

DAA PROJECT

ELEMENTARY CELLULAR AUTOMATON SIMULATOR AND PREDICTOR

GitHub Link:

<https://github.com/Prathamesh111-netizen/DAA-project-sem-4>

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Today's Discussion

OUTLINE OF TOPICS

Walkthrough of History / Problem Statement

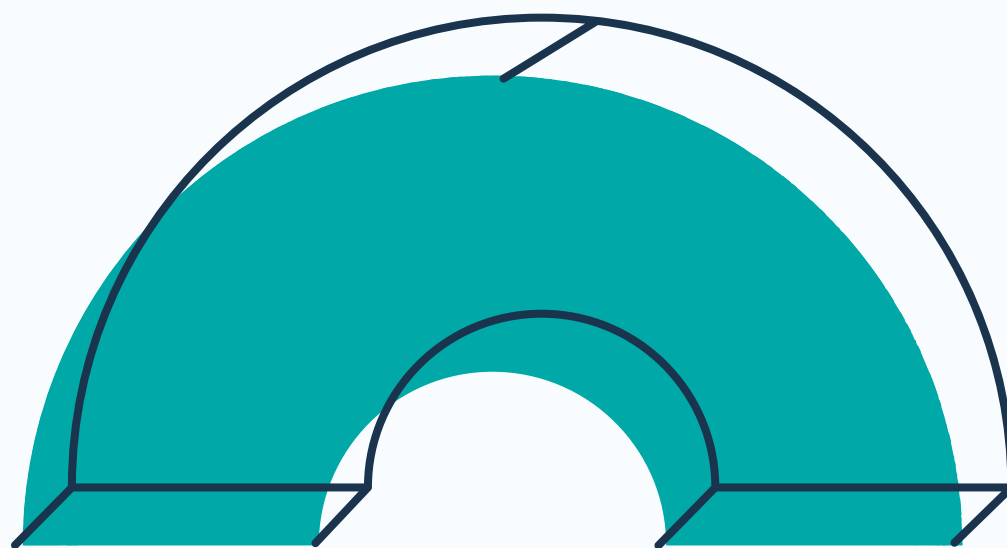
1 Dimensional Cellular Automata

1. Rules
2. First solution that came to our Mind
3. Most Optimised Possible

2 Dimensional Cellular Automata

1. Game of Life
2. First solution that came to our Mind
3. HashLife

The Westmire Way



A BRIEF HISTORY

The game made its first public appearance in the October 1970 issue of Scientific American, in Martin Gardner's "Mathematical Games" column, which was based on personal conversations with Conway.

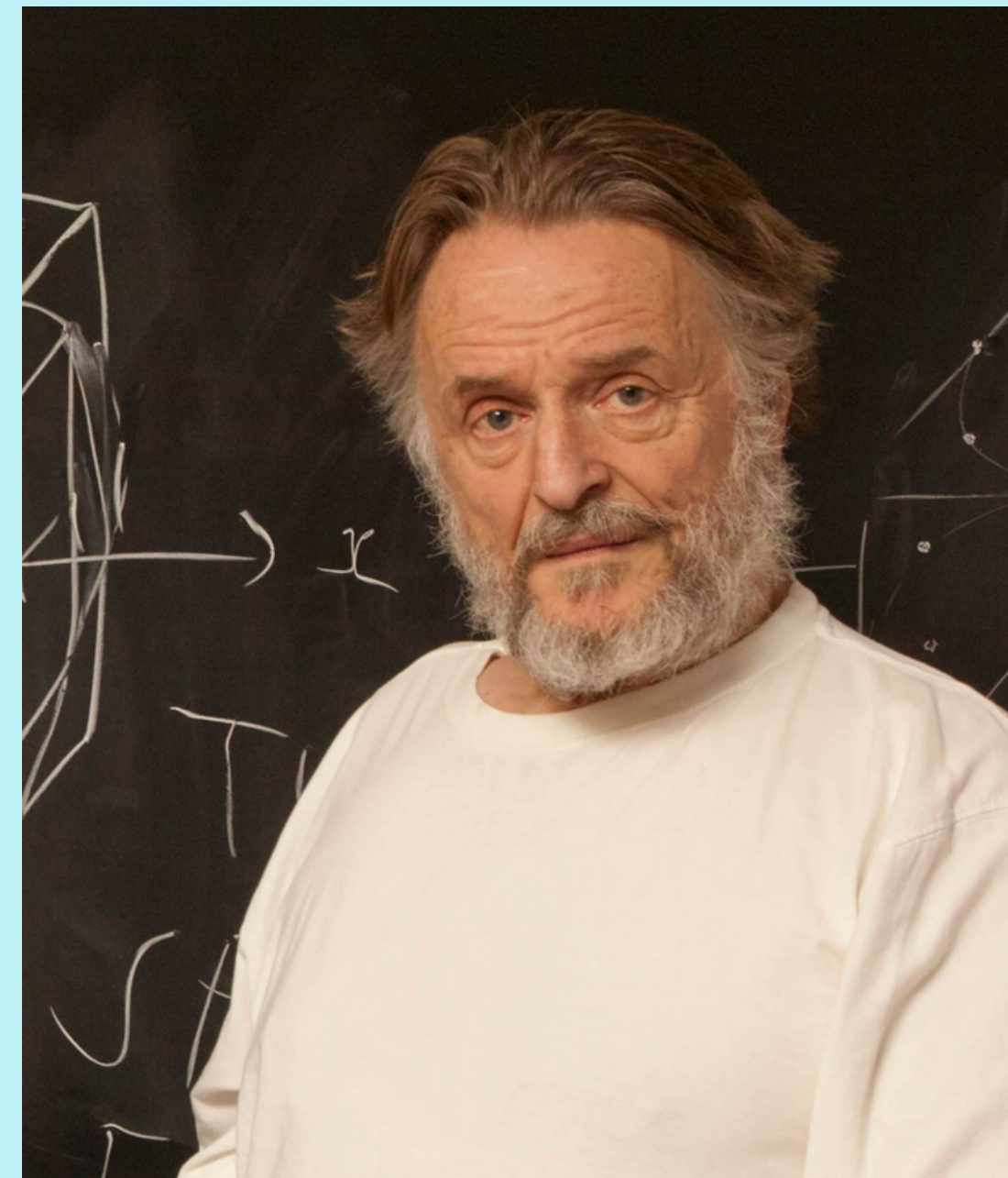
Theoretically, the Game of Life has the power of a universal Turing machine: anything that can be computed algorithmically can be computed within the Game of Life.

Gardner wrote, "Because of Life's analogies with the rise, fall and alterations of a society of living organisms, it belongs to a growing class of what are called 'simulation games' (games that resemble real-life processes)



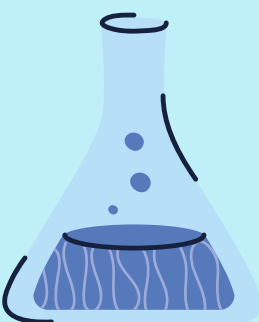
JOHN VON NEUMANN

Von Neumann's machine consisted of an infinite, two-dimensional grid of cells that could be in up to twenty-nine states and followed a large number of complex rules. It contained several sub-organisms that gathered materials from the environment, read the instructions and copied them, then performed the computation.



