

$$1) \quad V_1(t) \Rightarrow 10 \cos(\omega t) + 10 \sin(\omega t) \\ \Rightarrow 10 \cos(\omega t) + 10 \cos(\omega t - 90^\circ)$$

$$V_1(t) \Rightarrow 10 \angle 0^\circ + 10 \angle -90^\circ$$

$$V_1(t) \Rightarrow 10 [\cos(0^\circ) + i \sin(0^\circ)] + 10 [\cos(-90^\circ) + i \sin(-90^\circ)]$$

$$\Rightarrow 10 [1 + i(0)] + 10 [\cos(90^\circ) - i \sin(90^\circ)]$$

$$\Rightarrow 10 [1] + 10 [0 - i(1)]$$

$$V_1(t) \Rightarrow 10 - i(10)$$

$$V_1(t) \Rightarrow \sqrt{10^2 + 10^2} \tan^{-1} \left( \frac{-10}{10} \right)$$

$$\Rightarrow \sqrt{200} \tan^{-1}(-1)$$

$$V_1(t) \Rightarrow 14 \cdot 14 \angle -45^\circ$$

$$V_1(t) \Rightarrow 14 \cdot 14 \cos(\omega t - 45^\circ)$$

$$i_1(t) \Rightarrow 10 \cos(\omega t + 30^\circ) + 5 \sin(\omega t + 30^\circ)$$

$$i_1(t) \Rightarrow 10 \cos(\omega t + 30^\circ) + 5 \cos(\omega t + 30^\circ - 90^\circ)$$

$$\Rightarrow 10 \cos(\omega t + 30^\circ) + 5 \cos(\omega t - 60^\circ)$$

$$i_1(t) \Rightarrow 10 \angle 30^\circ + 5 \angle -60^\circ$$

$$\Rightarrow 10 [\cos(30^\circ) + i \sin(30^\circ)] + 5 [\cos(-60^\circ) + i \sin(-60^\circ)]$$

$$\Rightarrow 10 [0.866 + i(0.5)] + 5 [\cos(60^\circ) - i \sin(60^\circ)]$$

$$\Rightarrow 10 [0.866 + i(0.5)] + 5 [0.866 + i(0.5)]$$

$$\Rightarrow 8.66 + i(5) + 4.33 + i(2.5)$$

$$i_1(t) \Rightarrow \cancel{12.99 + i(2.5)} \Rightarrow 11.16 + 0.67i$$

$$i_1(t) = \sqrt{(\cancel{12.99})^2 + (2.5)^2} \tan^{-1}\left(\frac{2.5}{\cancel{12.99}}\right)$$

$$\Rightarrow \cancel{13.2283} \angle 10.89^\circ$$

$$i_1(t) \Rightarrow \sqrt{(11.16)^2 + (0.67)^2} \tan^{-1}\left(\frac{0.67}{11.16}\right)$$

$$\Rightarrow 11.18 \angle 3.435^\circ$$

$$i_1(t) \Rightarrow 11.18 \cos(\omega t + 3.435^\circ)$$

$$3) \quad i_2(t) \Rightarrow 20 \sin(\omega t + 90^\circ) + 15 \cos(\omega t - 60^\circ)$$

$$\Rightarrow 20 \cos(\omega t + 90^\circ - 90^\circ) + 15 \cos(\omega t - 60^\circ)$$

$$\Rightarrow 20 \cos(\omega t) + 15 \cos(\omega t - 60^\circ)$$

$$\hat{i}_2(t) \Rightarrow 20 \angle 0^\circ + 15 \angle -60^\circ$$

$$\Rightarrow 20 [\cos(0^\circ) + i \sin(0^\circ)] + 15 [\cos(-60^\circ) + i \sin(-60^\circ)]$$

