Low Light Enhancement using Deep Retinex Decomposition

Images have a wide range of applications in the field of engineering like in medical field, remote sensing, transmission and encoding, machine vision, robotics, pattern recognition, etc.

In some cases, the images captured by cameras contains blur, noise and low lightness in it. This causes difficulty to viewer in extracting the information from it. There can be many causes of this problem like low light environment, poor performance of the equipment, inappropriate configurations of the equipment.

The objective of this case study is to build a model (Deep Retinex Decomposition model) using deep learning techniques like CNN, Encoder-decoder that will learn from the existing dataset of low and high quality images and will be able to convert any poor quality image given to it into the high quality image.

```
!pip install tensorflow==1.15.0

import numpy as np
import matplotlib.pyplot as plt
import tensorflow as tf
import time
import os
import random
from PIL import Image
from glob import glob
from tqdm import tqdm
import pickle
```

Exploratory data analysis

https://github.com/weichen582/RetinexNet

The dataset named LOL (LOw Light paired) dataset used for the problem is taken from the above link. It contains 5000 low/normal light images pairs of different kinds such as household appliances, toys, books, garden, food items, playground, clubs, streets etc.

These raw images are resized to 128*128 and converted to Portable Network Graphics format.

Below figure shows the subset of these images.



```
def load_images(file):
    im = Image.open(file)
    newsize = (128, 128)
    im = im.resize(newsize)
    return np.array(im, dtype="float32") / 255.0
```

Training data

```
train_low_data_names = glob('/content/drive/MyDrive/Case_study_2/data_2/low/*.png')
train low data names.sort()
train high data names = glob('/content/drive/MyDrive/Case study 2/data 2/high/*.png')
train high data names.sort()
assert len(train_low_data_names) == len(train_high_data_names)
train low data = []
train_high_data = []
for idx in tqdm(range(5000)):
#for idx in tqdm(range(len(train_low_data_names))):
   low im = load images(train low data names[idx])
   train_low_data.append(low_im)
   high_im = load_images(train_high_data_names[idx])
   train high data.append(high im)
    100% | 5000/5000 [00:20<00:00, 248.60it/s]
print('Number of training data points: %d' % len(train_low_data))
    Number of training data points: 5000
```

Testing data

Sample low light and high light image

```
low_img = train_low_data[200]
print("Shape of the image", low_img.shape)

Shape of the image (128, 128, 3)

plt.imshow(low_img[ : , : , :])

<matplotlib.image.AxesImage at 0x7fb535c1f390>

0
20 -
40 -
60 -
80 -
100 -
120 -
```

20

40

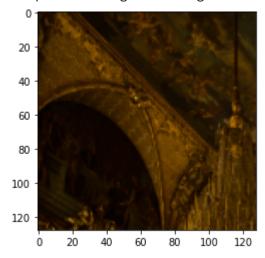
60

80

100

120

<matplotlib.image.AxesImage at 0x7fb535706a50>



▼ Observations from EDA

Dataset for training contains 5000 images, each of one is an RGB image with size 128×128×3.

Dataset for testing contains 15 images, each of one is an RGB image with size 128×128×3.

For each image, we have a pair of low and high light image.

