#include<iostream> #include<graphics.h> #include<math.h> #include<dos.h> #include<math.h> #include<conio.h> using namespace std; class transform

{

public:

int m,a[20][20],c[20][20];

int i,j,k; public:

void object(); void accept();

void operator \*(float b[20][20])

{

for(int i=0;i<m;i++)

{

for(int j=0;j<m;j++)

{

c[i][j]=0;

for(int k=0;k<m;k++)

{

c[i][j]=c[i][j]+(a[i][k]\*b[k][j]);

}

}

}

}

};

void transform::object()

{

int gd,gm; gd=DETECT;

initgraph(&gd,&gm,NULL); line(300,0,300,600); line(0,300,600,300);

for( i=0;i<m-1;i++)

{

line(300+a[i][0],300-a[i][1],300+a[i+1][0],300-a[i+1][1]);

}

line(300+a[0][0],300-a[0][1],300+a[i][0],300-a[i][1]);

for( i=0;i<m-1;i++)

{

line(300+c[i][0],300-c[i][1],300+c[i+1][0],300-c[i+1][1]);

}

line(300+c[0][0],300-c[0][1],300+c[i][0],300-c[i][1]);

int temp;

cout<<"Press 1 to continue"; cin>>temp;

closegraph();

}

void transform::accept()

{

cout<<"\n";

cout<<"Enter the Number Of Edges:"; cin>>m;

cout<<"\nEnter The Coordinates :"; for(int i=0;i<m;i++)

{

for(int j=0;j<3;j++)

{

if(j>=2)

a[i][j]=1; else cin>>a[i][j];

}

}

}

int main()

{

int ch,tx,ty,sx,sy;

float deg,theta,b[20][20]; transform t;

t.accept();

cout<<"\nEnter your choice"; cout<<"\n1.Translation" "\n2.Scaling" "\n3.Rotation";

cin>>ch; switch(ch)

{

case 1: cout<<"\nTRANSLATION OPERATION\n"; cout<<"Enter value for tx and ty:";

cin>>tx>>ty; b[0][0]=b[2][2]=b[1][1]=1;

b[0][1]=b[0][2]=b[1][0]=b[1][2]=0; b[2][0]=tx;

b[2][1]=ty;

t \* b;

t.object();

break;

case 2: cout<<"\nSCALING OPERATION\n"; cout<<"Enter value for sx,sy:"; cin>>sx>>sy;

b[0][0]=sx;

b[1][1]=sy; b[0][1]=b[0][2]=b[1][0]=b[1][2]=0; b[2][0]=b[2][1]=0;

b[2][2] = 1;

t \* b; t.object(); break;

case 3: cout<<"\nROTATION OPERATION\n"; cout<<"Enter value for angle:";

cin>>deg; theta=deg\*(3.14/100); b[0][0]=b[1][1]=cos(theta); b[0][1]=sin(theta);

b[1][0]=sin(-theta); b[0][2]=b[1][2]=b[2][0]=b[2][1]=0; b[2][2]=1;

t \* b; t.object(); break;

default:

cout<<"\nInvalid choice";

}

getch(); return 0;

}