JOHN HORTON CONWAY

Dr. Conway, called Life a “no-player, never-ending game.” Whenever the subject came up, he would bellow, “I hate Life!” But in his final years he learned to love Life again.



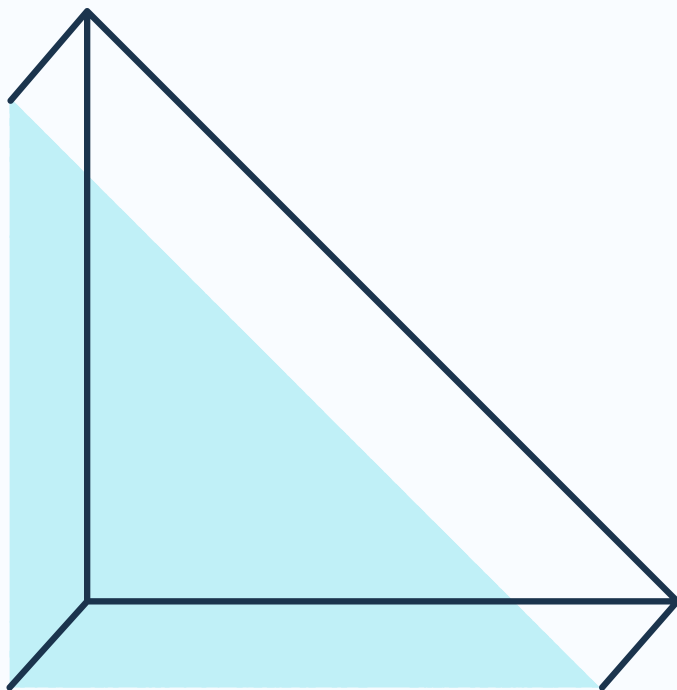
1 Dimensional

Rules

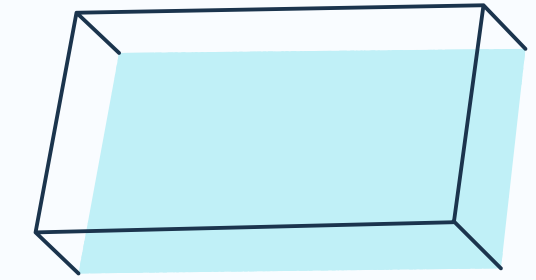
The simplest class of one-dimensional cellular automata.

Elementary cellular automata have two possible values for each cell (0 or 1), and rules that depend only on nearest neighbor values.

As a result, the evolution of an elementary cellular automaton can completely be described by a table specifying the state a given cell will have in the next generation based on the value of the cell to its left, the value the cell itself, and the value of the cell to its right



Explanation



101 : TRUE

Element with 0 state and both neighbours 1,
will become 1 in next generation

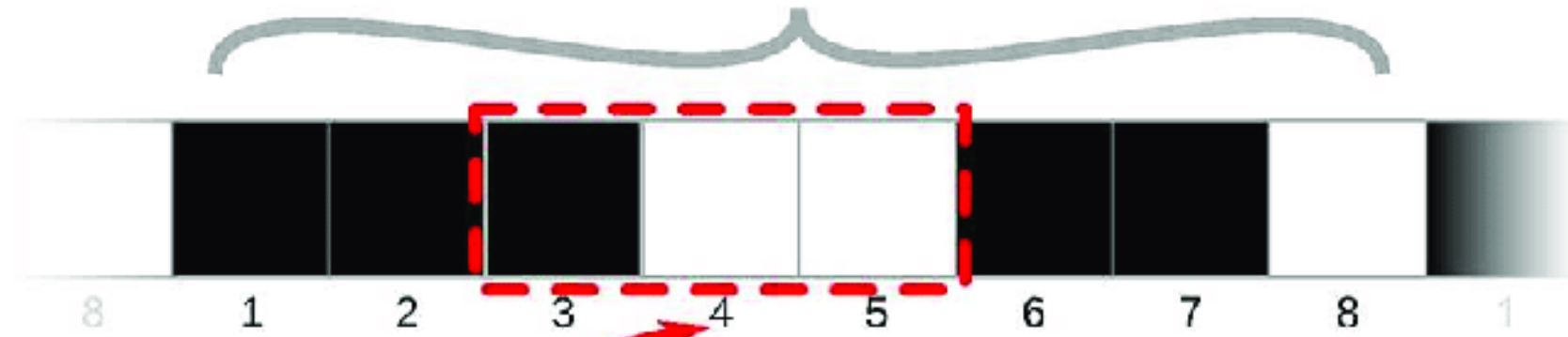
100 : FALSE

Element with 0 state and left neighbour 1, right
neighbour 0,
will become 0 in next generation

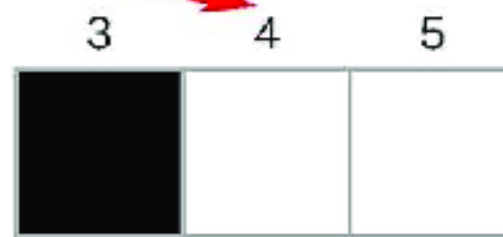
RULE 30

Binary Representation of 30 is considered

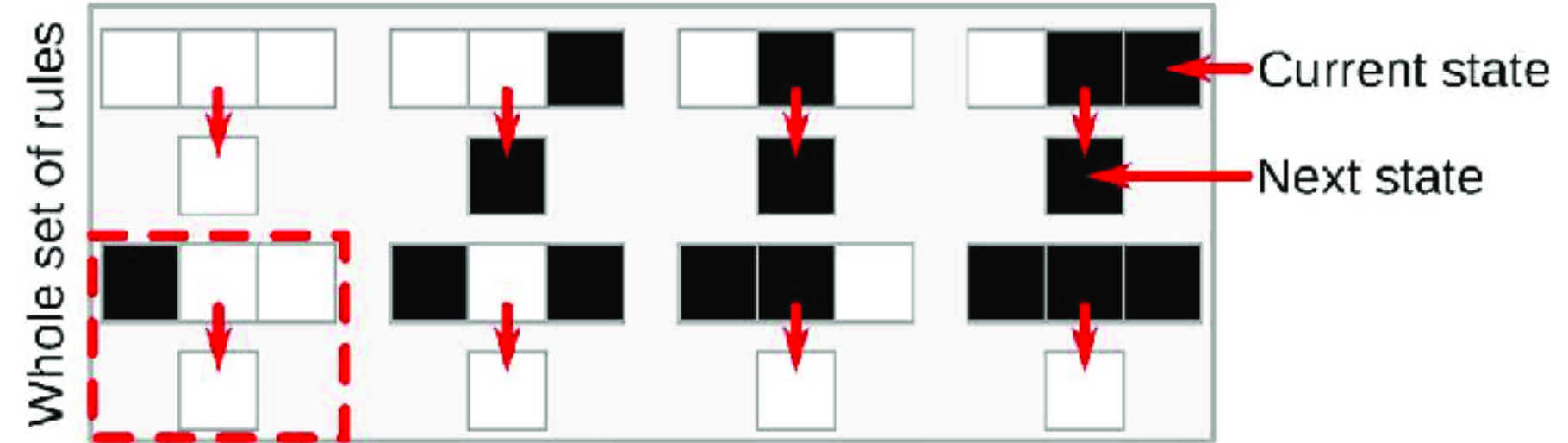
This is a cellular automaton with 8 cells



