Curtin University - Department of Computing

Operarting Systems Assignment Cover Sheet

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Unit name:	Operating Systems	Unit ID:	COMP2006
Lecturer / unit coordinator:	Sie Teng Soh	Tutor:	Friday 8-9am
Date of submission:	18/05/2020	Which assignment?	(Leave blank if the unit has only one assignment.)

I declare that:

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- The work I am submitting is *entirely my own*, except where clearly indicated otherwise and correctly referenced.
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- It is my responsibility to ensure that my submission is complete, correct and not corrupted.

Date of Signature: K.Prassana signature: 18/05/2020

(By submitting this form, you indicate that you agree with all the above text.)

```
Software Solution lift.h
```

```
typedef struct
  int start;
  int dest;
}Lift;
lift sim A.c
#include <pthread.h>
#include <stdlib.h>
#include <unistd.h>
#include <stdio.h>
#include "lift.h"
pthread_mutex_t mutex;
pthread_cond_t prod = PTHREAD_COND_INITIALIZER;
pthread_cond_t cons = PTHREAD_COND_INITIALIZER;
int num = 0;/*number of elements in buffer*/
int add = 0;/*the next index to add to*/
int rem = 0;/*index that has been used*/
Lift *buffer;/*Array of Lifts*/
int bufSize;/*size of Lift array called buffer*/
FILE *f = NULL;/*input file -- sim_input*/
FILE *output = NULL;/*output file -- sim_output*/
int previousFloor = 1;/*Previous Floor*/
int requestsServed = 0;/*number of requests served*/
int requestNo = 0;/*number of requests put into the buffer*/
/*Consumer thread Lift-x*/
void* lift(void * arg)
  int* buffSize = (void*)arg;
  int bufferSize = abs(*buffSize);
  int movement;/*previous position*/
  output = fopen("sim_output.txt", "w+");
  while(1)
     pthread_mutex_lock(&mutex);
    while(num == 0)
       pthread_cond_wait(&cons, &mutex);
    fprintf(output,"\n%s %d" , "Previous Position: Floor ", previousFloor);
```

```
fprintf(output,"\n%s", "Detail Operations:");
     fprintf(output, "\n%s %d %s %d", " Go from Floor ", previousFloor, " to Floor ",
     buffer[rem].start);
     fprintf(output, "\n%s %d %s %d", " Go from Floor ", buffer[rem].start, " to Floor ",
     buffer[rem].dest);
     if((previousFloor > buffer[rem].start)&&(buffer[rem].dest > buffer[rem].start))
       movement = (previousFloor - buffer[rem].start) + (buffer[rem].dest - buffer[rem].start);
     else if((previousFloor > buffer[rem].start)&&(buffer[rem].start > buffer[rem].dest))
       movement = (previousFloor - buffer[rem].start) + (buffer[rem].start - buffer[rem].dest);
     else if((previousFloor < buffer[rem].start)&&(buffer[rem].dest > buffer[rem].start))
       movement = (buffer[rem].start - previousFloor) + (buffer[rem].dest - buffer[rem].start);
     }
     else
       movement = (buffer[rem].start - previousFloor) + (buffer[rem].start - buffer[rem].dest);
     }
     requestsServed++;
     fprintf(output, "\n%s %d", " #movement for this request: ", movement);
     fprintf(output, "\n%s %d", " #request: ", requestsServed);
     previousFloor = buffer[rem].dest;
     fprintf(output, "\n%s %d", "Current position: Floor ", previousFloor);
     rem = (rem + 1) % bufferSize;
     num--;
     pthread_mutex_unlock(&mutex);
     pthread_cond_signal(&prod);
  }
  return NULL;
}
/*Producer thread Lift-R*/
void* request(void * arg)
  int *buffSize = (void*)arg;
  int bufferSize = abs(*buffSize);
  int ii;
  int start, dest;
  f = fopen("sim_input.txt", "r");
  output = fopen("sim_output.txt", "w+");
```

fprintf(output, "\n%s %d %s %d ", "Floor ", buffer[rem].start, " to Floor ", buffer[rem].dest);

```
buffer = (Lift*)malloc(bufferSize*sizeof(Lift));/*Array of lifts*/
  for(ii=1; ii < =50; ii++)
     pthread_mutex_lock(&mutex);
     while(num == bufferSize)
        pthread_cond_wait(&prod, &mutex);
     }
     fscanf(f, "\n%d %d", &start, &dest);/*put the number of the starting floor and destination
     floor into variables "start and dest"*/
     (buffer[add].start) = start;
     (buffer[add].dest) = dest;
     add = (add+1) % bufferSize;
     num++;
     fprintf(output, "\n%s %d %s %d", "New Lift Request from Floor ", buffer[add].start, " to ",
     buffer[add].dest);
     requestNo++;
     fprintf(output, "\n%s %d", "Request No: ", requestNo);
     pthread_mutex_unlock(&mutex);
     pthread_cond_signal(&cons);
  }
  pthread_mutex_unlock(&mutex);
  return NULL;
}
int main(int argc, char *argv[])
  int i;
  pthread_t tid;
  pthread_create(&tid, NULL, lift, &argv[1]);
  for(i=1; i<=3; i++)
     pthread_create(&tid, NULL, request, &argv[1]);
  }
  pthread_join(tid, NULL);
  fclose(f);
  fclose(output);
  free(buffer);
  return 0;
}
```

README File

In order to compile, type "make" to compile the program using the makefile This will create an executable file called "program"

In order to run this program type: ./program m m is whatever number you want the buffer size to be. I was unable to implement t, the time taken for each request.

