Roll No:- 228622

<u>Aim</u>:- Implement Breadth First Search Algorithm for Romanian Map Problem.

CODE:-

```
import collections
def bfs(graph,root):
  seen,queue=set([root]),collections.deque([root])
  while queue:
    vertex=queue.popleft()
    visit(vertex)
    for node in graph[vertex]:
      if node not in seen:
        seen.add(node)
        queue.append(node)
def allpath(st,end,gr):
  todo=[(st,[st])]
  while len(todo):
    node,path=todo.pop(0)
    for next_node in gr[node]:
      if next node in path:
        continue
         print('Ideal solution')
      elif next_node==end:
        yield path + [next_node]
      else:
        todo.append((next_node,path + [next_node]))
```

def visit(n):

```
print(n)
def bfs_shortest_path(grah, source, destination):
  checked=[]
  queue=[[source]]
  if source == destination:
    return "SOURCE IS DESTINATION:"
  while queue:
    path=queue.pop(0)
    node=path[-1]
    if node not in checked:
      neighbours = graph[node]
      for neighbour in neighbours:
         new_path=list(path)
        new_path.append(neighbour)
        queue.append(new_path)
        if neighbour == destination:
           return new_path
      checked.append(node)
  return "PATH DOES NOT EXIST:"
graph={'Oradea': ['Zerind', 'Sibiu'],
   'Zerind':['Oradea', 'Arad'],
   'Arad': ['Zerind', 'Sibiu', 'Timisoara'],
   'Timisoara': ['Arad', 'Lugoj'],
   'Lugoj': ['Timisoara', 'Mehadia'],
   'Mehadia': ['Lugoj', 'Drobeta'],
```

```
'Drobeta': ['Mehadia', 'Craiova'],
    'Craiova': ['Drobeta', 'Rimnicu', 'Pitesti'],
    'Pitesti': ['Rimnicu', 'Craiova', 'Bucharest'],
    'Sibiu': ['Oradea', 'Fagaras', 'Rimnicu', 'Arad'],
    'Fagaras': ['Sibiu', 'Bucharest'],
    'Rimnicu': ['Sibiu', 'Pitesti', 'Craiova'],
    'Bucharest': ['Urziceni','Giurgiu'],
    'Giurgiu': ['Bucharest'],
    'Urziceni': ['Bucharest', 'Vaslui', 'Hirsova'],
    'Vaslui': ['Lasi', 'Urziceni'],
    'Lasi': ['Neamt', 'Vaslui'],
    'Neamt': ['Lasi'],
    'Hirsova': ['Urziceni', 'Eforie'],
    'Eforie': ['Hirsova']
   }
print("GRAPH TRAVERSAL: ")
bfs(graph,'Arad')
print('\n\nall paths is')
[print (x) for x in allpath ('Arad', 'Bucharest', graph)]
print("\n SHORTERT PATH OF GARPH IS: : ", bfs_shortest_path(graph, 'Arad', 'Bucharest'))
```

```
File Edit Shell Debug Options Window Help

Fython 3.10.0 (tags/v3.10.0:b494f59, Oct 4 2021, 19:00:18) [MSC v.1929 64 bit (AMD64)] on win32

Type "help", "copyright", "credits" or "license()" for more information.

- RESTART C:/Users/Siddhesh Chindarkar/OneDrive/Documents/TY Notes/Fracticals/AI/Fracticall_BFS.py

GRAPH TRAVERSAL:

Arad

Zerind
Sibiu

Timisoara
Oradea
Fagaras
Rimnicu

Debug

Mehadia
Urziceni
Calova
Mehadia
Urziceni
Giurgiu
Drobeta
Vaslui
Hari
Eforie
Neamt

all paths is

['Arad', 'Sibiu', 'Finnicu', 'Pitesti', 'Bucharest']
['Arad', 'Sibiu', 'Finnicu', 'Craiova', 'Pitesti', 'Bucharest']
['Arad', 'Sibiu', 'Finnicu', 'Craiova', 'Pitesti', 'Bucharest']
['Arad', 'Zerind', 'Oradea', 'Sibiu', 'Rimnicu', 'Craiova', 'Pitesti', 'Bucharest']
['Arad', 'Timisoara', 'Lugoj', 'Mehadia', 'Drobeta', 'Craiova', 'Pitesti', 'Bucharest']
['Arad', 'Timisoara', 'Lugoj', 'Mehadia', 'Drobeta', 'Craiova', 'Pitesti', 'Finnicu', 'Sibiu', 'Fagaras', 'Bucharest']
['Arad', 'Timisoara', 'Lugoj', 'Mehadia', 'Drobeta', 'Craiova', 'Pitesti', 'Finnicu', 'Sibiu', 'Fagaras', 'Bucharest']
['Arad', 'Timisoara', 'Lugoj', 'Mehadia', 'Drobeta', 'Craiova', 'Pitesti', 'Finnicu', 'Sibiu', 'Fagaras', 'Bucharest']

SHORTERT PATH OF GARPH IS: : ['Arad', 'Sibiu', 'Fagaras', 'Bucharest']

SHORTERT PATH OF GARPH IS: : ['Arad', 'Sibiu', 'Fagaras', 'Bucharest']
```

