

# VITERBI ALGORITHM

# Introduction

- The Viterbi Algorithm (VA) was first proposed by **Andrew J. Viterbi** in 1967.
- The Viterbi algorithm is a dynamic programming algorithm.
- Use for finding the most likely sequence of hidden states-called the Viterbi path- that results in a sequence of observed events, especially in the context Hidden Markov Models.

# Applications

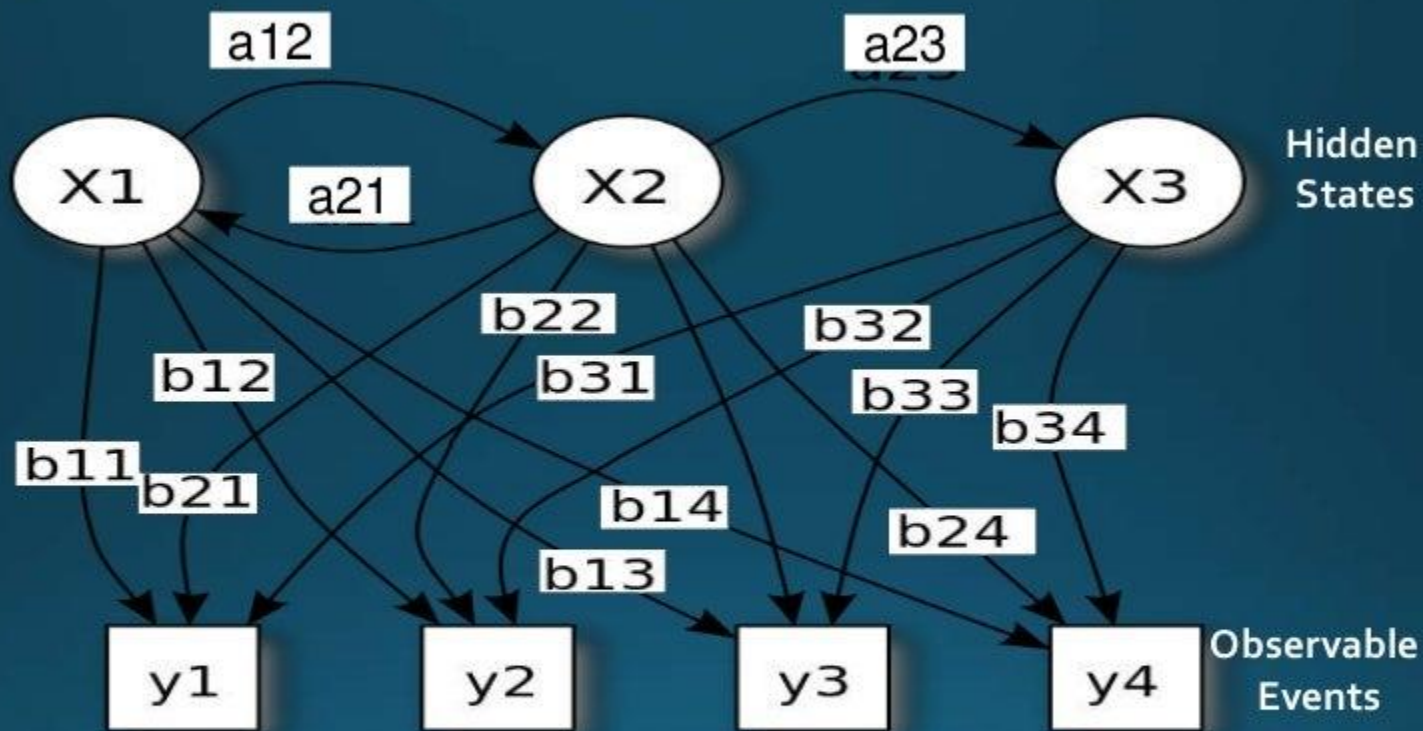
- The algorithm has found its original application in communication for decoding such as in dial-up modems, satellite, deep-space communications and wireless LANs.
- It is now also commonly used in speech recognition, speech synthesis, natural language processing, computational linguistics and bioinformatics.