$$\Rightarrow 20 [1 + i(0)] + 15 [\cos(60^\circ) - i \sin(60^\circ)]$$

$$\Rightarrow 20 [1] + 15 [0.5 - i(0.866)]$$

$$\hat{i}_2(t) \Rightarrow 20 + 7.5 - i(12.99)$$

$$\hat{i}_2(t) \Rightarrow 27.5 - i(12.99)$$

$$\Rightarrow \sqrt{(27.5)^2 + (12.99)^2} \tan^{-1} \left( \frac{-12.99}{27.5} \right)$$

$$\Rightarrow 30.41 \angle -25.28^\circ$$

$$\hat{i}_2(t) \Rightarrow 30.41 \cos(\omega t - 25.28^\circ)$$

$$v_1(t) \Rightarrow \cos(\omega t - 30^\circ)$$

$$v_2(t) \Rightarrow \cos(\omega t + 30^\circ)$$

$$v_3(t) \Rightarrow \cos(\omega t + 45^\circ)$$

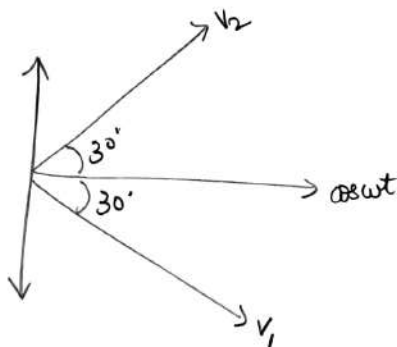
Case I: Comparing  $v_1(t)$  and  $v_2(t)$

$$v_1(t) \Rightarrow \cos(\omega t - 30^\circ)$$

$$v_1(t) \Rightarrow 1 \angle -30^\circ$$

$$v_2(t) \Rightarrow \cos(\omega t + 30^\circ)$$

$$v_2(t) \Rightarrow 1 \angle 30^\circ$$



$v_2$  leads  $v_1$  by  $60^\circ$

$v_1$  lags  $v_2$  by  $60^\circ$

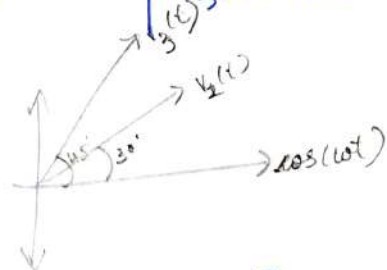
Case II: Comparing  $v_2(t)$  and  $v_3(t)$