Roll No:- 228622

Aim:- Implement Depth First Search Algorithm for Romanian Map Problem.

CODE:-

```
graph={ 'Oradea': ['Zerind', 'Sibiu'],
     'Zerind': ['Oradea', 'Arad'],
     'Arad': ['Zerind', 'Sibiu', 'Timisoara'],
     'Timisoara': ['Arad', 'Lugoj'],
     'Lugoj': ['Timisoara', 'Mehadia'],
     'Mehadia': ['Lugoj', 'Dobreta'],
     'Dobreta': ['Mehadia', 'Craiova'],
     'Craiova': ['Dobreta', 'Pitesti', 'Rimnicu Vilcea'],
     'Pitesti': ['Rimnicu Vilcea', 'Craiova', 'Bucharest'],
     'Rimnicu Vilcea': ['Sibiu', 'Pitesti', 'Craiova'],
     'Sibiu': ['Oradea', 'Rimnicu Vilcea', 'Arad', 'Fagaras'],
     'Fagaras': ['Sibiu', 'Bucharest'],
     'Bucharest': ['Urziceni', 'Giurgiu'],
     'Giurgiu': ['Bucharest'],
     'Urziceni': ['Bucharest', 'Valsui', 'Hirsova'],
     'Valsui': ['Lasi', 'Urziceni'],
     'Lasi': ['Valsui', 'Neamt'],
     'Neamt': ['Lasi'],
     'Hirsova': ['Urziceni', 'Eforie'],
     'Eforie': ['Hirsova'],
    }
def dfs(g, n, seen, d):
  if n not in seen:
     seen.append(n)
```

```
for i in g[n]:

if seen[-1] in d:

break

dfs(g, i, seen, d)

return seen
```

print('\n The nodes --> \n Oradea, Zerind, Arad, Timisoara, Arad, Lugoj, Mehadia, Dobreta, Craiova, Pitesti, Rimnicu Vilcea, Sibiu, Fagaras, Bucharest, Giurgiu, Urziceni, Valsui, Lasi, Neamt, Hirsova, Eforie')

```
X=input("\nEnter starting node:")
Y=input("Enter goal node:")
print("The path from Starting node to goal node is givem by:")
print(dfs(graph, X, [], Y))
```