This is what **cell 4** sees if it only has 2 neighbors



Cell 4 will look which of its rules should be activated



Cell 4's next state will be ☐

After all cells update their status, this will be the configuration of the CA:

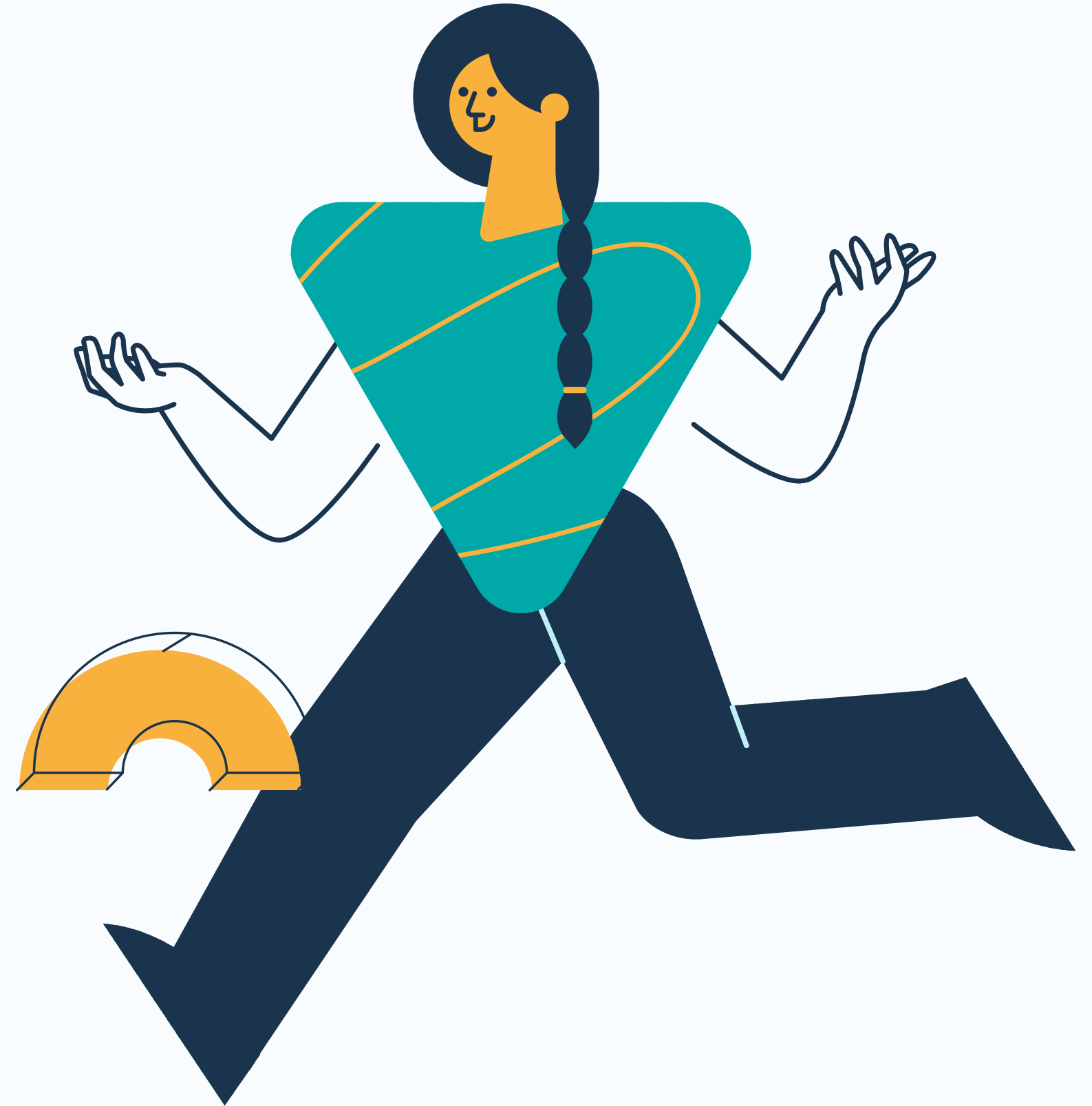


3Layer/sec

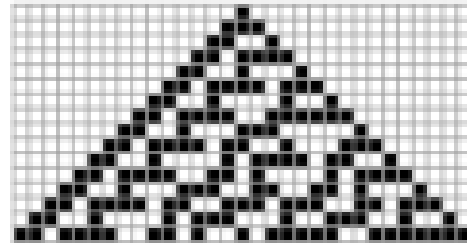
Naive Way

150Layer/sec

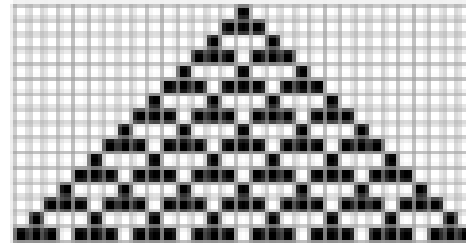
Optimised Way



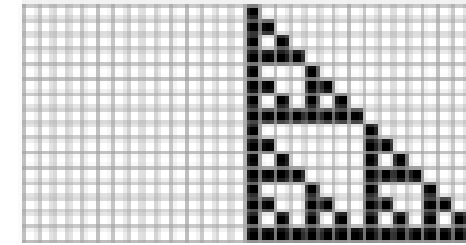
rule 30



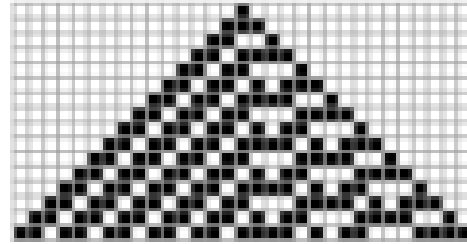
rule 54



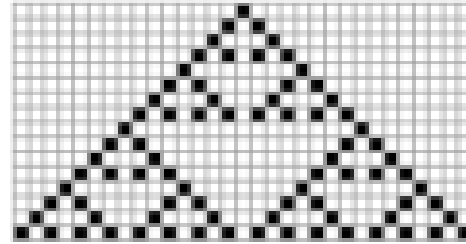
rule 60



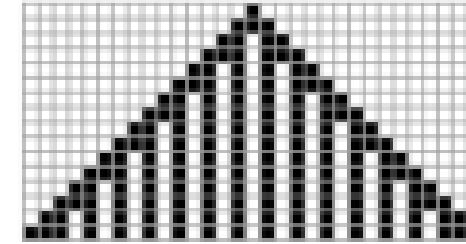
rule 62



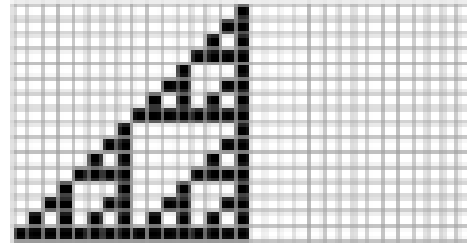
rule 90



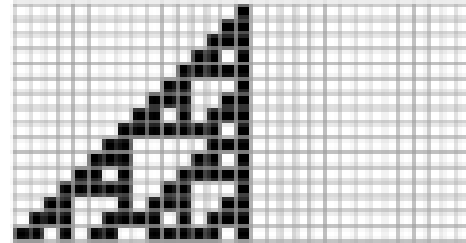
