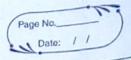
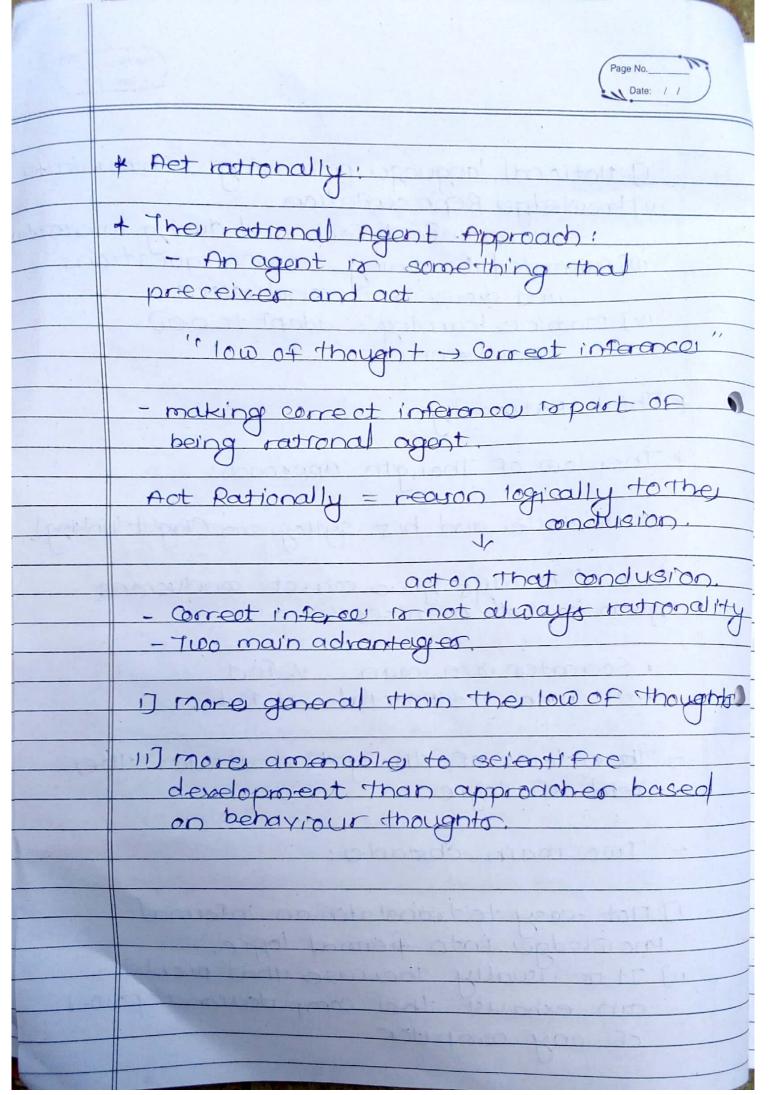


- knowing the preciese theory of mind, one must express this theory as computer program. \* General problem solver (GPS): - GRS is concerned with comparing the traces of its reasoning steps to traces of human subjects solving the some problem rather than correctly solves problems. \* Act like hyman: - for machiner to act like a human being. Turning test Approach is used. \* Turing test approach: - Alan Toring designed a test for intelligent behaviour. - This test allows madine ability to anieve human-level performance in all cognitive teak, sufficient to foot an interrogator. - for this test these are the requirements if Human Interrogator. AND two condidates: 1) Human 117 Machine -) computer would need.



1) Hational language processing & communicates 11] knowledge Representation - store inforbefore and during interrogation III] Automated Reasoning - answer questrons and drows new ondustons. iv] machine tearning - adapt to new circumstancer \* Think Rationally: \* The low of thoughth Approach: - Anistotle and his syllogism (Protthinking), given correct premiser! · Socreates in a man 1. fact All men are Mortal 1. Rules. - These lows of thoughto initrated they field of logic. - Two main obstacles: 1) Mot easy to translate an informal knowledge into formal logic. is I to usually the case that problem an exhaust the computational power of any computer.



## 9. Write other note on Rationality

Rationality what is rational at any given time depends on four things. The performance measure that depines the criterion of ources. The agent's prior knowledge can perform.

The agents actions that the agent can perform.

The agents percept sequence of date.

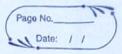
This leads to a definition of a rational agent por each agent percept sequence, a rational agent stow select an action that is expected to more mize its performance measure, given the exidence provided by the percept sequence and whatever built - In knowledge the agent has

deans a square if it is dirty and moves to the other square if not, this is the agent fun!

