

# MidcurveNN

## Application of Deep Learning to Geometric Algorithms

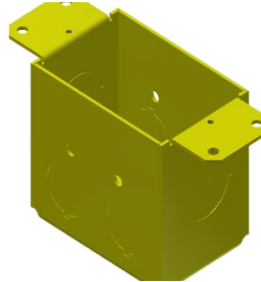
Yogesh Kulkarni

# Introduction

# Strength Analysis by CAE



Aerospace



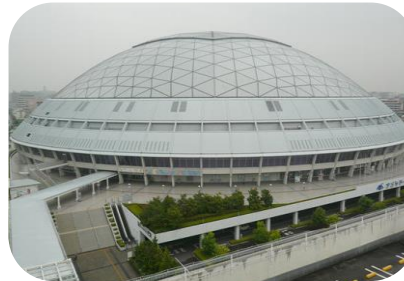
Machinery



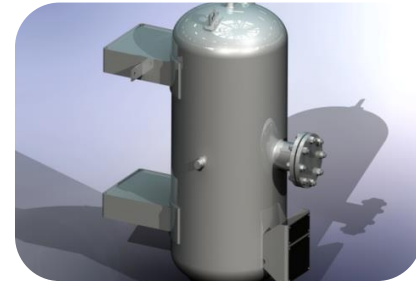
Consumer



Energy



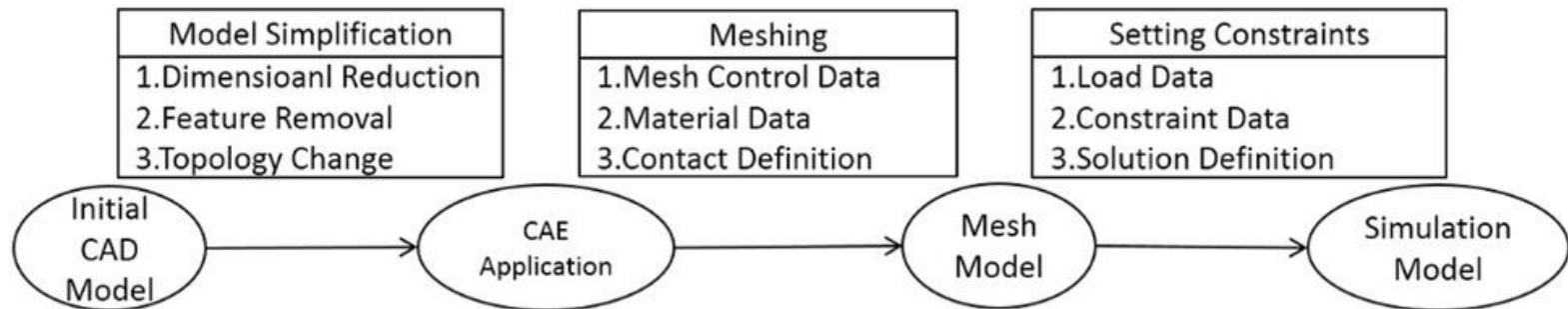
Construction



