

$$\frac{\partial \rho}{\partial t} + \frac{\partial q}{\partial x} = 0 \quad \text{--- (1)}$$

$\rho(x, t)$: # of cars per unit dist (density of cars)

$q(x, t)$: # of " passing a given x -positⁿ. per unit time.

Closing the model - constitutive relⁿ $q = Q(\rho)$. --- (1b)

$$q = \rho v \quad \text{--- (1c)} \quad v \equiv \text{"flow" velocity (velo of individual cars)}$$

$$v = v_m (1 - \rho/\rho_m) \quad \text{--- (1d)} \quad \begin{array}{l} v_m \equiv \text{max car velocity} \\ \rho_m \equiv \text{max car density} \end{array}$$

$$\frac{\partial q}{\partial x} = \frac{\partial Q(\rho)}{\partial x} = \frac{dQ}{d\rho} \frac{\partial \rho}{\partial x} = c(\rho) \frac{\partial \rho}{\partial x} \quad \dots \quad c(\rho) = \frac{dQ}{d\rho} \quad \text{--- (1e)}$$

$$\Rightarrow \text{(1) becomes} \quad \frac{\partial \rho}{\partial t} + c(\rho) \frac{\partial \rho}{\partial x} = 0 \quad \text{--- (2)}$$

$$\text{IC: } (t=0) \rightarrow \rho(x, 0) = f(x) = R \exp\left[-\frac{x^2}{L^2}\right] \quad \text{--- (3)}$$

$-\infty < x < \infty$, $L > 0$, $\rho_m \geq R > 0 \rightarrow$ const. parameters

METHOD OF CHARACTERISTICS:

$$\text{Seek } \rho = \rho[x(t), t] \quad \text{--- (4a)}$$

$$\frac{d\rho}{dt} = \frac{\partial \rho}{\partial x} \frac{dx}{dt} + \frac{\partial \rho}{\partial t} \quad \text{--- (4b)}$$

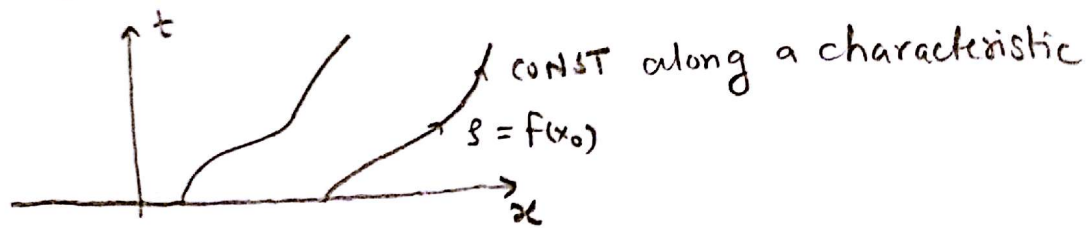
EQⁿ FOR CHARACTERISTICS.

$$\text{Comparing (4b) with (2), If we choose } \boxed{\frac{dx}{dt} = c(\rho)} \quad \text{--- (4c)}$$

$$\boxed{\frac{d\rho}{dt} = 0} \quad \text{ON curves that satisfy (4c)}$$

$$\therefore \frac{dg}{dt} = 0 \Rightarrow \boxed{g = \text{const. along characteristics}}$$