rule 94



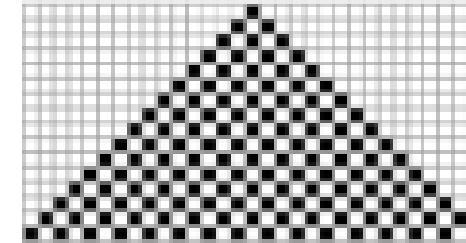
rule 102



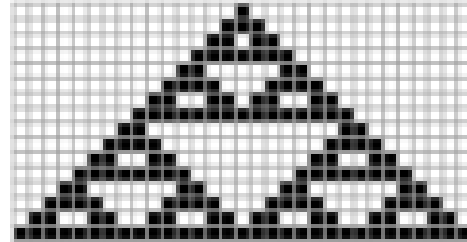
rule 110



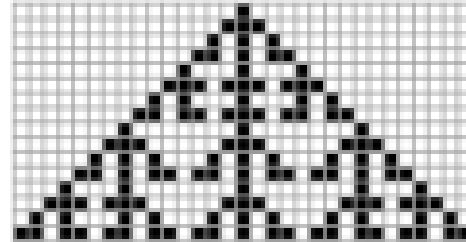
rule 122



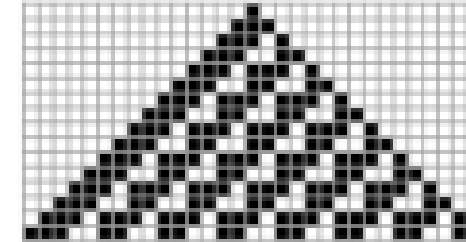
rule 126



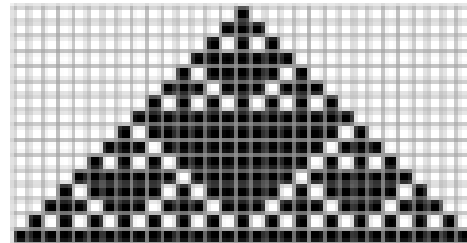
rule 150



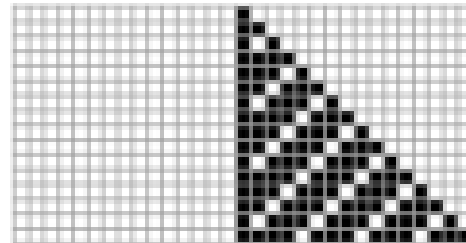
rule 158



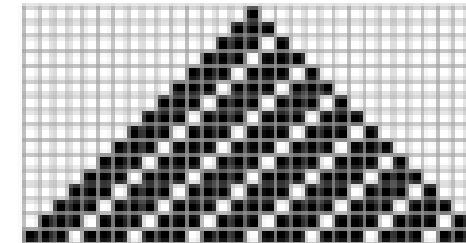
rule 182



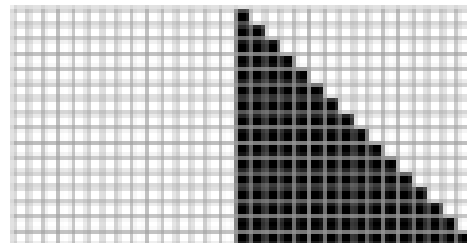
rule 188



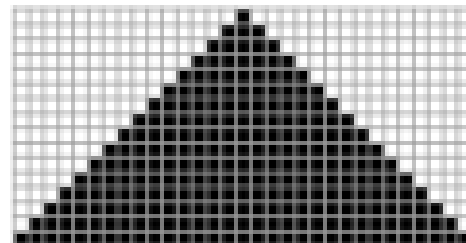
rule 190



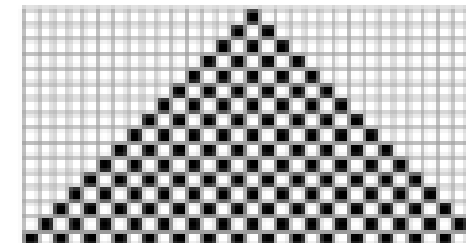
rule 220



rule 222



rule 250



2D : Game of Life

Birth

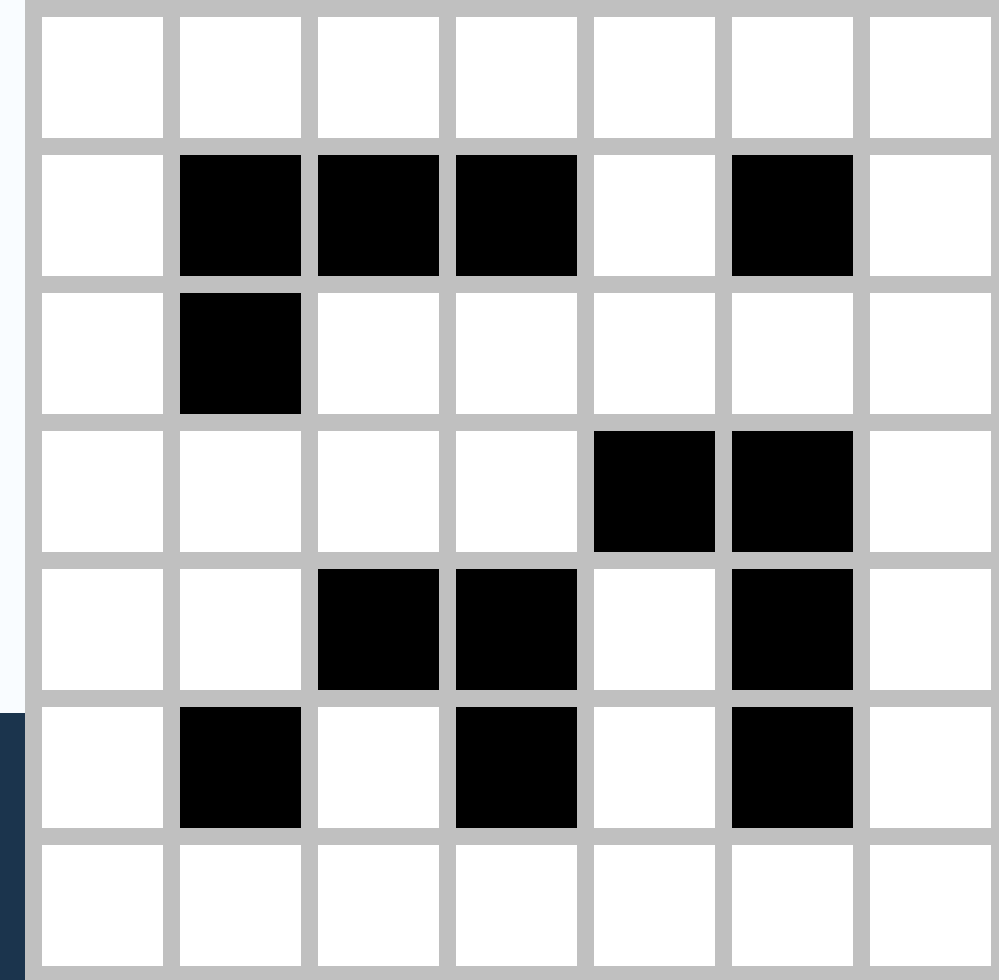
Any dead cell with three live neighbours becomes a live cell.

