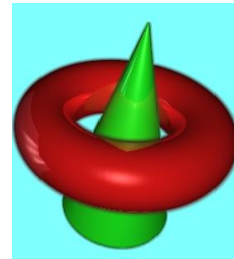
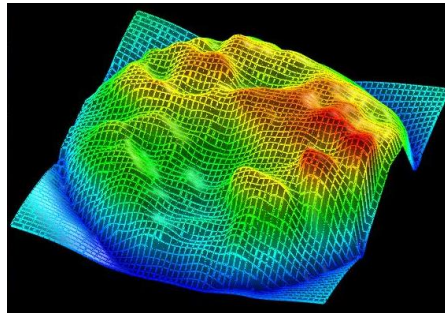
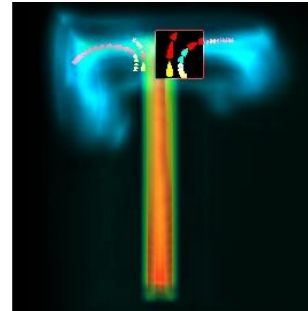
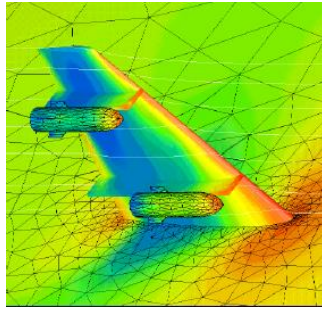
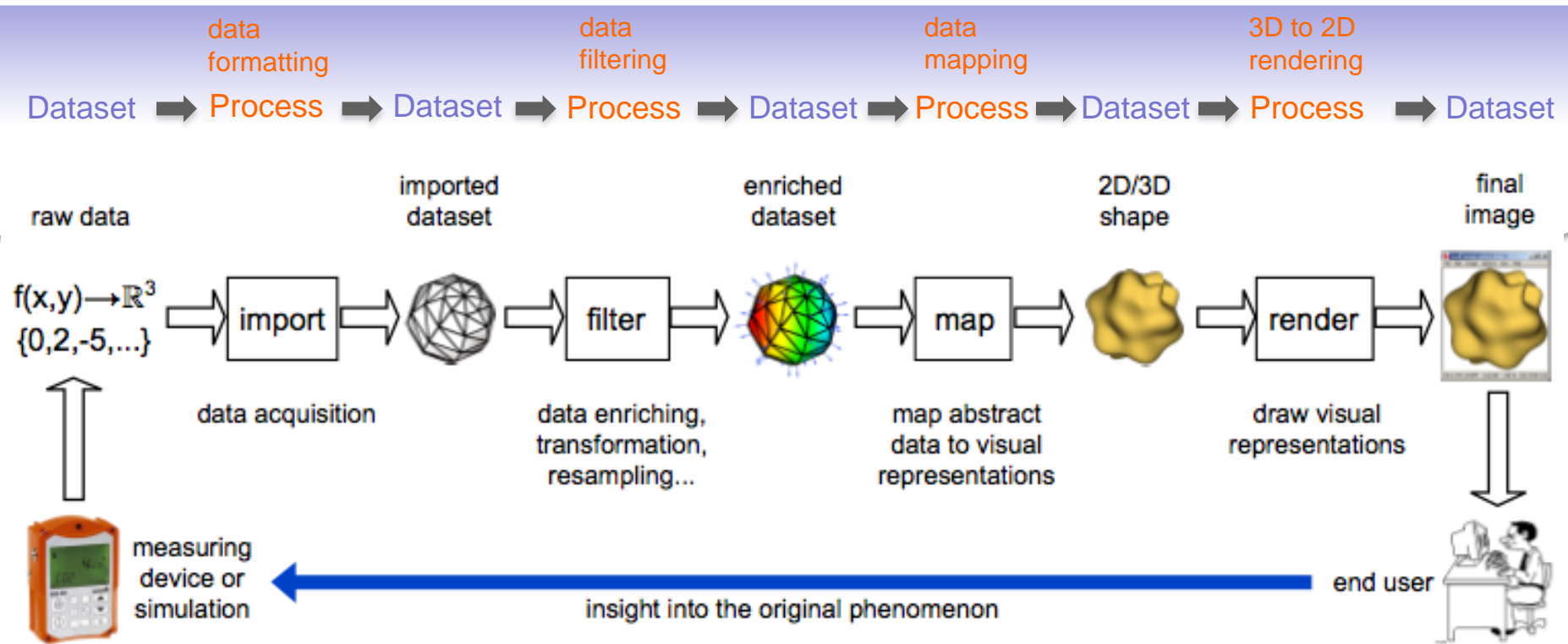


Vector Algorithms



The Visualization Pipeline - Recall



Vector algorithms (Chapter 6)

1. Scalar derived quantities

- divergence, curl, vorticity

2. 0-dimensional shapes

- hedgehogs and glyphs
- color coding

3. 1-dimensional and 2-dimensional shapes

- displacement plots
- stream objects

4. Image-based algorithms

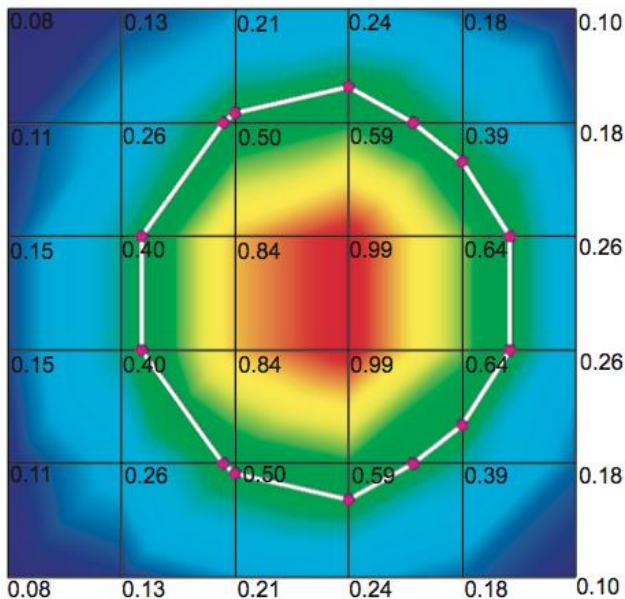
- image-based flow visualization in 2D, curved surfaces, and 3D
-

Basic problem

Input data

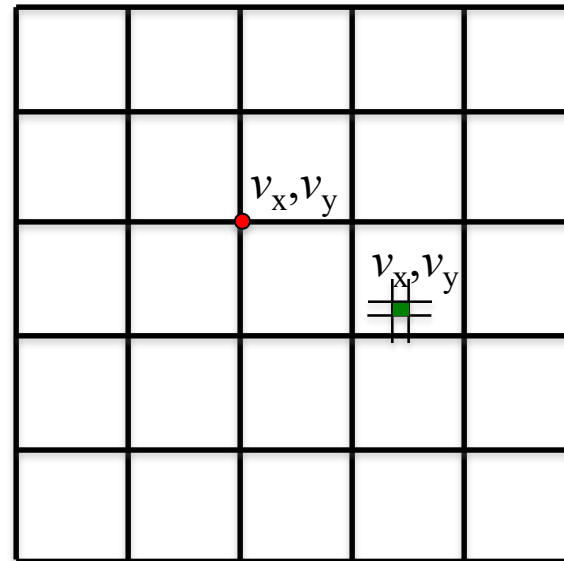
- vector field $v : D \rightarrow \mathbf{R}^n$
- domain D 2D planar surfaces, 2D surfaces embedded in 3D, 3D volumes
- variables $n=2$ (fields tangent to 2D surfaces) or $n=3$ (volumetric fields)

Challenge: comparison with scalar visualization



Scalar visualization

- challenge is to map D to 2D screen
- after that, we have 1 pixel per scalar value



Vector visualization

- challenge is to map D to 2D screen
- after that, we have 1 pixel for 2 or 3 scalar values!