Although a segmentation fault occurs, the program still partially works. If you get an abort message, simply run the program again.

Mutual Exclusion

The main problem in this program is the bounded buffer producer consumer problem. There are four threads, in total, accessing the shared buffer and as such there will be multi thread synchronization problems.

Without proper synchronization, the errors that may occur are, a producer doesn't block when a buffer is full, a consumer consumes an empty slot in the buffer, two producers write to the same slot and two consumers read the same slot. In order to implement the bounded buffer, a finite size array in memory is shared by the producer and consumer threads. Producer threads "produce" a value and places it in the buffer, consumer threads consume a value in the buffer by removing it. Information about the state of the buffer is also stored such as which slots in the buffer are free, which slot the next data item should be stored(this is the add global variable), which slots in the buffer are filled and from which slot should the next data item be read(this is the rem global variable).

In the producer thread pthread_cond_wait() forces the producer to wait, if the buffer is full, until there is an empty slot in the buffer. pthread_cond_signal() signals the consumer to begin it's function indicating that there is free space in the buffer. In the consumer pthread_cond_wait() forces the consumer to wait if there is no item in the buffer. If the buffer has items in it then it will enter it's critical section. After that it will signal the producer as there is once again free space in the buffer to produce an item. This way mutual exclusion is ensured.

Sample Input and Output

compiled using command "./program 1"

1 is the buffer size. I was unable to implement t, the time taken for each request.

sim input.txt

20.3

209

sim_output.txt

Current position: Floor 0 Previous Position: Floor 0

```
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 26
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 27
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 28
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 29
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 30
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
```

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0

```
#movement for this request: 0
  #request: 31
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 32
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 33
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 34
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 35
Current position: Floor 0
Previous Position: Floor 0
Floor 0 to Floor 0
Detail Operations:
  Go from Floor 0 to Floor 0
  Go from Floor 0 to Floor 0
  #movement for this request: 0
  #request: 36
Current position: Floor 0
New Lift Request from Floor 0 to 0
```

New Lift Request from Floor 0 to 0

Request No: 52

New Lift Request from Floor 0 to 0

Request No: 53

New Lift Request from Floor 0 to 0

Request No: 54

New Lift Request from Floor 0 to 0

Request No: 55

New Lift Request from Floor 0 to 0

Request No: 56

New Lift Request from Floor 0 to 0

Request No: 57

New Lift Request from Floor 0 to 0

Request No: 58

New Lift Request from Floor 0 to 0

Request No: 59

New Lift Request from Floor 0 to 0

Request No: 60

New Lift Request from Floor 0 to 0

Request No: 61

New Lift Request from Floor 0 to 0

Request No: 62

New Lift Request from Floor 0 to 0

Request No: 63

New Lift Request from Floor 0 to 0

Request No: 64

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 37

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 38

Current position: Floor 0

New Lift Request from Floor 0 to 0

Request No: 66

New Lift Request from Floor 0 to 0

Request No: 67

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 39

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 40

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 41

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0
Go from Floor 0 to Floor 0
#movement for this request: 0

#request: 42

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor $\,0\,$ to Floor $\,0\,$

#movement for this request: 0

#request: 44

Current position: Floor 0

Previous Position: Floor 0 Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 45

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 46

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 47

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 48

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 49

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 50

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 51

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 52

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 53

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

Previous Position: Floor 0 Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 55

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 56

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 57

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 58

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 D#request: 25ons:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 59