Decomposition

```
with tf.variable scope('DecomNet', reuse=tf.AUTO REUSE):
        conv = tf.layers.conv2d(input im, channel, kernel size * 3, padding='same', activatio
        for idx in range(layer num):
            conv = tf.layers.conv2d(conv, channel, kernel size, padding='same', activation=tf
        conv = tf.layers.conv2d(conv, 4, kernel_size, padding='same', activation=None, name='
   R = tf.sigmoid(conv[:,:,:,0:3])
   L = tf.sigmoid(conv[:,:,:,3:4])
   return R, L
def RelightNet(input L, input R, channel=64, kernel size=3):
    input im = concat([input R, input L])
   with tf.variable scope('RelightNet', reuse=tf.AUTO REUSE):
        conv0 = tf.layers.conv2d(input_im, channel, kernel_size, padding='same', activation=N
        conv1 = tf.layers.conv2d(conv0, channel, kernel_size, strides=2, padding='same', acti
        conv2 = tf.layers.conv2d(conv1, channel, kernel size, strides=2, padding='same', acti
        conv3 = tf.layers.conv2d(conv2, channel, kernel size, strides=2, padding='same', acti
        up1 = tf.image.resize nearest neighbor(conv3, (tf.shape(conv2)[1], tf.shape(conv2)[2]
        deconv1 = tf.layers.conv2d(up1, channel, kernel_size, padding='same', activation=tf.n
        up2 = tf.image.resize nearest neighbor(deconv1, (tf.shape(conv1)[1], tf.shape(conv1)[
        deconv2= tf.layers.conv2d(up2, channel, kernel size, padding='same', activation=tf.nn
        up3 = tf.image.resize nearest neighbor(deconv2, (tf.shape(conv0)[1], tf.shape(conv0)[
        deconv3 = tf.layers.conv2d(up3, channel, kernel_size, padding='same', activation=tf.n
        deconv1 resize = tf.image.resize nearest neighbor(deconv1, (tf.shape(deconv3)[1], tf.
        deconv2_resize = tf.image.resize_nearest_neighbor(deconv2, (tf.shape(deconv3)[1], tf.
        feature gather = concat([deconv1 resize, deconv2 resize, deconv3])
        feature fusion = tf.layers.conv2d(feature gather, channel, 1, padding='same', activat
        output = tf.layers.conv2d(feature_fusion, 1, 3, padding='same', activation=None)
   return output
def data augmentation(image, mode):
   if mode == 0:
        # original
        return image
   elif mode == 1:
       # flip up and down
        return np.flipud(image)
   elif mode == 2:
        # rotate counterwise 90 degree
        return np.rot90(image)
   elif mode == 3:
        # rotate 90 degree and flip up and down
        image = np.rot90(image)
        return np.flipud(image)
   elif mode == 4:
        # rotate 180 degree
        return np.rot90(image, k=2)
```

```
elif mode == 5:
       # rotate 180 degree and flip
        image = np.rot90(image, k=2)
        return np.flipud(image)
   elif mode == 6:
        # rotate 270 degree
        return np.rot90(image, k=3)
   elif mode == 7:
        # rotate 270 degree and flip
        image = np.rot90(image, k=3)
        return np.flipud(image)
class lowlight_enhance:
 def __init__(self, train_low_data, train_high_data, eval_low_data, batch_size, patch_size,
   self.DecomNet layer num = 5
    self.sess = tf.Session()
   self.train low data = train low data
   self.train high data = train high data
   self.eval low data = eval low data
   self.batch size = batch size
   self.patch size = patch size
    self.epoch = epoch
   self.learning_rate = learning_rate
    self.train phase = train phase
   self.train low data ph = tf.placeholder(tf.float32, [None, None, None, 3], name='train lo
    self.train high data ph = tf.placeholder(tf.float32, [None, None, None, 3], name='train h
    self.lr ph = tf.placeholder(tf.float32, name='lr ph')
   self.ckpt dir = ckpt dir
    [R low, I low] = DecomNet(self.train low data ph, layer num=self.DecomNet layer num)
    [R_high, I_high] = DecomNet(self.train_high_data_ph, layer_num=self.DecomNet_layer_num)
   I_low_3 = concat([I_low, I_low, I_low])
   I_high_3 = concat([I_high, I_high, I_high])
   self.output R low = R low
   self.output_I_low = I_low_3
   # loss
   self.recon_loss_low = tf.reduce_mean(tf.abs(R_low * I_low_3 - self.train_low_data_ph))
   self.recon_loss_high = tf.reduce_mean(tf.abs(R_high * I_high_3 - self.train_high_data_ph)
    self.recon_loss_mutal_low = tf.reduce_mean(tf.abs(R_high * I_low_3 - self.train_low_data_
    self.recon_loss_mutal_high = tf.reduce_mean(tf.abs(R_low * I_high_3 - self.train_high_dat
   self.equal R loss = tf.reduce mean(tf.abs(R low - R high))
   self.Ismooth loss low = self.smooth(I low, R low)
```

```
self.Ismooth loss high = self.smooth(I high, R high)
 self.loss Decom = self.recon loss low + self.recon loss high + 0.001 * self.recon loss mu
 self.lr_ph = tf.placeholder(tf.float32, name='learning_rate')
