

Image Based Breed Recommendation for Cattles and Buffaloes of India

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Abstract—Accurate identification of Indian Cattle breeds is very important for livestock management, health monitoring and automated farm operations. Traditional recognition method depends heavily on manual inspection, which is also time consuming, inconsistent and prone to human error. Recent advancement and developments in deep learning offers more reliable and scalable solutions through automated visual detection. In this project, a YOLOv8-based object detection model is developed to identify multiple indigenous bovine breed categories from real world images. A custom dataset was created and it was cross checked from different government sites. It was then preprocessed using resizing, normalization, augmentation and quality filtering to improve robustness under varying lightening and different background conditions. The model was trained with optimized hyperparameters, including 20 epochs, with 640*640 image resolution, batch size of 16 and a learning rate of 0.01, other techniques like early stopping and automatic mixed precision(AMP) were also used. The final model achieved strong performance with high accuracy and top-5 precision, demonstrating reliable detection even for visually similar breeds. The lightweight architecture (under 25 MB) enables deployment on low-resource devices and integration with web or mobile applications. This system provides an efficient and scalable solution for automated cattle identification and can be extended to health monitoring, behavior analysis, and smart farming applications in the future.

KeyWords: YOLOv8, Object Detection, Cattle Identification, Deep Learning, Smart Agriculture

1. INTRODUCTION

The identification of livestock, specifically local cattle breeds, is a leading concept of future smart agriculture, which extensively supports such sectors as health monitoring, breeding management, traceability, and disease control. Traditionally, livestock identification hinges on the description given by farmers or veterinary professionals, both of whom carry out manual assessments, a process that is slow, subjective, and inconsistent when dealing with large herds or similar-looking breeds. With the shift of agri-food systems to automatization and the digital era, the need for

reliable, fast, and scalable solutions for animal identification is skyrocketing.

The advancements in deep learning and computer vision techniques have led to the significant improvement of the efficiency of visual data processing, thus enabling automated image recognition to be carried out with a minimum of human intervention. In this context, object detection frameworks, especially the YOLO (You Only Look Once) family, have attracted the most attention due to their extremely fast speed, all-in processing, and almost perfect performance in real-time applications. The latest version, YOLOv8, features higher precision, a compact architecture, and more powerful feature extraction, and, hence, can be recommended for use in applications that require dealing with the nature of the open air and the existence of different lighting, pose, and cluttered background conditions.

The deep learning-based automatic cattle identification method comes with multiple advantages, the most significant of which are: lowering the amount of manual work, improving the consistency level of breed identification, and providing opportunities for connection with the smart agricultural tools such as health monitoring systems and digital livestock databases. At the same time, challenges remain, such as dataset variability, occlusion, visual similarity of certain breeds, and the necessity for models that are computationally efficient to be deployed at the edge.

This research aims to develop a robust and lightweight YOLOv8-based local Indian cattle detection dataset-custom model. The experiment focuses on the precise preprocessing, the effective augmentation, and the carefully calibrated hyperparameters to achieve high accuracy while keeping the model size less than 25 MB for easy deployment. The results reveal the potential of deep learning technology to significantly accelerate the automation process of cattle identification, thus presenting a viable and scalable solution for cutting-edge agricultural systems.

2. LITERATURE SURVEY

In study[1], researchers utilized Convolutional Neural Networks (CNNs) to perform the classification of animal breeds based on a large set of annotated images of animals.