$g = f(x_0) \equiv \text{constant along characteristics.}$



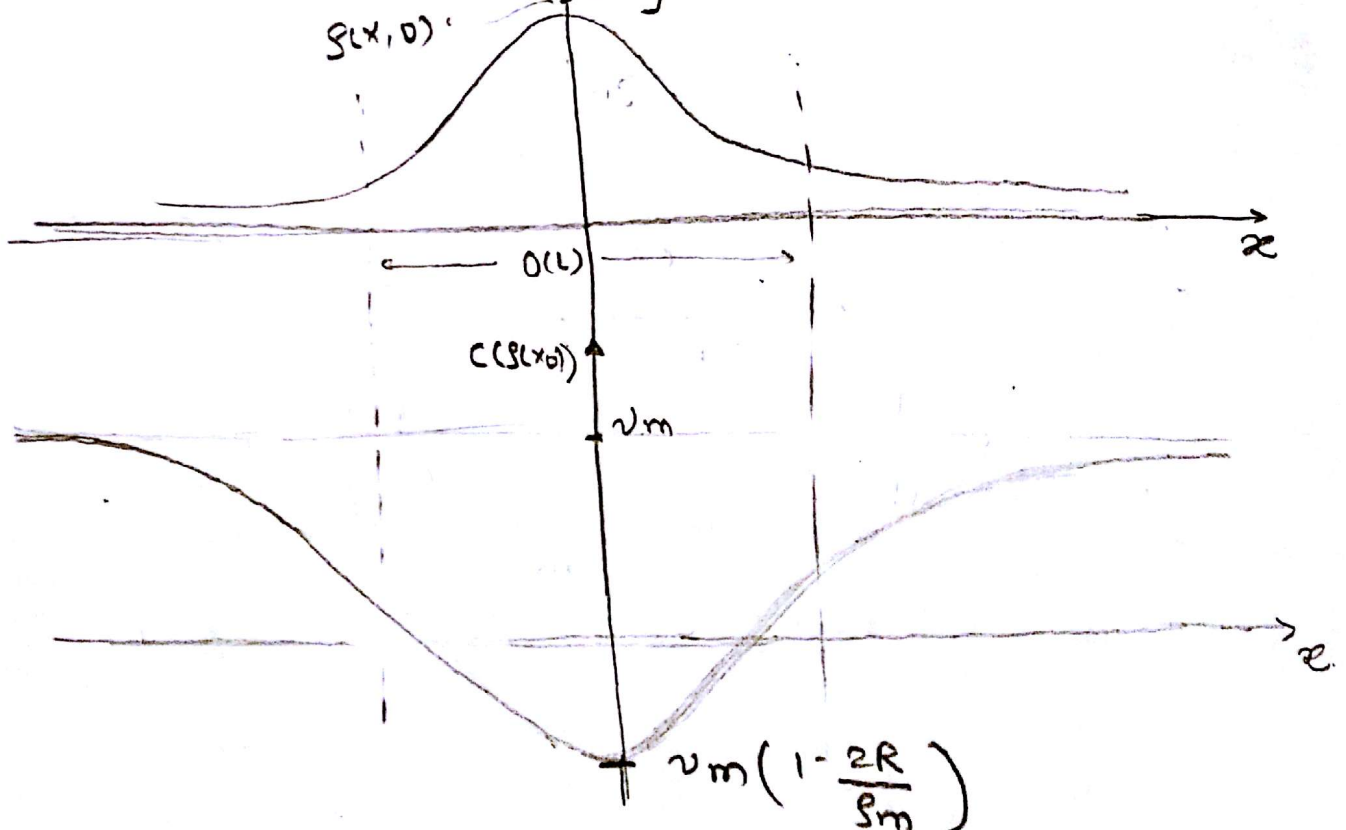
$\Rightarrow c(g) \equiv c(f(x_0)) = \text{const. along characteristics.}$

$$\Rightarrow \boxed{\frac{dx}{dt} = c(f(x_0))} \Rightarrow \boxed{x = x_0 + c(f(x_0))t}$$

CHAR. ARE STRAIGHT LINES.