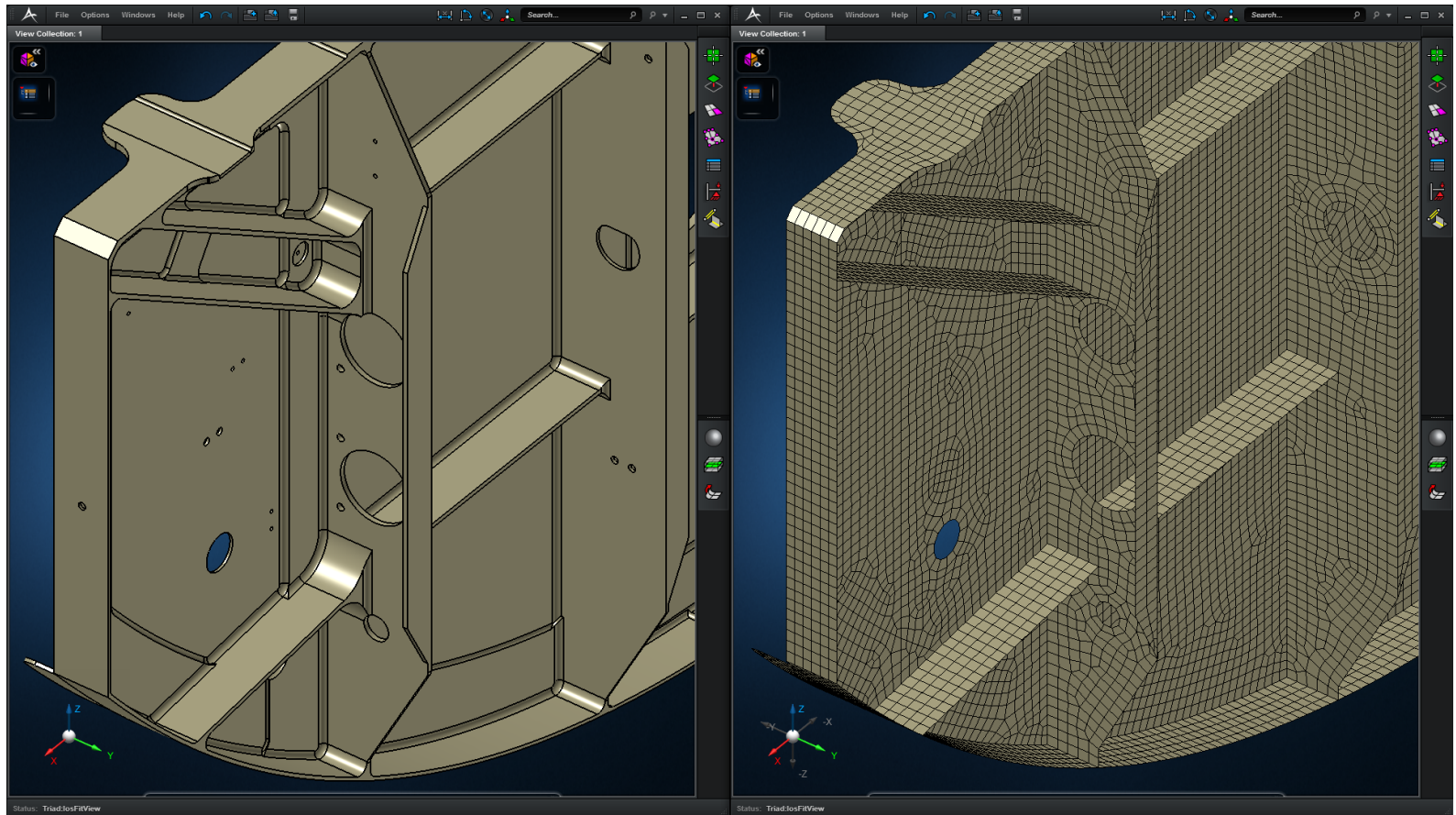
Industrial

# Can we use shapes directly?

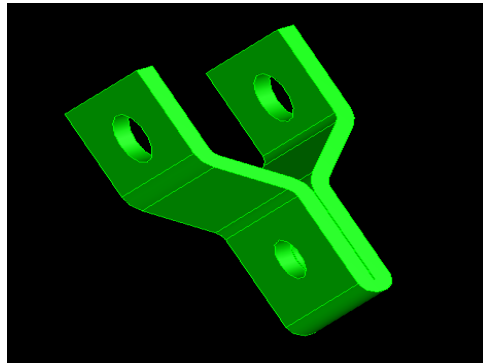
- CAD : Designing Shapes
- CAE : Engineering Analysis
- CAD->CAE: Simplification for quicker results.



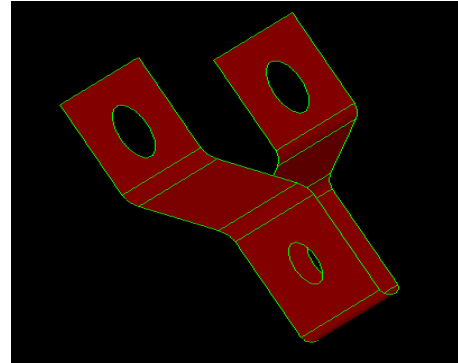
# CAD-CAE



# Midsurface is?



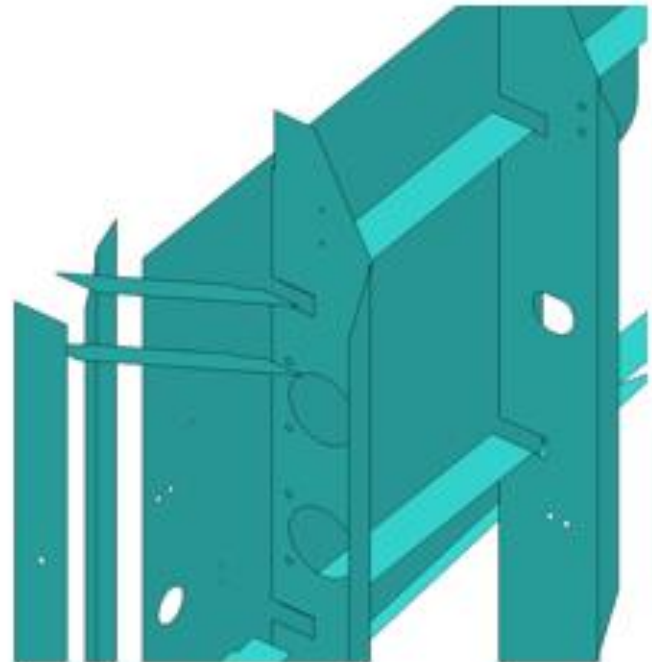
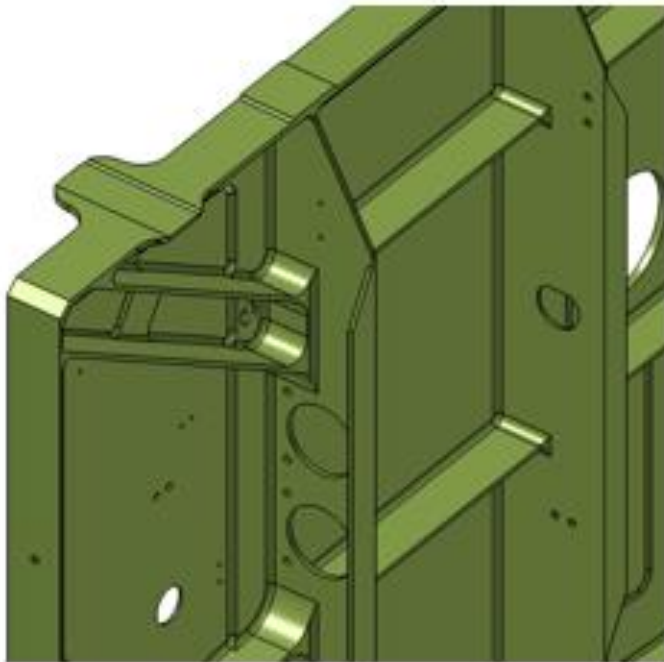
Input: Solid