Roll No:- 228622

<u>Aim:</u>- Implement Depth Limited Search Algorithm for Romanian Map Problem.

```
graph={
'Oradea': ['Zerind', 'Sibiu'],
'Zerind':['Oradea', 'Arad'],
'Arad': ['Zerind', 'Sibiu', 'Timisoara'],
'Timisoara': ['Arad', 'Lugoj'],
'Lugoj': ['Timisoara', 'Mehadia'],
'Mehadia': ['Lugoj', 'Drobeta'],
'Drobeta': ['Mehadia', 'Craiova'],
'Craiova': ['Drobeta', 'Rimnicu', 'Pitesti'],
'Pitesti': ['Rimnicu', 'Craiova', 'Bucharest'],
'Sibiu': ['Oradea', 'Fagaras', 'Rimnicu', 'Arad'],
'Fagaras': ['Sibiu', 'Bucharest'],
'Rimnicu': ['Sibiu', 'Pitesti', 'Craiova'],
'Bucharest': ['Urziceni', 'Giurgiu'],
'Giurgiu': ['Bucharest'],
'Urziceni': ['Bucharest', 'Vaslui', 'Hirsova'],
'Vaslui': ['Lasi', 'Urziceni'],
'Lasi': ['Neamt', 'Vaslui'],
'Neamt': ['Lasi'],
'Hirsova': ['Urziceni', 'Eforie'],
'Eforie': ['Hirsova']
}
def dls(s,g,path,level,max_depth):
  print("Current Level is:",level)
```

```
print("Testing for",g+" "+"Node from",s)
  path.append(s)
  e="Max Depth Limit Reached!"
  while True:
    if level>max_depth:
      print("Current Level Reaches Maximum Depth")
      return False
    break
  if s==g:
    print("Goal Node Found!")
    return path
  print("Goal Node Test Failed!")
  print("Expanding Current Node",s)
  print("----")
  for neighbor in graph[s]:
    if dls(neighbor,g,path,level+1,max_depth):
      return path
    path.pop()
    return False
  return False
s=input("Enter Source Node=")
g=input("Enter Goal Node=")
max_depth=int(input("Enter Maximum Depth Limit="))
print()
path=list()
output=dls(s,g,path,0,max_depth)
if (output):
```

```
print("There Exists a path from source to goal")
print("Path is:",path)
else:
print("No Path From Source to Goal in given depth Limit")
```

```
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Python 3.10.0 (tags/v3.10.0:b494559, oct 4 2021, 19:00:18) [MSC v.1929 64 bit (AMD64)] on vin32

Type "help", "copyright", "credita" or "license()" for more information.

**RSTART: G:\Unsera\Siddheah Chindarkar\OneDrive\Documents\TY Notes\Practicals\AI\Practical3_DLS.py
Enter Goal Nodes\Uniterion
Enter Maximum Depth Limit:3

Current Level is: 0
Testing for Urricent Node from Hirsova
Goal Node Test Falled!
Expanding Current Node Hirsova
Current Level is: 1
Testing for Urricent Node from Urricent
Goal Node Found!
There Exists a path from source to goal
Path is: ['Hirsova', 'Urricent']

**There Exists a path from source to goal
Path is: ['Hirsova', 'Urricent']
```

Roll No:- 228622

<u>Aim:</u>- Implement Iterative Deep Depth First Search for Romanian Map Problem.

```
graph = {'Oradea': ['Zerind', 'Sibiu'],
     'Zerind': ['Oradea', 'Arad'],
     'Arad': ['Zerind', 'Sibiu', 'Timisoara'],
     'Timisoara': ['Arad', 'Lugoj'],
     'Lugoj': ['Timisoara', 'Mehadia'],
     'Mehadia': ['Lugoj', 'Drobeta'],
     'Drobeta': ['Mehadia', 'Craiova'],
     'Craiova': ['Drobeta', 'Rimnicu', 'Pitesti'],
     'Pitesti': ['Rimnicu', 'Craiova', 'Bucharest'],
     'Sibiu': ['Oradea', 'Fagaras', 'Rimnicu', 'Arad'],
     'Fagaras': ['Sibiu', 'Bucharest'],
     'Rimnicu': ['Sibiu', 'Pitesti', 'Craiova'],
     'Bucharest': ['Urziceni', 'Giurgiu'],
     'Giurgiu': ['Bucharest'],
     'Urziceni': ['Bucharest', 'Vaslui', 'Hirsova'],
     'Vaslui': ['Lasi', 'Urziceni'],
     'Lasi': ['Neamt', 'Vaslui'],
     'Neamt': ['Lasi'],
     'Hirsova': ['Urziceni', 'Eforie'],
     'Eforie': ['Hirsova']
     }
def iddfs(g, n, seen, dst, dep, lim):
  if n not in seen:
```

```
seen.append(n)
if dep <= lim:
    for i in g[n]:
        if seen[-1] is dst:
            return seen
        iddfs(g, i, seen, dst, dep + 1, lim)
    else:
        print("Maximum limit reached")
return None</pre>
```

print(iddfs(graph, 'Arad', [], 'Hirsova', 0, int(input("Enter max limit: "))))

```
File Edit Shell Debug Options Window Help

Python 3.10.0 (tags/v3.10.0:b494f59, Oct 4 2021, 19:00:18) [MSC v.1929 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more information.

>>> = RESTART: C:\Users\Siddhesh Chindarkar\OneDrive\Documents\TY Notes\Practicals\AI\Practical4_IDDFS.py
Enter max limit: 8
Maximum limit reached
['Arad', 'Zerind', 'Oradea', 'Sibiu', 'Fagaras', 'Bucharest', 'Urziceni', 'Vaslui', 'Lasi', 'Neamt', 'Hirsova']
```