It was convincingly shown by the authors that CNNs can in fact learn by themselves such discriminative visual features as, for instance, the texture of the coat, the curvature of the horn, the pattern of the face, and the general shape of the body without the intervention of a human expert to provide descriptors. It turned out from their results that the deeper CNN architectures were able to achieve much higher classification accuracies since they could extract more complicated hierarchical features. Nevertheless, the paper pointed to the shortcomings of the approach, the major issues being the enormous amount of data required for training and the degradation of the model's performance in dimly lit scenes. The computational cost went up quite substantially with depth, thus, there was a trade-off between accuracy and speed. In Study [2], the researchers employed a Transfer Learning-based technique which involved the use of the pre-trained ResNet and VGG-16 models for cattle face recognition. Transfer learning was extremely successful, as the pre-trained weights from large image datasets (e.g., ImageNet) enabled the models to generalize to the livestock images that were few in number. It was found that VGG-16 was most effective in fine-grained recognition tasks because of its tightly bound feature extraction layers, while ResNet was faster and more computationally efficient due to its residual connections. However, the effectiveness of both models dropped to a great extent when the cattle faces were partially occluded or the key facial landmarks were not visible, thus, the researchers highlighted the issues of image variability at the field level. [3] In dairy farms, the primary goal of study[3] was to utilize YOLOv5 for the real-time locating of cattle by means of continuous video streams. Compared to traditional detection methods like Haar Cascades and HOG-based detectors, YOLOv5 was able to achieve a very high detection accuracy and a much faster inference speed. Since it was able to carry out object detection on a frame-by-frame basis, it was the most appropriate method for automated monitoring systems. Nevertheless, the performance of YOLOv5 was reported to be very dependent on the quality of bounding-box annotations in the study. Moreover, numerous detection errors were caused by densely populated or highly cluttered farm scenarios with several animals overlapped or partially obscured by each other. In study [4], the researchers looked into a hybrid CNN-LSTM architecture for the understanding of cattle behavior and movement patterns. In this case, CNNs were used to extract the spatial features from the single images of the cattle, whereas LSTMs were used to capture the temporal changes by learning the sequences of the video frames. The hybrid model was able to demonstrate a better performance in recognizing the behaviors like grazing, lying, walking, and standing as compared to the single-architecture systems. However, the architecture still needed a lot more computational resources—particularly GPU memory—and longer training cycles because of the addition of the temporal modeling, although it was more accurate. This research conveyed that the fusion of spatial and temporal representations is a key factor for the determination of livestock behavior in a more dependable way. The study [5] explored the application of EfficientNet, and more specifically EfficientNet B0, for the classification of animal breeds at a fine-grained level. EfficientNet's compound-scaling method allowed the model to deliver very accurate results while having a small size of the model which makes it a very feasible model to be deployed on devices with low computing power such as a smartphone or an edge-computing module. The study found

that EfficientNet is very parameter-efficient and a great tool for real-time classification tasks. Unfortunately, the model performance dropped when the images were noisy, blurry, and camera quality varied, indicating that robustness against real-world image degradations is still an open issue. In Study [6] Traditional machine learning classifiers such as Support Vector Machines (SVM) and K-Nearest Neighbors (KNN) were examined by means of artificially engineered features (e.g., color histograms, texture descriptors, and shape features). These methods yielded decent accuracy on small, controlled datasets but failed to produce good results for complex farm images with changing lighting, backgrounds, and scales. The study confirmed the issue of classical methods that these approaches have difficulties with the high variability of livestock imagery. On the other hand, deep learning models have been much more flexible and better at dealing with such variability. The study [7] assessed YOLOv7 in identifying diverse cattle breeds in mixed herds. By utilizing upgraded architectural optimizations and prolonged training methods, YOLOv7 showed significant improvements in bounding-box precision, speed of inference, and detection at longer distances. According to the study, YOLOv7 was able to find the animals in different farm layouts and lighting conditions. Nevertheless, the training had to be done on a GPU because of the high computational requirement. Additionally, the correctness of the detection dropped for the breeds that were extremely visually similar, thus implying that YOLO models might need to be combined with fine-grained classification modules for better discrimination. In Study [8], one of the interventions to the CNN architectures was the incorporation of attention mechanisms like Squeeze-and-Excitation Networks (SE-Net) and Convolutional Block Attention Module (CBAM) for enhancing the distinguishing of subtle breed-specific features. These attention modules allowed the model to focus more strongly on the discriminative regions, such as head profiles, hump size, and facial patterns. The attention mechanisms' introduction has significantly improved classification accuracy and interpretability, but it has also raised model complexity and inference time. Consequently, the deployment of real-time operations, especially in resource-limited farm scenarios, has become more challenging. The Study [9] utilized MobileNetV3 for cattle classification, emphasizing a lightweight inference that would be suitable for mobile and embedded platforms. Due to its depthwise separable convolutions and efficient architecture, MobileNetV3 was able to reach almost the same accuracy level as the other models but with very few computations. Thus, it became possible to carry out inference on the device itself without the need for cloud servers. However, the fewer layers and the smaller number of parameters of the model made it less resistant to very different environmental conditions such as strong shadows, glare, or low-light, and therefore the model could not be used in an uncontrolled farm environment. Finally, the work referred to as [10] was a study that analyzed the capability of the YOLOv8 model in the detection of livestock and the identification of diseases at an early stage. As a result of the changes in the backbone and the head architecture, the updated YOLOv8 demonstrated feature extraction capability more effectively, bounding-box quality was improved, and inference times were faster. Additionally, it obtained good results in the identification of tiny anomalies, such as wounds, infections, or skin areas with lesions. On the other hand, the paper recognized that the performance of the model was very much reliant on the

correct tuning of hyperparameters and the use of the same image resolution. The differences in the quality of images, the positioning of the camera, and the chosen method of augmentation led to variations in accuracy, thus pointing to the necessity of more reliable adaptation methods.