# Hidden Markov Model

- Markov models are used to model sequences of events (or observations) that occur one after another .
- In a Hidden Markov model, the state is not directly visible, but the output/observations, dependent on the state, is visible.
- Each state has a probability distribution over the possible output .
- The sequence of observations generated by a HMM gives some information about the sequence of states.



## An example of Hidden Markov Model (State Diagram)



$a_{ij}$  -> Probability of transition from one state to another

$b_{ij}$  -> Probability of an observation for a state

# The Viterbi Algorithm

## Input:

- The state space  $S = \{s_1, s_2, \dots, s_N\}$ .
- The observation space  $O = \{o_1, o_2, \dots, o_K\}$ .
- Transition matrix  $A$  of size  $N.N$  such that  $A_{ij}$  stores the transition probability of transiting from state  $s_i$  to  $s_j$  state.
- Emission matrix  $B$  of size  $N.K$  such that  $B_{ij}$  stores the probability of observing  $o_j$  from state  $s_i$ .
- An array of initial probabilities  $\pi$  of size  $N$  such that  $\pi_i$  stores the probability of state  $s_i$  at time  $t=1$ .
- Sequence of observations  $y_1, y_2, \dots, y_T$ .

### Output :

The most likely hidden state sequence  $X = \{x_1, x_2, \dots, x_T\}$ .

### Algorithm:

*function* VITERBI(  $O, S, \pi, A, T, B$  ) :  $X$

*for each state*  $s$  *from* 1 *to*  $N$  *do*

Viterbi[  $s, 1$  ]  $\leftarrow \pi_s * B_{s, o_1}$

Backpointer[  $s, 1$  ]  $\leftarrow 0$

*for each time step*  $t$  *from* 2 *to*  $T$  *do*

*for each state*  $s$  *from* 1 *to*  $N$  *do*

Viterbi[  $s, t$  ]  $\leftarrow \max_{k=1}^N ( \text{Viterbi}[ k, t-1 ] * A_{k,s} * B_{s, o_t} )$

Backpointer[  $s, t$  ]  $\leftarrow \underset{k=1}{\text{argmax}}^N ( \text{Viterbi}[ k, t-1 ] * A_{k,s} * B_{s, o_t} )$

*End for*

*End for*

*Cont....*

$Z_T \leftarrow \operatorname{argmax}_N (\text{Viterbi}[s, T])$

$X_T \leftarrow S_{Z_T}^{s=1}$

for  $i \leftarrow T, T-1, \dots, 2$  do

$Z_{i-1} \leftarrow \text{Backpointer}[Z_i, i]$

$X_{i-1} \leftarrow S_{Z_{i-1}}$

End for

Return  $X$

End function

The complexity of the algorithm is  $O(T * N^2)$



# Implementation Example

- Consider a doctor diagnoses fever by asking patients how they feel. The patients may only answer that they feel normal, dizzy, or cold.
- There are two states, "Healthy" and "Fever", but the doctor cannot observe them directly, they are *hidden* from him.
- On each day, there is a certain chance that the patient will tell the doctor he/she is "normal", "cold", or "dizzy", depending on his/her health condition.

Inputs:

- ❑ States (S)='Healthy' , 'Fever'.
- ❑ Observation (O)='Normal' , 'Cold' , 'Dizzy'.
- ❑ Start\_probability ( $\pi$ ) = Healthy: 0.6, Fever: 0.4

- ❑ Transition Probability(A)=

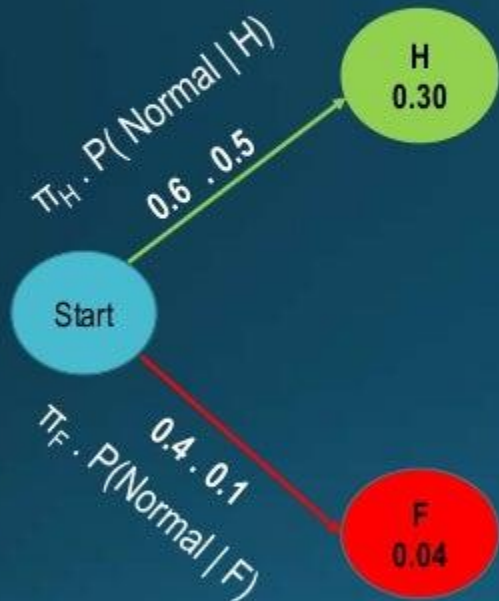
	Healthy	Fever
Healthy	0.7	0.3
Fever	0.4	0.6