  optimizer = tf.train.AdamOptimizer(self.lr ph, name='AdamOptimizer')
 self.var Decom = [var for var in tf.trainable variables() if 'DecomNet' in var.name]
 self.train_op_Decom = optimizer.minimize(self.loss_Decom, var_list = self.var_Decom)
 self.sess.run(tf.global variables initializer())
 self.saver Decom = tf.train.Saver(var list = self.var Decom)
 print("[*] Initialize model successfully...")
def gradient(self, input tensor, direction):
  self.smooth_kernel_x = tf.reshape(tf.constant([[0, 0], [-1, 1]], tf.float32), [2, 2, 1, 1]
 self.smooth_kernel_y = tf.transpose(self.smooth_kernel_x, [1, 0, 2, 3])
 if direction == "x":
      kernel = self.smooth kernel x
 elif direction == "y":
      kernel = self.smooth kernel y
 return tf.abs(tf.nn.conv2d(input tensor, kernel, strides=[1, 1, 1, 1], padding='SAME'))
def ave gradient(self, input tensor, direction):
 return tf.layers.average pooling2d(self.gradient(input tensor, direction), pool size=3, s
def smooth(self, input I, input R):
 input_R = tf.image.rgb_to_grayscale(input_R)
 return tf.reduce_mean(self.gradient(input_I, "x") * tf.exp(-10 * self.ave_gradient(input_
def evaluate test(self):
 print("Evaluating for test data")
 Reflectance = []
 Illuminance = []
 for idx in range(len(self.eval low data)):
    input_low_eval = np.expand_dims(self.eval_low_data[idx], axis=0)
    if train phase == "Decom":
     result_1, result_2 = self.sess.run([self.output_R_low, self.output_I_low], feed_dict=
    Reflectance.append(result 1)
    Illuminance.append(result 2)
 return Reflectance, Illuminance
```

```
def evaluate train(self):
 print("Evaluating for train data")
 Reflectance = []
 Illuminance = []
 for idx in tqdm(range(len(self.train low data))):
 #for idx in tqdm(range(start_id, end_id)):
    input low train = np.expand dims(self.train low data[idx], axis=0)
    if train phase == "Decom":
      result_1, result_2 = self.sess.run([self.output_R_low, self.output_I_low], feed_dict=
    Reflectance.append(result 1)
    Illuminance.append(result_2)
 return Reflectance, Illuminance
def train(self):
 numBatch = 30
 # load pretrained model
 train_op = self.train_op_Decom
 train loss = self.loss Decom
 saver = self.saver_Decom
 iter num = 0
 start_epoch = 0
 start step = 0
 lr1 = self.learning_rate
  start_time = time.time()
 image_id = 0
 for epoch in range(start_epoch, self.epoch):
    for batch_id in range(start_step, numBatch):
      # generate data for a batch
      batch_input_low = np.zeros((self.batch_size, self.patch_size, self.patch_size, 3), dt
      batch input high = np.zeros((self.batch size, self.patch size, self.patch size, 3), d
      for patch_id in range(self.batch_size):
        h, w, = self.train low data[image id].shape
        x = random.randint(0, h - self.patch_size)
        y = random.randint(0, w - self.patch_size)
        rand mode = random.randint(0, 7)
        batch input low[patch id, :, :, :] = data augmentation(self.train low data[image id
```

```
batch input high[patch id, :, :, :] = data augmentation(self.train high data[image
          image id = (image id + 1) % len(self.train low data)
          if image id == 0:
            tmp = list(zip(self.train_low_data, self.train_high_data))
            random.shuffle(list(tmp))
            train low data, train high data = zip(*tmp)
        # train
        _, loss = self.sess.run([train_op, train_loss], feed_dict={self.train_low_data_ph: ba
                                                                     self.train high data ph:
                                                                     self.lr ph: lr1[epoch]})
        print("%s Epoch: [%2d] [%4d/%4d] time: %4.4f, loss: %.6f" \
              % (train_phase, epoch + 1, batch_id + 1, numBatch, time.time() - start_time, lo
        iter num += 1
 def save pretrained(self):
    self.save(self.saver Decom, self.ckpt dir, "RetinexNet-%s" % self.train phase)
 def load pretrained(self):
   load_model_status = self.load(self.saver_Decom, self.ckpt_dir)
   print("[*] Model restore success!")
 def save(self, saver, ckpt_dir, model_name):
   if not os.path.exists(ckpt dir):
      os.makedirs(ckpt_dir)
   print("[*] Saving model %s" % model name)
   saver.save(self.sess, \
                os.path.join(ckpt_dir, model_name), \
               )
 def load(self, saver, ckpt dir):
   ckpt = tf.train.get_checkpoint_state(ckpt_dir)
   full_path = ckpt_dir + '/RetinexNet-Decom'
   saver.restore(self.sess, full path)
   return True
epoch = 100
\#epoch = 10
learning rate = 0.001 * np.ones([epoch])
learning_rate[20:] = learning_rate[0] / 10.0
batch size = 16
patch_size = 48
train_phase = "Decom"
ckpt dir = "/content/drive/MyDrive/Case study 2"
```