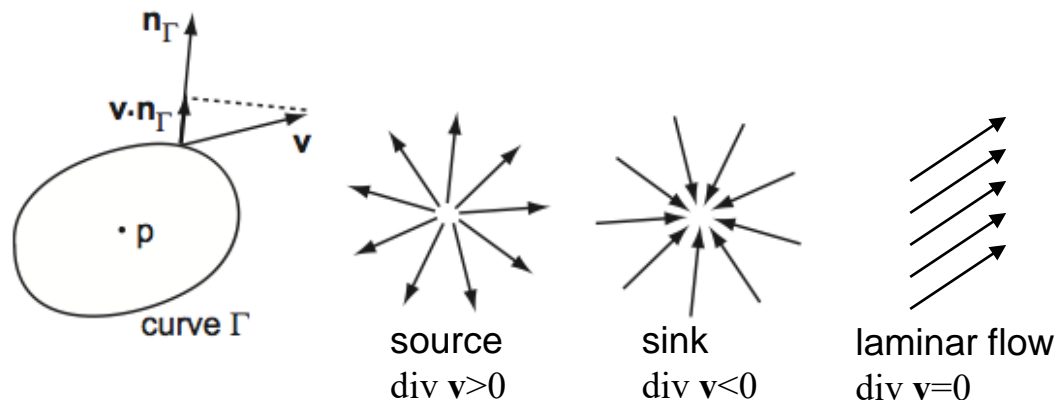
First solution: Reuse scalar visualization

- compute derived scalar quantities from vector fields
- use known scalar visualization methods for these

1.Divergence

- think of vector field as encoding a fluid flow
- intuition: amount of mass (air, water) created, or absorbed, at a point in D
- given a field $\mathbf{v} : \mathbf{R}^3 \rightarrow \mathbf{R}^3$, $\operatorname{div} \mathbf{v} : \mathbf{R}^3 \rightarrow \mathbf{R}$ is

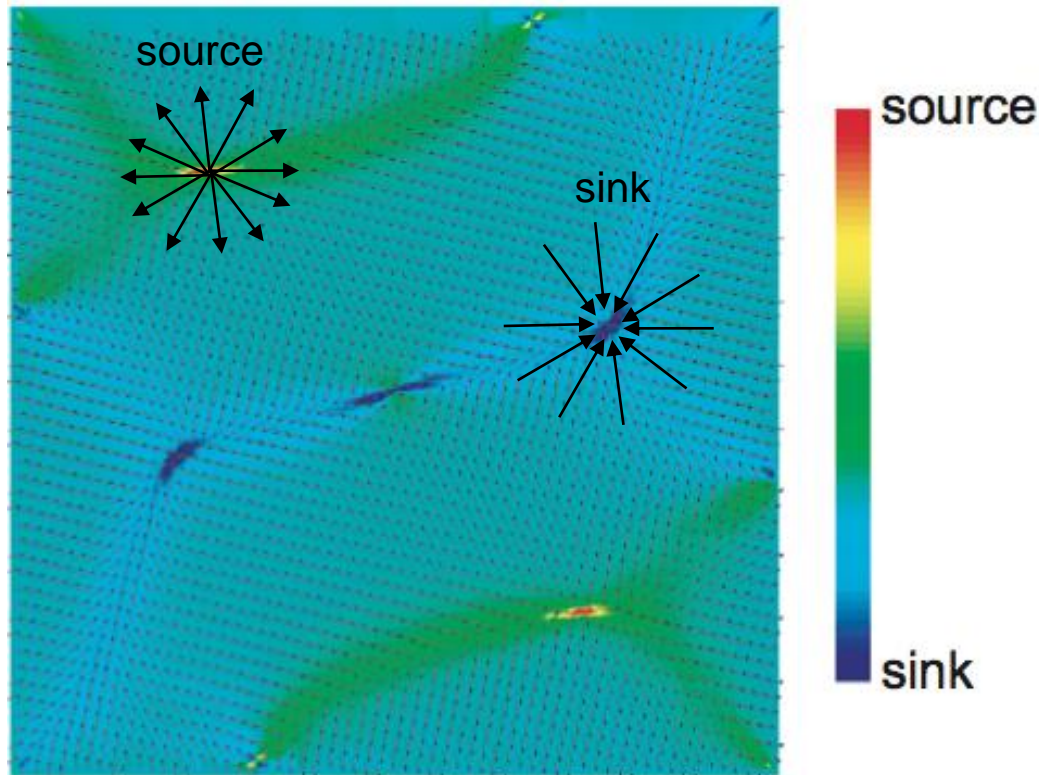
$$\operatorname{div} \mathbf{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \quad \text{equivalent to} \quad \operatorname{div} \mathbf{v} = \lim_{\Gamma \rightarrow 0} \frac{1}{|\Gamma|} \int_{\Gamma} (\mathbf{v} \cdot \mathbf{n}_{\Gamma}) ds$$



$\operatorname{div} \mathbf{v}$ is sometimes denoted as $\nabla \cdot \mathbf{v}$

Divergence

- compute using definition with partial derivatives
- visualize using e.g. color mapping



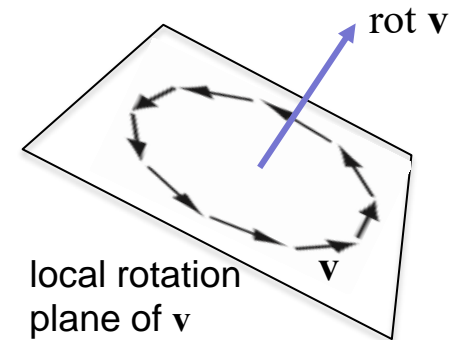
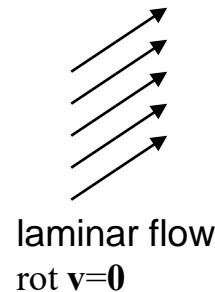
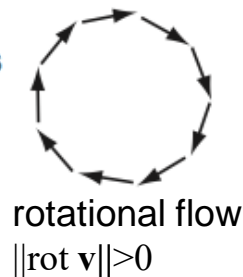
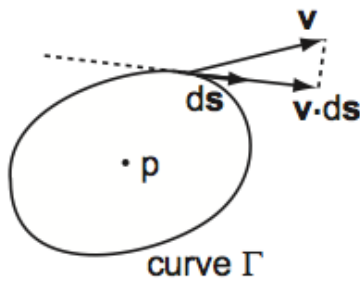
- gives a good impression of where the flow 'enters' and 'exits' some domain
-