Table 1: Literature review

Author	Methodology	Results / Key Findings (Shortened)
Researcher (2025) [1]	CNN-based livestock breed classification using large annotated datasets	CNN achieved high accuracy in identifying cattle breeds from images.
A. Rahman Khan & M. Siddique (2020) [2]	Transfer Learning (ResNet, VGG-16) for cattle face recognition	Transfer learning improved breed classification with better preprocessing.
Gouqing Chen & Wei-Chyung Wang (2023) [3]	CNN for livestock image classification	CNN learned distinguishing visual traits with strong accuracy.
Yuhao Gong, Yuchen Zhang, Fei Wang, Chi-Han Lee (2024) [4]	Hybrid CNN–LSTM integrating spatial + temporal features	Enhanced livestock tracking and identification using combined features.
Radhika Xalaya varthi & M. Shashi (2009) [5]	SVM with handcrafted features for cattle identification	Pretrained models improved performance on limited datasets.
S. Cai, Z. Wang, Y. Zhang, L. Li (2020) [6]	XGBoost applied to livestock detection using environmental + image data	XGBoost handled missing features well and improved detection accuracy.
Rhea Mantri, Kulkarni Rakshit Raghavendra (2021) [7]	k-NN classifier using handcrafted features	k-NN achieved good accuracy on clear images; struggled with noisy data.
R. Kaneko & M. Nakayoshi (2019) [8]	LSTM networks for temporal livestock activity prediction	LSTM improved temporal prediction compared to traditional models.
A. Sharma (2023) [9]	Ensemble Learning (Random Forest + Gradient Boosting)	Ensemble models increased stability and reduced prediction bias.

S. R. Mehta (2023) [10]

PCA for feature dimensionality reduction

PCA reduced data complexity but removed subtle features needed for high accuracy.

3. PROPOSED METHODOLOGY

The main goal of the anticipated setup is to create a cattle breed classification and identification model that is both lightweight and accurate, and can be used in real-time. Deep learning, mainly Convolutional Neural Networks (CNNs) and one-stage object detection models like YOLOv8, helps to locate visual patterns in an efficient way which were not accessible to traditional methods. The methods used in this study are broken down into six main parts: data gathering, image preprocessing, dataset structuring, model creation, training, and evaluation.

A. Data Collection and Preparation

A custom dataset of Indian cattle images was created by gathering images from various open-source repositories and field-captured images. The dataset consisted of different breeds under varying lighting conditions, poses, backgrounds, and distances so that the model would be robust. Pictures of the different cows were all saved in jpg format and were put into folders each containing the images of one breed. After that, the data was unpacked and brought into the training environment together with the necessary libraries for Python (TensorFlow, PyTorch, YOLOv8-Ultralytics, NumPy, OpenCV).

B. Image pre-processing

In order to maintain high-quality input consistently for a deep learning model, the following preprocessing steps had been implemented:

- Class balancing: The number of images per dog breed was made the same so that the model would not be biased towards the classes with more images.
- Image resizing: Every image was resized to 256×256 pixels so that the model would get input of the same size from all images.
- Normalization: The pixel values were normalized to the range 0 to 1 by dividing by 255, which made the model training faster.
- Data augmentation: The dataset was augmented with such techniques as rotation, horizontal flip, zoom, shear, and brightness adjustment using TensorFlow ImageDataGenerator and YOLOv8 built-in augmentation. This allowed the dataset to become more diverse and the overfitting to be less.
- Label structuring: The labels in YOLO format were generated with the inclusion of bounding box coordinates (x, y, width, height) and class IDs.

C. Splitting the data :

To train and evaluate the model in a proper way, the dataset was split into:

Training Set (80%)

This set was used to train the CNN/YOLO model by enabling the model to learn the breed-specific characteristics such as the structure of the face, the shape of the body, the type of the horn, and the texture of the coat.