▼ Plotting Reflectance and Illuminantion of a sample image

plt.imshow(R_img[:,:,:])

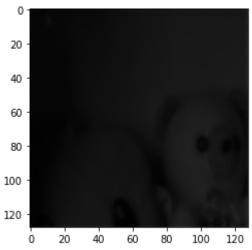
<matplotlib.image.AxesImage at 0x7fb4d9efae10>



Plotting Illuminance of an image



<matplotlib.image.AxesImage at 0x7fb4d9e70610>



Adjustment

```
Reflectance 111 = np.array(Reflectance 1, dtype='float32')
Reflectance 111.shape
     (5000, 128, 128, 3)
Illuminance 111 = np.array(Illuminance 1, dtype='float32')
Illuminance 111.shape
     (5000, 128, 128, 3)
Reflectance_test_1 = list()
for i in tqdm(range(len(Reflectance test))):
 R = Reflectance_test[i]
 R1 = R[0,:,:,:]
 Reflectance test 1.append(R1)
     100% | 15/15 [00:00<00:00, 46465.70it/s]
Illuminance test 1 = list()
for i in tqdm(range(len(Illuminance test))):
 I = Illuminance_test[i]
 I1 = I[0,:,:,:]
 Illuminance_test_1.append(I1)
    100%| 15/15 [00:00<00:00, 47197.72it/s]
Reflectance_test_111 = np.array(Reflectance_test_1, dtype='float32')
Reflectance_test_111.shape
     (15, 128, 128, 3)
Illuminance test 111 = np.array(Illuminance test 1, dtype='float32')
Illuminance_test_111.shape
     (15, 128, 128, 3)
class lowlight enhance 2:
 def __init__(self, train_high_data, Reflectance, Illuminance, Reflectance_test, Illuminanc
   self.sess = tf.Session()
   self.train high data = train high data
   self.R low = Reflectance
```

```
self.I low = Illuminance
 self.R low test = Reflectance test
  self.I low test = Illuminance test
 self.batch size = batch size
 self.patch size = patch size
 self.epoch = epoch
  self.learning_rate = learning_rate
  self.train_phase = train_phase
 self.train high data ph = tf.placeholder(tf.float32, [None, None, None, 3], name='train h
  self.R low ph = tf.placeholder(tf.float32, [None, None, None, 3], name='R low ph')
  self.I low ph = tf.placeholder(tf.float32, [None, None, None, 3], name='I low ph')
 self.lr ph = tf.placeholder(tf.float32, name='lr ph')
 self.ckpt_dir_2 = ckpt_dir_2
 I_delta = RelightNet(self.I_low_ph, self.R_low_ph)
 I_delta_3 = concat([I_delta, I_delta])
 self.output I delta = I delta 3
 self.output S = self.R low ph * I delta 3
  self.relight_loss = tf.reduce_mean(tf.abs(self.R_low_ph * I_delta_3 - self.train_high_dat
 self.Ismooth_loss_delta = self.smooth(I_delta, self.R_low_ph)
 self.loss_Relight = self.relight_loss + 3 * self.Ismooth_loss_delta
  self.lr ph = tf.placeholder(tf.float32, name='learning rate')
 optimizer = tf.train.AdamOptimizer(self.lr ph, name='AdamOptimizer')
  self.var_Relight = [var for var in tf.trainable_variables() if 'RelightNet' in var.name]
 self.train_op_Relight = optimizer.minimize(self.loss_Relight, var_list = self.var_Relight
 self.sess.run(tf.global variables initializer())
 self.saver Relight = tf.train.Saver(var list = self.var Relight)
 print("[*] Initialize model successfully...")
def gradient(self, input_tensor, direction):
 self.smooth\_kernel\_x = tf.reshape(tf.constant([[0, 0], [-1, 1]], tf.float32), [2, 2, 1, 1])
  self.smooth_kernel_y = tf.transpose(self.smooth_kernel_x, [1, 0, 2, 3])
 if direction == "x":
```

```
kernel = self.smooth kernel x
 elif direction == "y":
      kernel = self.smooth kernel y
  return tf.abs(tf.nn.conv2d(input tensor, kernel, strides=[1, 1, 1, 1], padding='SAME'))
def ave gradient(self, input tensor, direction):
 return tf.layers.average pooling2d(self.gradient(input tensor, direction), pool size=3, s
def smooth(self, input I, input R):
 input_R = tf.image.rgb_to_grayscale(input_R)
 return tf.reduce_mean(self.gradient(input_I, "x") * tf.exp(-10 * self.ave_gradient(input_
def evaluate_test(self):
 print("Evaluating for test data")
 R low hat = []
 I_low_hat = []
 for idx in range(len(self.R low test)):
    input_R_low = np.expand_dims(self.R_low_test[idx], axis=0)