Curl

2. Curl (also called rotor)

- consider again a vector field as encoding a fluid flow
- intuition: how quickly the flow 'rotates' around each point?
- given a field $\mathbf{v} : \mathbf{R}^3 \rightarrow \mathbf{R}^3$, $\text{rot } \mathbf{v} : \mathbf{R}^3 \rightarrow \mathbf{R}^3$ is

$$\text{rot } \mathbf{v} = \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z}, \frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x}, \frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \quad \text{equivalent to} \quad \text{rot } \mathbf{v} = \lim_{\Gamma \rightarrow 0} \frac{1}{|\Gamma|} \int_{\Gamma} \mathbf{v} \cdot d\mathbf{s}$$

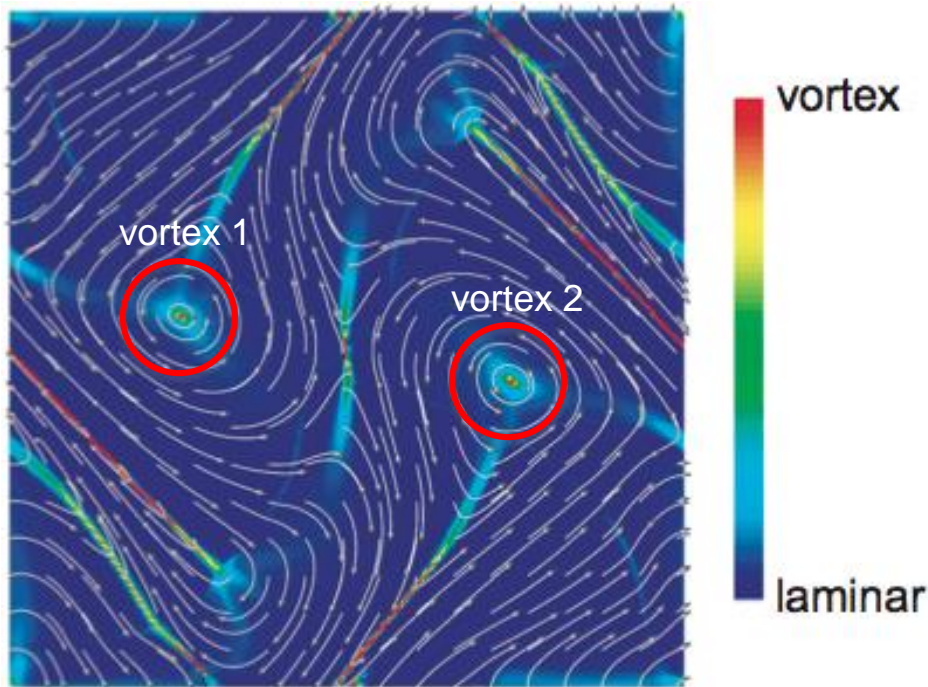


- $\text{rot } \mathbf{v}$ is locally perpendicular to plane of rotation of \mathbf{v}
- its magnitude: 'tightness' of rotation – also called **vorticity**

$\text{rot } \mathbf{v}$ is sometimes denoted as $\nabla \times \mathbf{v}$

Curl

- compute using definition with partial derivatives
- visualize magnitude $\|\text{rot } \mathbf{v}\|$ using e.g. color mapping

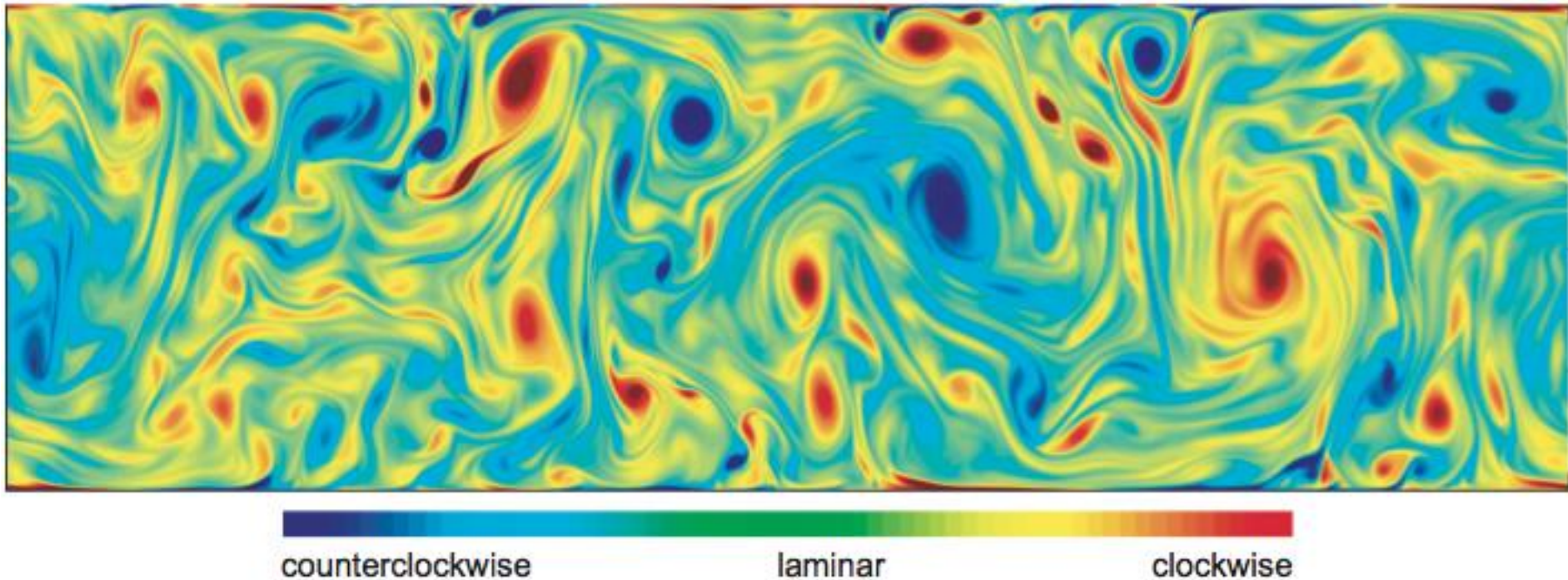


- very useful in practice to find **vortices** = regions of high vorticity
 - these are highly important in flow simulations (aerodynamics, hydrodynamics)
-

Curl

Example of vorticity

- 2D fluid flow
- simulated by solving Navier-Stokes equations
- visualized using vorticity



Observations

- vortices appear at different scales
 - see the 'pairing' of vortices spinning in opposite directions
 - what happens with the flow close to the boundary? Why
-