Roll No:- 228622

Aim:- Implement Recursive Best First Search for Romanian Map Problem.

```
graph = {
  'Oradea': ({'Zerind':71, 'Sibiu':151},380),
  'Zerind': ({'Oradea':71, 'Arad':75},374),
  'Arad': ({'Zerind':75, 'Sibiu':140, 'Timisoara':118},366),
  'Timisoara': ({'Arad':118, 'Lugoj':111},329),
  'Lugoj': ({'Timisoara':111, 'Mehadia':70},244),
  'Mehadia': ({'Lugoj':70, 'Dobreta':75},241),
  'Sibiu': ({'Oradea':151, 'Rimnicu Vilcea':80, 'Arad':140, 'Fagaras':99},253),
  'Fagaras': ({'Sibiu':99, 'Bucharest':211},176),
  'Rimnicu Vilcea': ({'Sibiu':80, 'Pitesti':97, 'Craiova':146},193),
  'Bucharest': ({'Urziceni':85,'Fagaras':211,'Pitesti':101,'Giurgiu':90},0),
  'Dobreta': ({'Mehadia':75, 'Craiova':120},242),
  'Craiova': ({'Dobreta':120, 'Pitesti':138, 'Rimnicu Vilcea':97},160),
  'Pitesti': ({'Rimnicu Vilcea':97, 'Craiova':138, 'Bucharest':101},100),
  'Urziceni': ({'Bucharest':85, 'Valsui':142, 'Hirsova':98},80),
  'Giurgiu': ({'Bucharest':90},77),
  'Valsui': ({'Lasi':92, 'Urziceni':142},199),
  'Hirsova': ({'Urziceni':98, 'Eforie':86},151),
  'Lasi': ({'Valsui':92, 'Neamt':87},226),
  'Eforie': ({'Hirsova':86},161),
  'Neamt': ({'Lasi':87},234)
}
def greedy_search_rec(graph,prev,dst,path,q):
  # n:(h(n))
  print("Connected nodes of current node",prev,"withn h(n) values: ")
```

```
for n in graph[prev][0]: #neighbour list prev=Arad, -> Z,S,T
    if n not in path:
      q[n] = graph[n][1] #n=z [1]=374
       print(n,"->",q[n])
  while q:
    mn = min(q, key=q.get)
    print("Taking minimum h(n) vertex: ",mn)
    #print(mn)
    if dst == mn:
      return path + [dst]
    #del q[mn]
    new path = greedy search rec(graph,mn,dst,path + [mn],q)
    if new_path:
       return new_path
  return []
sourec = input("Enter the source vertex: ")
dest = input("Enter the destination vertex: ")
path = greedy_search_rec(graph,sourec,dest,[sourec],{})
if path:
  print(path)
else:
  print("Path not found")
```

Roll No:- 228622

```
la IDLE Shell 3.10.5
File Edit Shell Debug Options Window Help
   Python 3.10.5 (tags/v3.10.5:f377153, Jun 6 2022, 16:14:13) [MSC v.1929 64 bit (
   AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more information.
>>>
    = RESTART: C:\Users\Siddhesh Chindarkar\OneDrive\Documents\TY Notes\Practicals\A
    I\Practical5_Greedy Algorithm.py
    Enter the source vertex: Arad
    Enter the destination vertex: Bucharest
    Connected nodes of current node Arad withn h(n) values:
    Zerind -> 374
   Sibiu -> 253
    Timisoara -> 329
    Taking minimum h(n) vertex: Sibiu
    Connected nodes of current node Sibiu withn h(n) values:
    Oradea -> 380
   Rimnicu Vilcea -> 193
    Fagaras -> 176
   Taking minimum h(n) vertex: Fagaras
    Connected nodes of current node Fagaras withn h(n) values:
    Bucharest -> 0
   Taking minimum h(n) vertex: Bucharest
['Arad', 'Sibiu', 'Fagaras', 'Bucharest']
```