$$t-x \text{ plane slope} = \frac{1}{c(f(x_0))}$$

$$g(x, 0) = f(x) = R \exp\left[-\frac{x^2}{L^2}\right]$$



$$a = g(s) = v_m \left[s - \frac{s^2}{s_m} \right]$$

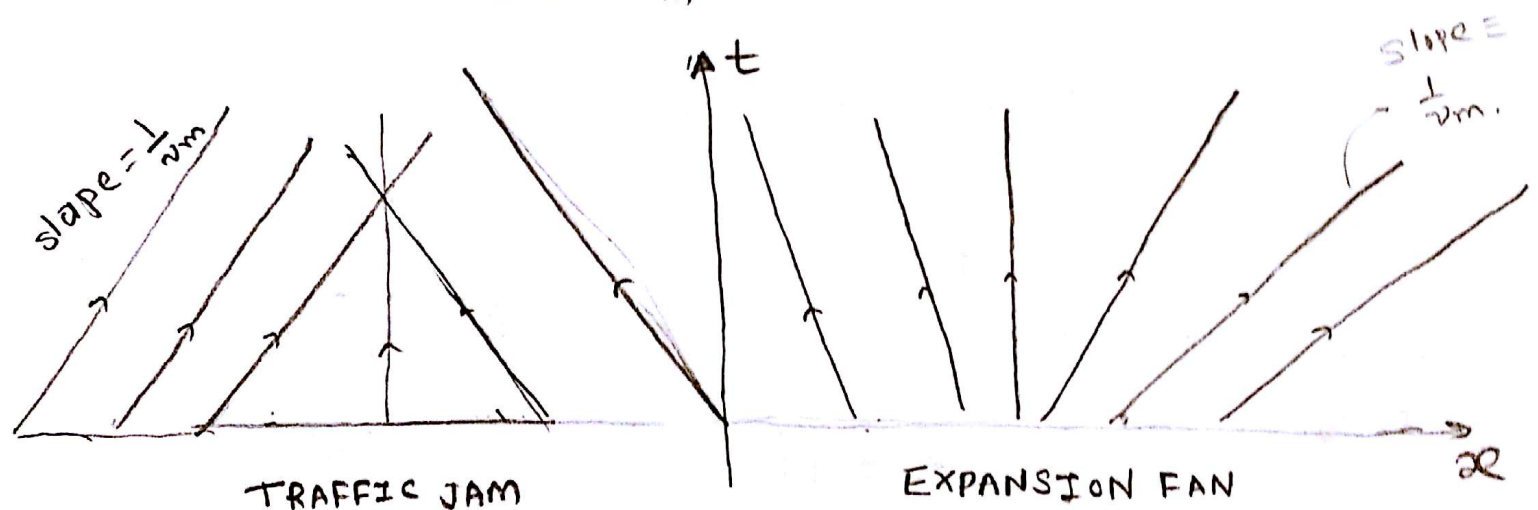
$$\rightarrow c(s) = \frac{ds}{dt} = v_m \left[1 - \frac{2s}{s_m} \right]$$

$$\rightarrow c(s(x_0)) = v_m \left[1 - \frac{2s(x_0, 0)}{s_m} \right]$$

$$= v_m \left[1 - \frac{2R}{s_m} \exp\left(-\frac{x^2}{L^2}\right) \right]$$

$$@ x=0 \rightarrow c = v_m \left[1 - \frac{2R}{s_m} \right] \dots \text{assume } \frac{2R}{s_m} > 1$$

$$@ x \rightarrow \pm \infty \quad c = v_m$$



→ TIME OF INCIPIENT BREAKING (τ_B)

$\tau_B \equiv$ earliest time @ which $|\frac{\partial s}{\partial x}| \rightarrow \infty$

$$x_0 = x - c(s)t$$

$$\frac{\partial s}{\partial x} = \frac{\partial x_0}{\partial x} f'(x_0) \dots s(x, t) = f(x - c(s)t)$$

$$= \left[1 - \frac{dc}{ds} \cdot \frac{\partial s}{\partial x} t \right] \cdot f'(x_0) \dots x_0 = x - c(s)t$$

$$\rightarrow \frac{\partial \mathcal{L}}{\partial x} = \frac{f'(x_0)}{1 + f'(x_0) \frac{dc}{ds} t}$$

$$\left(\frac{\partial \mathcal{L}}{\partial x} \right) \rightarrow \infty \quad \text{as } t \rightarrow t_B$$

$$\rightarrow 1 + f'(x_0) \frac{dc}{ds} t_B = 0$$

$$t_B = \frac{-1}{f'(x_0) \left(\frac{dc}{ds} \right)} = \frac{-1}{c'(x_0)} \quad \dots \mathcal{L} \equiv f.$$