- ❑ Emission Probability(B)=

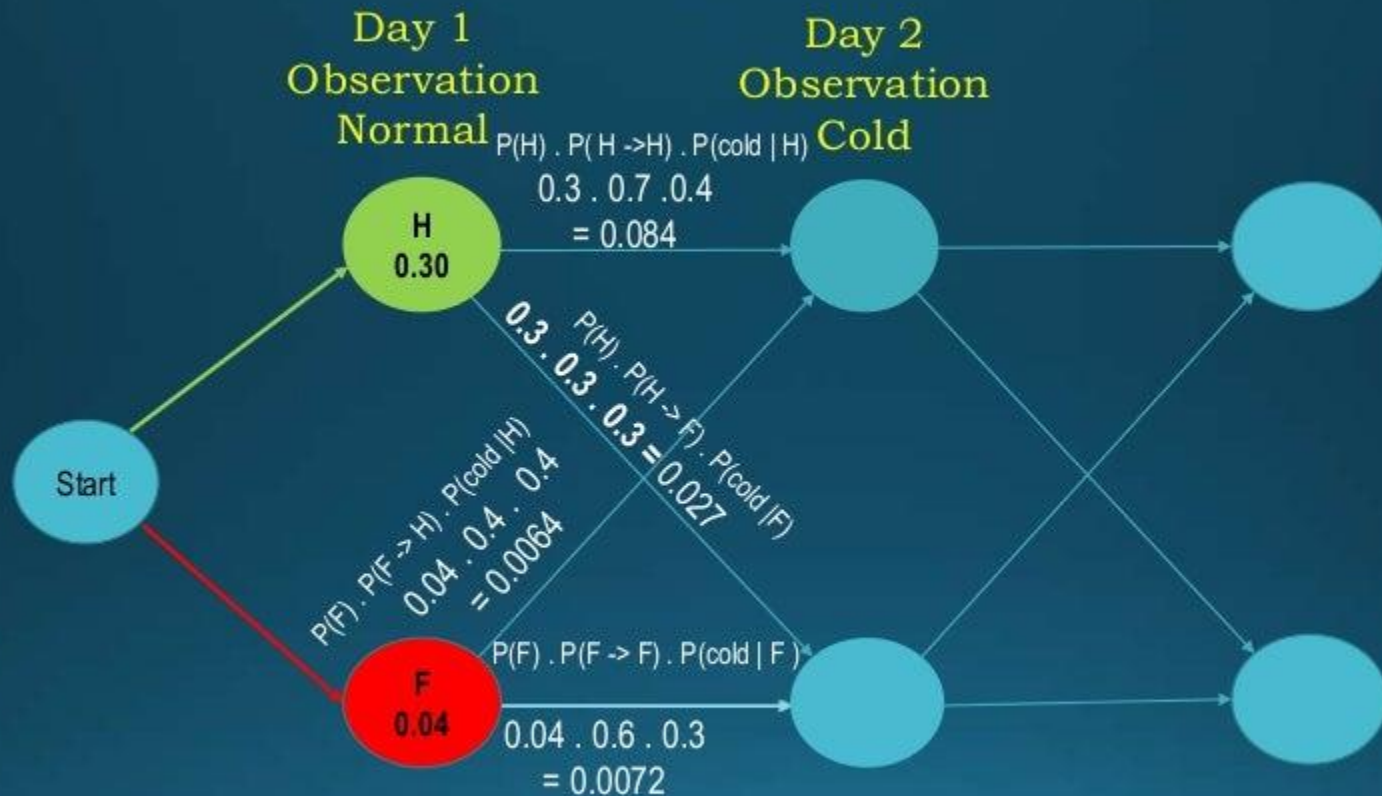
	Normal	Cold	Dizzy
Healthy	0.5	0.4	0.1
Fever	0.1	0.3	0.6