    input I low = np.expand dims(self.I low test[idx], axis=0)
    if train phase == "Relight":
      result_1, result_2 = self.sess.run([self.output_S, self.output_I_delta], feed_dict={s
    R low hat.append(result 1)
    I_low_hat.append(result_2)
 return R low hat, I low hat
def evaluate train(self):
 print("Evaluating for train data")
 R low hat = []
 I_low_hat = []
 for idx in tqdm(range(len(self.R_low))):
 #for idx in tqdm(range(start id, end id)):
    input R low = np.expand dims(self.R low[idx], axis=0)
    input I low = np.expand dims(self.I low[idx], axis=0)
    if train phase == "Relight":
     result 1, result 2 = self.sess.run([self.output S, self.output I delta], feed dict={s
    R low hat.append(result 1)
    I low hat.append(result 2)
 return R low hat, I low hat
def train(self):
```

```
numBatch = 30
 train op = self.train op Relight
 train loss = self.loss Relight
 saver = self.saver_Relight
 iter num = 0
 start epoch = 0
 start step = 0
 lr1 = self.learning rate
 start time = time.time()
 image id = 0
 for epoch in range(start_epoch, self.epoch):
   for batch_id in range(start_step, numBatch):
      # generate data for a batch
      batch_R_low = np.zeros((self.batch_size, 128, 128, 3), dtype="float32")
      batch I low = np.zeros((self.batch size, 128, 128, 3), dtype="float32")
      batch_input_high = np.zeros((self.batch_size, 128, 128, 3), dtype="float32")
      for patch id in range(self.batch size):
        batch R low[patch id, :, :, :] = self.R low[image id, :, :, :]
        batch_I_low[patch_id, :, :, :] = self.I_low[image_id, :, :, :]
        batch_input_high[patch_id, :, :, :] = self.train_high_data[image_id][:,:,:]
        image_id = (image_id + 1) % len(self.R_low)
        if image id == 0:
          tmp = list(zip(self.R_low, self.I_low))
          random.shuffle(list(tmp))
          R_{low}, I_{low} = zip(*tmp)
      # train
      _, loss = self.sess.run([train_op, train_loss], feed_dict={self.R_low_ph: batch_R_low
                                                                   self. I low ph: batch I lo
                                                                   self.lr ph: lr1[epoch], \
                                                                   self.train_high_data_ph:
      print("%s Epoch: [%2d] [%4d/%4d] time: %4.4f, loss: %.6f" \
            % (train phase, epoch + 1, batch id + 1, numBatch, time.time() - start time, lo
      iter num += 1
def save pretrained 2(self):
  self.save_2(self.saver_Relight, self.ckpt_dir_2, "RetinexNet-%s" % self.train_phase)
def load pretrained 2(self):
 load model status = self.load 2(self.saver Relight, self.ckpt dir 2)
 print("[*] Model restore success!")
```

```
def save 2(self, saver, ckpt dir, model name):
   if not os.path.exists(ckpt dir):
      os.makedirs(ckpt dir)
   print("[*] Saving model %s" % model_name)
   saver.save(self.sess, \
               os.path.join(ckpt dir, model name))
 def load 2(self, saver, ckpt dir):
   ckpt = tf.train.get_checkpoint_state(ckpt_dir)
   full path = ckpt dir + '/RetinexNet-Relight'
   saver.restore(self.sess, full path)
    return True
train phase = "Relight"
ckpt_dir_2 = "/content/drive/MyDrive/Case_study_2"
model2 = lowlight_enhance_2(train_high_data, Reflectance_111, Illuminance_111, Reflectance_te
     [*] Initialize model successfully...
model2.save pretrained 2()
     [*] Saving model RetinexNet-Relight
model2.load pretrained 2()
     INFO:tensorflow:Restoring parameters from /content/drive/MyDrive/Case study 2/RetinexNet
     [*] Model restore success!
Output S, Output I delta = model2.evaluate train()
     Evaluating for train data
           5000/5000 [00:12<00:00, 398.14it/s]
Output_S_test, Output_I_delta_test = model2.evaluate_test()
     Evaluating for test data
```