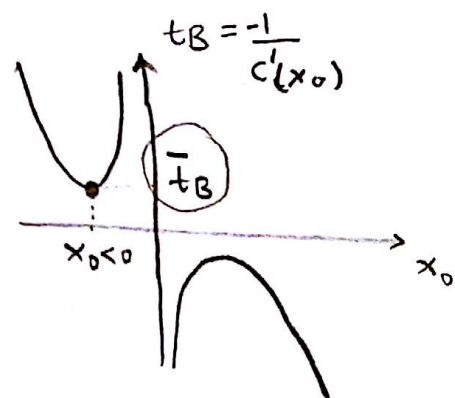
$\min(t_B) = \bar{t}_B \equiv \text{time of incipient breaking.}$

$$c(x_0) = v_m \left[1 - \frac{2R}{s_m} \exp\left(-\frac{x_0^2}{L^2}\right) \right]$$

$$c'(x_0) = v_m \left(-\frac{2R}{s_m} \right) \cdot \left(-\frac{2x_0}{L^2} \right) \exp\left(-\frac{x_0^2}{L^2}\right)$$

$$c'(x_0) = \frac{4v_m R}{s_m L^2} x_0 \exp\left(-\frac{x_0^2}{L^2}\right)$$

$$\rightarrow t_B = -\frac{1}{c'(x_0)} = -\frac{1}{x_0} \exp\left(\frac{x_0^2}{L^2}\right)$$



$$\rightarrow \bar{t}_B = \min \{ t_B \}, \quad x_0 < 0.$$

$$\rightarrow \frac{dt_B}{dx_0} = 0 \quad \rightarrow -\frac{1}{x_0^2} \exp\left(\frac{x_0^2}{L^2}\right) + \frac{1}{x_0} \cdot \frac{2x_0}{L^2} \exp\left(\frac{x_0^2}{L^2}\right) = 0$$

$$\rightarrow \frac{1}{x_0} = \frac{2x_0}{L^2} \quad \rightarrow x_0^2 = \frac{L^2}{2} \quad \Rightarrow x_0 = \pm \frac{L}{\sqrt{2}}$$

$$\therefore x_0 < 0 \text{ @ } \bar{t}_B \Rightarrow x_0 = -\frac{L}{\sqrt{2}}$$

\bar{t}_B occurs at $x_0 = -\frac{L}{\sqrt{2}}$

$$c'(x_0 = -\frac{L}{\sqrt{2}}) = v_m \left(\frac{-2R}{s_m} \right) \cdot \left(-\frac{2L}{\sqrt{2} \cdot L^2} \right) \exp \left(-\frac{L^2}{2L^2} \right)$$

$$\Rightarrow c'(x_0 = -\frac{L}{\sqrt{2}}) = 2\sqrt{2} \frac{R v_m}{s_m L} \exp \left(-\frac{1}{2} \right)$$

$$\Rightarrow \bar{t}_B = \frac{1}{c'(x_0 = -\frac{L}{\sqrt{2}})}$$

$$\Rightarrow \bar{t}_B = \left(\frac{1}{2\sqrt{2}} \right) \left(\frac{L}{R} \right) \left(\frac{s_m}{v_m} \right) \exp(1/2)$$

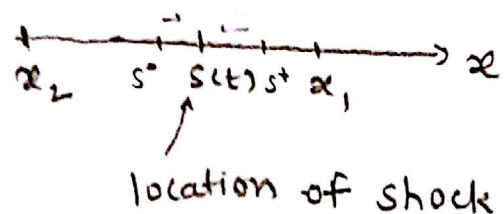
$$\Rightarrow \boxed{\bar{t}_B = \left(\frac{\sqrt{e}}{2\sqrt{2}} \right) \left(\frac{L}{R} \right) \left(\frac{s_m}{v_m} \right)}$$

