# MATH 231: Numerical ODEs

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# Question 1: Eigenvalues of special tridiagonal matrices

This question is about finding eigenvalues of tridiagonal linear systems arising from applications, specifically finding the eigenvalues of an  $n \times n$  matrix of the form,

$$A = \left(\begin{array}{cccc} a & b & & \\ c & a & b & & \\ & \ddots & \ddots & \ddots & \\ & & c & a & b \\ & & c & a \end{array}\right)$$

where a, b, c are real numbers with bc > 0 (i.e. b and c have the same signs).

(a) Show that the eigenvalue problem of A is equivalent to the equations

$$cv_{j-1} + (a - \lambda)v_j + bv_{j+1} = 0, \quad j = 1, \dots, n$$
  
 $v_0 = 0 = v_{n+1}$ 

where  $\mathbf{v} = (v_1, \dots, v_n)^T$  is an eigenvector of A associated with the eigenvalue  $\lambda$ .

(b) The recurrence relation (1) is a second order linear difference equation and can be solved similar to second order linear differential equations. By guessing  $v_j = r^j$  for some constant r, show that r satisfies

$$r_{\pm} = \frac{\lambda - a \pm \sqrt{(\lambda - a)^2 - 4bc}}{2b}$$
, with  $r_{+}r_{-} = \frac{c}{b}$ 

(c) Show by contradiction that  $r_{+}$  must be distinct.

Hint: if  $r_{\pm} = r$  are repeated, then  $v_j = Ar^j + Bjr^j$  for some constants A, B.

(d) Since  $r_{\pm}$  are distinct, the general solution for (1) is  $v_j = Ar_+^j + Br_-^j$  for constants A, B. Use this to conclude from (2) and (3) that,

$$\left(\frac{br_+^2}{c}\right)^{n+1} = 1$$

(e) From part (c), (3) and (4), show that  $r_{\pm}$  must be complex valued and conclude that (4) has the solutions for k = 1, ..., n,

$$r_{\pm,k} = \sqrt{\frac{c}{b}} \exp\left(\frac{\pm ik\pi}{n+1}\right), \quad \text{where } i = \sqrt{-1}$$

(f) Using part (e), conclude that the eigenvalues of A is given by

$$\lambda_k = a + 2\operatorname{sgn}(b)\sqrt{bc}\cos\left(\frac{\pi k}{n+1}\right), \quad k = 1, \dots, n$$

(g) Find the eigenvalues of the  $n \times n$  finite difference matrix  $A_h = \frac{1}{h^2}\begin{pmatrix} 2 & -1 & & & \\ -1 & 2 & \ddots & & \\ & \ddots & \ddots & & \\ & & -1 & 2 & -1 \\ & & & -1 & 2 \end{pmatrix}$ , where

$$h = \frac{1}{n+1}.$$

Conclude that  $A_h$  is symmetric positive definite and find its condition number  $\kappa(A_h)$  with respect to  $\|\cdot\|_2$ . Show that  $\kappa(A_h) = O(h^{-2})$  as number of grid points n increases. What does this mean for solving  $A_h x = b$  when n is large?

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#### Solution

(a) Let  $(\lambda, \vec{v})$  be an eigenpair of A

$$A\vec{v} = \lambda \vec{v}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$

$$\begin{pmatrix} (a - \lambda)v_1 + bv_2 \\ cv_1 + (a - \lambda)v_2 + bv_3 \\ \vdots \\ cv_{n-2} + (a - \lambda)v_{n-1} + b_n \\ c_{n-1} + (a - \lambda)v_n \end{pmatrix} = \vec{0}.$$

We can write the above relation as the following,

$$cv_{j-1} + (a - \lambda)v_j + bv_{j+1} = 0. (1)$$

☺

Where  $0 \le j \le n + 1$  and  $v_0 = 0 = v_{n+1}$ 

(b) Using the hint we guess the following form of the solution  $v_i = r^j$ . Substituting in 1,

$$cr^{j-1} + (a - \lambda) r^j + br^{j+1} = 0$$
  
 $c + (a - \lambda) r + br^2 = 0$ 

Using the quadratic formula, we get

$$r_{\pm} = \frac{\lambda - a \pm \sqrt{(a - \lambda)^2 - 4bc}}{2b}.$$

As  $r_{\pm}$  are the roots to a quadratic, hence

$$r_{+}r_{-} = \frac{c}{h} \tag{2}$$

(c) If 1 has a repeated root, say  $r_{\pm}=r$ , then solution to the recursion would look like,

$$v_j = Ar^j + Bjr^j.$$

Checking the boundary conditions,  $v_0 = 0 = v_{n+1}$ 

$$v_0 = Ar^0 + B(0)r^0 = A = 0. (3)$$

$$v_{n+1} = (0)r^{n+1} + B(n+1)r^{n+1} = B(n+1)r^{n+1} = 0 \implies B = 0.$$
(4)

Combining 3 & 4 gives,

$$v_i = 0$$
.