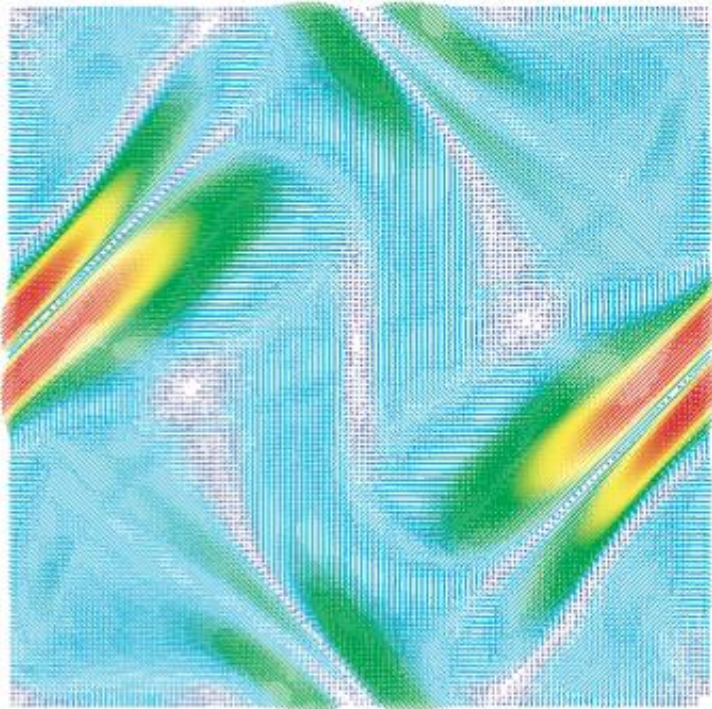
Vector glyphs

Icons, or signs, for visualizing vector fields

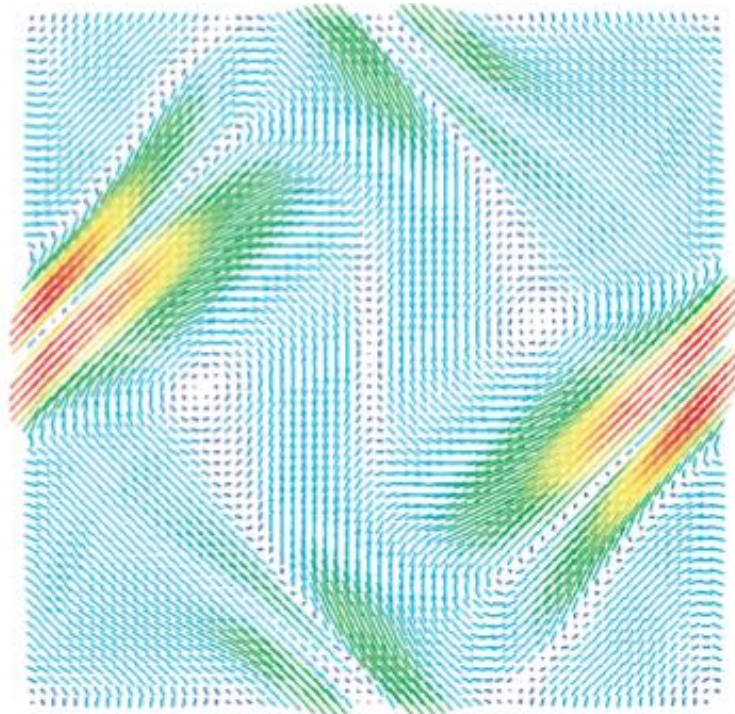
- placed by (sub)sampling the dataset domain
- attributes (scale, color, orientation) map vector data at sample points

Simplest glyph: Line segment (hedgehog plots)

- for every sample point $x \in D$
 - draw line $(x, x + k\mathbf{v}(x))$
 - optionally color map $\|\mathbf{v}\|$ onto it