- Extending the soln using jump condition to times $t > \bar{t}_B$

As derived in class, shock propagation velocity

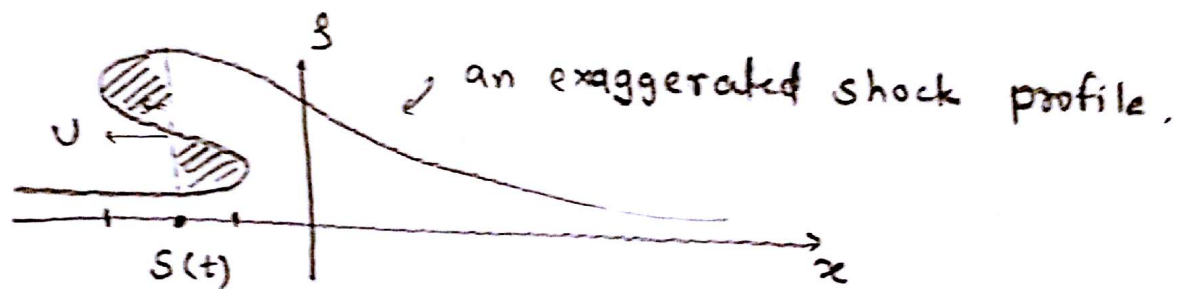
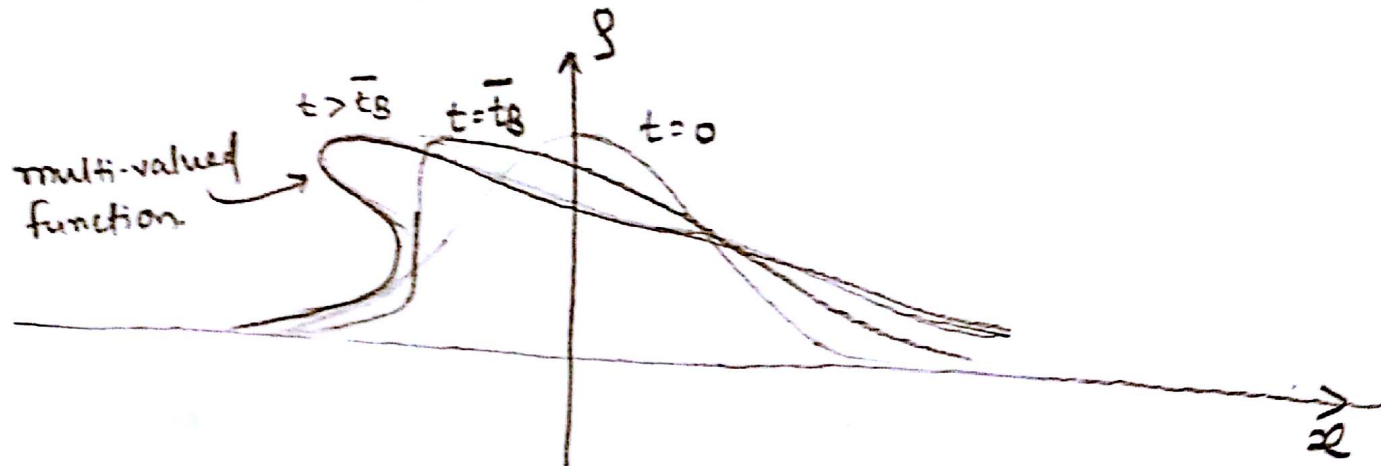
$$U = \frac{[q]}{[s]} \quad \text{where } [q] = q(s^+, t) - q(s^-, t)$$

$$[s] = s(s^+, t) - s(s^-, t)$$

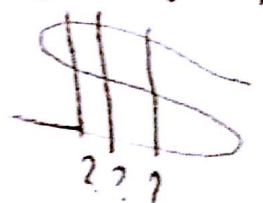


I'll start by trying to draw the evolution of the given Gaussian IC.