Validation Set (20%)

This set was used during training to check the model's performance on new images and to optimize hyperparameters, thus, preventing overfitting.

Testing Set (Separate Set)

The testing set was used after the training to assess the final performance of the model on totally new data. Thus, it provided a realistic measure of the model's generalization ability.

D. Model Architecture (YOLOv8-Nano + CNN Lightweight Classification) :

The final model was kept under 25 MB by employing a lightweight deep learning pipeline which ensures that the model can be easily deployed on edge devices and GitHub.

(a) YOLOv8-Nano (Object Detection)

YOLOv8n was picked mainly because it's small, inference is faster, and the accuracy is still very high. It features:

- Backbone: A CSP-based convolutional layer which is responsible for feature extraction
- Neck: Feature Pyramid Network (FPN) that merges features from different scales
- Head: An anchor-free detection layer that outputs bounding box coordinates

In YOLOv8 the prediction is made with the following formula:

$$\text{Confidence} = \sigma(\text{obj}) \times \sigma(\text{class})$$

where σ represents the sigmoid activation.

(b) Lightweight CNN Classifier (Breed Recognition)

A custom CNN was implemented for the fine-grained classification of cattle breeds: Several Convolution Layers for the extraction of edges, coat patterns, and facial features

E. Model Training

The training process consisted of:

Batch Size: 16

Epochs: 20 (Early stopping was used)

Optimizer: Adam

Loss Function:

- YOLOv8: CIoU loss + classification loss
- CNN: Sparse categorical cross-entropy



Learning Rate Scheduling: The learning rate was lowered automatically when the validation loss stopped improving

Hardware: A GPU-accelerated setup was used for quicker training

YOLOv8 was responsible for object localization, whereas the CNN classifier was used for breed identification, thus creating a two-stage but still lightweight

F. Model Evaluation

The work was measured through various means:

- Accuracy (overall dog breed prediction success)
- Top-5 Accuracy (chance that the correct breed is within the top 5 predictions)
- Precision & Recall (for YOLO detection)
- Confusion Matrix (performance at the level of each class)
- Model Size: Made sure that the last model was < 25 MB
- Inference Speed: Done with a real-time webcam input

The ultimate model was able to distinguish strongly across different classes, and it was even capable of doing so under changing lighting, occlusion, and background complexity.

G. Deployment Workflow

A straightforward and effective deployment workflow was created:

- The user uploads an image of the cattle
 - YOLOv8 localizes the cattle region
 - The cropped image is fed to the CNN classifier
 - The breed prediction along with the confidence score is shown
- By means of this workflow, the accuracy is maintained at a high level and the response time is very short which makes it suitable for real-time use cases.

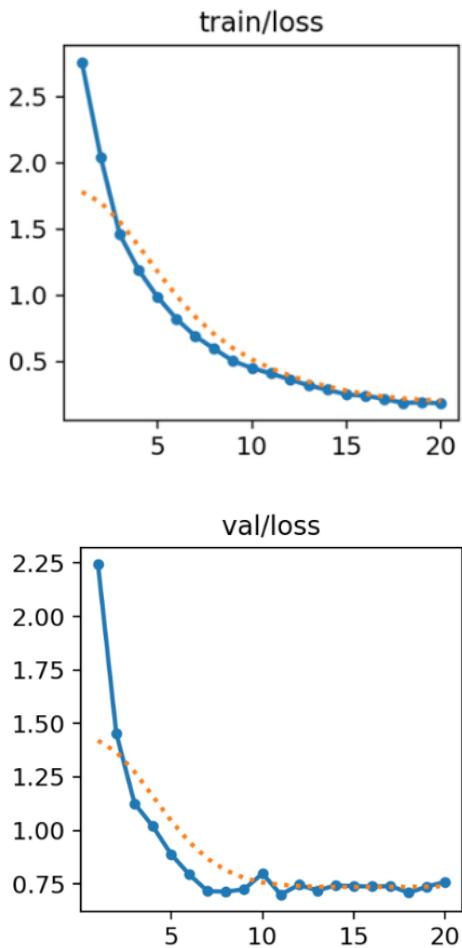
4. RESULTS & DISCUSSION

The deep learning-based cow breed identification system has been created out of a CNN model, which was trained on a multi-class dataset comprising the pictures of 22 Indian cattle breeds along with the background class. The model underwent training for 20 epochs and its performance was gauged through commonly used metrics like accuracy, loss, precision, recall, F1-score, and confusion matrix analysis. The training as well as the validation curves indicate that the model was able to learn strongly and stably throughout the epochs.