Plotting a sample low light and high light image (training data)

```
hl_img = Output_S[0]
hl img2 = Output I delta[0]
```

Sample low light image

Sample high light image

Sample predicted high light image

```
hl_image_final = hl_img*hl_img2

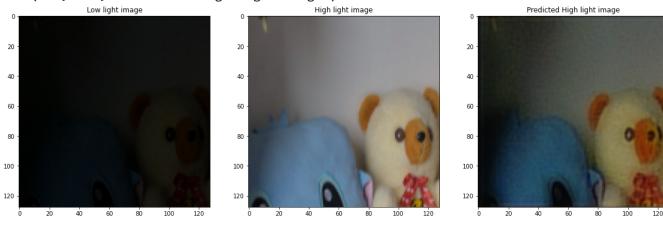
plt.figure(figsize=(20,12))

plt.subplot(1,3,1)
plt.imshow(low_img[ : , : , :])
plt.title('Low light image')

plt.subplot(1,3,2)
plt.imshow(high_img[ : , : , :])
plt.title('High light image')

plt.subplot(1,3,3)
plt.imshow(hl_image_final[ : , : , :])
plt.title('Predicted High light image')
```

Text(0.5, 1.0, 'Predicted High light image')



▼ Plotting a sample low light and high light image (testing data)

Sample low light image

Sample high light image

Sample predicted high light image

```
hl_image_final = hl_img*hl_img2

plt.figure(figsize=(20,12))

plt.subplot(1,3,1)
plt.imshow(low_img[ : , : , :])
plt.title('Low light image')

plt.subplot(1,3,2)
plt.imshow(high_img[ : , : , :])
plt.title('High light image')

plt.subplot(1,3,3)
plt.imshow(hl_image_final[ : , : , :])
plt.title('Predicted High light image')
```

Text(0.5, 1.0, 'Predicted High light image')