Output: Midsurface

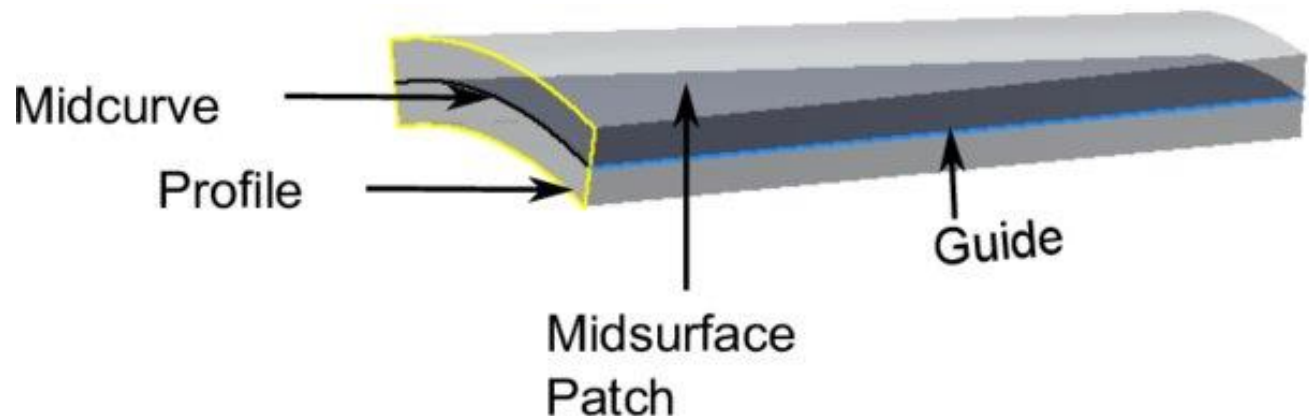
- Widely used for CAE of Thin-Walled parts
- Computation is challenging and still unsolved

# Look at the output



# Midsurface Computation

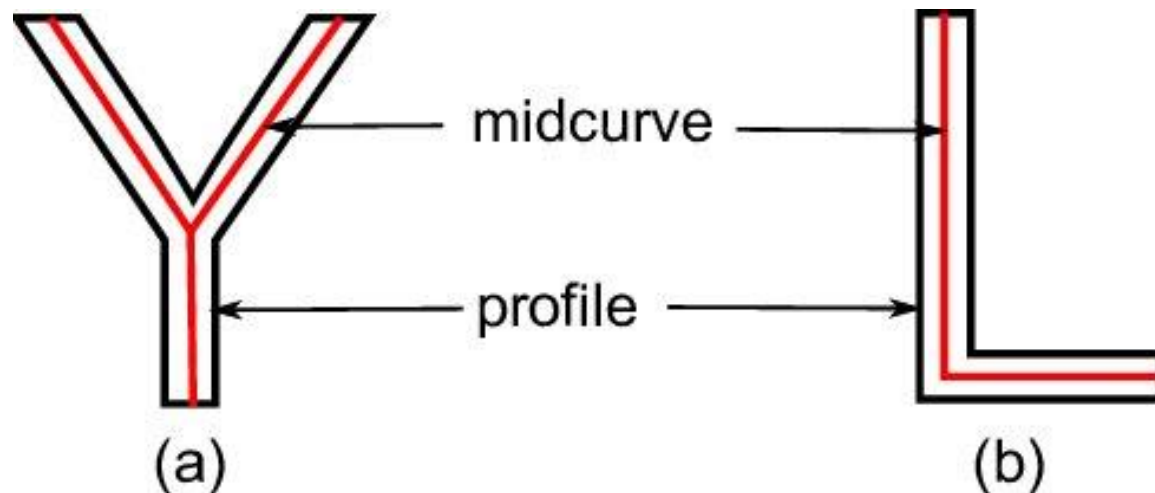
- Midsurface of a Patch is Midcurve of its profile extruded.
- So, it boils down to computing 1D midcurve of a 2D profile





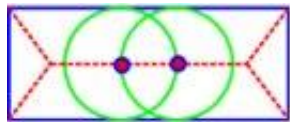
# What is a Midcurve?

- Midsurface : From 3D thin Solid to 2D Surface
- Midcurve : From 2D Profile to 1D Curve

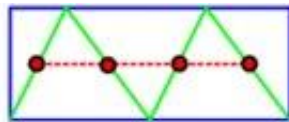


# Many Approaches

- More than 6 decades of research...
- Most CAD-CAE packages...
- Rule-based!! Heuristic!! Case-by-case basis!!



