned Aerial System (UAS) stages to help and create chosen agribusiness tasks like a guide or sensor-based Variable Rate Application (VRA).

Tomoya MORIBE et al., [35] have explained that Brilliant horticulture has pulled in a lot of consideration as the use of Wireless Sensor Network (WSN). WSN can adequately bolster cultivating by gathering the information in a homestead field. Of the different organic yield data, leaf temperature has pulled in a great deal of consideration since transpiration and photosynthesis exercises can be assessed from this and noncontact estimation is conceivable utilizing an infrared thermometer.

Nikki J. Stehr et al.,[36] have explained in that paper about Drones, or unmanned aerial vehicles (UAVs), have been utilized by the military since WWI for remote observation. In the most recent decade, ranchers have started utilizing them to screen their fields just as helping accuracy farming projects. There are gauges that 80 to 90% of the development in the automaton showcase in the following decade will originate from agribusiness. The convenience that's more, the capacity to practice every framework implies there will be a UAV for each circumstance. The Federal Aviation Administration (FAA) guideline right now restrains ramble use to recreational. Rules for business use are required to turn out in September of 2015. UAVs can screen handle more regularly than satellites, take increasingly point by point pictures, and are not hindered by mists.

Imre Petkovics et al.,[37] have published a paper that quickly depicts the points of interest of accuracy horticulture from the perspective of information needs and the chance of giving such information. It focuses on the most helpful and proficient type of gathering vital information utilizing rambles. Explicit automaton qualities are recorded/examined to encourage choosing the correct one as per the ranchers' heterogeneous necessities concerning information assortment on their harvests. Choosing the suitable automaton for the particular needs of ranchers is conveyed out by a multi-criteria dynamic programming.

Giuseppe Potrino et al., [38] has given a paper that faces with the help of automatons in the exactness agribusiness space. In these last years, new advances permit administrators of the segment to look with changed dangers, for example, parasites and unexpected climatic changes that can harshly debase the yield or the nature of the developed items. The utilization of test systems for this reason for existing is important assistance to scientists to test these technologies and to design explicit methodologies furthermore, coordination methods ready

to proficiently bolster ranchers, what's more, accomplish the objective. Right now, principle commitment is to play out an examination between two distinct kinds of parasites' search calculations (Random Search and Distributed Search) in request to give a sign of their presentation.

R. P. Ram Kumar et al., [39] has published a paper which says India bags second place into absolute arable land with the agrarian items including rice, wheat, sugarcane, onion, tomato, potato, beans, and mangoes. As per the announcement "Agribusiness is the foundation of our India," cultivating assumes a noteworthy job in India's financial development. The target of the paper is to improve the development and developed items through Smart Farming by fusing rambles. The uses of automatons, an unmanned airplane, in the cultivating are tended to right now. The automatons can be modified and computerized in the exercises from checking the dirt dampness to keeping up the domesticated animals and concern coordinations. The broad investigation suggests that fusing rambles change the conventional technique for cultivating into Smart Farming.

Chunhua Zhang • John M. Kovacs et al., [40] has published a paper which explains Precision Agriculture (PA) is the use of geospatial procedures and sensors (e.g., geographic information systems, remote sensing, GPS) to recognize varieties in the field and to manage them utilizing elective techniques. Specifically, high-goals satellite symbolism is currently more usually used to read these varieties for harvest and soil conditions. In any case, the accessibility and the frequently restrictive expenses of such symbolism would recommend an elective item for this specific application in PA. In particular, pictures are taken by low height remote detecting stages, or little Unmanned Aerial Systems (UAS), is demonstrated to be a potential elective given their minimal effort of activity in ecological observing, high spatial, and fleeting goals, and their high adaptability in picture securing programming.

Paolo Tripicchio and Massimo Satler et al.,[41] have published a paper that says The utilization of drones in farming is getting more what's more, increasingly well known. The paper presents a novel way to deal with recognize distinctive field's furrowing procedures by methods for an RGB-D sensor. The introduced framework can be handily coordinated in industrially accessible Unmanned Aerial Vehicles (UAVs). In request to effectively characterize the furrowing systems, two unique estimation calculations have been created. Test tests show that the proposed technique can give a decent grouping of the field's furrowing profundities.

Jeremiah Karpowicz et al., [42] have explained the usage of UAVs in agriculture as most farmers aren't doing anything naturally not quite the same as they did before UAVs went along. Accuracy agribusiness experts have been utilizing soil maps and satellite pictures for quite a while, yet the distinction an automaton can make is around the speed of that data. At the point when you need to depend on satellites and planes, there's a considerable slack as far as getting the information rapidly enough. With rambles, data is in a split second available, permitting cultivators to settle on quick choices.

