

# REAL TIME OPERATING SYSTEM PROGRAMMING-I: $\mu$ C/OS-II and VxWorks

## Lesson-7: $\mu$ C/OS-II Mailbox IPC functions

# **1. Mailbox Functions**

## Mailbox Functions

- Used to communicate a pointer for information.
- $\mu$ C/OS-II permits one message-pointer per mailbox.
- At the pointer, there can be a string or data structure of no size limit.

## Mailbox Functions...

- Assume an event pointer to the mailbox = \*mboxMsg,
- Pointer to the message, \*MsgPointer (for retrieving the message itself).

# OSMboxCreate (\*mboxMsg)

OS\_Event \*OSMboxCreate  
(void \*mboxMsg)

- To create a mailbox message pointer ECB of a mailbox message. (Example 9.19 Step 6)
- Before initializing for Example 9.19 Step 8)

# OSMboxPend(\*mboxMsg, timeout, \*MboxErr)

- void \*OSMboxPend  
(OS\_Event \*mboxMsg, unsigned short  
timeOut, unsigned byte \*MboxErr)
  - To check if mailbox message not pending  
(available) then read \*mboxMsg is and empty  
mailbox [\* mboxMsg = NULL again]. If message  
is not available [\*mboxMsg points to NULL],  
then wait, suspend the task (block further  
running) till \*mboxMsg not Null or timeout  
(Example 9.19 Step 39)

## OSMboxAccept (\*mboxMsg)

void \*OSMboxAccept (OS\_EVENT \*  
mboxMsg)

—To check if mailbox message at the \*MsgPointer, is available at \*mboxMsg. Unlike OSMboxPend function, it does not block (suspend) the task if message is not available. If available, it returns the pointer (Example 9.19 Steps 40 and 52)

# OSMboxPost (\*mboxMsg, \*MsgPointer)

unsigned byte OSMboxPost (OS\_EVENT  
\*mboxMsg, void \*MsgPointer)

- Sends a message of task at address MsgPointer by posting the address pointer to the mboxMsg.
- If box is already full (\*mboxMsg not Null) , then the message is not placed and error status sent. (Example 9.19 steps 24 and 40)



# OSMboxQuery (\*mboxMsg, \*mboxData)

unsigned byte OSMboxQuery  
(OS\_EVENT \*mboxMsg,  
OS\_MBOX\_DATA \*mboxData)

- To get mailbox error information
- pointer Null or Not Null,

## **2. Macros for mailbox functions to find status after execution of OS mailbox Functions**

# Macros for mailbox functions

- OS\_NO\_ERR and
- OS\_ERR\_EVENT\_TYPE

To get mailbox error information, at data structure pointed by \*mboxData

### **3. Example for mailbox functions application**

# Example for application of for mailbox functions

- Programming Example for communication a message to display task after delivering the chocolate in chocolate vending machine

## Step A: Initiating the Mailbox

```
#define OS_MAX_EVENTS 8
/*When total number of IPCs needed in an
application = 8*/
#define OS_MboX_EN 1
/*When the use of semaphores is
contemplated */
```

## Step B: Global IPC functions and their parameters declarations

```
OS_EVENT *mboxStrMsgthanks;  
/* When mail box is to be used to send an  
amount message */  
int *i = 0; char [ ] mboxStrMsgthanks;  
mboxStrMsgthanks = OSMboxCreate  
(*i);  
/* When mail box is to be used the initially it  
is to point to null */
```

## Step C: Main function

```
void main (void) {  
    OSInit ();  
    /* Create First task */  
    OSTaskCreate (FirstTask, void (*)  
    0,(void *)&FirstTaskStack[  
    FirstTaskStackSize], FirstTaskPriority);  
    OSStart ();  
}
```



## Step D: First task

```
static void FirstTask (void *taskPointer) {  
    /*Create Application Tasks*/  
    OSTaskCreate (ReadTask, void (*) 0,(void  
    *)&ReadTaskStack [ReadTaskStackSize],  
    ReadTaskPriority);  
    OSTaskCreate (DeliveryTask, void (*)  
    0,(void *)&DeliveryTaskStack  
    [DeliveryTaskStackSize],  
    DeliveryTaskPriority);  
}
```

## Step D: First task...

```
/*System clock time set */  
OSTimeSet (presetTime);  
OSTickInit (); /* Initiate system timer  
ticking*/  
while (1) {OSTaskSuspend  
(FirstTaskPriority); /* Suspend first task  
indefinitely and Run only the application related  
tasks */  
}
```

## Step E: ReadTask

```
static void ReadTask (void *taskPointer)
{...
int *amount;
while (1) {...;
/* Code similar to one given in earlier lessons*/
...;
OSTimeDelay (3000);
}; }
```

## Step F: DeliveryTask

```
static void DeliveryTask (void
*taskPointer) {..
while (1) {
...; /* Code similar to one given in earlier
lessons*/
mboxStrMsgthanks = “Collect Nice
Chocolate Thansk for your visit, Visit
Again”; /* define thanks message*/
```

## Step F: DeliveryTask...

```
OSMboxPost (mboxStrMsgthanks);  
/* Post the message into the mailbox*/  
OSTimeDelay (3000);  
/* Delay to enable lower priority display task  
run*/  
OSTimeDlyResume (ReadTaskPriority);  
/* Resume to delayed higher priority read task  
*/  
};}
```

## Step G: DisplayTask...

```
static void DisplayTask (void *taskPointer)
{..
String displayThanks;;
while (1) {
displayThanks = OSMboxPend
(mboxStrMsgthanks, 0, *MboxErr);
/* Wait for mailbox message, read
mboxStrMsgthanks in displayThanks and then
reset the mboxStrMsgthanks to null*/
```

## Step G: DisplayTask...

...; ...; ...;

OSTimeDlyResume

(DeliveryTaskPriority); /\* Resume to delayed  
higher priority delivery task \*/

}}

# Summary



## We learnt

- $\mu$ C/OS-II has mailbox functions
- Simple feature of  $\mu$ C/OS-II mailbox—one message pointer per mailbox.
- Any number of messages or bytes, provided the same pointer accesses them in each mailbox

# End of Lesson-7 on $\mu$ C/OS-II Mailbox Functions