MAT



CAT

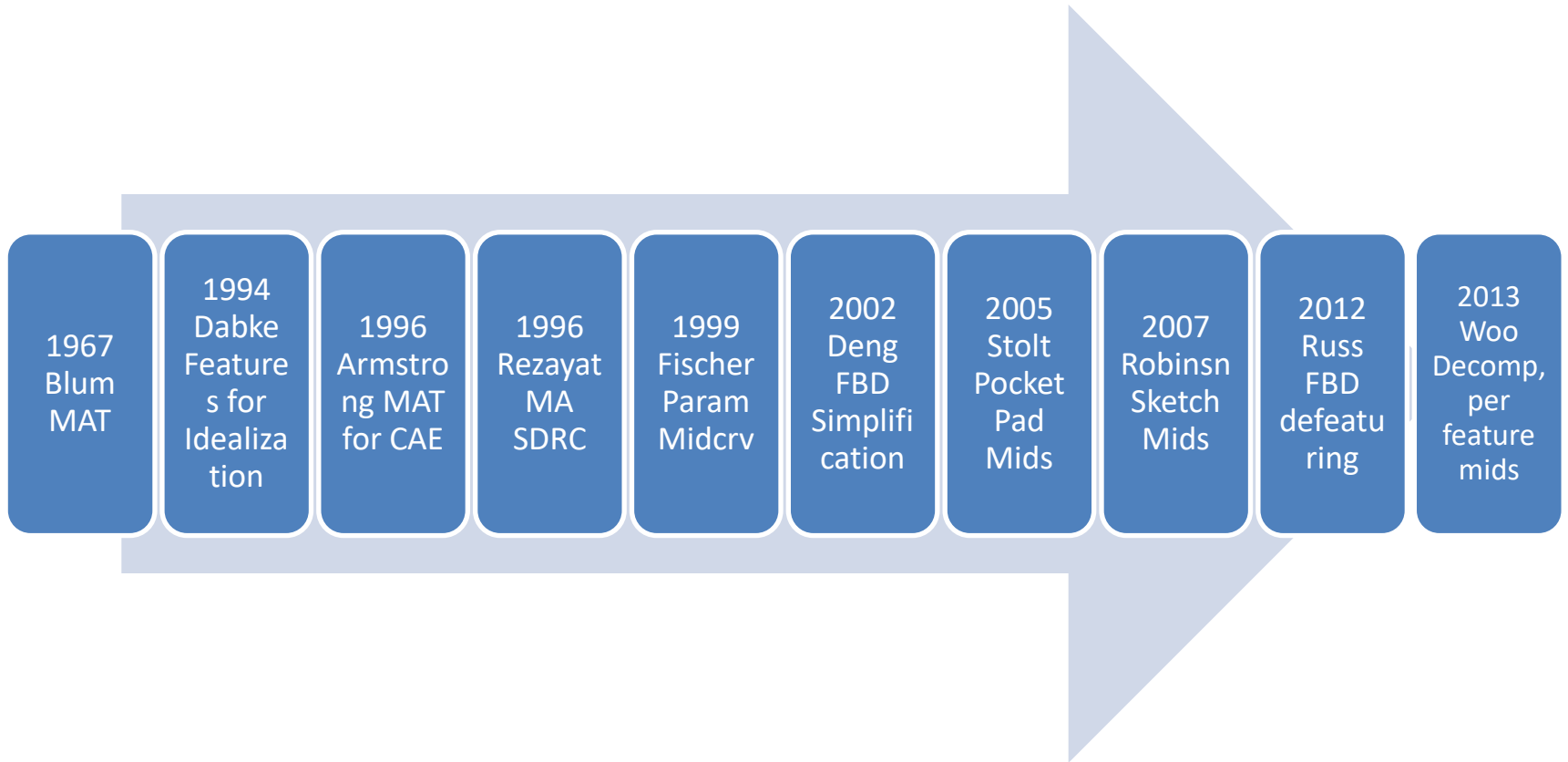


Thinning

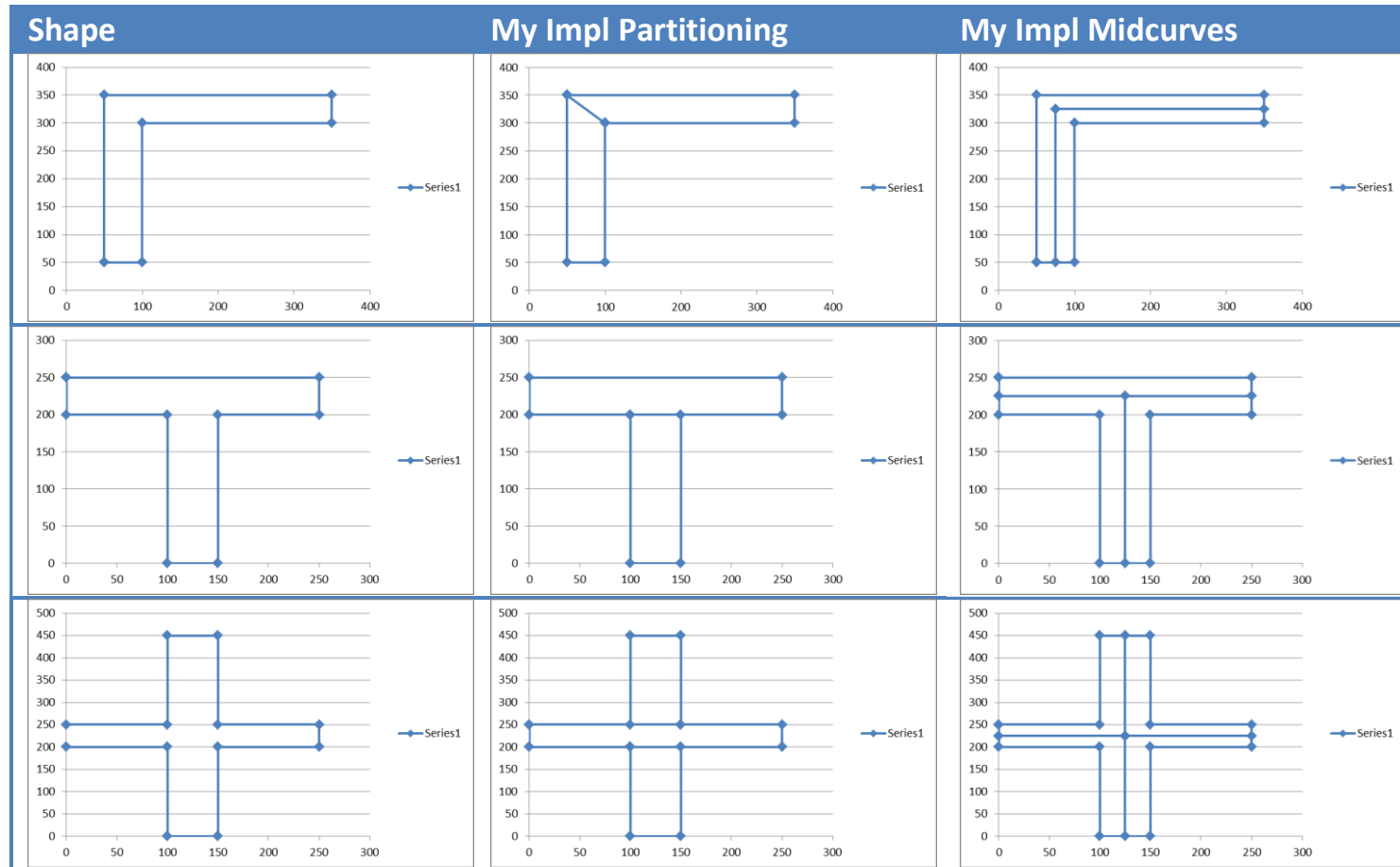


Pairs

# When-What



# 2017: My PhD Work: Rule-based



# Limitations

- Fully rule-based
