4. Helper Function Definitions 5. Weight Initializations 6. Forward Propagation 7. Back Propagation 8. Update the parameters 9. Neural Network Model Definition 10. Predict Output 11. Putting Everything Together 11.1. Variation of Cost with Number of Iterations 11.2. Accuracy on the Test Set 1. Introduction In this notebook, we will attempt to train a two-layer neural network to identify correctly the handwritten digit. While the images of the dataset will comprise only a single handwritten digit, it will go a long way in illustrating the power of a shallow neural network and lay the groundwork for moving to more complex and interesting applications of this technology. And now lets get started! 2. Reading in the data The first task is to import utf-8 encoded data, decompress it and store it in a numpy array of the correct dimensions. There are supposed to be 60000 examples in the training set and 10000 examples in the test set. In [1]: import numpy as np from tgdm import tgdm import matplotlib.pyplot as plt %matplotlib inline In [2]: def load\_data(): This function returns training and test features and labels Arguments: None Returns: training\_images, training\_labels, test\_images, test\_labels import gzip with open("./Data/train-images-idx3-ubyte.gz", 'rb') as f: training\_images = np.frombuffer(gzip.decompress(data), dtype=np.uint8).copy() with open("./Data/train-labels-idx1-ubyte.gz", 'rb') as f: training\_labels = np.frombuffer(gzip.decompress(data), dtype=np.uint8).copy() with open("./Data/t10k-images-idx3-ubyte.gz", 'rb') as f: data = f.read()test\_images = np.frombuffer(gzip.decompress(data), dtype=np.uint8).copy() with open("./Data/t10k-labels-idx1-ubyte.gz", 'rb') as f: data = f.read()test\_labels = np.frombuffer(gzip.decompress(data), dtype=np.uint8).copy() return training\_images[16:].reshape((-1,28,28)), np.squeeze(training\_labels[8:]), test\_images[16:].reshape((-1,28,28)), np.squeeze(test\_labels[8:]) training\_images, training\_labels, test\_images, test\_labels = load\_data() I'll first validate the data that has been read to confirm that indeed the data is in the form that I expect it to be in (need to do this since the original data wasn't exactly divisible by 784 which led me to drop the first few pixel values and also dropped the first few values of labels as evident from the function I have written. This is just a sanity check to ensure that the dropped pixels and labels don't cause any shift in the pixel values that belong to a particular example) In [4]: print(training\_images.shape) print(training\_labels.shape) print(test\_images.shape) print(test\_labels.shape) training\_images = training\_images[:1000] training\_labels = training\_labels[:1000] test\_images = test\_images[:200] test\_labels = test\_labels[:200] print(f'Number of unique pixel values in the training set:{len(np.unique(training\_images.reshape((training\_images.shape[0], -1))))}') print(f'Number of unique pixel values in the test set:{len(np.unique(test\_images.reshape((test\_images.shape[0], -1))))}') print(f'Number of unique labels in training set:{len(np.unique(training\_labels))}\nNumber of unique labels in test set:{len(np.unique(test\_labels))}') plt.figure(figsize=(10,10)) for i in range(25): plt.subplot(5,5, i+1)plt.xticks([]) plt.yticks([]) plt.grid(False) plt.imshow(training\_images[i], cmap=plt.cm.binary) plt.xlabel(training\_labels[i]) (60000, 28, 28) (60000,)(10000, 28, 28) (10000,)Number of unique pixel values in the training set:256 Number of unique pixel values in the test set:256 Number of unique labels in training set:10 Number of unique labels in test set:10 Aaand its a resounding yes! We can now proceed to the next step in our deep learning journey and that is deciding on the model. We will also have to reshape the images in the datasets to one dimensional vectors instead of the two-dimensional form they are in now (why didn't we do this earlier? - because I wanted to be sure that everything was matching up) Note that henceforth we will be taking a subset of the training and test data since that is more than sufficient for the application we are using the data for. 3. Choice of model Now here's the tricky bit! Since its a 2 layer Neural Network that we're confined to, the one hyperparameter we can play around with is the number of units in each hidden layer. It might need a fair bit of tuning to arrive at a combination that is optimal for our application. **Proposed Architecture for Neural