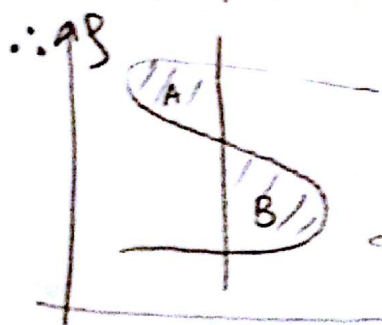
We know that the right half of the lobe does NOT form a shock (expansion fan). The shock formation happens @ $x < 0$ @ $t = \bar{t}_S$.



- We want to fit the multi-valued part by a jump.
- Question is - where to put the straight line?
- The answer lies in a simple argument.



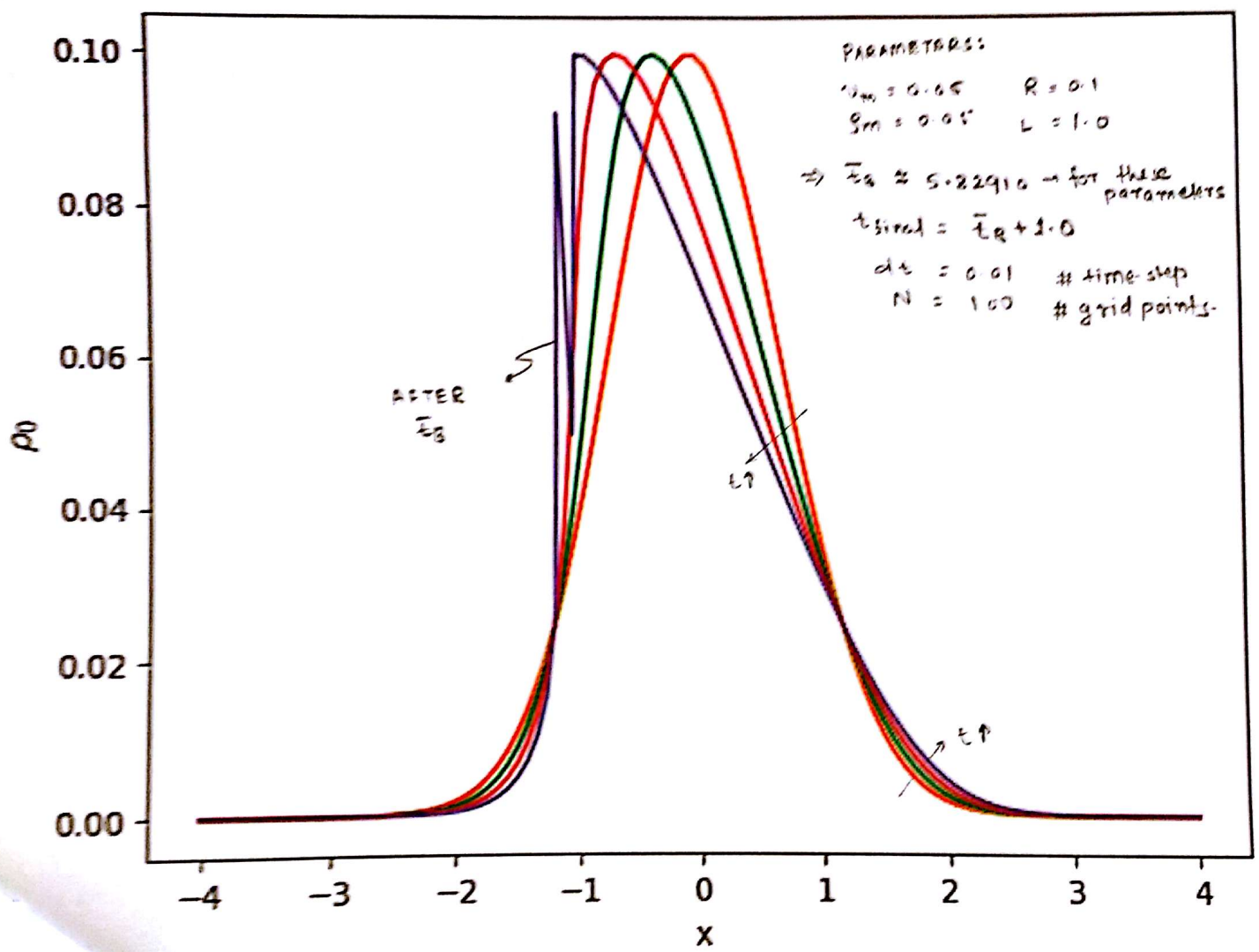
We want the straight-line jump to also satisfy the conservation (we know that the multivalued part does, by construction). → area under the st line = 0