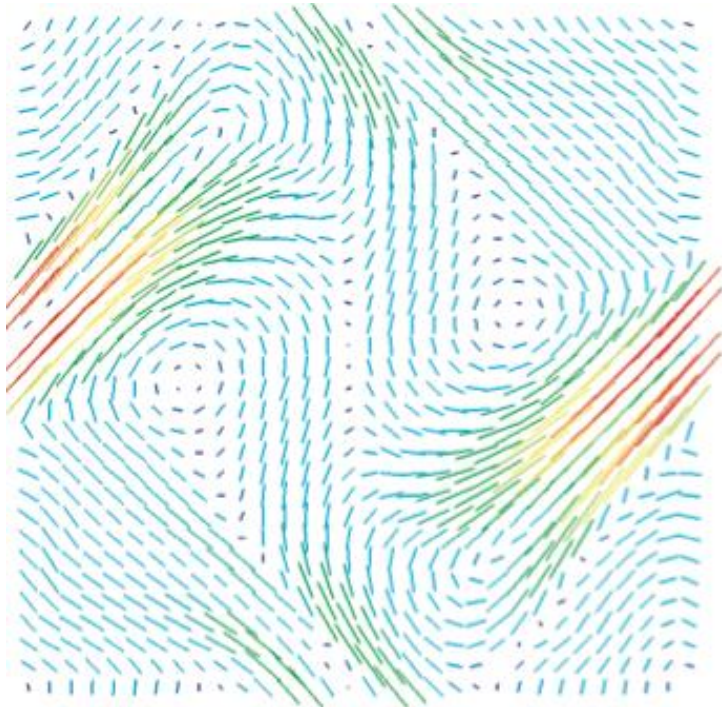
128² glyph grid



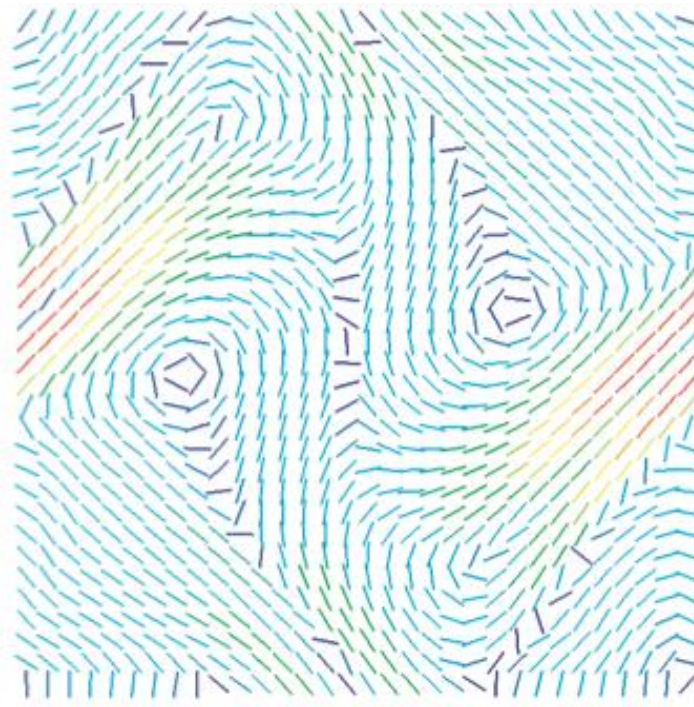
64² glyph grid

MHD simulation
256² grid

Vector glyphs



32^2 glyph grid



32^2 glyph grid, no line scaling

MHD simulation
 256^2 grid

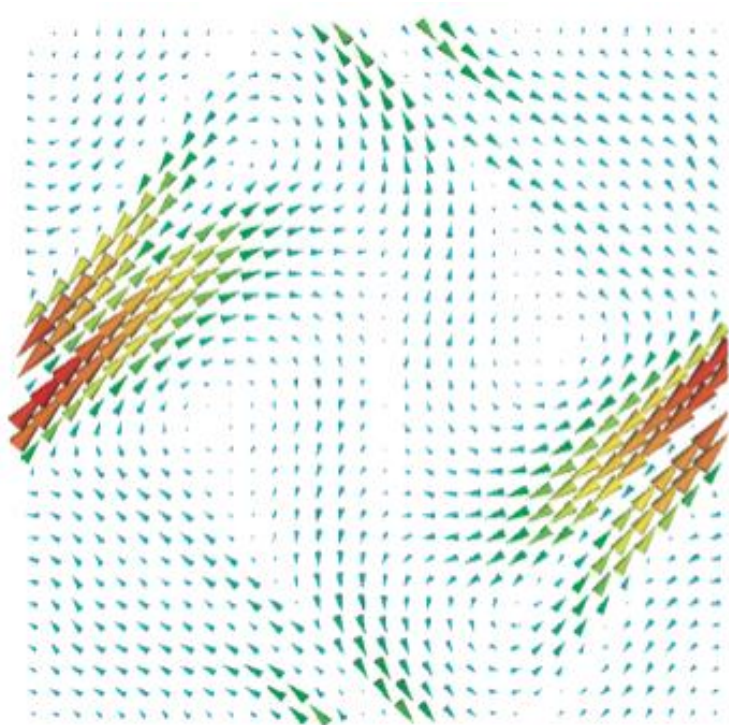
Observations

•trade-offs

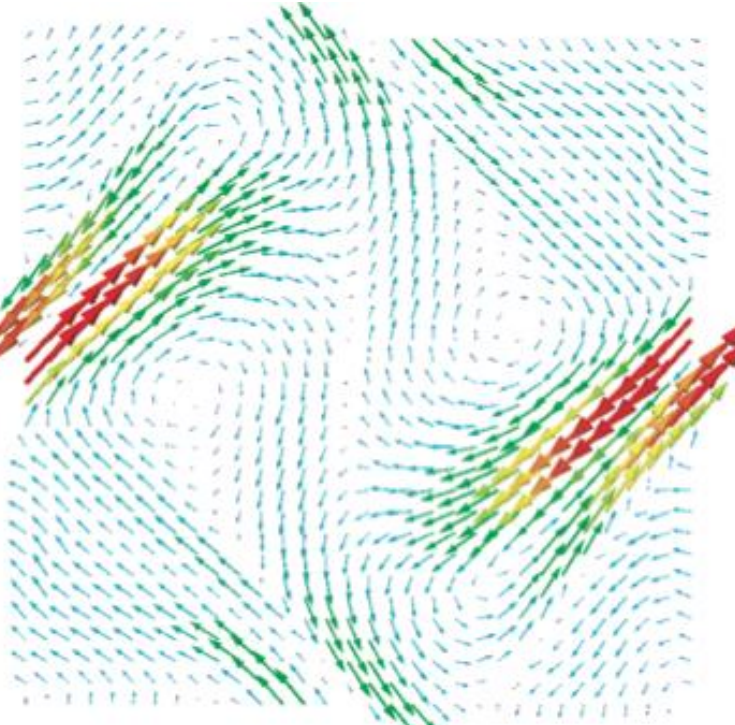
- more samples: more data points depicted, but more potential clutter
- less samples: less data points depicted, but higher clarity
- more line scaling: easier to see high-speed areas, but more clutter
- less line scaling: less clutter, but harder to perceive directions

Can you observe other pro's and con's of line glyphs?

Vector glyphs



3D cone glyphs



3D arrow glyphs

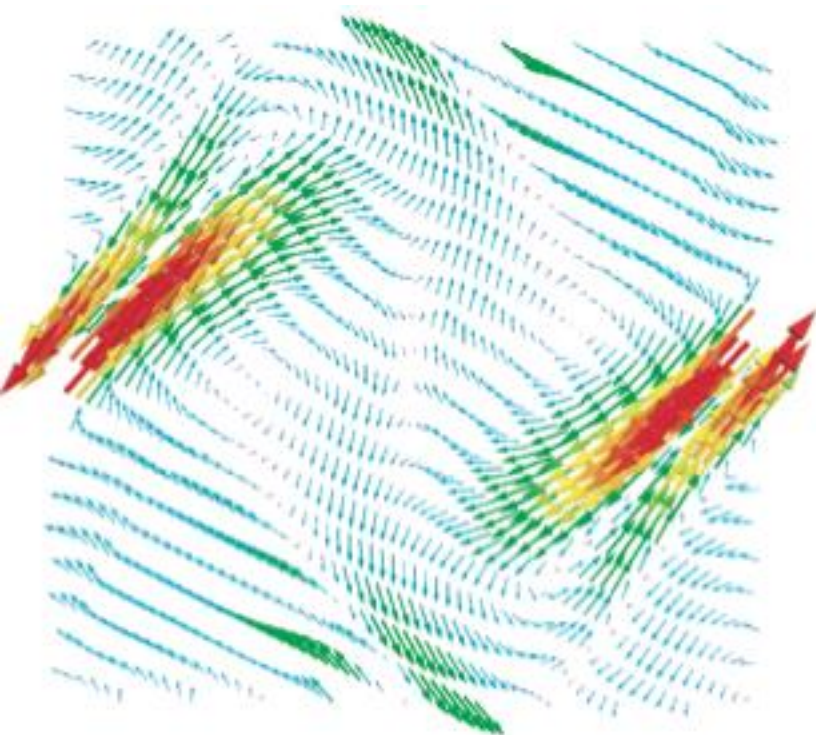
MHD simulation
256² grid

Variants

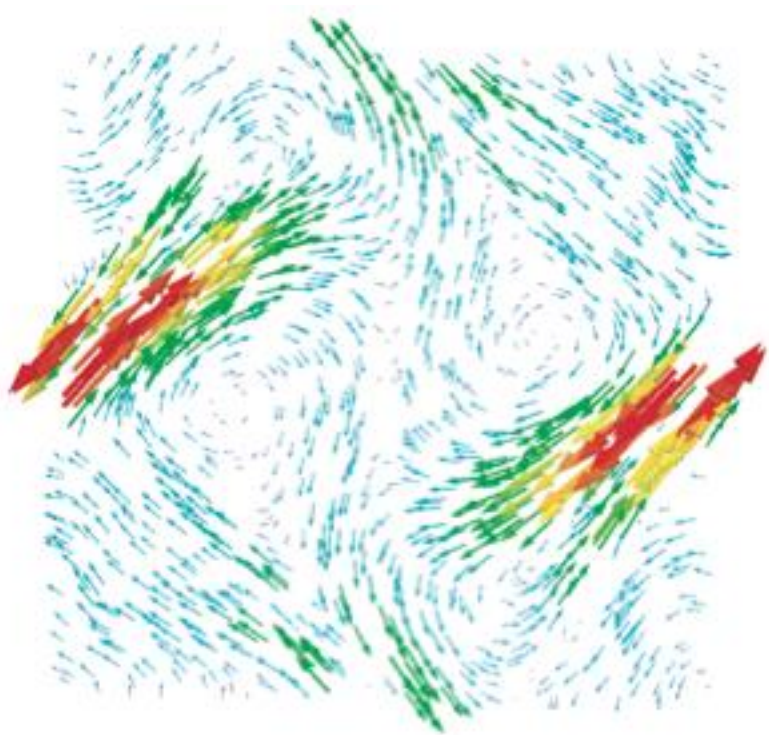
- cones, arrows, ...
 - show *orientation* better than lines
 - but take more space to render
 - shading: good visual cue to separate (overlapping) glyphs

Can you observe other pro's and con's of cone or arrow glyphs?