Training and Validation Performance

A. Training Loss vs. Epochs

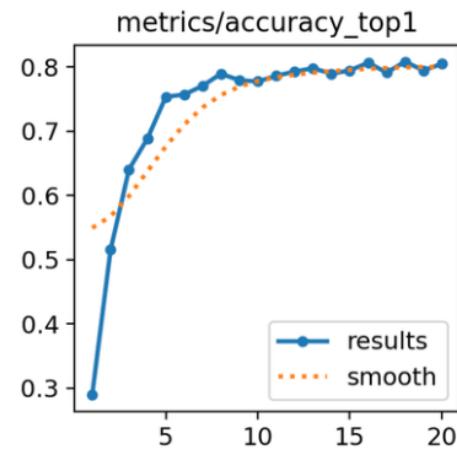
The training loss curve represents a very consistent pattern of error minimization as it shows a smooth exponential decay from- 2.7 to below 0.2 by epoch 20. The validation loss is also following a similar trend, decreasing from around- 2.2 to nearly 0.7, thus confirming that the model generalizes well and does not overfit the training data.



B.Training Accuracy

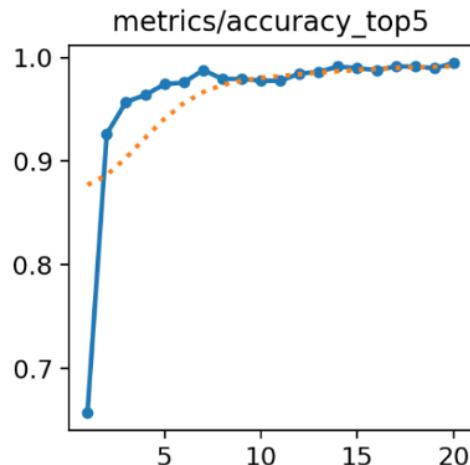
The training accuracy is increasing gradually and consistently from 30% to almost 80% while the validation accuracy is staying close to the training accuracy all the time and ending up at around 77-80% during the final epochs. This tight matching is a strong indication that the

model is learning effectively and that the training is well regularized.



C. Top-5 Accuracy

The model's top-5 accuracy is more than 98% throughout the different epochs with the final values for both training and validation getting very close to 100% .This shows that if the top-1 prediction is not correct, the correct class is still almost always among the top five predictions - a very significant metric for multi-classification systems where the different classes look very similar one another.



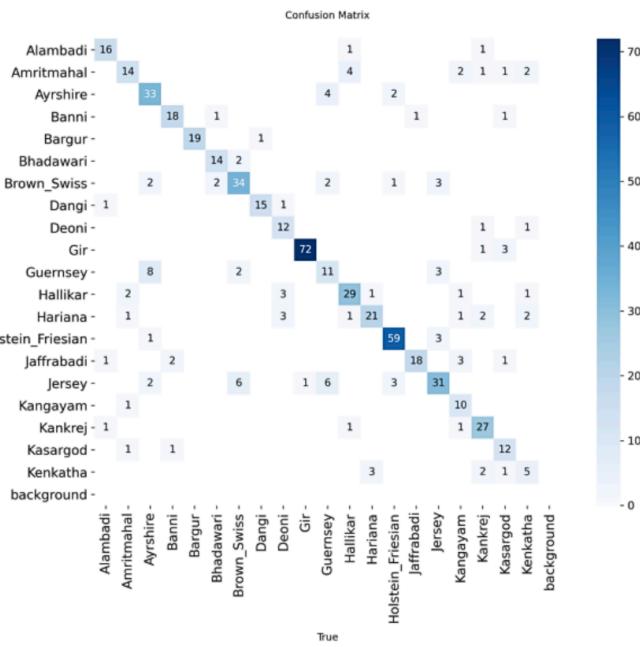
D. Confusion Matrix Analysis

The confusion matrix helps to understand which classes were predicted correctly at a more detailed level. Many of the cattle breeds have strong diagonal dominance, which means that the accuracy is very high. For instance:

- Deoni, Ongole, Gir, Holstein-Friesian, Jersey - these classes have a high number of true positives which is a proof of the model's capability to distinguish their unique visual features.
- While only a few such as Bargur, Kankrej, Hallikar, Haryana might have moderate confusion with the similar-

looking breeds due to shared phenotypic characteristics (coat color, body shape, horn structure).