Survival

Any live cell with two or three live neighbours survives.

Death

All other live cells die in the next generation. Similarly, all other dead cells stay dead



THINK !



Brute Force

Implemented a naive solution, where we traverse through each box and check his neighbours each time



Not better

Put constraints on the traversal, Visit only live nodes and their neighbours, etc.



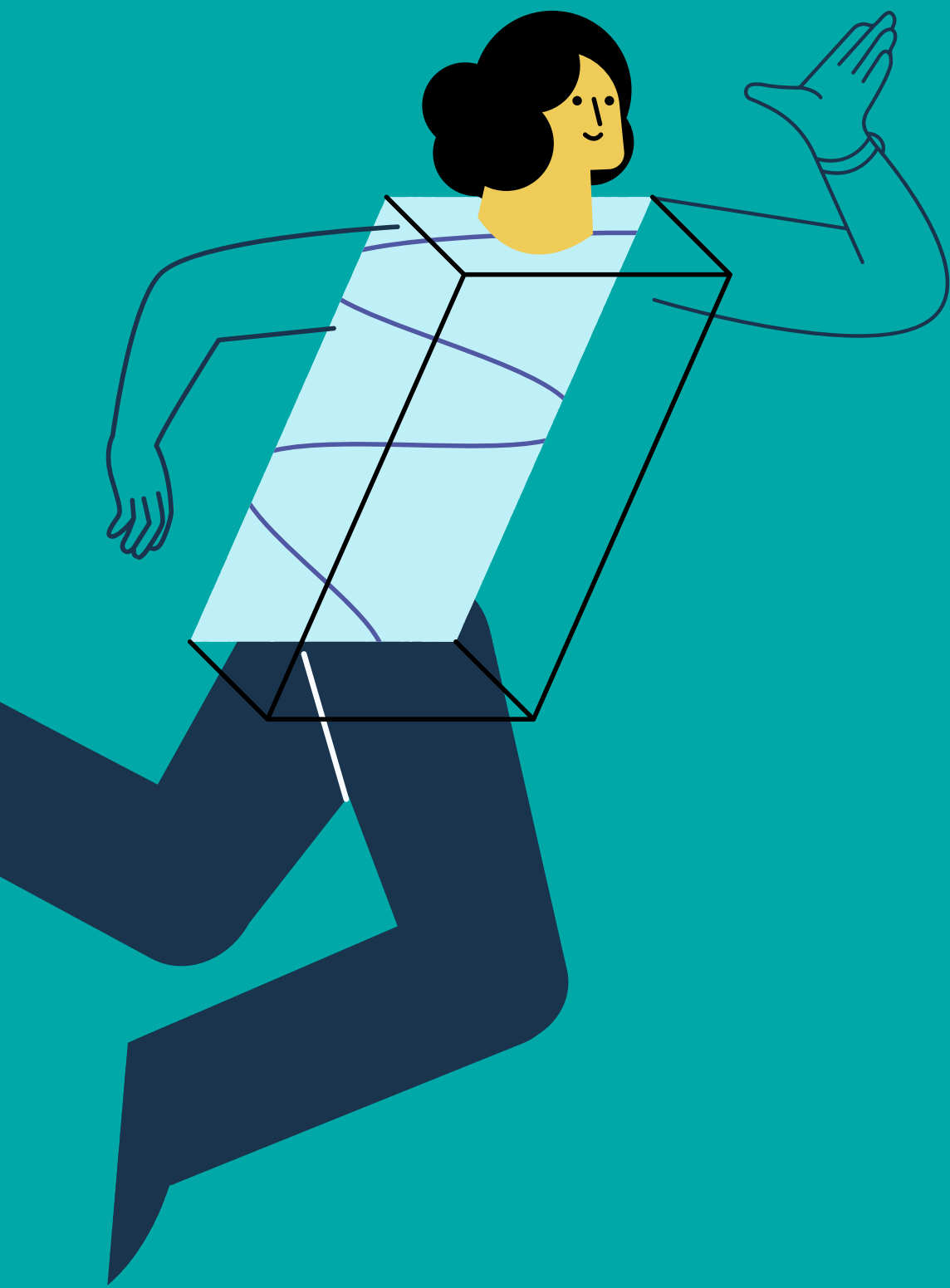
Bits

Use Bit manipulation to reduce calculations time complexity



Research !