# Operations

Day 1  
Observation  
Normal



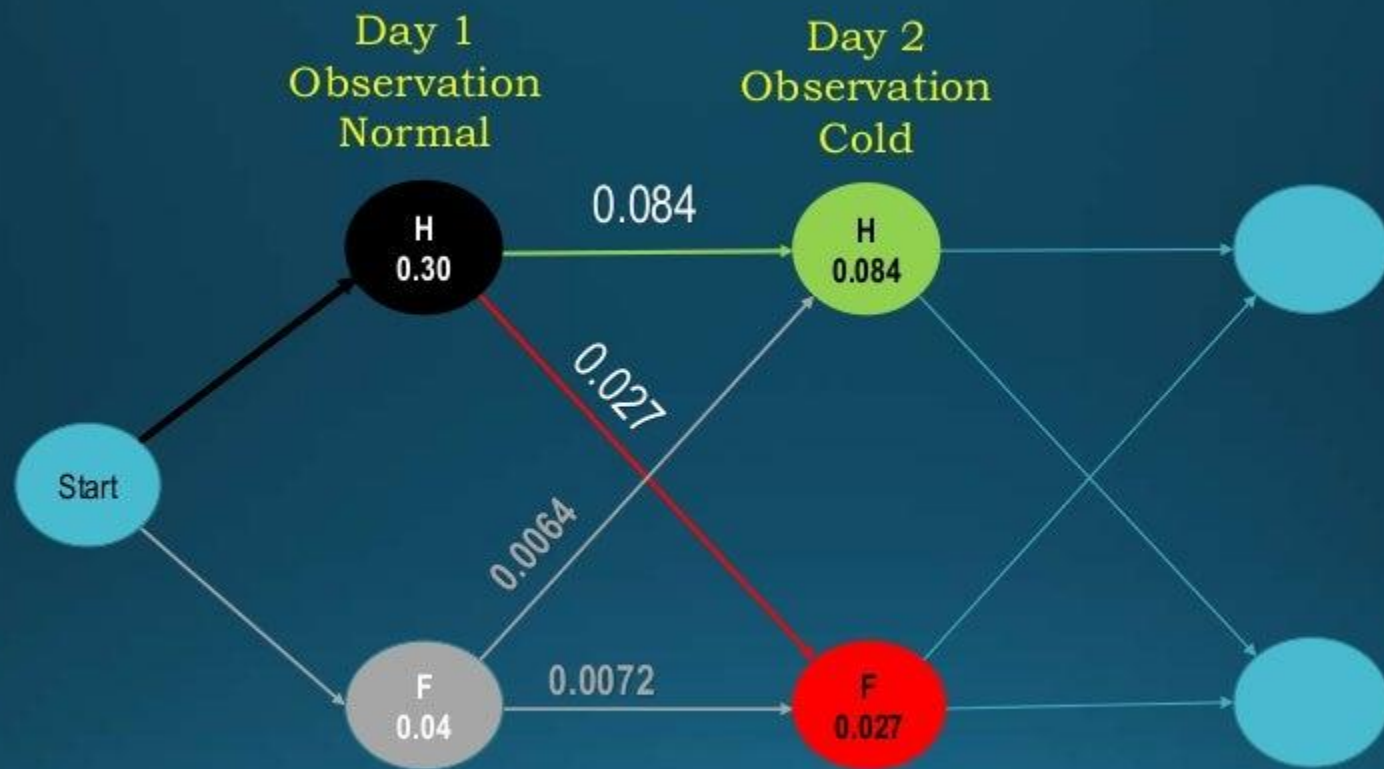
Calculate  
 $P(\text{start}) * P(\text{normal} | \text{state})$