Network** Proposed Architecture Now that we have the general architecture ready, we can proceed to the specifics We will set: 1. Learning rate  $\alpha$  of 0.1 2. Number of units in hidden layer  $(n^{[1]})$ as 512 3. Number of iterations or epochs as 500 4. Hidden layer activation function is taken as the relu function 5. Output layer activation function is the softmax function 4. Helper Function Definitions Here we will define certain common functions that will prove to be useful during the forward and backward propagation steps of training the neural network. The functions that we will define in this section are: 1. Flatten and reshape Training and Test features 2. One hot vector representation for Y 3. Sigmoid Activation Function (as well as derivative and cost function for backpropagation) 4. Tanh function(as well as derivative for backpropagation) 5. Relu function (as well as derivative for backpropagation) 6. Softmax Function In [5]: def reshape\_X(X): Reshape training and test features and convert each example from two to one-dimensional form Arguments: Training or test data Returns: Vector containing flattened examples return X.reshape(X.shape[0], -1).T/255 def one\_hot\_encoding(Y): Convert labels to its appropriate one-hot encoding representation Arguments: training or test labels Returns: One-hot representation of labels in appropriate format shape = (len(Y), Y.max() + 1)one\_hot\_Y = np.zeros(shape) rows = np.arange(Y.size) one\_hot\_Y[rows, Y] = 1return one\_hot\_Y.T def sigmoid(z): Sigmoid activation function implementation Arguments: Linear function that is to be converted to a non-linear form Returns: Sigmoid vector s = 1/(1 + np.exp(-z))return s def relu(z): ReLU activation function implementation Arguments: Linear function that is to be converted to a non-linear form Returns: ReLU vector r = np.maximum(0,z)return r def tanh(z): Tanh activation function implementation Arguments: Linear function that is to be converted to a non-linear form Returns: Tanh vector exp1 = np.exp(z)exp2 = np.exp(-z)t = (exp1 - exp2)/(exp1 + exp2)return t def softmax(z): Softmax activation function implementation Arguments: Linear function that is to be converted to a non-linear form Returns: Softmax vector  $e_x = np.exp(z - np.max(z))$  $softmax = e_x/np.sum(e_x, axis = 0, keepdims = True)$ return softmax def sigmoid\_prime(z): The first derivative of the sigmoid activation layer Arguments: Two options: one using A and the other using Z. We have chosen the one using Z since that is assumed to be passed between the forward and backward propagation step Returns: The first derivative of the activation function vector with respect to Z  $s_{prime} = np.exp(-z)/(1+np.exp(-z))**2$ return s\_prime def relu\_prime(z): The first derivative of the relu activation layer Arguments: Two options: one using A and the other using Z. We have chosen the one using Z since that is assumed to be passed between the forward and backward propagation step Returns: The first derivative of the activation function vector with respect to Z  $r_{prime} = (z > 0) * 1$ return r\_prime def tanh\_prime(z): The first derivative of the tanh activation layer Arguments: Two options: one using A and the other using Z. We have chosen the one using Z since that is assumed to be passed between the forward and backward propagation step Returns: The first derivative of the activation function vector with respect to Z  $t_{prime} = 1 - ((tanh(z))**2)$ return t\_prime def softmax\_prime(z): The first derivative of the softmax activation layer Arguments: Two options: one using A and the other using Z. We have chosen the one using Z since that is assumed to be passed between the forward and backward propagation step Returns: The first derivative of the activation function vector with respect to Z signal = softmax(z)softmax\_prime = np.multiply( signal, 1 - signal ) + sum(- signal \* np.roll( signal, i, axis = 1 ) for i in range(1, signal.shape[1] )) return softmax\_prime def softmax\_loss\_function(A, Y): Loss function for the output layer Arguments: Output vector of the softmax and one-hot encoded Y Returns: Loss vector for softmax activation layer loss = -np.sum(np.dot(Y, np.log(A).T))/Y.shape[1]loss = -np.sum(np.sum(Y \* np.log(A), axis = 1))/Y.shape[1]return loss def sigmoid\_loss\_function(A, Y): Loss function for the output layer Arguments: Output vector of the softmax and one-hot encoded Y Returns: Loss vector for softmax activation layer loss = -np.sum(Y \* np.log(A) + (1-Y)\*np.log(1-A), axis = 1)/Y.shape[1]return loss 5. Weight Initialization In this section, we will define the number of layers and number of units in each layer and initialize the weights and biases corresponding to each layer def initialize\_parameters(layer\_units): Initialize the weights and biases of the different layers in the neural network Arguments: List containing the number of units in each layer as well as the number of features in the input layer Returns: Dictionary containing parameters corresponding to the different layers in the neural network np.random.seed(3) parameters = {} L = len(layer\_units) for i in range(1,L): parameters["W"+str(i)] = np.random.randn(layer\_units[i], layer\_units[i-1]) \* 0.01 parameters["b"+str(i)] = np.random.randn(layer\_units[i], 1) \* 0.01 **return** parameters 6. Forward Propagation In this section we will define all functions that will be helpful during forward propagation In [7]: def forward\_propagation\_linear(A\_prev, W, b): Computes the value of Z - the input to the activation function Arguments: The activations from the previous layer and the weights and biases of the current layer  $Z = np.dot(W, A\_prev) + b$ return Z def forward\_propagation\_activation(A\_prev,W, b, activation = "sigmoid"): Converts linear function to a non-linear form as per activation function chosen Arguments: Linear vector output from perceptron and choice of activation function Returns: Activation vector of the layer if activation=="sigmoid": Z = forward\_propagation\_linear(A\_prev, W, b) A = sigmoid(Z)elif activation=="softmax": Z = forward\_propagation\_linear(A\_prev, W, b) A = softmax(Z)elif activation=="tanh": Z = forward\_propagation\_linear(A\_prev, W, b) A = tanh(Z)elif activation=="relu": Z = forward\_propagation\_linear(A\_prev, W, b) cache = {"Z":Z, "A\_prev":A\_prev, "W": W, "b":b, "activation": activation} return A, cache def forward\_propagation\_model(X\_train, parameters, activations\_list): The complete forward propagation step Arguments: Input Training features, the parameters corresponding to each layer and a list containing activation functions for each layer Returns: Activation of the final layer as well the caches (defined in forward\_propagation\_activation function) list L = len(parameters) - 1caches = [] $A = X_{train}$ for i in range(1, L):  $A_prev = A$ A, cache = forward\_propagation\_activation(A\_prev, parameters["W"+str(i)], parameters["b"+str(i)], activations\_list[i-1]) return A, caches Before moving to implement back-propagation, we need to ensure that the functions defined above work as intended # Reshape training\_images training\_images\_flatten = reshape\_X(training\_images) # Convert training\_labels to one hot encoding format training\_labels\_one\_hot = one\_hot\_encoding(training\_labels) # Initialise parameters parameters = initialize\_parameters([training\_images\_flatten.shape[0], 512, 10]) AL, caches = forward\_propagation\_model(training\_images\_flatten, parameters, ["relu", "softmax"]) cost = softmax\_loss\_function(AL, training\_labels\_one\_hot) print(cost) 2.302116721777529 Thus begins our journey to reduce this cost vector. 7. Back Propagation In this section we will define the essential functions that we'll be using in the back propagation step. def back\_propagation\_linear(dZ, A\_prev, W, b): Calculate the derivative of the loss function with respect to the activation, weights and biases that can be used in gradient descent Arguments: Derivative of linear function (Z) of the current layer, activation vector of the previous layer, weights and biases of the current layer Returns: Derivative wrt activation of the previous layer, derivative wrt weights and biases of the current layer  $m = A_prev.shape[1]$  $dW = np.dot(dZ, A\_prev.T)/m$ db = np.sum(dZ, axis = 1, keepdims = True)/m $dA_prev = np.dot(W.T, dZ)$ return dA\_prev, dW, db def back\_propagation\_activation(dA, Z, A\_prev, W, b, activation\_function = "sigmoid"): Calculate the derivative of the loss function with respect to the activation, weights and biases that can be used in gradient descent Arguments: Derivative wrt activation function of the current layer, linear function (Z) of the current layer, activation vector of the previous layer, weights and biases of the Returns: Derivative wrt activation of the previous layer, derivative wrt weights and biases of the current layer  $m = A_prev.shape[1]$ if activation\_function == "sigmoid":  $dZ = dA * sigmoid_prime(Z)$ dA\_prev, dW, db = back\_propagation\_linear(dZ, A\_prev, W, b) elif activation\_function == "relu":  $dZ = dA * relu_prime(Z)$ dA\_prev, dW, db = back\_propagation\_linear(dZ, A\_prev, W, b) elif activation\_function == "tanh":  $dZ = dA * tanh_prime(Z)$ dA\_prev, dW, db = back\_propagation\_linear(dZ, A\_prev, W, b) elif activation\_function == "softmax":  $dZ = dA * softmax_prime(Z)$ dA\_prev, dW, db = back\_propagation\_linear(dZ, A\_prev, W, b) return dA\_prev, dW, db def back\_propagation\_model(AL, Y, caches): Computes the gradient dictionary of all the layers in the network Arguments: Activation vector of the final layer, labels in one hot encoding and the cache list Returns: The gradients of the different layers in the network gradients = {} L = len(caches)if caches[L-1]["activation"] == "sigmoid": dAL = - (np.divide(Y, AL) - np.divide(1 - Y, 1 - AL)) $gradients["dA"+str(L-1)], gradients["dW"+str(L)], gradients["db"+str(L)] = back_propagation_activation(dA = dAL, delta)$ Z = caches[L-1]["Z"], $A_{prev} = caches[L-1]["A_{prev}"],$ W = caches[L-1]["W"],b = caches[L-1]["b"],activation\_function=caches[L-1]["activation"]) elif caches[L-1]["activation"] == "softmax": dZL = AL - Y $gradients["dA"+str(L-1)], gradients["dW"+str(L)], gradients["db"+str(L)] = back_propagation_linear(dZ = dZL,$  $A_{prev} = caches[L-1]["A_{prev}"],$ W = caches[L-1]["W"],b = caches[L-1]["b"])for 1 in reversed(range(L-1)): cache = caches[1] $gradients["dA"+str(1)], gradients["dW"+str(1+1)], gradients["db"+str(1+1)] = back_propagation_activation(gradients["dA"+str(1+1)], gradients["dA"+str(1+1)], gradients["dA"+str(1+1)], gradients["dA"+str(1+1)] = back_propagation_activation(gradients["dA"+str(1+1)], gradients["db"+str(1+1)] = back_propagation_activation(gradients["dA"+str(1+1)], gradients["db"+str(1+1)] = back_propagation_activation(gradients["dA"+str(1+1)], gradients["db"+str(1+1)] = back_propagation_activation(gradients["dA"+str(1+1)], gradients["db"+str(1+1)] = back_propagation_activation(gradients["dB"+str(1+1)], gradients["db"+str(1+1)] = back_propagation_activation(gradients["dB"+str(1+1)], gradients["dB"+str(1+1)] = back_propagation_activation(gradients["dB"+str(1+1)], gradients["dB"+str(1+1)], gradients["dB"+str(1$ cache["Z"], cache["A\_prev"], cache["W"], cache["b"], cache["activation"]) return gradients 8. Update the parameters Here we will define the function to update the weights and biases in each layer as per the gradients computed in the back propagation step. In [10]: def update\_parameters(parameters, gradients, learning\_rate): Update the weights and biases using the gradients from the back propagation step Arguments: Parameters of all the layers, Gradients from all the layers and the learning\_rate Returns: Updated value of parameters that moves to minimize the cost function for i in range(1, len(parameters)-1): parameters["W"+str(i)] = parameters["W"+str(i)] - (learning\_rate \* gradients["dW"+str(i)]) parameters["b"+str(i)] = parameters["b"+str(i)] - (learning\_rate \* gradients["db"+str(i)]) return parameters We will write a small function to test the accuracy of the model so as to confirm movement in the correct direction In [11]: def accuracy\_score(AL, labels = training\_labels): Computes the accuracy of the predictions wrt the labels Arguments: Activations from the final layer and training labels Returns: Accuracy score in percentage  $AL_{to}$ \_numbers = np.argmax(AL, axis = 0)accuracy = np.sum(AL\_to\_numbers == labels)/labels.shape[0] return accuracy \* 100 9. Neural Network Model Definition We've arrived!! Well atleast almost. All that remains is to combine the different functions we have defined in the course of this notebook to form the neural network model and viola! - we'll have what we were looking for. In [12]: def neural\_network\_model(training\_images, training\_labels, layer\_units, activations\_list, learning\_rate = 0.1, num\_iterations = 500): Combines all the helper function to realise the neural network as per inputs provided Arguments: Training features and labels, number of units in each layer, type of activation function in each layer, learning rate and number of iterations Returns: Accuracies, costs and updated parameters # Reshape training\_images training\_images\_flatten = reshape\_X(training\_images) # Convert training\_labels to one hot encoding format training\_labels\_one\_hot = one\_hot\_encoding(training\_labels) # Initialise parameters