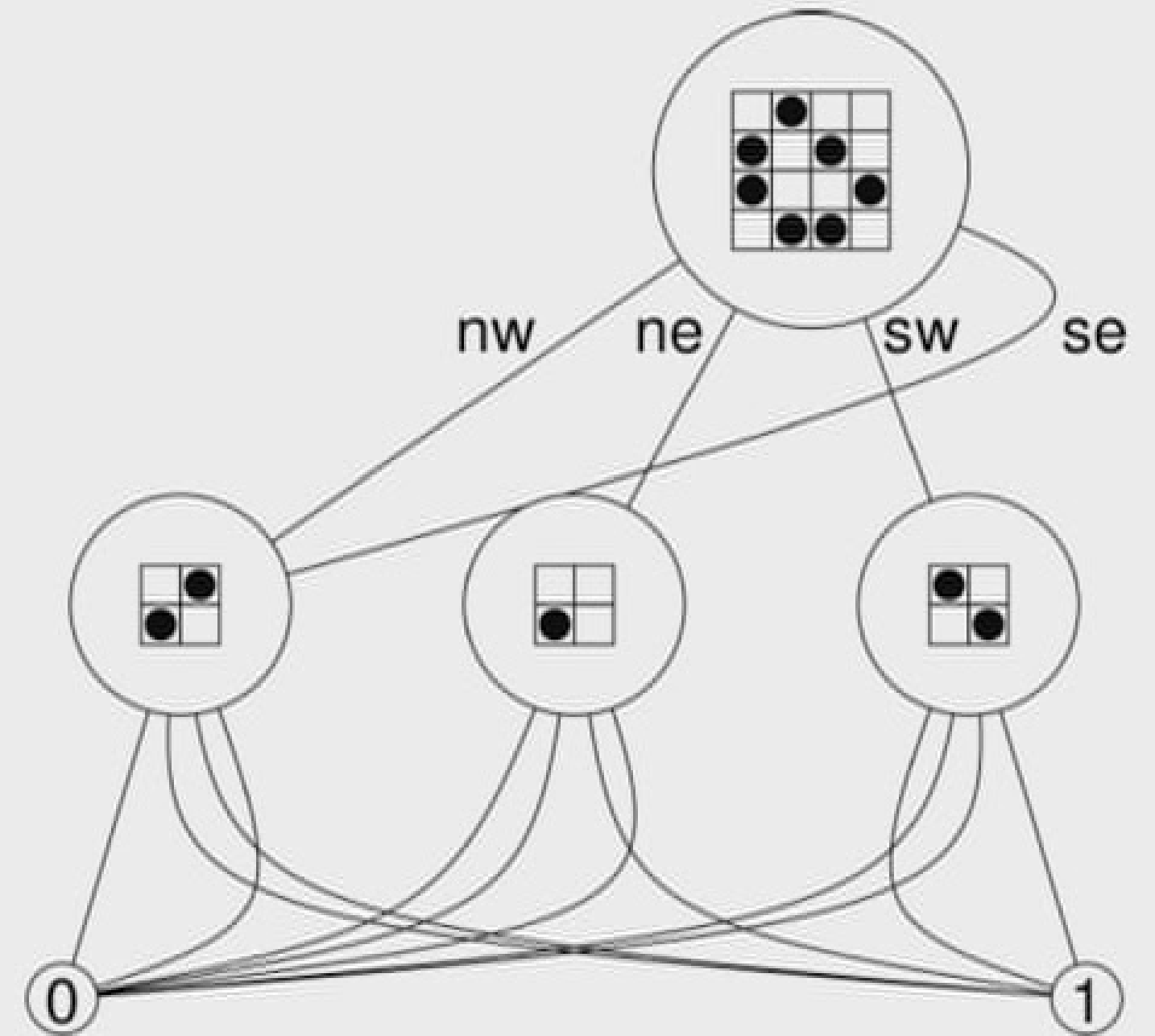
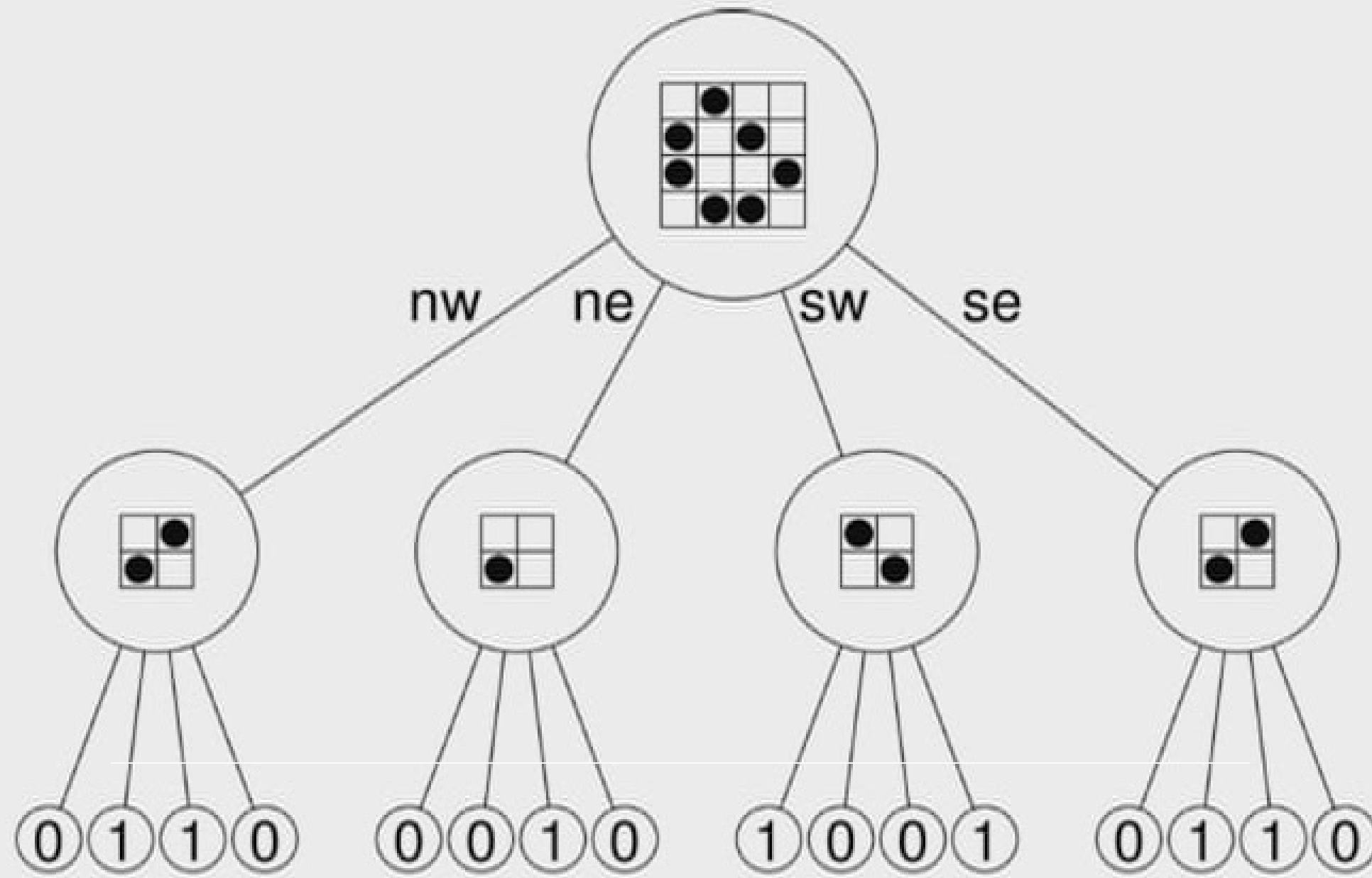
SuperSpeed Method Found



What Plan did we had in mind?

The Ins and Outs

Canonicalized Quadtrees



Each node has a **level** k , where the size of the node is $2^k \times 2^k$ cells.

- level 0 is a 1×1 block (leaf node) which are just binary values, on or off.
- level 1 is a 2×2 block whose children are level 0 blocks
- level 2 is 4×4 block whose children are level 1 blocks
- level 3 is an 8×8 block whose children are level 2 blocks

The Hashlife algorithm defines an recursive process that:

- takes a level k node, size $2^k \times 2^k$
- returns a level $k-1$ node, size $2^{k-1} \times 2^{k-1}$
- advanced 2^{k-2} generations in time.

Eventually, we end up processing blocks of size 4×4 ($k = 2$), where we can use basic brute-force, computing the 2×2 successor of a 4×4 cell by straightforward computation. The clever part is that by memoizing the recursion to cache the intermediate products, we can *dramatically* reduce computation requirements, as most CA patterns are very repetitive in space and in time.