$$\therefore \int_A g dx = \int_B g dx$$

∴ We construct the jump @ such an x -value where

the areas of $A \leftarrow B$ are "EQUAL".
Equal area construction!



WAVES IN FLUIDS – HW 2: TRAFFIC FLOW

Consider as a simple model of one-way, one-lane traffic flow (without off- or on-ramps) the following first-order conservation law:

$$\frac{\partial \rho}{\partial t} + \frac{\partial q}{\partial x} = 0, \quad (1)$$

where $\rho(x, t)$ is the number of cars per unit mile (i.e. the density of cars) and $q(x, t)$ is the number of cars crossing a given x position (a given position along the highway) per unit time (i.e. the flux of cars). The model is closed by specifying an algebraic relation between the flux q and the density ρ : $q = Q(\rho)$. Noting that $q \equiv \rho v$, where v is the "flow" velocity (i.e. the velocity of individual cars), assume that $v = v_m(1 - \rho/\rho_m)$, where v_m is the maximum car velocity and ρ_m is the maximum car density. With $Q(\rho)$ now specified, equation (1) becomes

$$\frac{\partial \rho}{\partial t} + c(\rho) \frac{\partial \rho}{\partial x} = 0, \quad (2)$$

where the wave (not car) speed $c(\rho) \equiv dQ/d\rho$. At some initial instant ($t = 0$), imagine that the distribution of cars may be approximated by a Gaussian, i.e.

$$\rho(x, 0) = f(x) = R \exp\left(-\frac{x^2}{L^2}\right) \quad (3)$$

for $-\infty < x < \infty$, where $L > 0$ and $\rho_m \geq R > 0$ are constant parameters.

1. Does a traffic jam (i.e. wave breaking) occur? If so, determine the earliest time \bar{t}_B and the x -location x_B at which braking occurs as a function of the model and initial-condition parameters.
2. Using the method of characteristics, write a short computer (e.g. Matlab) program to determine the solution for $\rho(x, t)$ at any given (input) time t such that $0 < t < \bar{t}_B$. Make plots showing the evolution of ρ versus x for various increasing times t . (You will need to pick some reasonable values for the various parameters.)
3. **EXTRA CREDIT** Extend your solution using an appropriate jump condition to times $t > \bar{t}_B$.

2. ON THE CHARACTERISTICS $\rightarrow \frac{dx}{dt} = c(\rho) \because \rho = \text{const. on charact.}$

$$\frac{dx}{dt} = c(x_0)$$

$$x(t) = c(x_0)t + x_0 \rightarrow \text{think of this as an eqn for } x_0.$$

$\Rightarrow x_0 = x_0(x, t) \rightarrow$ I give you x, t you tell me where it came from (i.e., x_0)

INPUT $t = \text{some time}$

$\begin{array}{c|c} x & x_0 \\ \hline \vdots & \vdots \end{array} \rightarrow \text{plot this.}$

Use Newton algorithm to find x_0 .
- Raphson

Assign the value of $g(x_0)$ to $g(x, t) \rightarrow$ as the "s"
is const. on that characteristic!
 \therefore we've found $g(x, t)$ without any numerical time stepping!