Which is the trivial eigenvector. Hence, we cannot have a repeated root if we want a non-zero eigenvector.

(d) From (c) we have that roots are distinct. Therefore, we look for solutions of the form  $v_j = Ar_+^j + Br_-^j$  for some constants A and B defined by the "boundary conditions" of the recursion. We have,

$$v_0 = A + B = 0 \implies A = -B$$

$$v_{n+1} = Ar_+^{n+1} + Br_-^{n+1} = 0 \implies r_+^{n+1} = r_-^{n+1}$$
(5)

From, 2 and 5, it follows that

$$(r_+^2)^{(n+1)} = \left(\frac{c}{b}\right)^{n+1}$$

$$\left(\frac{br_+^2}{c}\right)^{(n+1)} = 1$$
(6)

(e) We can observe in 6 that  $\frac{br_+^2}{c}$  are the roots of unity, therefore,

$$\frac{br_+^2}{c} = \exp\left(\frac{ik\pi}{n+1}\right) \implies r_+ = \sqrt{\frac{c}{b}} \exp\left(\frac{ik\pi}{n+1}\right) \quad k = 0, \dots, n+1.$$

Similarly,

$$\frac{br_-^2}{c} = \exp\left(\frac{im\pi}{n+1}\right) \implies r_- = \sqrt{\frac{c}{b}} \exp\left(\frac{im\pi}{n+1}\right) \quad m = 0, \dots, n+1.$$

Using 2,

$$r_+r_- = \frac{c}{b} \exp\left(\frac{i(k+m)\pi}{n+1}\right) = \frac{c}{b} \implies k = -m.$$

Therefore we have,

$$r_{\pm,k} = \sqrt{\frac{c}{b}} \exp\left(\frac{\pm ik\pi}{n+1}\right) \quad k = 1, \dots, n.$$

## Question 2: Classical iterative methods for strictly diagonally dominant matrices

- (a) Show that the diagonal part of any strictly diagonally dominant (S.D.D.) matrix is invertible.
- (b) Recall the Gershgorin's theorem below, which can give useful information about the eigenvalues of a matrix. The eigenvalues of a complex valued matrix A lies in the union of n discs  $\bigcup_{i=1}^{n} D_i$  on the complex plane, where

$$D_i = \left\{ z \in \mathbb{C} : |z - a_{ii}| \le \sum_{j \ne i} |a_{ij}| \right\}$$

Using Gershgorin's theorem, conclude S.D.D. matrices are invertible. Hint: Show that  $0 \notin D_i$  for all i = 1, ..., n.

The next two parts are about showing convergence of Jacobi and Gauss-Seidel iterations for S.D.D. matrices.

- (c) Recall the matrix  $-M^{-1}N$  associated with the Jacobi iteration takes the form  $-D^{-1}(L+U)$ , where A=L+D+U.
  - (i) Let A be S.D.D. and  $\lambda$  be any eigenvalue of  $-D^{-1}(L+U)$ . Show that  $\det(L+U+\lambda D)=0$  using part (a).
  - (ii) Now suppose  $|\lambda| \ge 1$ . Deduce from A being S.D.D. that  $L + U + \lambda D$  must also be S.D.D.
  - (iii) Deduce a contradiction by applying the result from part (b) to  $L + U + \lambda D$ , and conclude that  $|\lambda| < 1$ .
  - (iv) Combine parts (i)-(iii) to conclude that Jacobi iteration converges for S.D.D. matrices.
- (d) Follow a similar argument as part (c) to show that Gauss-Seidel iterations converges for S.D.D. matrices.

## Solution

(a) Let A be a S.D.D matrix and.

$$\implies a_{ii} > \sum_{\substack{j=1\\j\neq i}}^n a_{ij} \ge 0 \implies a_{ii} > 0 \quad \forall 1 \le i \le n.$$

Let D be the matrix containing the diagonial entries of A, hence

$$D = \begin{bmatrix} a_{11} & & \\ & \ddots & \\ & & a_{nn} \end{bmatrix}.$$

As, all  $a_{ii} > 0$ , therefore we  $D^{-1}$  exists.