Vector glyphs



samples on a rotated grid

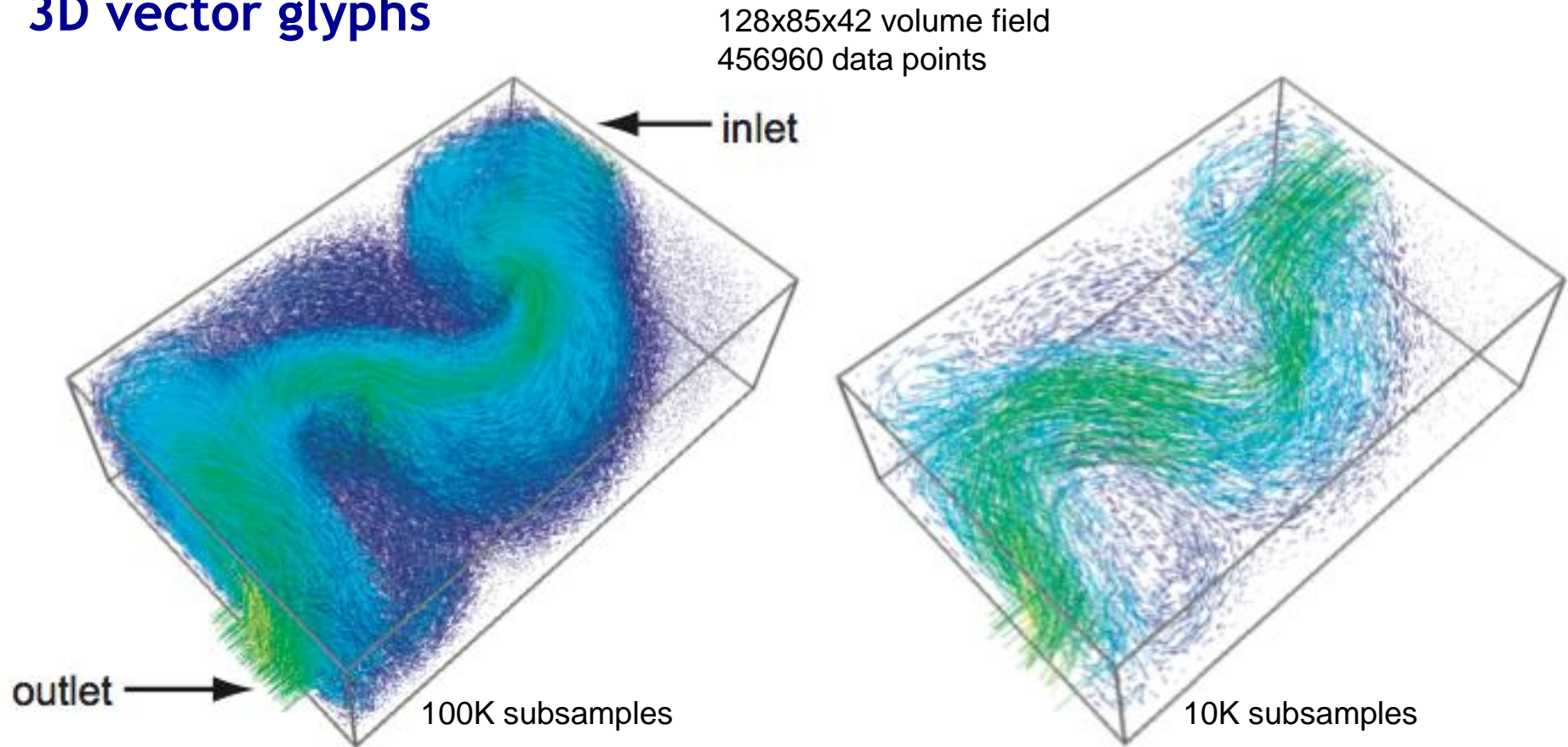


random samples, quasi-uniform density

How to choose sample points

- avoid uniform grids!
- random sampling: generally OK

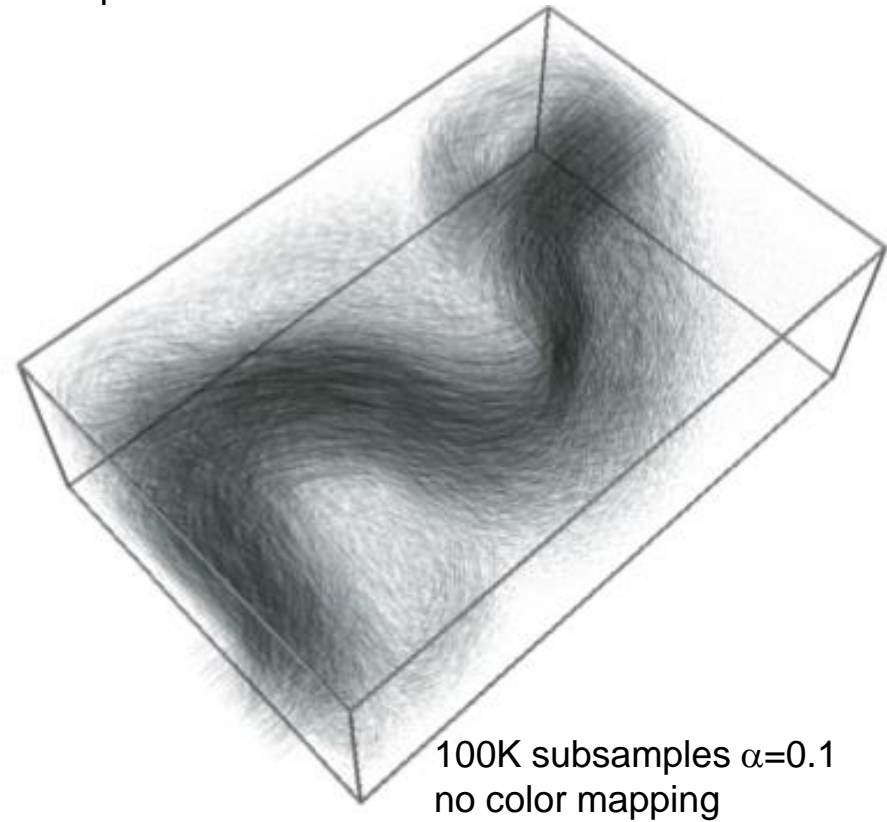
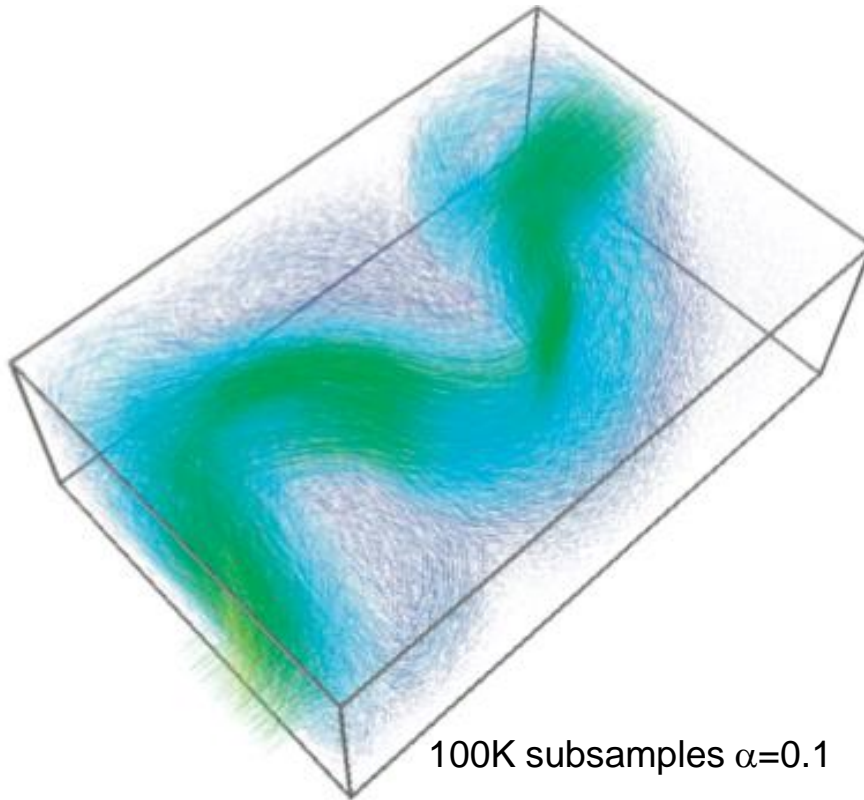
3D vector glyphs