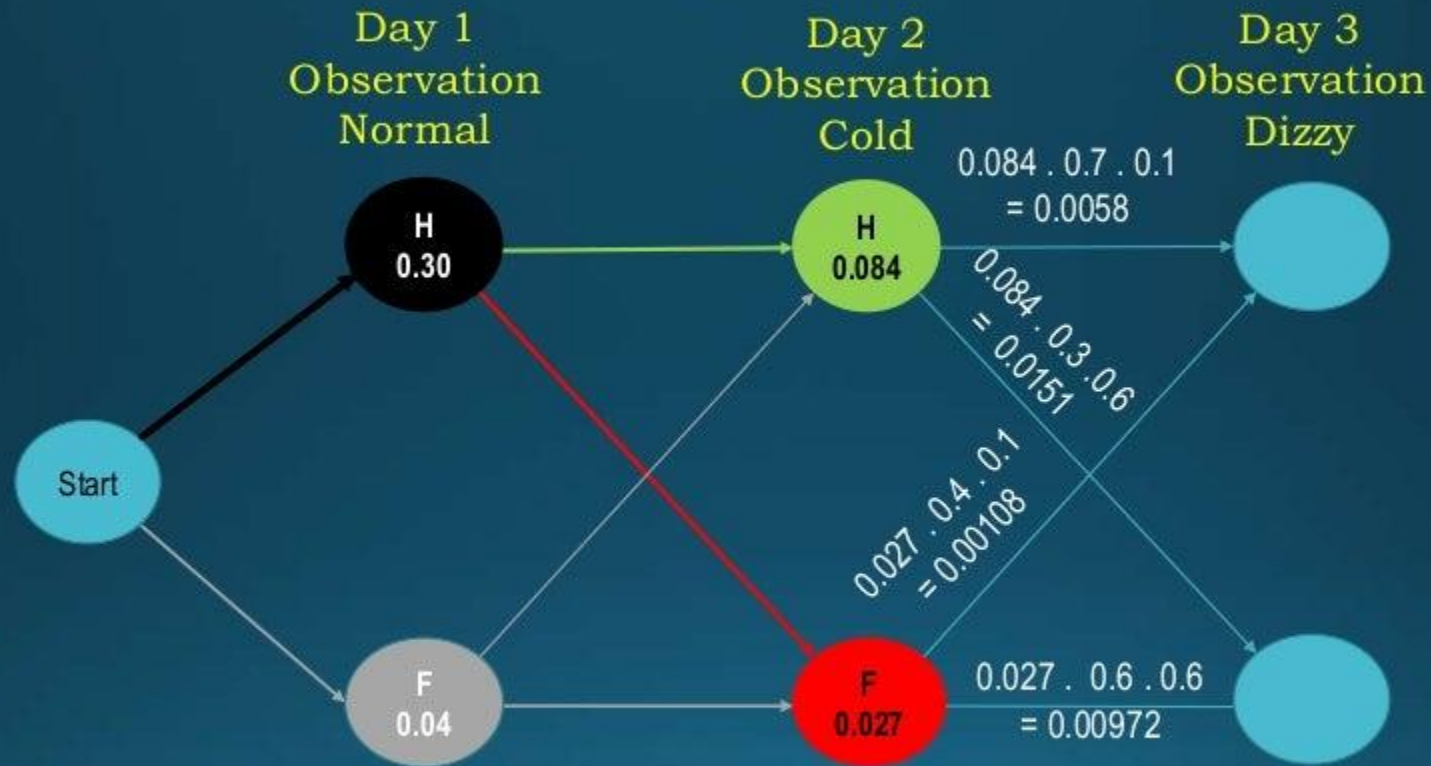
Calculate

$P(\text{old\_state}) * P(\text{old\_state} \rightarrow \text{new\_state}) * P(\text{cold} | \text{new\_state})$