(b) Let  $\lambda_i$  be the eigenvalues associated with disc  $D_i$ . Suppose  $0 \in D_i$  for some  $1 \le i \le n$ , therefore, we have,

$$a_{ii} \leqslant \sum_{\substack{j=0\\j\neq i}}^{n} a_{ij}.$$

Which is false as A is a S.D.D matrix, hence ,  $0 \notin D_i$ . Therefore we have,  $|\lambda_i| > 0 \quad \forall i, 1 \le i \le n \implies A^{-1}$  exists.

(c) (i) Given that  $\lambda$  is an eigenvalue of  $-D^{-1}(L+U)$ . Therefore we have  $\vec{v}$  such that  $\vec{v} \neq 0$ ,

$$-D^{-1}(L+U)\vec{v} = \lambda \vec{v}$$
$$(L+U)\vec{v} = -\lambda D\vec{v}$$
$$(L+U+\lambda D)\vec{v} = \vec{0}.$$

As there is a non-zero null vector associated with  $L + U + \lambda D$ , therefore  $\det(L + U + \lambda D) = 0$ .

(ii) Given that A is S.D.D. Suppose  $|\lambda| \ge 1$ . Consider,

$$\begin{aligned} |(L+U+\lambda D)_{ii}| &= |\lambda a_{ii}| = |\lambda||a_{ii}| \\ &> |\lambda|| \sum_{\substack{j=1\\j\neq i}}^n a_{ij}| \\ &\geq |\sum_{\substack{j=1\\j\neq i}}^n a_{ij}| \\ &= |\sum_{\substack{j=1\\j\neq i}}^n (L+U+\lambda D)_{ij}| \end{aligned}$$

Hence,  $(L + U + \lambda D)$  is S.D.D. .

- (iii) If  $|\lambda| \ge 1$  and A is S.D.D, gives that  $(L + U + \lambda D)$  is S.D.D. Therefore,  $(L + U + \lambda D)$  is invertible. Which is a contradiction as  $det(L + U + \lambda D) = 0$ . Therefore,  $|\lambda| < 1$ .
- (iv) Let M = D and N = L + U. From parts (i)-(iii) we get,

$$\lambda_i \leq \lambda_{max} < 1 \implies \rho(-M^{-1}N) < 1.$$

By theorem of convergence of iterative solvers we get, iterations based on  $-M^{-1}N$  converges to 0.

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(d) (i) Let  $\lambda$  be an eigenvalue of  $-(L+D)^{-1}(U)$ . Therefore we have  $\vec{v}$  such that  $\vec{v} \neq 0$ ,

$$-(L+D)^{-1}(L+U)\vec{v} = \lambda \vec{v}$$

$$(U)\vec{v} = -\lambda(L+D)\vec{v}$$

$$(U+\lambda(L+D))\vec{v} = \vec{0}.$$

As there is a non-zero null vector associated with  $U + \lambda (L + D)$ , therefore  $\det(U + \lambda (L + D)) = 0$ .

(ii) Given that A is S.D.D. Suppose  $|\lambda| \ge 1$ . Consider,

$$\begin{split} |(U + \lambda (L + D))_{ii}| &= |\lambda a_{ii}| = |\lambda| |a_{ii}| \\ &> |\lambda| |\sum_{\substack{j=1 \\ j \neq i}}^n a_{ij}| \\ &\geq |\lambda \sum_{\substack{j=1 \\ j \neq i}}^{i-1} a_{ij} + \sum_{\substack{j=i+1 \\ j = i+1}}^n a_{ij}| \\ &= |\sum_{\substack{j=1 \\ j \neq i}}^n (U + \lambda (L + D))_{ij}| \end{split}$$

Hence,  $(U + \lambda(L + D))$  is S.D.D. .

- (iii) If  $|\lambda| \ge 1$  and A is S.D.D, gives that  $(U + \lambda(L + D))$  is S.D.D. Therefore,  $(L + U + \lambda(L + D))$  is invertible. Which is a contradiction as  $det(U + \lambda(L + D)) = 0$ . Therefore,  $|\lambda| < 1$ .
- (iv) Let M = L + D and N = U. From parts (i)-(iii) we get,

$$\lambda_i \leq \lambda_{max} < 1 \implies \rho(-M^{-1}N) < 1.$$

By theorem of convergence of iterative solvers we get, iterations based on  $-M^{-1}N$  converges to 0.

## Question 3: Classical iterative methods for symmetric positive definite matrices

This question is about coding and comparing classical iterative methods for the S.P.D. matrix  $A_h$  from Q1(g).