Roll No:- 228622

Aim:- Implement A* Algorithm for Romanian Map Problem.

```
graph={
  "O":({"Z":71,"S":151},380),
  "Z":({"O":71,"A":75},374),
  "A":({"Z":75,"S":140,"T":118},366),
  "T":({"A":118,"L":111},329),
  "L":({"T":111,"M":70},244),
  "M":({"L":70,"D":75},241),
  "S":({"O":151,"F":99,"RV":80,"A":140},253),
  "F":({"S":99,"B":211},176),
  "RV":({"S":80,"P":97,"C":146},193),
  "B":({"F":211,"P":101,"U":85,"G":90},0),
  "P":({"RV":97,"C":138,"B":101},100),
  "C":({"RV":146,"P":138,"D":120},160),
  "D":({"M":75,"C":120},242),
  "U":({"B":85,"V":142,"":98},80),
  "G":({"B":90},77),
  "V":({"L":92,"U":142},199),
  "H":({"U":98,"E":86},151),
  "I":({"V":92,"N":87},226),
  "E":({"H":86},161),
  "N":({"L":87},234)
  }
def get min(q):
  mn=(0,(0,float("INF")))
  for i in q:
    if sum(q[i])<sum(mn[1]):
```

```
mn=(i,q[i])
  return mn[0]
def a_star(graph,prev,dst,path,pcost,q):
  print("Connected nodes of current nodes", prev, "with h(n) values:")
  for n in graph[prev][0]:
    if n not in path:
      q[n]=(graph[n][1],graph[prev][0][n])
      print(n,"-->",q[n])
      add1=sum(q[n])
      path_cost=pcost+add1
      print("A* value for ",n,"is:",path cost)
  while q:
    mn=get_min(q)
    print("Selectiong Minimum vertex:",mn)
    print("
    if dst==mn:
      return path+[dst]
    pc=pcost+q[mn][1]
    print("Previous path cost:",pc)
    new_path=a_star(graph,mn,dst,path+[mn],pc,q)
    if new_path:
      return new_path
  return[]
source=input("Enter Source vertex:")
dest=input("Enter destination vertex:")
heuristic=int(input("Enter given heuristic value for source:"))
path=a star(graph,source,dest,[],0,{source:(heuristic,0)})
if path:
  print(path)
```

else:

print("Path is not found")

```
lDLE Shell 3.10.5
  File Edit Shell Debug Options Window Help
          Python 3.10.5 (tags/v3.10.5:f377153, Jun 6 2022, 16:14:13) [MSC v.1929 64 bit (AMD64)] on win32 Type "help", "copyright", "credits" or "license()" for more information.
        = RESTART: C:\Users\Siddhesh Chindarkar\OneDrive\Docu
Enter Source vertex:A
Enter destination vertex:B
Enter given heuristic value for source:399
Connected nodes of current nodes A with h(n) values:
Z --> (374, 75)
A* value for Z is: 449
S --> (253, 140)
A* value for S is: 393
T --> (329, 118)
A* value for T is: 447
Selectiong Minimum vertex: S
            = RESTART: C:\Users\Siddhesh Chindarkar\OneDrive\Documents\TY Notes\Practicals\AI\Practical6_Astar Algorithm.py
            Previous path cost: 140
         Previous path cost: 140
Connected nodes of current nodes S with h(n) values:
O --> (380, 151)
A* value for O is: 671
F --> (176, 99)
A* value for F is: 415
RV --> (193, 80)
A* value for RV is: 413
A --> (366, 140)
A* value for A is: 646
Selectiong Minimum vertex: RV
          Previous path cost: 220
Connected nodes of current nodes RV with h(n) values:
P --> (100, 97)
A* value for P is: 417
C --> (160, 146)
A* value for C is: 526
           Selectiong Minimum vertex: P
          Edit Shell Debug Options Window Help
         Enter destination vertex:B
Enter destination vertex:B
Enter given heuristic value for source:399
Connected nodes of current nodes A with h(n) values:
2 --> (374, 75)
A* value for Z is: 449
S --> (253, 140)
A* value for S is: 393
T --> (329, 118)
A* value for T is: 447
Selectiong Minimum vertex: S
          Previous path cost: 140
Connected nodes of current nodes S with h(n) values:
O --> (380, 151)
A* value for O is: 671
F --> (176, 99)
A* value for F is: 415
RV --> (193, 80)
A* value for RV is: 413
A --> (366, 140)
A* value for A is: 646
Selectiong Minimum vertex: RV
          Previous path cost: 220
Connected nodes of current nodes RV with h(n) values:
P --> (100, 97)
A* value for P is: 417
C --> (160, 146)
A* value for C is: 526
Selectiong Minimum vertex: P
          Previous path cost: 317
Connected nodes of current nodes P with h(n) values:
C --> (160, 138)
A* value for C is: 615
B --> (0, 101)
A* value for B is: 418
Selectiong Minimum vertex: B
            ['S', 'RV', 'P', 'B']
```