- Need to adjust for new shapes
- So, not scalable



# Idea



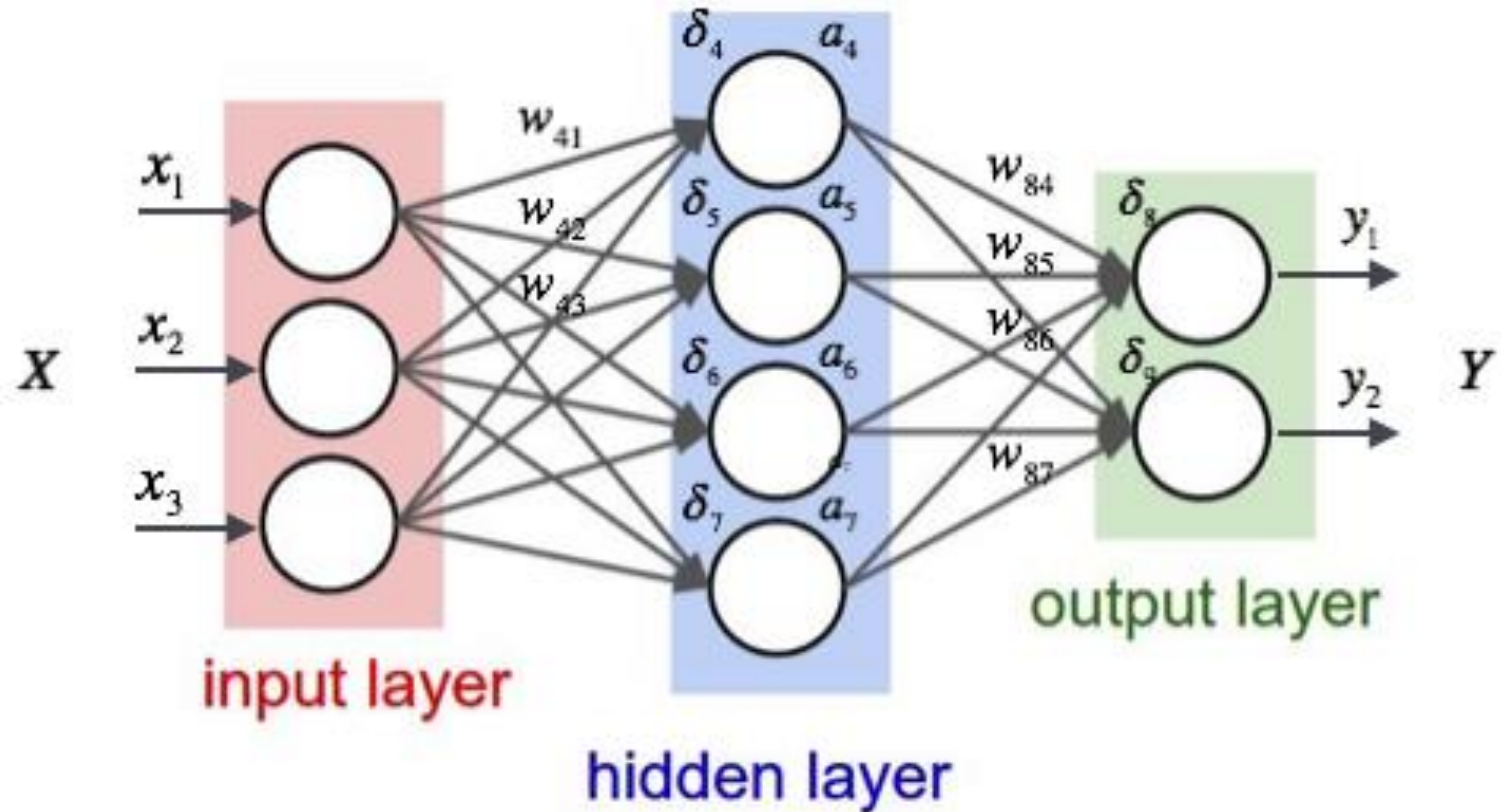
Can Neural Networks “learn” the  
dimension reduction transformation?