- (a) Write a pseudocode for the classical iterative methods: Richardson, optimal Richardson, Jacobi, Gauss-Seidel, S.O.R., and optimal S.O.R.
- (b) Implement a program to solve  $A_h x = b$  with  $b = (1, ..., 1)^T \in \mathbb{R}^{20}$  and  $x_0 = (1, 0, ..., 0)^T \in \mathbb{R}^{20}$  using Richardson (with  $\omega = \lambda_{\text{max}}^{-1}$ ), optimal Richardson, Jacobi, Gauss-Seidel, S.O.R. (with  $\theta = 1.2$ ) and optimal S.O.R. Generate a plot comparing the log of their residual in  $\ell_2$  norm versus iterations up to 5000. Rank the performance of each method by comparing the iterations needed to reach the residual tolerance of  $10^{-14}$ . Use sparse representation when appropriate.

  Hint: Use Q1(q) to find parameters for Richardson and vary  $\theta$  to find an approximate optimal
  - Hint: Use Q1(g) to find parameters for Richardson and vary  $\theta$  to find an approximate optimal parameter for S.O.R.
- (c) Comment on the decreases in performance when n=1000. Explain briefly how this relates to  $\kappa(A_h)=O(h^{-2})$ .

# Algorithm 1: Richardson Iteration

```
1 function RichardsonIteration(A,b,x_0,\omega,tol,maxIter):
       A: The matrix to find the solution to
       b: The resultant vector in Ax = b
       x_0: The initial guess
       \omega: Richardson parameter (fixed)
       maxIter: The maximum of iterations
       Output: x: The solution to Ax = b
       M \leftarrow \omega^{-1}I
       N \leftarrow A - M
 3
 4
       x \leftarrow x_0
       r \leftarrow b - Ax
       while ||r||_2 < tol and i < maxIter:
 6
           x \leftarrow x + \omega r
           r \leftarrow b - Ax
 8
 9
       end
       return x;
10
```

# Algorithm 2: Optimal Richardson Iteration

```
1 function OptimalRichardsonIteration(A,b,x_0,tol,maxIter):
        Input:
        A: The matrix to find the solution to
        b: The resultant vector in Ax = b
        x_0: The initial guess
        maxIter: The maximum of iterations
        Output: x: The solution to Ax = b
 \mathbf{2}
              \overline{\lambda_{max}\left(A\right) + \lambda_{min}\left(A\right)}
        M \leftarrow \omega^{-1}I
 3
        N \leftarrow A - M
 4
        x \leftarrow x_0
        r = b - Ax
 6
        while ||r||_2 < tol \ and \ i < maxIter:
            x \leftarrow x + \omega r
 8
            r \leftarrow b - Ax
 9
        end
10
        return x;
11
```

```
Algorithm 3: Jacobi Iteration
```

```
1 function JacobiIteration(A,b,x_0,tol,maxIter):
       Input:
       A:The matrix to find the solution to
       b: The resultant vector in Ax = b
       x_0: The initial guess
       maxIter: The maximum of iterations
       Output: x: The solution to Ax = b
       M \leftarrow \operatorname{diag}(A)
 2
       N \leftarrow A - M
 3
       x \leftarrow x_0
       r \leftarrow b - Ax
       while ||r||_2 < tol \ and \ i < maxIter:
 6
            x \leftarrow M^{-1}(x + b - Nx)
           r \leftarrow b - Ax
           i = i + 1
 9
       end
10
       {\tt return} \; x
11
```

### **Algorithm 4:** Gauss-Sidel Iteration

```
1 function GaussSiedelIteration(A, b, x_0, tol, maxIter):
       Input:
        A: The matrix to find the solution to
       b: The resultant vector in Ax = b
       x_0: The initial guess
       maxIter: The maximum of iterations
       Output: x: The solution to Ax = b
       M \leftarrow \operatorname{diag}(A) + \operatorname{lower}(A)
       N \leftarrow A - M
 3
        x \leftarrow x_0
        r \leftarrow b - Ax
        i \leftarrow 0
 6
        while ||r||_2 < tol \ and \ i < maxIter:
            x \leftarrow M^{-1}(x + b - Nx)
            r \leftarrow b - Ax
 9
           i = i + 1
10
11
        end
12
       return x;
```