Roll No:- 228622

<u>Aim:</u>- Implement Naïve Bayes Learning Algorithm for Restaurant Waiting Problem.

```
#import operator
#data set => already taken for prediction
dataset = {
"Ans":
            ["Yes","No","Yes","Yes","No","Yes","No","Yes","No","Yes"],
"Alternate":
              ["Yes","Yes","No","No","No","Yes","No","Yes","Yes","No","Yes"],
"Bar":
           ["No","Yes","Yes","Yes","No","No","Yes","No","No","Yes","Yes","No"],
            ["Yes","No","No","No","Yes","No","Yes","Yes","Yes","No","No","Yes"],
"Fri/Sat":
             ["No","Yes","No","Yes","No","Yes","No","Yes","No","Yes","No","Yes"],
"Hungry":
"Patrons":
["Some","Full","Full","None","Full","Some","Full","Full","Some","Full","Some"],
"Price":
["High","Low","Low","Low","High","High","Low","High","Low","High","Low"],
"Raining":
             ["Yes","Yes","No","No","No","No","Yes","No","Yes","No","No"],
"Type":
["French","Thai","Burger","Italian","Italian","Thai","French","Thai","Burger","Italian","Burge
r","French"],
"WaitEstimate": ["10-30","0-10",">60","30-60","10-30","0-10",">60","30-60","30-
60",">60","10-30","0-10"]
}
#input data to test or predict
test case={
"Alternate":
             "Yes",
"Bar":
           "No",
"Fri/Sat":
            "No",
"Hungry":
             "Yes".
```

```
"Patrons":
               "Full",
"Price":
             "High",
"Raining":
               "No",
"Reservation": "No",
"Type":
              "Thai",
"WaitEstimate": "10-30"
}
def build_probs(ds, test_case):
  ans = ds["Ans"]#output attribute (ans)
  length = len(ans) #total length of output(ans)
  ans set = set(ans) #unique (individual) classes yes and no
  count_ans = {k: ans.count(k) for k in ans_set}
  calc prob = {k: count ans[k] / length for k in ans set}
  for ft in ds:
    if ft != "Ans":
       counts = {attr: {k: 0 for k in ans_set} for attr in set(ds[ft])}
       for i in range(length):
         counts[ds[ft][i]][ans[i]] +=1
       for k in ans_set:
         calc_prob[k] *= counts[test_case[ft]][k]/ count_ans[k]
  print(test_case,":\n",max(calc_prob, key=calc_prob.get))
build_probs(dataset, test_case)
```

```
File Edit Shell Debug Options Window Help

Python 3.10.5 (tags/v3.10.5:f377153, Jun 6 2022, 16:14:13) [MSC v.1929 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more information.

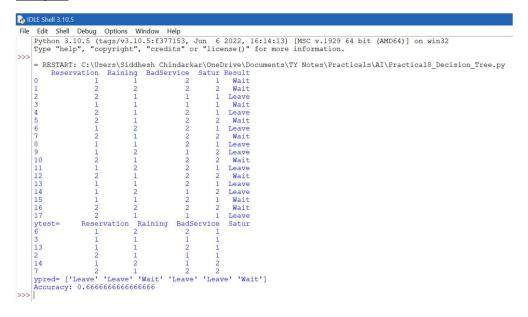
>>> = RESTART: C:\Users\Siddhesh Chindarkar\OneDrive\Documents\TY Notes\Practicals\AI\Practical7_Resturant_Waiting_Problem.py
{'Alternate': 'Yes', 'Bar': 'No', 'Fri/Sat': 'No', 'Hungry': 'Yes', 'Patrons': 'Full', 'Price': 'High', 'Raining': 'No', 'Reservation': 'No', 'Type': 'Thai', 'WaitEstimate': '10-30'}:

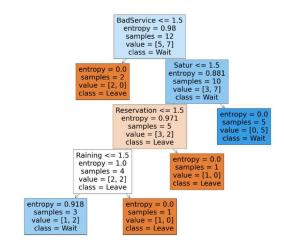
>>> |
```