Tom McKinnon et al., [43] has told in his paper that Agricultural drones will give the data about collecting the field level data in a new method. The most important reason to use drones is that the outputs are on-demand; whenever and wherever that is used., the drone can be easily made and deployed. It is hard to overcome the immediacy and convenience of the collection of data and real-time outputs; only drones can be able to get these advantages.

Sindhuja Sankaran et al., [44] Recently, progresses in the accessibility of little unmanned flying vehicles (UAVs) have extended the uses of UAVs in farming. Specialists are investigating UAVs in agribusiness for stock administration, crop portrayal (volume, thickness), and stress identification. A portion of the one of a kind highlights of UAVs that make them appealing for farming applications incorporates straightforwardness of use, adaptability of gaining high goals pictures through height modification, better security under gentle to direct wind conditions, and the capacity to procure pictures at a determined georeferenced position. UAVs can likewise be worked to cover a little or huge farming field that is in any case blocked off to ranchers. When all is said in done, information from UAVs is more affordable to get from satellites or elevated stages.

METHODOLOGY:

- **3.1 Dataset:** Appropriate datasets are required at all stages of object recognition research, starting from the training phase to evaluating the performance of recognition algorithms. All the images collected for the dataset were downloaded from the Internet, searched by disease, and plant names on various sources in different languages. Images in the dataset were grouped into classes. To distinguish healthy leaves from diseased ones, one more class was added in the dataset. It contains only images of healthy leaves.
- **3.2 Image Pre-processing and Labelling:** Images downloaded from the Internet were in various formats along with different resolutions and quality. To get better feature extraction, final images intended to be used as a dataset for deep neural network classifiers were pre-processed to gain consistency. Furthermore, the procedure of image pre-processing involved cropping of all the images manually, making the square around the leaves, to highlight the region of interest (plant leaves). During the phase of collecting the images for the dataset, images with smaller resolution and dimensions less than 500 px were not considered as valid images for the dataset. Besides, only the images where the region of interest was in the higher resolution were marked as eligible images for the dataset. In that way, it was ensured that images contain all the needed information for feature learning. Images used for the dataset were image resized to 256×256 to reduce the time of training, which was automatically computed by the written script in Python, using the OpenCV framework.
- **3.3 Classification of the Images:** Images that are being trained to the model are classified using Convolutional Neural Networks. The input image filters out the diseased or not diseased plants by binary classification. These classified images are used to find the accuracy of the image taken by the drone. These images are converted using some binary techniques which will help us get the pixel values easy in the binary format. In the future, different texture features and color features will be extracted from the images to improve the classification performance. Further, before its practical implementation, the proposed

methodology will also be tested with the larger dataset. Convolutional Neural Networks are category of neural networks which has multiple convolutional layers and mostly used for image processing, classification and segmentation. It will be used to classify and filter over the input.

3.4 Materials for Drone:

Material Name	Specifications	Description
AX_2810Q 900Kv motors	Power supply: 900Kv DC	It uses power supply to rotate the
		motors and make help the
		propellers to rotate.
Skywalker 40A esc	Current: 60A	It controls the speed of the drone
		with dynamic braking
DJI NAZA M LITE with GPS	Flight controller with	Flight controller which can
COMPASS COMBO	GPS tracker	locate the position of the Drone
FLYSKY FS16 Transmitter &	Radio signals transmitted	Uses radio signals to control the
Receiver	at range of 2.4GHz	moments of drone
Aluminium hexa frame	Dimensions:900mm	These are used to hold the
		propellers and motors
Gens Ace Li-po Battery	Capacity 5500mAh	Gives power supply
		They rotate to provide the
Propellers	Dimensions:12*4.5inch	pressure to raise drone

CONCLUSION:

It is concluded that a device is developed that extracts the features from pictures and classifies the ailments with the usage of deep learning Algorithms. This system is to develop the Drone module for real-time Disease identification with the help of Image processing modules. Disease identification with Image processing helps in the identification of Disease on the spot while spraying of pesticide this helps in the reduction in the use of fertilizer and more manpower in the removal of Diseases. Fixed cameras are directly connected to a laptop for spot correction of images like cropping, color correction, rotation, etc. after the correction the images are saved in a sequence which is captured based on lighting conditions that lead to the next step for creating datasets for all the images for further processes. The method that is followed to capture the images in farmland is fixing the camera on the drone and also manual methods are used to collect images accurately without any texture and shading defects.

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