## Question 4: Steepest Descent and Conjugate Gradient

- (a) Let A be a S.P.D. matrix. Show that  $(x, y)_A := x^T A y$  for  $x, y \in \mathbb{R}^n$  forms an inner product on  $\mathbb{R}^n$ .
- (b) Using part (a), conclude that  $\|\boldsymbol{x}\| = (\boldsymbol{x}, \boldsymbol{x})_A^{1/2}$  for  $\boldsymbol{x} \in \mathbb{R}^n$  is a norm on  $\mathbb{R}^n$ . Hint: You can assume the Cauchy-Schwarz inequality  $|(x, y)_A| \leq ||x||_A ||y||_A$  holds.
- (c) For the method of Steepest Descent, show that  $\nabla f(x_k)$  and  $\nabla f(x_{k+1})$  are orthogonal (i.e. zig-zaging behavior), where  $f(y) = \frac{1}{2}y^TAy - y^Tb$ . Hint: Recall how the step size for Steepest Descent is determined.
- (d) Repeat the experiment from  $\mathbf{Q3(b)}$  with  $\boldsymbol{b}=(1,\ldots,1)^T\in\mathbb{R}^{1000}$  and  $\boldsymbol{x}_0=(1,0,\ldots,0)^T\in\mathbb{R}^{1000}$

using the method of Steepest Descent and Conjugate Gradient. Generate a plot comparing the log of their residual in  $\ell_2$  norm versus iterations up to 5000. Rank their performance by comparing the iterations needed to reach the residual tolerance of  $10^{-14}$ , as well as versus the classical iterative methods. Verify your CG method terminates after the desired number of iterations. Use sparse representation when appropriate.

# Solution

- (a) (.,.) is an inner-product if:
  - (i) Conjugate Symmetery:

$$(x,y)_A = (y,x)_A.$$

(ii) Linearity

$$(a\vec{x} + b\vec{y}, \vec{z})_A = a(\vec{x}, \vec{z})_A + b(\vec{y}, \vec{z})_A.$$

(iii) Positive-Definiteness:

$$(\vec{x}, \vec{x})_A > 0.$$

(i) 
$$(x, y)_A = x^T A y = y^T A x = (y, x)_A$$
.

(ii) 
$$(a\vec{x} + b\vec{y}, \vec{z})_A = (a\vec{x} + b\vec{y})^T A \vec{z} = a\vec{x}^T A \vec{z} + b\vec{y}^T A \vec{z} = a(\vec{x}, \vec{z})_A + b(\vec{y}, \vec{z})_A .$$

(iii) 
$$(x, x)_A = \vec{x}^T A \vec{x} > 0 \quad \text{As } A \text{ as is SPD.}$$

Therefore,  $(.,.)_A$  is an inner-product.

- (b)  $\|.\|_A$  is an norm if:
  - (i) Positive Definitness:

$$||x||_A > 0 \quad \forall \vec{x} \neq 0 \quad \land \quad ||\vec{x}||_A = 0 \iff \vec{x} = \vec{0}.$$

(ii) Scalar Multiplication

$$\|\lambda \vec{x}\|_A = \lambda \|\vec{x}\|_A.$$

(iii) Sub-additivity (Triangle Inequality):

$$\|\vec{x} + \vec{y}\|_A = \|\vec{x}\|_A + \|\vec{y}\|_A.$$

(i) Let  $x \in \mathbb{R}^n$  and  $\vec{x} \neq \vec{0}$ 

$$||x||_A = \sqrt{\vec{x}^T A \vec{x}} > 0$$
 ,as A is SPD.

Let 
$$\|\vec{x}\|_A = 0$$

$$\|\vec{x}\|_A = 0 = \sqrt{\vec{x}^T A \vec{x}} \iff \vec{x} = 0$$
, as A is SPD.

(ii) Scalar Multiplication

$$\|\lambda \vec{x}\|_{A} = \sqrt{\lambda \vec{x}^{T} A \lambda \vec{x}} = \sqrt{\lambda^{2} \vec{x}^{T} A \vec{x}} = \lambda \|\vec{x}\|_{A}.$$

(iii) Sub-additivity (Triangle Inequality):

$$\begin{split} \|\vec{x} + \vec{y}\|_{A} &= \sqrt{(\vec{x} + \vec{y})^{T} A (\vec{x} + \vec{y})} \\ &= \sqrt{\vec{x}^{T} A \vec{x} + \vec{x}^{T} A \vec{y} + \vec{y}^{T} A \vec{x} + \vec{y}^{T} A \vec{y}} \\ &= \sqrt{\vec{x}^{T} A \vec{x} + 2 \vec{x}^{T} A \vec{y} + \vec{y}^{T} A \vec{y}} \\ &= \sqrt{\|\vec{x}\|_{A}^{2} + 2 (\vec{x}, \vec{y}) + \|\vec{y}\|_{A}^{2}} \\ &\leq \sqrt{\|\vec{x}\|_{A}^{2} + 2 \|\vec{x}\|_{A} \|\vec{y}\|_{A} + \|\vec{y}\|_{A}^{2}} \\ &= \|\vec{x}\|_{A} + \|\vec{y}\|_{A}. \end{split}$$

Therefore,  $||x||_A$  is valid norm.