# How?



- Supply lots of training data of profiles and their corresponding midcurves and train.
- Then given an unseen profile, can Neural Network compute a midcurve, mimicking the original profile shape?

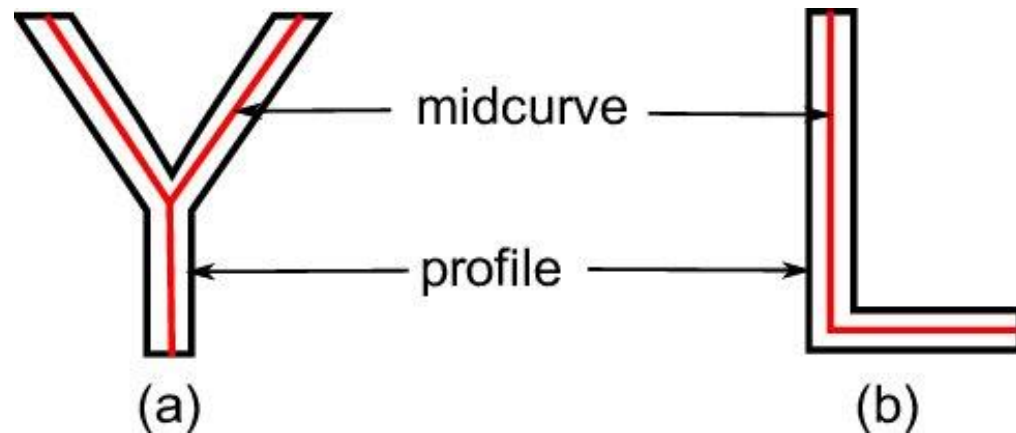
# Midcurve by Neural network





# Midcurve == Dimension Reduction

- Like PCA (Principal Component Analysis), wish to find Principal curve
- That 'represents' the original profile shape

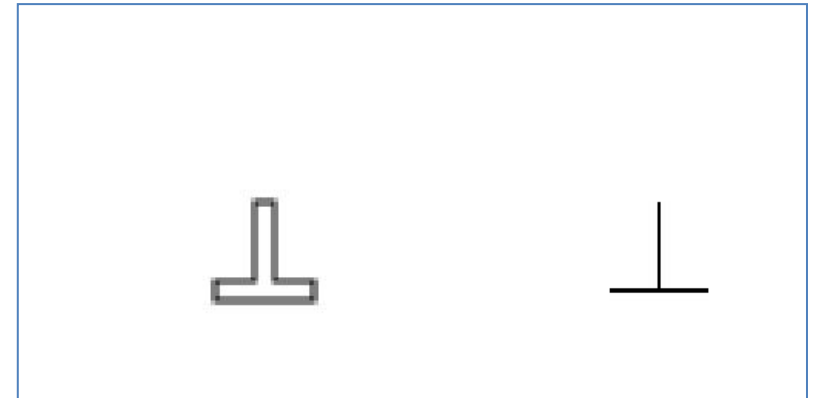
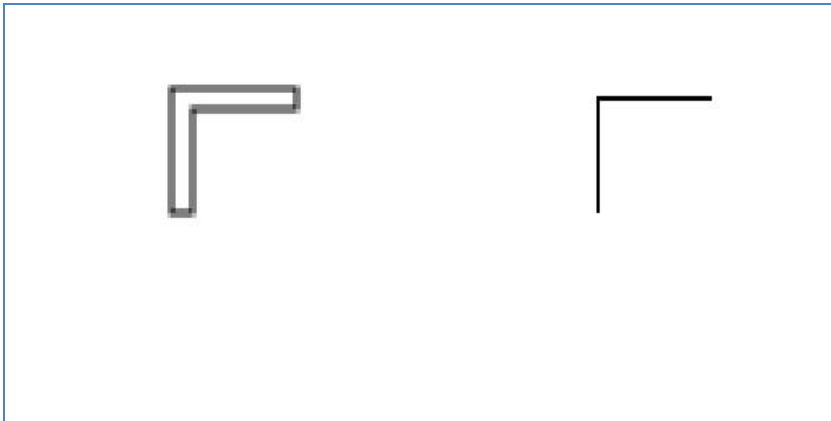


# Variable Size Encoder Decoder

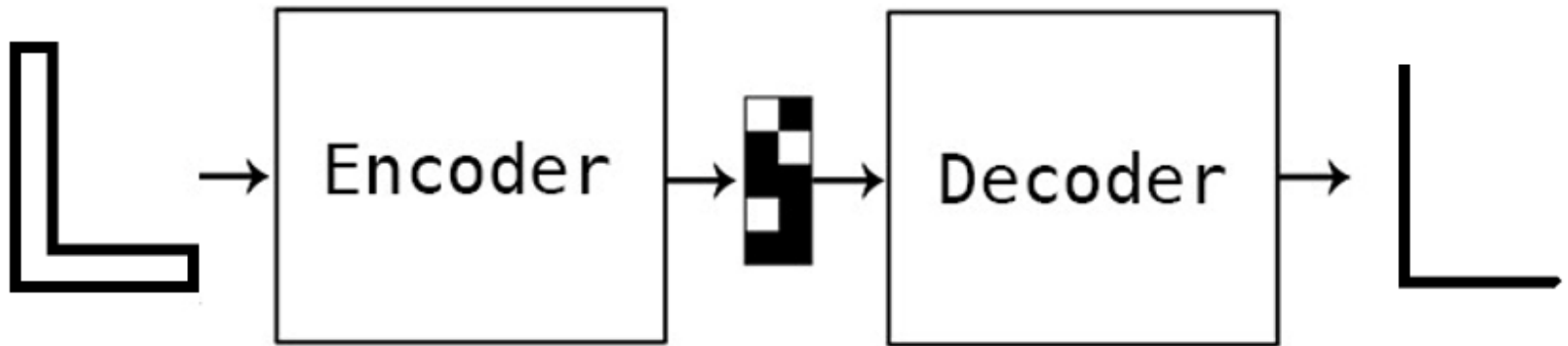
- OK for NLP, say Machine Translations, where padding values like “-1” can be added along with other words (vectors or indices)
- But in Geometry, its not OK.
- Because any value can represent a Valid Input, even though we don't want it to be the input.