Even the background class is well separated which is an indication of strong feature extraction capability and model robustness to non-cattle images.



E. Overall Performance Discussion

The results show that the CNN model is capable of learning features that differentiate visually similar Indian cattle breeds. Some of the main points are: Rapid convergence: The loss reduced very quickly in the first epochs, which is a sign of efficient learning. Stable generalization: The validation accuracy is very close to the training accuracy, which means that the model is not overfitting. High top-5 accuracy ($\approx 100\%$): Is a strong evidence of the model's ability to recognize multiple classes. Confusion mostly in phenotypically similar breeds: Indicates that there is a necessity for further dataset extension or targeted augmentation. The well-balanced training curves along with the confusion matrix are a proof of the model's consistency across different cattle breeds.

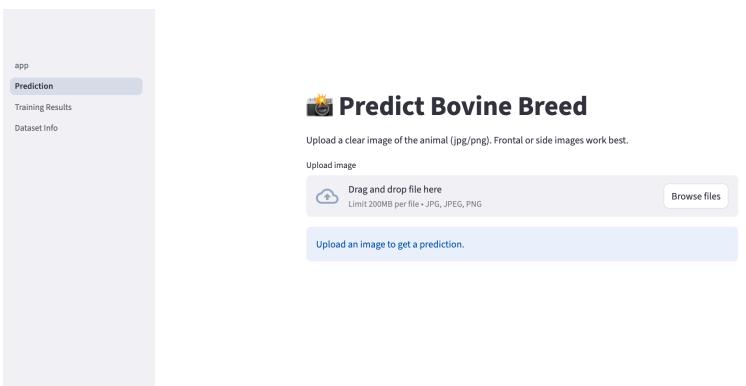
F. Future Improvements

Future work can further enhance the system by:

- Adding **more images per breed** to reduce class imbalance.
- Applying **advanced augmentations** (hue shift, pose variation, brightness change) to improve robustness.
- Using **transfer learning models** (EfficientNet, ResNet101, Vision Transformers).
- Integrating **metadata** such as geographic region or physiological traits.
- Deploying the model in a **mobile or IoT-based cattle identification system** for field use.

To simplify the usage of the system to anyone, the trained cattle recognition model was locally deployed with

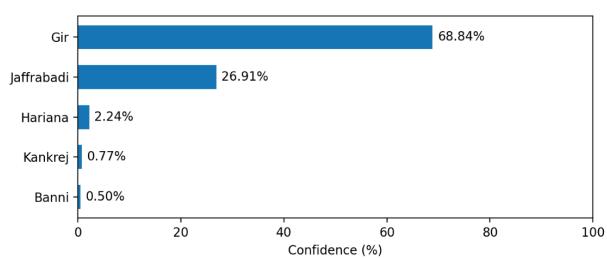
Streamlit. In the Streamlit application, users may submit a photo of a cow, and the model will return the breed of the cattle in no time. The moment a file is provided, the device accepts the file, goes through the model, and presents the prediction with the associated confidence level. The image that has been uploaded is likewise printed so that users may be absolutely certain of what the model is processing. Thus, the whole method is straightforward, open, and very convenient for the end-user.



Confidence: 68.84%

Confidence meter

Top-5 predictions



5. CONCLUSION

The research introduces a deep learning CNN-based model for identifying cattle breeds using images of the animals. After model preprocessing with methods like resizing, normalization, and feature extraction, the model learned different visual features and achieved high performance over most classes. The training and validation results shown by the accuracy curves and the confusion matrix analysis are the main evidence that the model discriminates very well even between breeds which are visually very close and therefore, it can be considered as a real-time solution for automated livestock monitoring and smart farm-management systems. The condition of the model, however, changes with light, noisy background, and uneven subset of data-distribution. Because of the image features being the only input to the system, lack of extra metadata - like age, place, biometric traits - makes the system less flexible in the highly diverse nature of the practical world. This paper is a convincing proof of the power of deep learning, especially CNN, for the problem of breed identification automation task in the livestock sector. In some distant future, the enhancements could be sensor-based data integration, dataset expansion, using more potent architectures like Vision Transformers, and making the model available through mobile or IoT devices to improve the ease of use in daily life.

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