- same idea/technique as 2D vector glyphs
 - 3D additional problems
 - more data, same screen space
 - occlusion
 - perspective foreshortening
 - viewpoint selection
-

3D vector glyphs

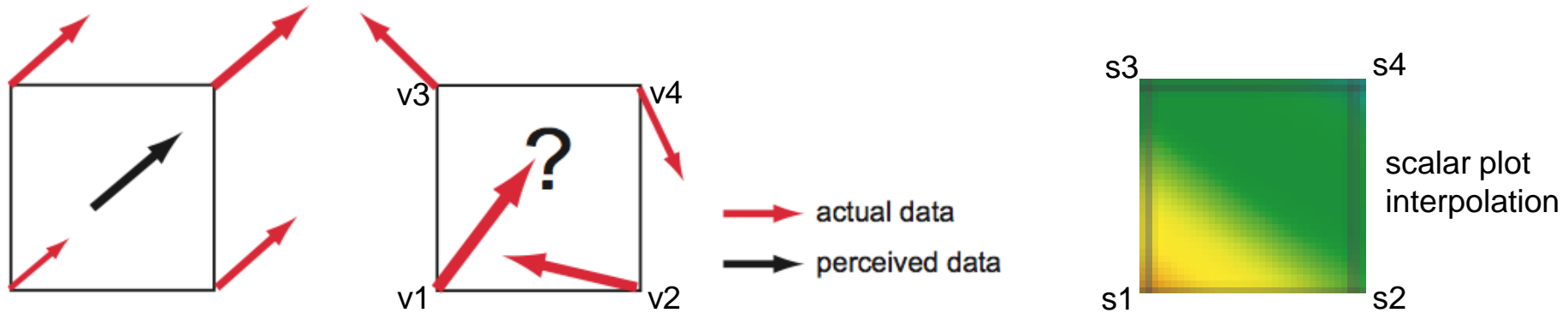
128x85x42 volume field
456960 data points



Alpha blending

- extremely simple and powerful tool
 - reduce *perceived* occlusion
 - low-speed zones: highly transparent
 - high-speed zones: opaque and highly coherent (why?)
-

Glyph problem revisited



Recall the 'inverse mapping' proposal

- we render something...
- ...so we can visually map it to some data/phenomenon

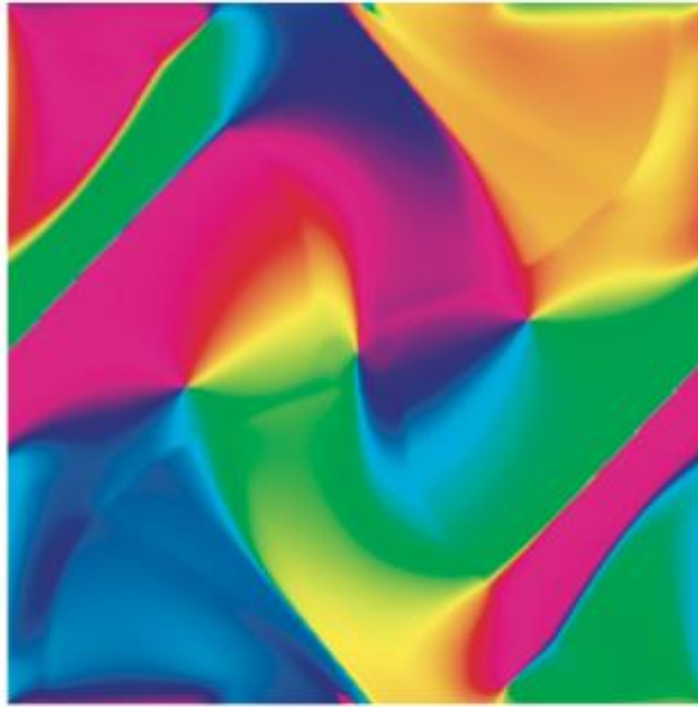
Glyph problems

- **no interpolation** in glyph space (unlike for scalar plots with color mapping!)
- a glyph takes more space than a pixel
- we (humans) aren't good at visually interpolating arrows...
- scalar plots are **dense**; glyph plots are **sparse**
 - this is why glyph positioning (sampling) is extra important