AAA	AAB	ABA	ABB
AAC	AAD	ABC	ABD
ACA	ACB	ADA	ADB
ACC	ACD	ADC	ADD

BAA BAB BBA BBB

BAC BAD BBC BBD

BCA BCB BDA BDB

BCC BCD BDC BDD

CAA CAB

CBA CBB

DAA DAB

DBA DBB

CAC CAD

CBC CBD

DAC DAD

DBC DBD

CCA CCB

CDA CDB

DCA DCB

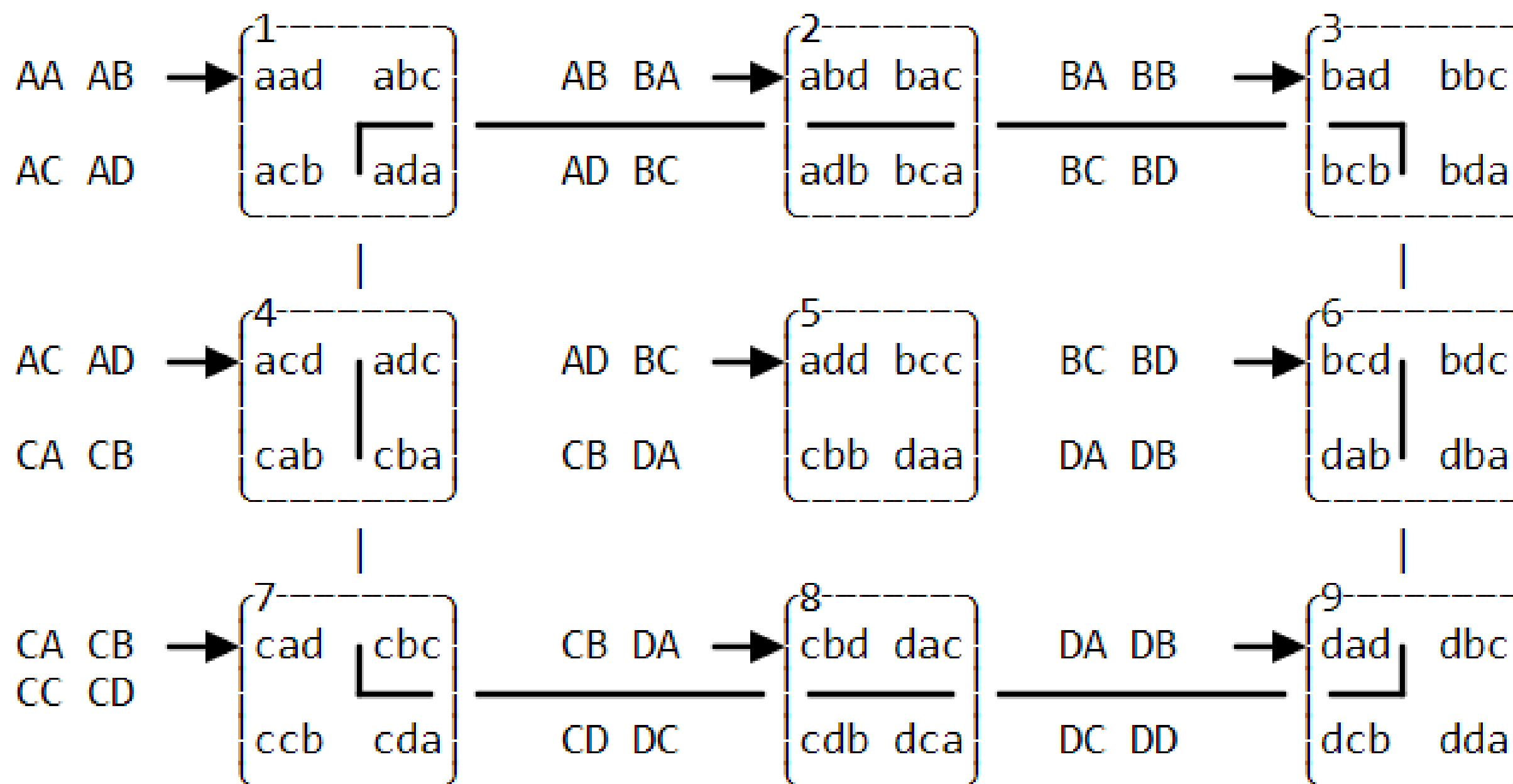
DDA DDB

CCC CCD

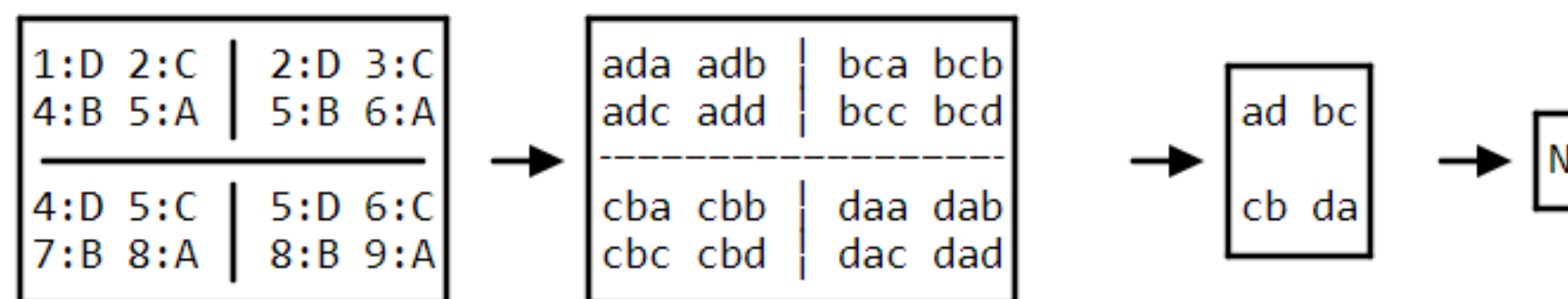
CDC CDD

DCC DCD

DDC DDD



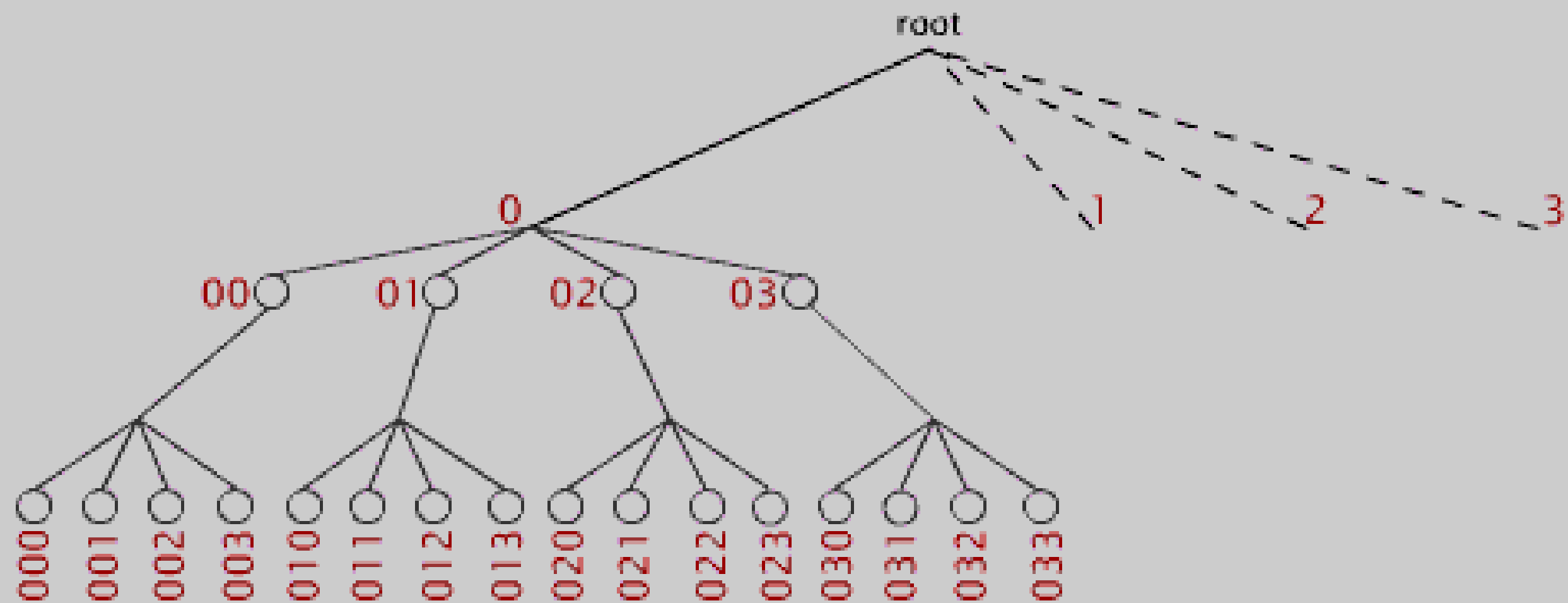
Finally, we can select from those great-grandchildren sized successor blocks the “inner” parts to make up one full child-sized successor (a 4×4 block of great-grandchild successors)



Hashlife is a memoized algorithm for computing the long-term fate of a given starting configuration in Conway's Game of Life and related cellular automata, much more quickly than would be possible using alternative algorithms that simulate each time step of each cell of the automaton.