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 60

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 61

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 62

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 63

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 64

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 66

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 67

Current position: Floor 0

New Lift Request from Floor $\,0\,$ to $\,0\,$

Request No: 68

New Lift Request from Floor 0 to 0

Request No: 69

New Lift Request from Floor 0 to 0

Request No: 70

New Lift Request from Floor 0 to 0

Request No: 71

New Lift Request from Floor 0 to 0

Request No: 72

New Lift Request from Floor 0 to 0

Request No: 73

New Lift Request from Floor 0 to 0

Request No: 74

New Lift Request from Floor 0 to 0

Request No: 75

New Lift Request from Floor 0 to 0

Request No: 76

New Lift Request from Floor 0 to 0

Request No: 77

New Lift Request from Floor 0 to 0

Request No: 78

New Lift Request from Floor 0 to 0

Request No: 79

New Lift Request from Floor 0 to 0

Request No: 80

New Lift Request from Floor 0 to 0

Request No: 82

New Lift Request from Floor 0 to 0

Request No: 83

New Lift Request from Floor 0 to 0

Request No: 84

New Lift Request from Floor 0 to 0

Request No: 85

New Lift Request from Floor 0 to 0

Request No: 86

New Lift Request from Floor 0 to 0

Request No: 87

New Lift Request from Floor 0 to 0

Request No: 88

New Lift Request from Floor 0 to 0

Request No: 89

New Lift Request from Floor 0 to 0

Request No: 90

New Lift Request from Floor 0 to 0

Request No: 91

New Lift Request from Floor 0 to 0

Request No: 92

New Lift Request from Floor 0 to 0

Request No: 93

New Lift Request from Floor 0 to 0

Request No: 94

New Lift Request from Floor 0 to 0

Request No: 95

New Lift Request from Floor 0 to 0

Request No: 96

New Lift Request from Floor 0 to 0

Request No: 97

New Lift Request from Floor 0 to 0

Request No: 98

New Lift Request from Floor 0 to 0

Request No: 99

New Lift Request from Floor 0 to 0

Request No: 100

New Lift Request from Floor 0 to 0

Request No: 101

New Lift Request from Floor 0 to 0

Request No: 102

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 68

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 69

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 70

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 71

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 72

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 73

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 74

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 75

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 76

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 77

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

Previous Position: Floor 0

Floor 0 to Floor 0 **Detail Operations:**

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 79

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 80

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 81

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 82

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 83

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 84

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 85

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 86

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 87

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 88

#Tequest. od

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

Previous Position: Floor 0 Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 90

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 91

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 92

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 93

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 94

Current position: Floor 0 Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 95

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 96

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 97

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 98

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 99

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 101

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 102

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 103

Current position: Floor 0

New Lift Request from Floor 0 to 0

Request No: 104

New Lift Request from Floor 0 to 0

Request No: 105

New Lift Request from Floor 0 to 0

Request No: 106

New Lift Request from Floor 0 to 0

Request No: 107

New Lift Request from Floor 0 to 0

Request No: 108

New Lift Request from Floor 0 to 0

Request No: 109

New Lift Request from Floor 0 to 0

Request No: 110

New Lift Request from Floor 0 to 0

Request No: 111

New Lift Request from Floor 0 to 0

Request No: 112

New Lift Request from Floor 0 to 0

Request No: 114

New Lift Request from Floor 0 to 0

Request No: 115

New Lift Request from Floor 0 to 0

Request No: 116

New Lift Request from Floor 0 to 0

Request No: 117

New Lift Request from Floor 0 to 0

Request No: 118

New Lift Request from Floor 0 to 0

Request No: 119

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 104

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 105

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 106

Current position: Floor 0

Previous Position: Floor 0

Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

Previous Position: Floor 0 Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0 #movement for this request: 0

#request: 108

Current position: Floor 0

New Lift Request from Floor 0 to 0

Request No: 120

New Lift Request from Floor 0 to 0

Request No: 121

New Lift Request from Floor 0 to 0

Request No: 122

New Lift Request from Floor 0 to 0

Request No: 123

New Lift Request from Floor 0 to 0

Request No: 124

New Lift Request from Floor 0 to 0

Request No: 125

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0 Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 109

Current position: Floor 0

New Lift Request from Floor 0 to 0

Request No: 126

New Lift Request from Floor 0 to 0

Request No: 127

New Lift Request from Floor 0 to 0

Request No: 128

New Lift Request from Floor 0 to 0

Request No: 129

New Lift Request from Floor 0 to 0

Request No: 130

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 110

Current position: Floor 0

New Lift Request from Floor 0 to 0

Request No: 131

New Lift Request from Floor 0 to 0

Request No: 132

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor $\,0\,$ to Floor $\,0\,$

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 111

Current position: Floor 0

Previous Position: Floor 0 Floor 0 to Floor 0

Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 112

Current position: Floor 0

New Lift Request from Floor 0 to 0

Request No: 133

New Lift Request from Floor 0 to 0

Request No: 134

New Lift Request from Floor 0 to 0

Request No: 135

New Lift Request from Floor 0 to 0

Request No: 136

Previous Position: Floor 0

Floor 0 to Floor 0 Detail Operations:

Go from Floor 0 to Floor 0

Go from Floor 0 to Floor 0

#movement for this request: 0

#request: 113

Current position: Floor 0

New Lift Request from Floor 0 to 0

Request No: 137

There is a bug that causes the floor numbers to not show. This is most likely due to an issue with the incrementation of the add and rem indexes. However despite this error, the number of lines outputted seems to correspond with the input and buffer size.

The scenarios that this program would not be able to handle would be if the buffer size was greater than 100.