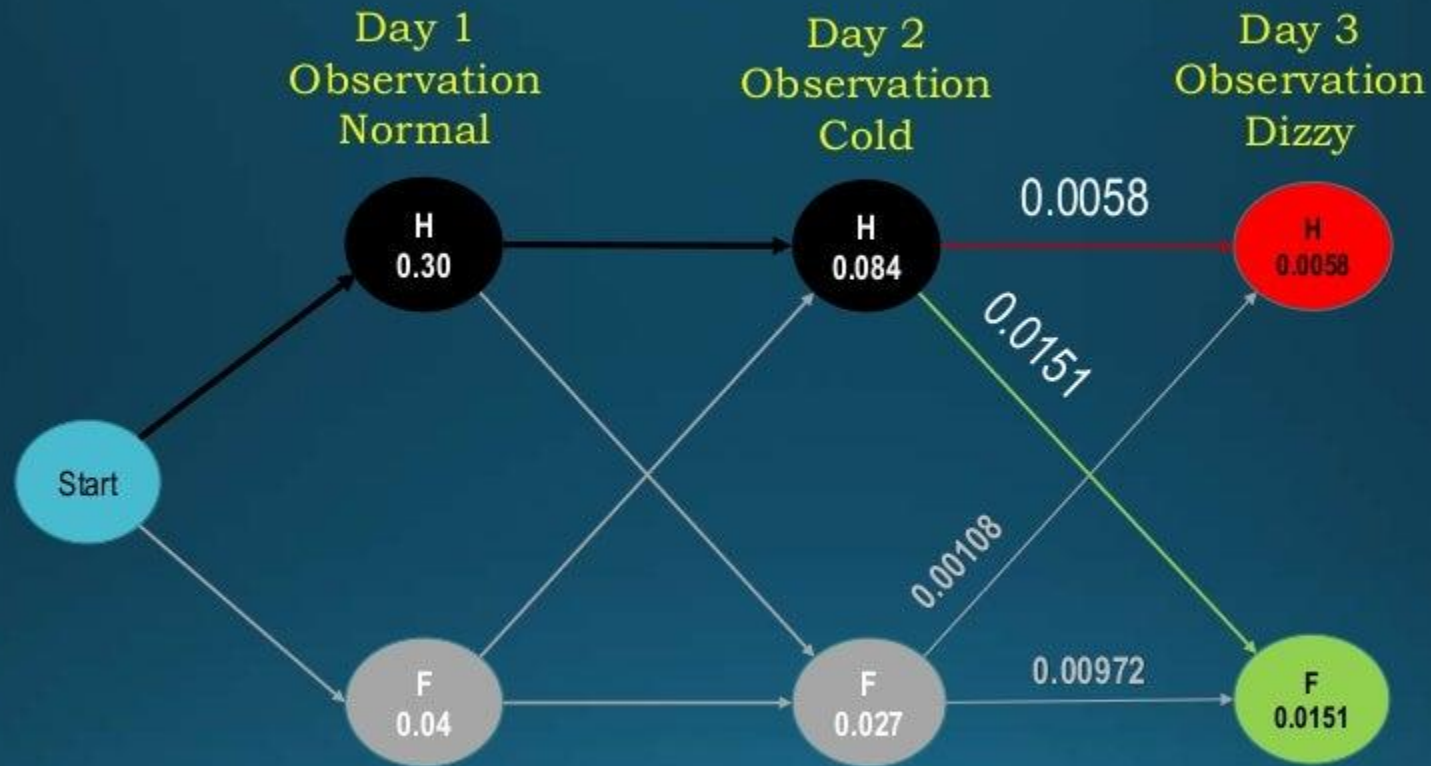


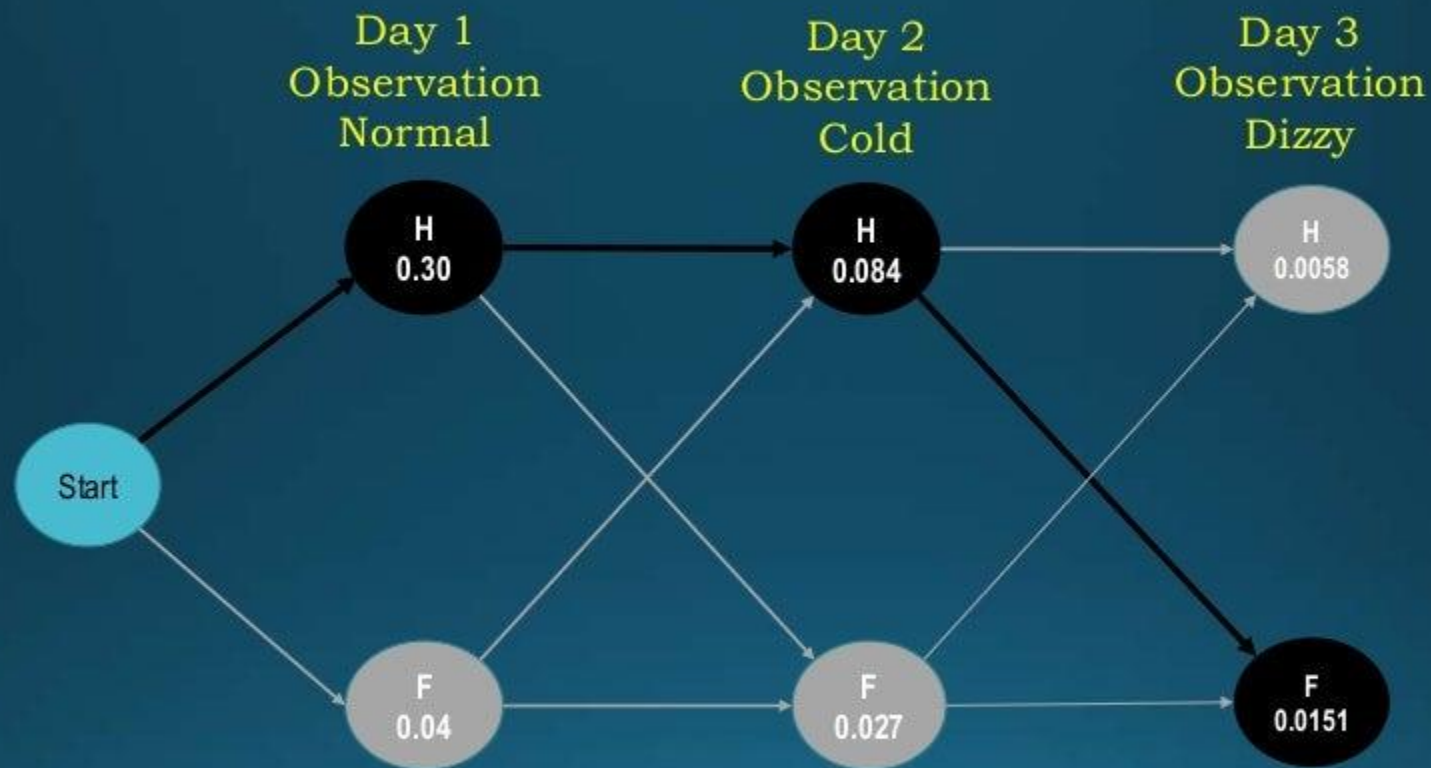
For each State H/F, Select the path with the Highest probability



Calculate

$$P(\text{old\_state}) * P(\text{old\_state} \rightarrow \text{new\_state}) * P(\text{Dizzy} \mid \text{new\_state})$$





For time step T, select the state that has the highest probability and backtrack to the path that produced the highest probability using the backpointer and return the states.



# Result

Day 1  
Observation  
Normal

( 0.30 )  
“HEALTHY”

Day 2  
Observation  
Cold

( 0.084 )  
“HEALTHY”

Day 3  
Observation  
Dizzy

( 0.0151 )  
“FEVER”

## Advantages

1. Ability to correct wrong bits transmitted by adding redundant information.
2. The State diagram offers a complete description of the system.
3. It is possible to reconstruct lost data.

## Disadvantages

1. Computation becomes complex for large number of states.
2. More bandwidth needed for redundant information.

# CONCLUSION

- Viterbi algorithm is widely used in communication.
- Use to find the hidden states of finite states Hidden Markov Model.
- Also used extensively in recognition problems

THANK YOU