Table 1: Table of parameters used to model message propogation

Parameter	Description
λ	Rate at which susceptible nodes acquire the infection
β	Direct transmission rate (contact rate)
ε	Transmission reducing factor
$\sigma^{\scriptscriptstyle -1}$	Average time period of a exposed node
$\gamma^{-1}$	Average time period of infection
$\omega^{-1}$	Average time period of recovery
$ au^{-1}$	Average time period of a carrier node
μ	Death rate of nodes
ρ	Probability that an infected node becomes carrier

The CISER equations are as follows

$$\frac{dS}{dt} = -(\beta I + \varepsilon \beta C)S - \mu S + \omega R \tag{1}$$

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$$\frac{dE}{dt} = (\beta I + \varepsilon \beta C)S - (\sigma + \mu)E \tag{2}$$

$$\frac{dI}{dt} = \sigma E - (\gamma + \mu)I \tag{3}$$

$$\frac{dC}{dt} = \rho \gamma I - (\tau + \mu)C \tag{4}$$

$$\frac{dR}{dt} = (1 - \rho)\gamma I + \tau C - (\omega + \mu)R \tag{5}$$

The real parts of the roots of the cubic polynomial  $P(\lambda) = \lambda^3 + a_1 \lambda^2 + a_2 \lambda + a_3$  are negative if the coefficients of this polynomial satisfy the following four conditions:

1. 
$$a_1 = c_1 + c_2 + c_3 > 0$$

2. 
$$a_2 = c_1c_2 + c_1c_3 + c_2c_3 - \sigma\beta > 0$$

3. 
$$a_3 = c_1 c_2 c_3 (1 - R_0) > 0$$

4. 
$$a_1a_2 - a_3 > 0$$

By the definition of the coefficients of c, the first condition holds true. Let us consider the following lemma.

## Lemma:

If the basic reproduction number is less than one and the condition (3) is true, then the conditions (2) and (4) are also true.

**Proof:** 

$$\frac{dS}{dt} = \frac{dy_1}{dt}, \frac{dE}{dt} = \frac{dy_2}{dt}, \frac{dI}{dt} = \frac{dy_3}{dt}, and \frac{dC}{dt} = \frac{dy_4}{dt},$$

$$\frac{dy_1}{dt} = -(\beta y_3 + \varepsilon \beta y_4) \overline{S} - (\beta y_3 + \varepsilon \beta y_4) y_1 - (\beta \overline{I} + \varepsilon \beta \overline{C} - (\omega + \mu)) y_1 - w(y_2 + y_3 + y_4)$$
(6)

$$\frac{dy_2}{dt} = (\beta y_3 + \varepsilon \beta y_4) \overline{S} + (\beta \overline{I} + \varepsilon \beta \overline{C}) y_1 
+ (\beta y_3 + \varepsilon \beta y_4) y_1 - (\sigma + \mu) y_2$$
(7)

$$\frac{dy_3}{dt} = \sigma y_2 - (\gamma + \mu)y_3 \tag{8}$$

$$\frac{dy_4}{dt} = \rho \gamma y_3 - (\tau + \mu) y_4 \tag{9}$$

Let us define the Lyapunov function as:

V: IR 
$$^4 \rightarrow IR^+$$
 by V(y) =  $y_1^2 + y_2^2 + y_3^2 + y_4^2$ 

Evaluating the condition on the parameters that make  $\frac{dV(y)}{dt} \le 0$ ,  $\forall y \in IR^4$  and if the directional derivative of the solution  $y = y(t_0, y_0, t)$  of the IVP along the closed curve V(y) is negative at any time t, then the endemic equilibrium point  $\bar{x}$  of the original IVP is asymptotically stable.

$$\frac{dV(y)}{dt} = \frac{\partial V(y)}{\partial y} \cdot \frac{dy}{dt} \tag{10}$$

$$\frac{dV(y)}{dt} = 2[-\beta S y_1 y_3 - \varepsilon \beta S y_1 y_4 - (\beta \overline{I} + \varepsilon \beta \overline{C} - (\omega + \mu)) y_1^2 
- w(y_1 y_2 + y_1 y_3 + y_1 y_4)] + 2[\beta S y_2 y_3 + \varepsilon \beta S y_2 y_4 
+ (\beta \overline{I} + \varepsilon \beta \overline{C}) y_1 y_2 - (\sigma + \mu) y_2^2] + 2[\sigma y_3 y_2 - (\gamma + \mu) y_3^2] 
+ 2[\rho \gamma y_3 - (\tau + \mu) y_4^2]$$
(11)