Vector color coding



magnitude=luminance



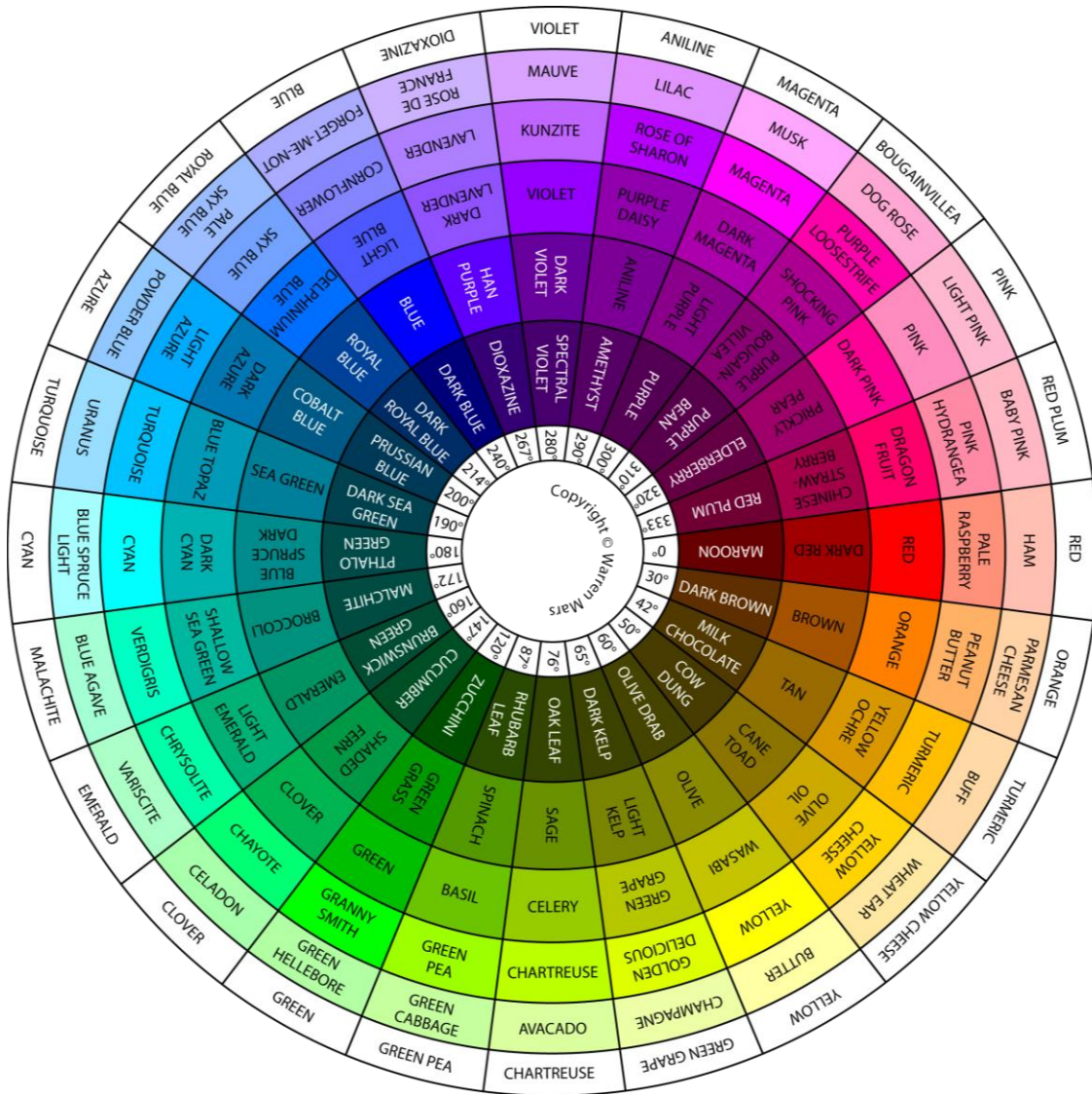
constant luminance (direction coding only)



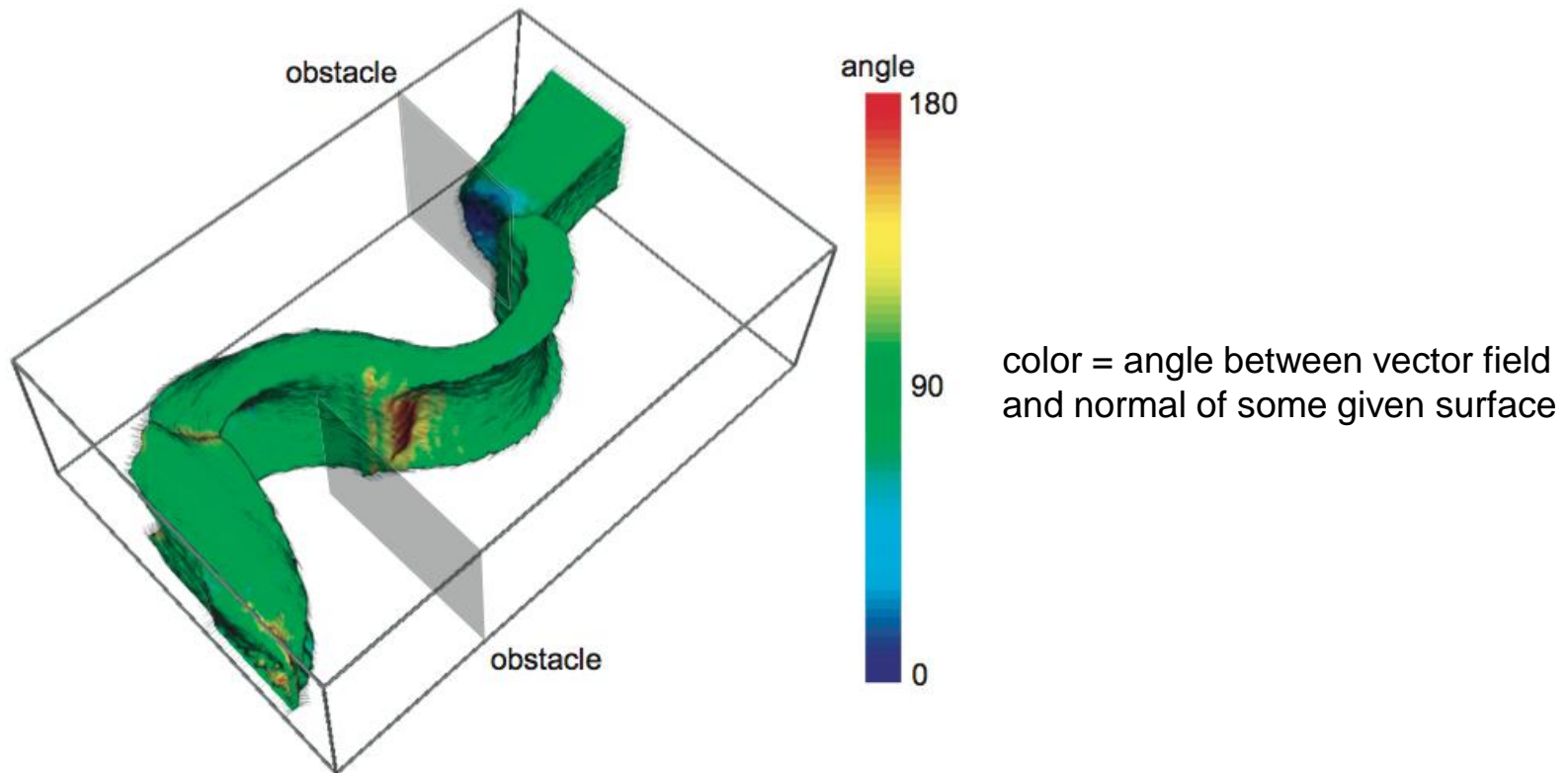
direction
color wheel

Reduce vector data to scalar data (using HSV color model)

- direction = hue
 - magnitude = luminance (optional)
 - no occlusion/interpolation problems...
 - ...but images are highly abstract (recall: we don't naturally see directions)
-



Vector color coding



See if vectors are tangent to some given surface

- color-code angle between vector and surface normal
 - easily spot
 - tangent regions (flow stays on surface, green)
 - inflow regions (flow enters surface, red)
 - outflow regions (flow exits surface, blue)
-