# A Twist to the problem

- Input: Black & White Image of 2D profile
- Output: Black & White Image of 1D midcurve



# For Dimension Reduction



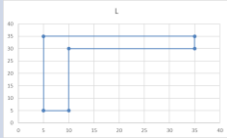
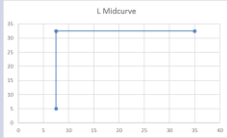
# For Deep Learning

- Need lots of data
- Had just few input output image pairs
- How to augment/populate large variations...

# DATA PREPARATION

# Data

Original input and output are in the form of polylines, meaning a list of points, each having x,y coordinates

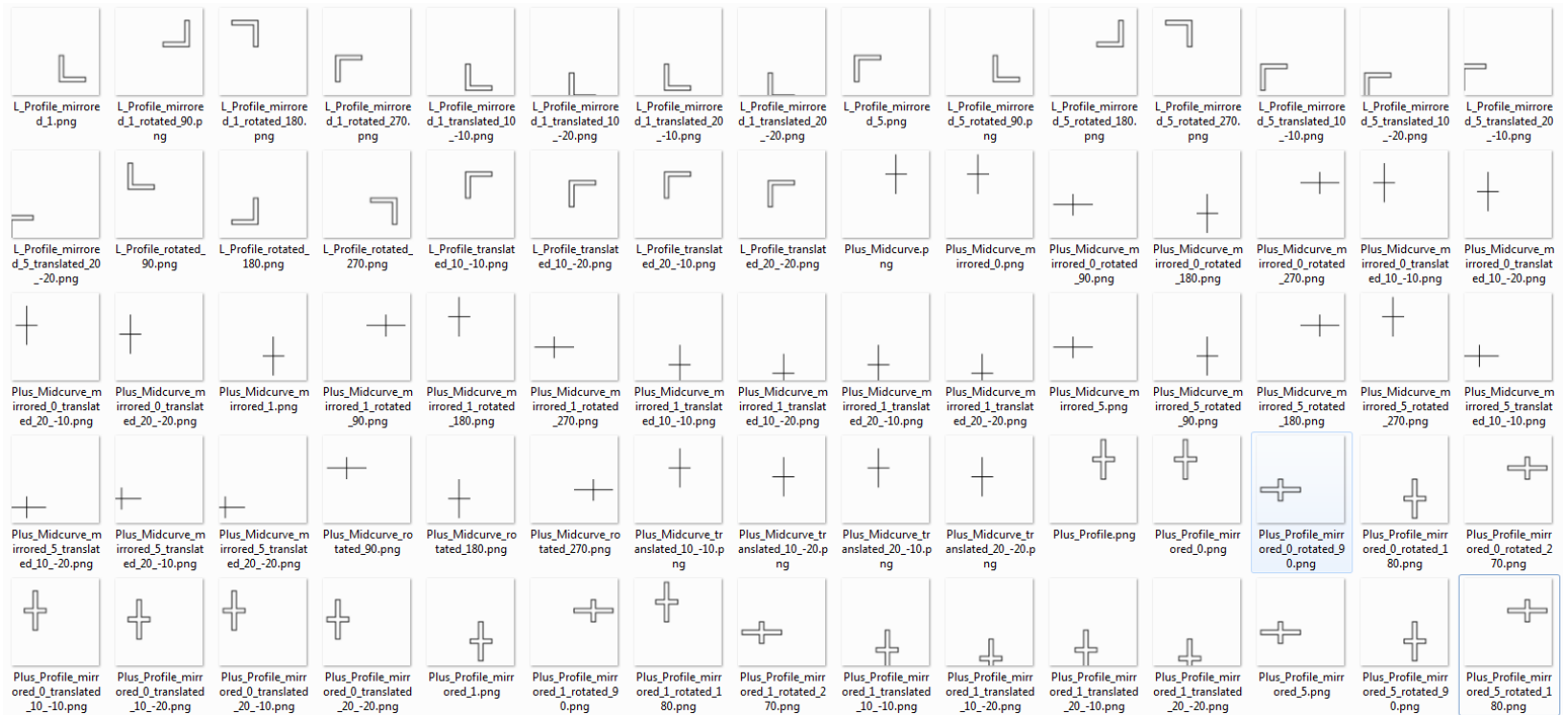
Profile Data		Profile Picture	Midcurve Data		Midcurve Picture
5.0	5.0		7.5	5.0	
10.0	5.0		7.5	32.5	
10.0	30.0		35.0	32.5	
35.0	30.0		7.5	32.5	
35.0	35.0				
5.0	35.0				

# Augmentation

- Such few profile shapes, are just not enough for Neural Networks to train.
- Need more with as much diversity as possible.
- Will need to artificially augment data with transformations, like pan, rotate, mirror, etc.
- All needs to be automatically, programmatically