Roll No:- 228622

<u>Aim:</u>- Implement Decision Tree Algorithm for the Restaurant Waiting Problem.

```
import pandas as pd
from sklearn.tree import DecisionTreeClassifier
from sklearn .model selection import train test split
from sklearn import metrics
from matplotlib import pyplot as plt
from sklearn import tree
col_names=['Reservation','Raining','BadService','Satur','Result']
hoteldata=pd.read_csv("dtree.csv",header=None,names=col_names)
feature_cols=['Reservation','Raining','BadService','Satur']
X=hoteldata[feature cols]
Y=hoteldata.Result
X_train,X_test,Y_train,Y_test,=train_test_split(X,Y,test_size=0.3,random_state=1)
print(hoteldata)
clf=DecisionTreeClassifier(criterion="entropy",max depth=5)
clf=clf.fit(X train,Y train)
Y pred=clf.predict(X test)
print("ytest=",X test)
print("ypred=",Y_pred)
print("Accuracy:",metrics.accuracy_score(Y_test,Y_pred))
fig=plt.figure(figsize=(25,20))
t=tree.plot_tree(clf,feature_names=feature_cols,class_names=['Leave','Wait'],filled=True)
fig.savefig("decistion tree.png")
```





Roll No:- 228622

Aim:- Implement Majority Voting Classifier in Ensemble Learning.

```
Code:-
import numpy as np
from numpy import *
from sklearn import datasets
from sklearn import model selection
from sklearn.ensemble import RandomForestClassifier
from sklearn.ensemble import VotingClassifier
from sklearn.linear_model import LogisticRegression
from sklearn.naive_bayes import GaussianNB
from sklearn.tree import DecisionTreeClassifier
import warnings
warnings.filterwarnings("ignore")
iris=datasets.load_iris()#iris dataset 5cols
x,y=iris.data[:,1:3],iris.target#first paramete for row, and second for col,here: in row is for
all row
m1=LogisticRegression(random state=1)
```

labels=['Logistic Regression','Random Forest', 'Naive Bayes', 'Decision Tree'] for m, label in zip([m1,m2,m3,m4],labels):
 scores=model_selection.cross_val_score(m,x,y,cv=5,scoring='accuracy')
 print("Accuracy: %0.2f [%s]" %(scores.mean(), label))

voting clf hard=VotingClassifier(estimators=[(labels[0],m1),

(labels[1],m2),

m2=RandomForestClassifier(random_state=1)

m3=GaussianNB()

m4=DecisionTreeClassifier()

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(labels[2],m3),
(labels[3],m4)],
voting='hard')
```

scores1=model_selection.cross_val_score(voting_clf_hard,x,y,cv=5,scoring='accuracy')
print("Accuracy of combined Model Using Hard Voting: %0.2f" %(scores1.mean()))

```
File Edit Shell Debug Options Window Help

Python 3.10.5 (tags/v3.10.5:f377153, Jun 6 2022, 16:14:13) [MSC v.1929 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more information.

>>>

= RESTART: C:\Users\Siddhesh Chindarkar\OneDrive\Documents\TY Notes\Practicals\A I\Practical9_Ensemble_Learning.py Accuracy: 0.95 [Logistic Regression] Accuracy: 0.94 [Random Forest] Accuracy: 0.91 [Naive Bayes] Accuracy: 0.93 [Decision Tree] Accuracy of combined Model Using Hard Voting: 0.95
```