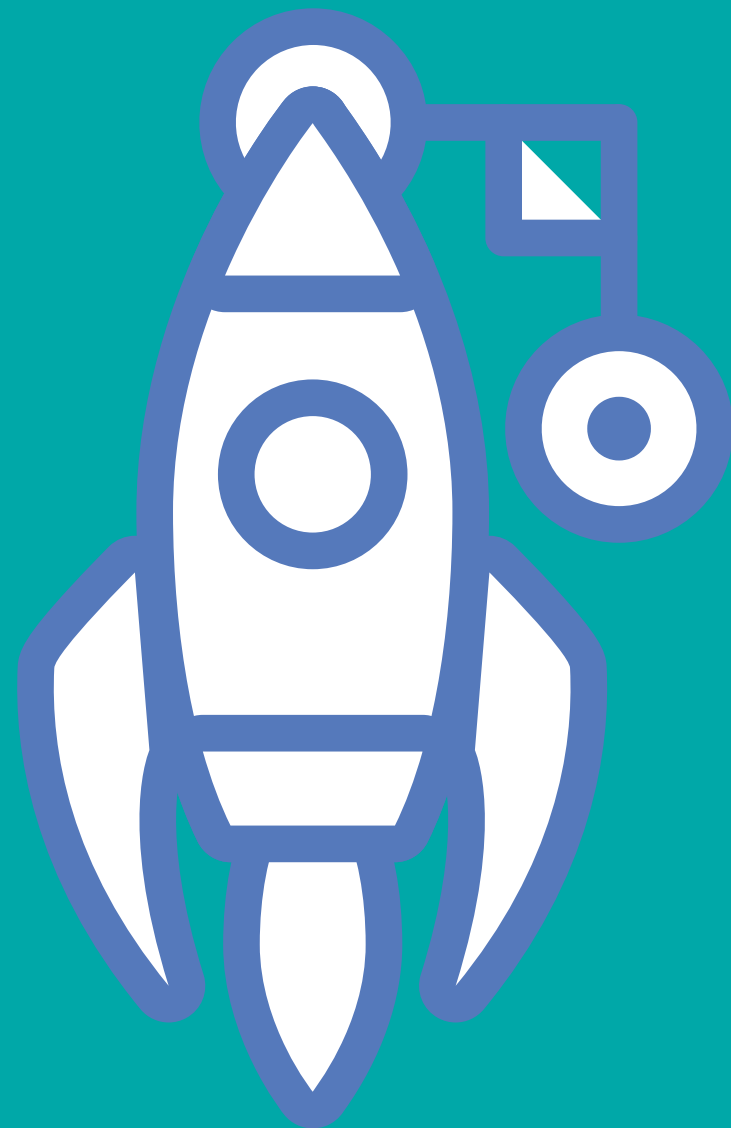
The algorithm was first described by Bill Gosper in the early 1980s while he was engaged in research at the Xerox Palo Alto Research Center.





000	001	010	011	100	101	110	111
002	003	012	013	102	103	112	113
020	021	030	031	120	121	130	131
022	023	032	033	122	123	132	133
200	201	210	211	300	301	310	311
202	203	212	213	302	303	312	313
220	221	230	231	320	321	330	331
222	223	232	233	322	323	332	333

Superspeed and caching



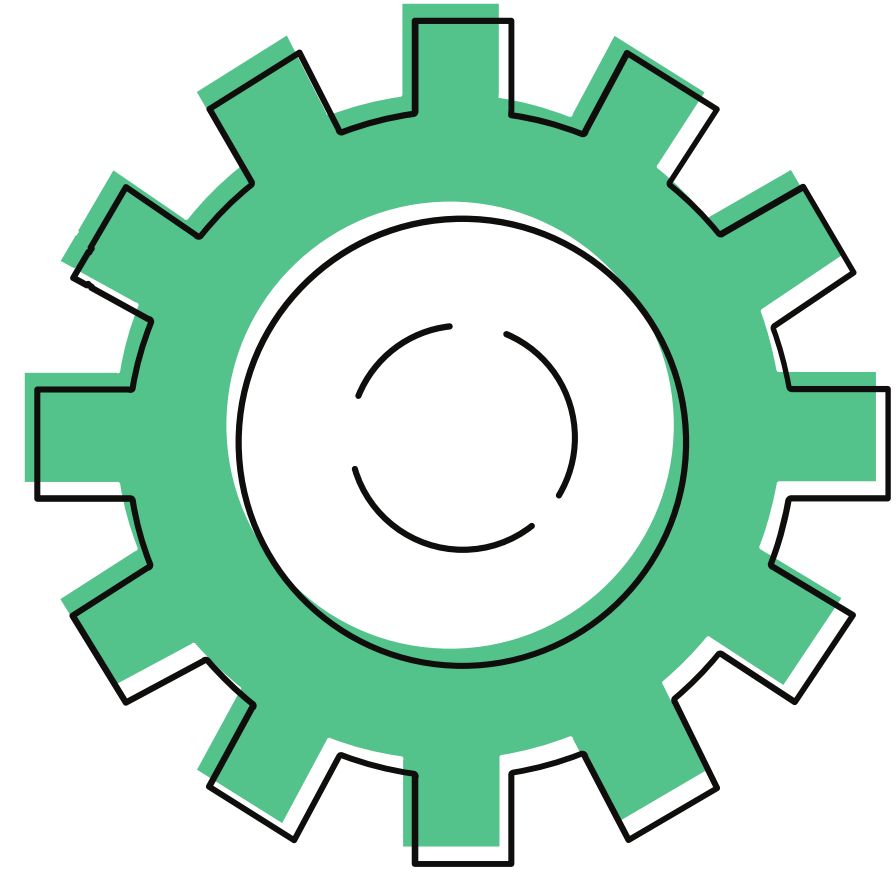
One could compute twice the number of generations forward for a node at the $(k+1)$ -th level compared to one at the k th.

To take full advantage of this feature, subpatterns from past generations should be saved as well.

The typical behaviour of a Hashlife program on a conducive pattern is as follows: first the algorithm runs slower compared to other algorithms because of the constant overhead associated with hashing and building the tree; but later, enough data will be gathered and its speed will increase tremendously – the rapid increase in speed is often described as "exploding".

Applications

- Traffic
- Game theory (Firing squad synchronization problem, Majority problem)
- Pseudo-randomness
- Computing with particle colliding
- Quantum gravity: Fredkin and Wolfram are strong proponents of CA-based physics and in 2016, Gerard 't Hooft published a book-length development of the idea to rebuild quantum mechanics using cellular automata.



- Biology
 - Chemical Reactions
 - Artificial Intelligence
-

**THANK
YOU**