SpawnBoxNode

-rclcpp::Client::SharedPtr spawn_client_
-rclcpp::Client::SharedPtr send_coordinates_client_
-std::pair x_range_
-std::pair y_range_
-double spawn_x_
-double spawn_y_

+SpawnBoxNode()
+spawn_box()
+send_coordinates()
+is_valid_spawn(x: double, y: double): bool
+print_spawn_coordinates()
+random_value(min: double, max: double): double