parameters = initialize\_parameters(layer\_units) costs = [] accuracies = [] for i in tqdm(range(num\_iterations)): AL, caches = forward\_propagation\_model(training\_images\_flatten, parameters, activations\_list) accuracy = accuracy\_score(AL, training\_labels) if activations\_list[len(activations\_list)-1] =="softmax": cost = softmax\_loss\_function(AL, training\_labels\_one\_hot) elif activations\_list[len(activations\_list)-1] == "sigmoid": cost = sigmoid\_loss\_function(AL, training\_labels\_one\_hot) costs.append(cost) **if** i % 100 == 0: accuracies.append(accuracy) gradients = back\_propagation\_model(AL, training\_labels\_one\_hot, caches) parameters = update\_parameters(parameters, gradients, learning\_rate) accuracies.append(accuracy) return accuracies, costs, parameters At this stage it would be great to do a sanity check to ensure everything is working properly In [13]: layer\_units = [reshape\_X(training\_images).shape[0], 512, 10] activation\_list = ["relu", "softmax"] learning\_rate = 0.1 num iterations = 250accuracies, costs, parameters = neural\_network\_model(training\_images, training\_labels, layer\_units, activation\_list, learning\_rate, num\_iterations) print('The accuracy on the training set after training is {0:.2f}%'.format(accuracies[len(accuracies)-1])) The accuracy on the training set after training is 92.40% 10. Predict Output In this section, we will define the function to predict the output. In [14]: def predict(X\_flatten, parameters, activations\_list): Calculates the activation vector for the test data Arguments: Input Features, trained weights and parameters and activations of each layer Returns: Predicted number of neural network AL, caches = forward\_propagation\_model(X\_flatten, parameters, activations\_list)  $AL_{to_numbers} = np.argmax(AL, axis = 0)$ return AL\_to\_numbers In [15]: predictions = predict(reshape\_X(test\_images), parameters, activation\_list) accuracy = np.sum(predictions == test\_labels)/test\_labels.shape[0] print(f'The accuracy on the test set after training is {accuracy\*100}%') The accuracy on the test set after training is 87.5% 11. Putting Everything Together Which brings us to the final section of the project. Here we will finally train the model on the training set and use it for making predictions on the test set and explore some salient details about the model In [16]: layer\_units = [reshape\_X(training\_images).shape[0], 512, 10] activation\_list = ["relu", "softmax"] learning\_rate = 0.1 num\_iterations = 500 accuracies, costs, parameters = neural\_network\_model(training\_images, training\_labels, layer\_units, activation\_list, learning\_rate, num\_iterations) print('The accuracy on the training set after training is {0:.2f}%'.format(accuracies[len(accuracies)-1])) 500/500 [00:23<00:00, 21.37it/s] The accuracy on the training set after training is 97.10% 11.1. Variation of Cost with number of iterations The costs can be plotted to check how they vary per iteration and confirm whether the costs are indeed reducing in general In [17]: plt.plot(costs) plt.xlabel("Number of iterations") ticks = range(1,519, 25)tick\_labels = [str(tick - 1) if tick!=1 else str(tick) for tick in ticks] plt.xticks(ticks, tick\_labels, rotation = 45) plt.yticks(np.linspace(0,2.5,10)) plt.title("Variation of Cost with Number of iterations") plt.ylabel('Softmax Cost') plt.grid() Variation of Cost with Number of iterations 2.500 2.222 1.944 1.667 1.389 1.111 0.833 0.556 0.278 0.000 > \$ \$ \$ \$\phi\_{\infty}\sight\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\ph\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi\_{\infty}\phi Number of iterations 11.2. Accuracy on the Test Set Accuracy on the test set is another important metric to confirm that we have not overfitted our model to have high variance and hence the model is not generalizable. In [18]: predictions = predict(reshape\_X(test\_images), parameters, activation\_list) accuracy = np.sum(predictions == test\_labels)/test\_labels.shape[0] print(f'The accuracy on the test set after training is {accuracy\*100}%') The accuracy on the test set after training is 91.5% So we have not overfitted our model on the training data. Also our initial assumptions for learning rate, activation functions, number of units in the layers and number of iterations have yielded some really good results!

**Demystifying Neural Networks** 

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1. Introduction