Steps for Zone 9 part collide

- 1 In Robot TP
- 1.1 Make Teach Pendant **ON**-- Controller **T1**
- 1.2 Press IO button -- Go to Robot press enter -- Go to Robot output press Enter)



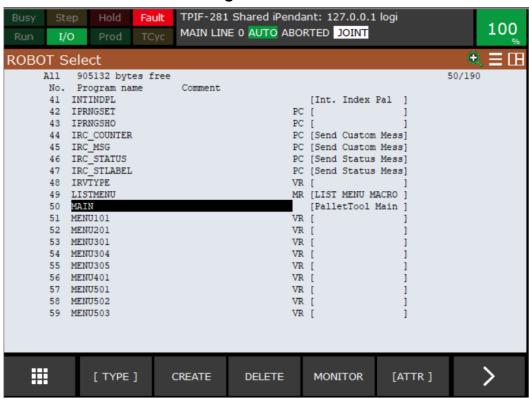
1.3 Go to vacume Gripper 1 2 3 and 4 - Press ON



1.4 Press FCTN button-- Go to ABORT ALL press Enter



1.5 Press **Select --** Go to **Main Program** -- Press **Enter**



- 1.6 Make Teach Pendant OFF -- Controller Auto
- 2 Manual Resetting procedure In **HMI**
- 2.1 Press cycle stop -- Turn the switch to Manual mode -- Press both Reset Button
- 2.2 After Idle
- 2.3 Press cycle stop -- Turn the switch to Auto mode -- Press both Reset Button
- 2.4 After Idle

- Go to parameter page -- Press Pallet parameters-- Press Changes Required -- once the changes are done then press Apply
- 2.6 Press Cycle start