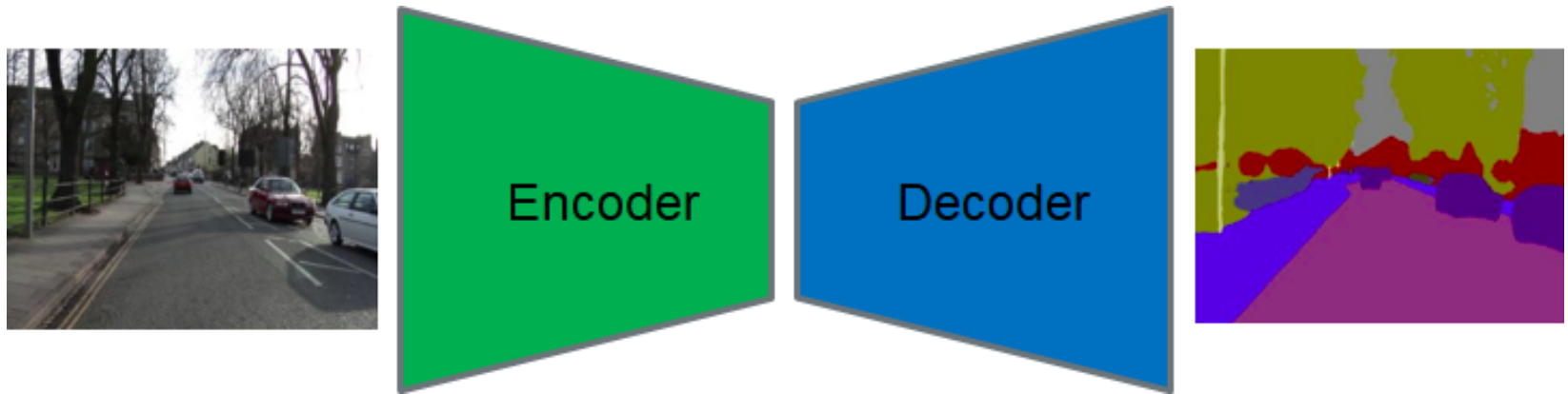


# Training Data Samples



# MIDCURVE BY NEURAL NETWORK

# Simple Encoder Decoder



# Keras Implementation

```
input_img = Input(shape=(input_dim,))

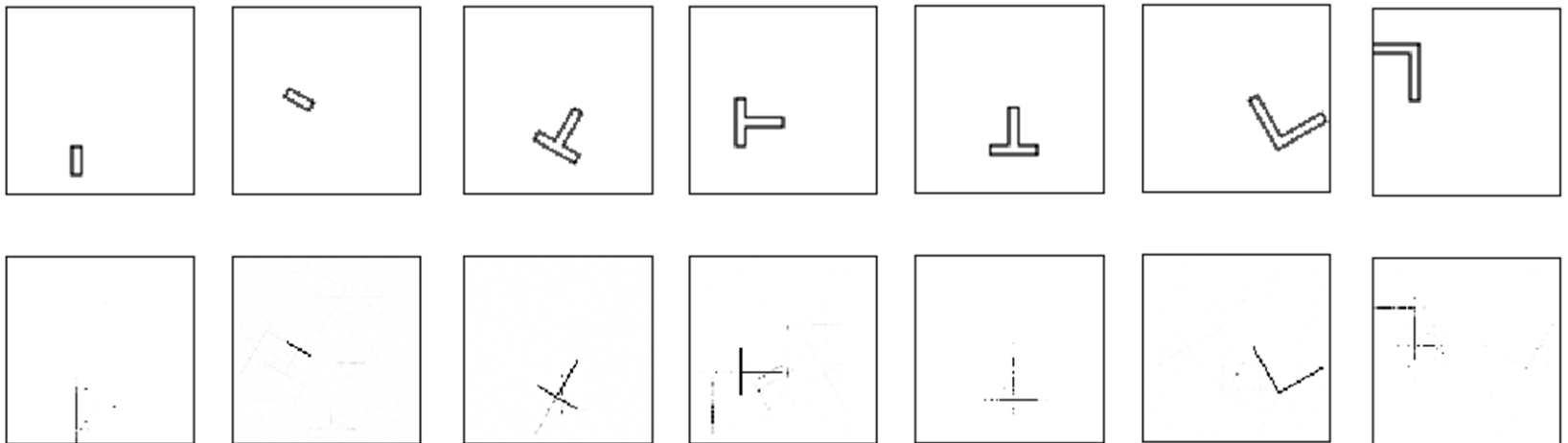
encoded = Dense(encoding_dim,
activation='relu',activity_regularizer=regularizers.l1(10e-5))(input_img)
decoded = Dense(input_dim, activation='sigmoid')(encoded)

autoencoder = Model(input_img, decoded)

encoder = Model(input_img, encoded)
encoded_input = Input(shape=(encoding_dim,))
decoder_layer = autoencoder.layers[-1]
decoder = Model(encoded_input, decoder_layer(encoded_input))

autoencoder.compile(optimizer='adadelta', loss='binary_crossentropy')
```

# Results



# Results

- Not very perfect but encouraging
- NN is correct with
  - The location (bounding box)
  - Dimension Reduction is seen
- But, still some stray points and misses

# What can be done?

- For the noise, use bounding boxes
- Feedback into error term: differencing with the known output expected
- Classify single pixel image as the skeleton, and rest as noise.

# What Next?

- Add denoiser network after the current one
- More Network Architectures
- Sequence-to-Sequence based approaches, taking closed thin polygon as input and polyline as output
- Extending to 3D, ie Midsurface



Thank you

*yogeshkulkarni@yahoo.com*