This above identity is including the variable  $S \in \Omega$  and its limit value in the neighborhood of  $\bar{x}$  is  $\bar{S}$ . Hence,

$$\frac{dV(y)}{dt} = 2[-\beta \overline{S} y_1 y_3 - \varepsilon \beta \overline{S} y_1 y_4 - (\beta \overline{I} + \varepsilon \beta \overline{C} - (\omega + \mu)) y_1^2 
- w(y_1 y_2 + y_1 y_3 + y_1 y_4)] + 2[\beta \overline{S} y_2 y_3 + \varepsilon \beta \overline{S} y_2 y_4 
+ (\beta \overline{I} + \varepsilon \beta \overline{C}) y_1 y_2 - (\sigma + \mu) y_2^2] + 2[\sigma y_3 y_2 - (\gamma + \mu) y_3^2] 
+ 2[\rho \gamma y_3 - (\tau + \mu) y_4^2]$$
(12)

Using the property  $\pm ab \le a^2 + b^2$ ,  $\forall a, b \in IR$ , yield the following inequality:

$$\frac{dV(y)}{dt} \le -\left[\beta \overline{S}(y_{1}^{2} + y_{3}^{2}) + \varepsilon \beta \overline{S}(y_{1}^{2} + y_{4}^{2}) + 2(\beta \overline{I} + \varepsilon \beta \overline{C} - (\omega + \mu))y_{1}^{2} + w(3y_{1}^{2} + y_{2}^{2} + y_{3}^{2} + y_{4}^{2})\right] + \left[-\beta \overline{S}(y_{2}^{2} + y_{3}^{2}) - \varepsilon \beta \overline{S}(y_{2}^{2} + y_{4}^{2}) - (\beta \overline{I} + \varepsilon \beta \overline{C})(y_{1}^{2} + y_{2}^{2}) + 2(\sigma + \mu)(y_{2}^{2})\right] + \left[-\sigma(y_{2}^{2} + y_{3}^{2}) + 2(\gamma + \mu)y_{3}^{2}\right] + \left[-\rho\gamma(y_{3}^{2} + y_{4}^{2}) + 2(\tau + \mu)y_{4}^{2}\right]$$
(13)

The endemic equilibrium point  $\bar{x}$  is asymptotically stable only if the RHS of the above inequality is positive definite. That is, every coefficient  $C_i$  of the variable  $y_i^2$ , i = 1, 2, 4 must be positive.

$$C_1 = \beta \overline{S} + \varepsilon \beta \overline{S} + 2(\beta \overline{I} + \varepsilon \beta \overline{C} - (\omega + \mu)) + 3w - (\beta \overline{I} + \varepsilon \beta \overline{C}) \ge 0$$
 (14)

$$C_2 = w - \beta \overline{S} - \beta \overline{S} - (\beta \overline{I} + \varepsilon \beta \overline{C}) + 2(\sigma + \mu) - \sigma \ge 0$$
(15)

$$C_3 = \beta \overline{S} + w - \beta \overline{S} - \sigma + 2(\gamma + \mu) - \rho \gamma \ge 0$$
 (16)

$$C_{4} = \varepsilon \beta \overline{S} + w - \varepsilon \beta \overline{S} - \rho \gamma + 2(\tau + \mu) \ge 0$$

$$(17)$$

It follows that the message propagation endemic equilibrium point is asymptotically stable if the following conditions hold:

1. 
$$\beta(\overline{S} + \overline{I}) + \varepsilon\beta(\overline{S} + 2\overline{C}) + 2w - \mu \ge 0$$

2. 
$$w - \beta(\overline{S} + \overline{I}) - \varepsilon \beta(\overline{S} + \overline{C}) + \sigma + 2\mu \ge 0$$

3. 
$$w - \sigma + 2(\gamma + \mu) - \rho \gamma \ge 0$$

4. 
$$w - \rho \gamma + 2(\tau + \mu) \ge 0$$