$$v_2(t) \Rightarrow \cos(\omega t + 30^\circ)$$

$$v_2(t) \Rightarrow 1 \angle +30^\circ$$

$$v_3(t) \Rightarrow \cos(\omega t + 45^\circ)$$

$$v_3(t) \Rightarrow 1 \angle 45^\circ$$



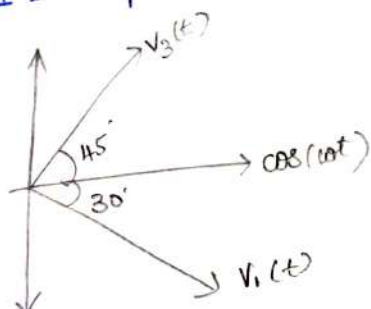
$v_3$  leads  $v_2$  by  $15^\circ$

$v_2$  lags  $v_3$  by  $15^\circ$

Case III: Comparing  $v_1(t)$  and  $v_3(t)$

$$v_1(t) \Rightarrow 1 \angle -30^\circ$$

$$v_3(t) \Rightarrow 1 \angle 45^\circ$$



$v_3$  leads  $v_1$  by  $75^\circ$

$v_1$  lags  $v_3$  by  $75^\circ$

$$2) \quad V_L(t) \Rightarrow 100 \cos(200t)$$

$$L \Rightarrow 0.25 \text{ H}$$

$$\omega \Rightarrow 200 \text{ rad/s}$$

$$1) \quad Z_L \Rightarrow ?$$

$$V_L \Rightarrow ?$$

$$I_L \Rightarrow ?$$

$$Z_L \Rightarrow j\omega L$$

$$\Rightarrow j(200)(0.25)$$

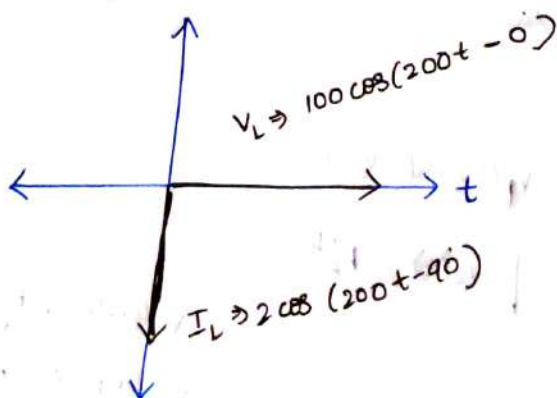
$$\Rightarrow j(50.00) \Rightarrow 50j$$

$$Z_L \Rightarrow 50j \Rightarrow 50 \angle 90^\circ$$

$$V_L(t) \Rightarrow 100 \cos(200t) \Rightarrow 100 \angle 0^\circ$$

$$I_L \Rightarrow \frac{V_L}{Z_L} \Rightarrow \frac{100 \angle 0^\circ}{50 \angle 90^\circ} \Rightarrow 2 \angle -90^\circ$$

$$I_L \Rightarrow 2 \cos(200t - 90^\circ)$$



In an inductor circuit, voltage always leads the current by  $90^\circ$   
current lags voltage by  $90^\circ$



$$V_c(t) \Rightarrow 100 \cos(200t)$$

$$C \Rightarrow 100 \mu F \quad \omega \Rightarrow 200 \text{ rad/s}$$

$$Z_c \Rightarrow \frac{-j}{\omega C}$$

$$\Rightarrow \frac{-j}{200(100 \times 10^{-6})} \Rightarrow \frac{-j}{2 \times 10^{-2}}$$

$$\Rightarrow \frac{-j(100)}{2} \Rightarrow -j(50)$$

$$\Rightarrow -50j \cdot \frac{j}{j} \Rightarrow \frac{-50j^2}{j} \Rightarrow \frac{50}{j}$$

↓

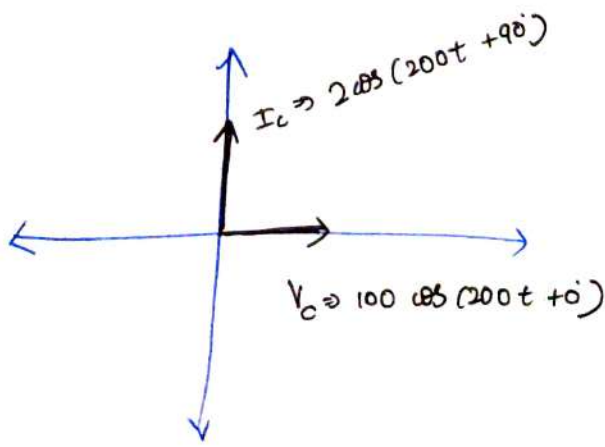
$$Z_c \Rightarrow 50 \angle -j \Rightarrow 50 \angle -90^\circ \Rightarrow 50 \cos(200t - 90^\circ)$$

$$V_c \Rightarrow 100 \cos(200t)$$

$$\Rightarrow 100 (\cos(200t + 0^\circ)) \Rightarrow 100 \angle 0^\circ$$

$$I_c \Rightarrow \frac{V_c}{Z_c} \Rightarrow \frac{100 \angle 0^\circ}{50 \angle -90^\circ} \Rightarrow 2 \angle 0^\circ + 90^\circ \Rightarrow 2 \angle 90^\circ$$

$$\Rightarrow 2 \cos(200t + 90^\circ)$$



In a capacitor circuit  
current leads the  
voltage by  $90^\circ$   
(or)  
voltage lags the  
current by  $90^\circ$