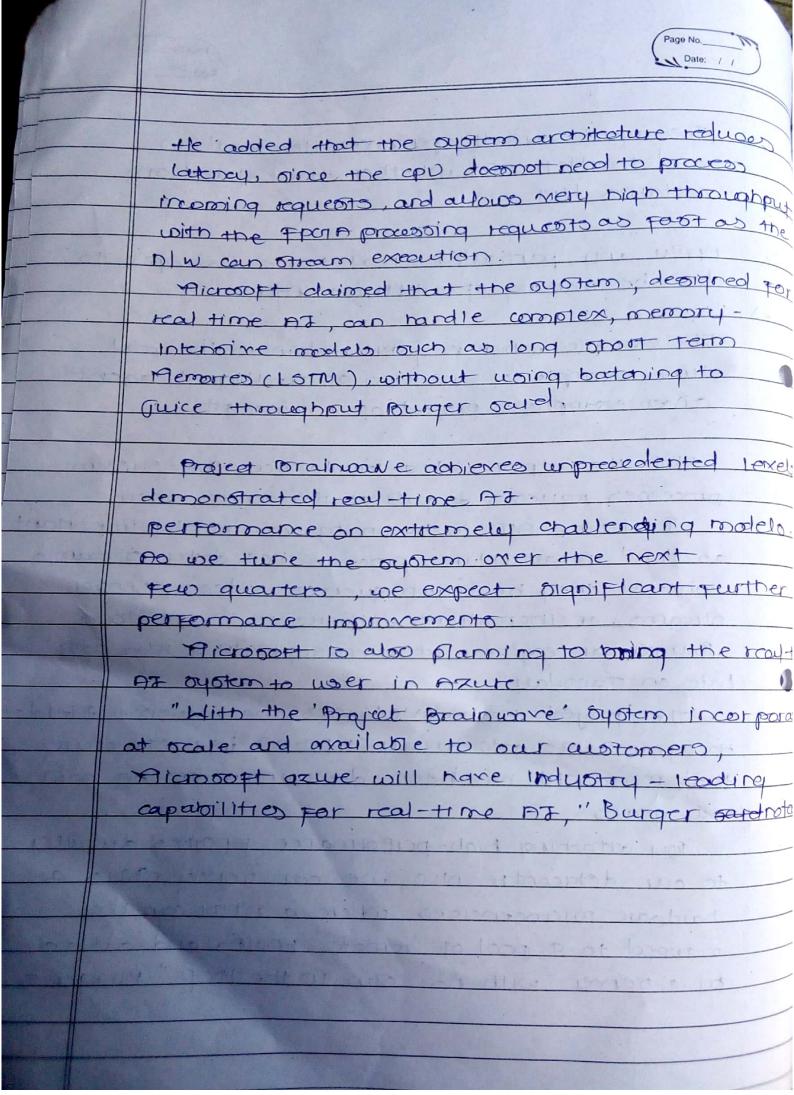
The performance measure awards one point for each dean square at each time of point of lipetime of Looo time ofeps.

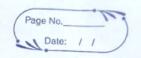
as priori but the drift diffribution and the initial location of the agent are not clean dost oquares stay clean and oucking clears the current square. The left and hight actions now the agent left and right except when this would take the agent outside the environment in which case the agent remains where it is

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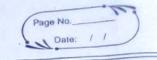
1	The agent correctly perceives its location
	and imation and whether that location.
- 10-6	contains dirt.
- 11.	a first continues programm dust? The rition
0.	Apply any particular real time example to
rop I	describe coorking of intelligent ment.
	- printer margina stant are the worthing
	The example which is given below is the real
	time example of working of intelligent agent.
	given example is project of microsopt
1	
J SYT	with the nelp of witry-low lateray, the system
- 1 - 1 1	processes requesto as Fast as it receives them
	Real-time AI is becoming increasingly important
L 1	as doud intrastructures process live date of reams
	other they be bearch queries videos, Gensor
Sal say	Burger, an engineer at microsoft in a blog post
<b>a</b>	late on Tuesday.
	The 'project mainwave' uses the massive field-
	foregrammable gate array (FPOIA) infrastrycture
100	that migrosoft has been deplaying over the past
4-74	rew years:
	By artaching high-performance program directly
	to our detecentre 110, we can serve DAMS as
	hardware microservices, where a DTH can be
	mapped to a pool of remote FPOIAS and called
	of a perver with no siw in the loop," Burger sour





- process with an suitable, example,
  - what actions and states to consider, of we will come to this point it shortly We will describe out states as "in (atymans)" where cityname in the name of eity in which we are currently in.
  - A problem can be defined formally by 4 components:
  - 1. Initial State:
    - agents start solving the problem.

      (e.i! in (h) ].
  - 2. State description
    - a description of the possible, actions available, to the agent, it is common to describe, it by means of successor function, given state, x than successor. In (20) returns a set of ordered pours < action, successor? where action from state, x and successor is the state, in which we can be by applying action.



- The initial state and the successor function together defined what is called state spacoi which is set of all possible states reachable, from the initial states.

3. Goal Test:

- we should be deerder whether the current table state is a goal

? e.i. is the current states rom (E) & ?

4. Path cost:

- a function that assigns a numarre value to each path, each otep we take in solving the problem should be somehow weighted, so If we travel from A to e our agent will pass by many cities, the cost to travel between two consecutive diti-en should have some measure.

A solution to a problem repath Born the initial states to goal state, the solution quantity is measured by the path cost, and optimal solution has the lowest path cost among all possible solutions.