Geometric 138

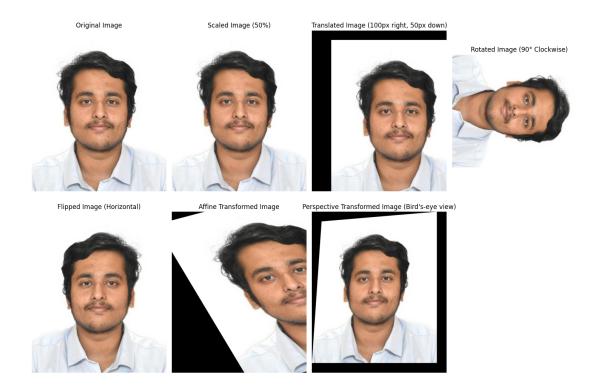
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[8]: import cv2
     import numpy as np
     import matplotlib.pyplot as plt
     # Load the image
     image = cv2.imread("C:/Users/Pratham.m/Downloads/pratham.jpg")
     # Get original dimensions
     height, width = image.shape[:2]
     # 1. Scaling: Reduce to 50% of original size
     scaled_image = cv2.resize(image, (width // 2, height // 2))
     # 2. Translation: Move 100 pixels to the right and 50 pixels down
     translation_matrix = np.float32([[1, 0, 100], [0, 1, 50]])
     translated_image = cv2.warpAffine(image, translation_matrix, (width, height))
     # 3. Rotation: Rotate 90 degrees clockwise
     rotated image 90 = cv2.rotate(image, cv2.ROTATE 90 CLOCKWISE)
     # 4. Flipping: Flip horizontally
     flipped_image = cv2.flip(image, 1)
     # 5. Affine Transformation: Mapping three points
     # Define source points and destination points
     src_points = np.float32([[50, 50], [200, 50], [50, 200]]) # Example points
     dst_points = np.float32([[10, 100], [200, 50], [100, 250]])
     affine_matrix = cv2.getAffineTransform(src_points, dst_points)
     affine_transformed_image = cv2.warpAffine(image, affine_matrix, (width, height))
     # 6. Perspective Transformation (Bird's-eye view)
     # Define source and destination points for perspective transformation
     src_pts_perspective = np.float32([[0, 0], [width, 0], [0, height], [width, u
      ⇔height]])
     dst_pts_perspective = np.float32([[50, 50], [width-50, 0], [0, height-50],
      \hookrightarrow [width-50, height-50]])
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perspective_matrix = cv2.getPerspectiveTransform(src_pts_perspective,_

dst_pts_perspective)

perspective_transformed_image = cv2.warpPerspective(image, perspective_matrix,_
→(width, height))
# Function to display images inline
def display_images(images, titles):
   plt.figure(figsize=(15, 10))
   for i in range(len(images)):
       plt.subplot(2, 4, i + 1)
       plt.imshow(cv2.cvtColor(images[i], cv2.COLOR_BGR2RGB)) # Convert BGR_
 →to RGB
       plt.title(titles[i])
       plt.axis('off')
   plt.tight_layout()
   plt.show()
# List of processed images and their titles
processed_images = [
   image, # Original
   scaled_image,
   translated_image,
   rotated image 90,
   flipped_image,
   affine_transformed_image,
   perspective_transformed_image # Bird's-eye view transformation
1
titles = [
    'Original Image',
    'Scaled Image (50%)',
    'Translated Image (100px right, 50px down)',
    'Rotated Image (90° Clockwise)',
    'Flipped Image (Horizontal)',
    'Affine Transformed Image',
    'Perspective Transformed Image (Bird\'s-eye view)'
]
# Display the images
display images (processed images, titles)
```



Original Image: This is the base image before any transformations. It serves as a reference for comparison.

Scaled Image (50%): The image has been resized to 50% of its original size, reducing both the height and width. This makes the image smaller while maintaining the aspect ratio.

Translated Image (100px right, 50px down): The image has been shifted (translated) 100 pixels to the right and 50 pixels downward. This creates a black border on the left and top, indicating the empty space created by the translation.

Rotated Image (90° Clockwise): The image has been rotated 90 degrees in the clockwise direction, repositioning it to be horizontally tilted.

Flipped Image (Horizontal): The image has been flipped horizontally, creating a mirror image. The left side of the original now appears on the right, and vice versa.

Affine Transformed Image: Three points on the original image were mapped to new positions, resulting in a skewed, distorted effect. Parts of the image appear stretched or compressed, and black triangles fill areas where the image has been warped.

Perspective Transformed Image (Bird's-eye view): The image was transformed using a perspective mapping, giving the appearance of being viewed from an angle. This effect simulates depth, as if the image is seen from a higher or skewed vantage point.

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