

• PCA, we find the direction of maximum variance.

$$\bar{z} = \frac{1}{N} \sum_i z_i$$

$$= \frac{1}{N} \sum_{i=0}^N u^T x_i$$

$$\bar{z} = u^T \frac{1}{N} \sum_{i=0}^N x_i$$

$$\bar{z} = u^T \mu$$

$$u^T x = u^T x$$

$$z = \sqrt{\lambda}$$

$$\text{var}(x) = \lambda \text{d} \times \text{d}$$

$$\lambda = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})^2$$

$$\Sigma = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})(x_i - \bar{x})^T$$

$$\dim(\Sigma) = N \times d \times d$$

Maximize  $\frac{1}{N} \sum_{i=1}^N (x_i - \bar{z})^2$

$$= \frac{1}{N} \sum_{i=1}^N (u^T x_i - u^T \mu)^2$$

$$= \frac{1}{N} \sum_{i=1}^N (u^T (x_i - \mu))^2$$

$u$  is the eigenvector

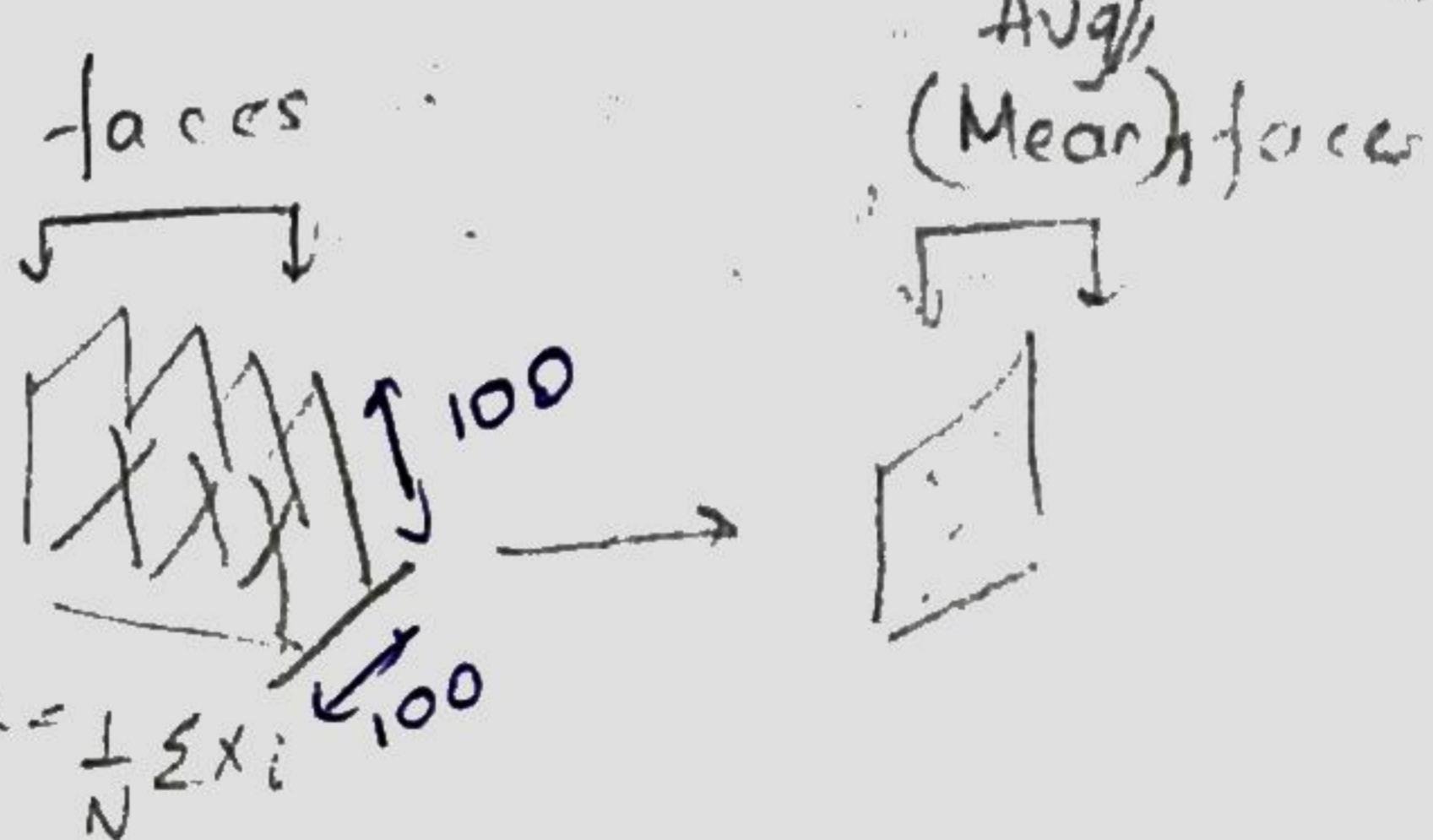
eigen value  $\lambda$ .

$$\frac{1}{N} \sum_{i=1}^N (u^T x_i - \mu^T \mu)(x_i^T u - \mu^T \mu)$$

$$= \frac{1}{N} \sum_{i=1}^N u^T [x_i - \mu] [x_i - \mu]^T u + \frac{1}{N} \sum_{i=1}^N u^T \Sigma (x_i - \mu) (x_i - \mu)^T u$$

$$= \|u^T \Sigma u\|, \text{ such that } u^T u = 1$$

Via lagrangian method,  
of the largest



Eigen-face:-

Each feature is

a photo  $\Rightarrow d = \text{No. of points} = 10^8 \times 10^2 = 10^4$

$$\dim(\Sigma) = d \times d = 10^4 \times 10^4$$

Finding eigen vectors of  $10^4 \times 10^4$  matrix is difficult.

No. of photos = 1000

$$\text{Max vectors} = 10^4$$

But as almost all photos are

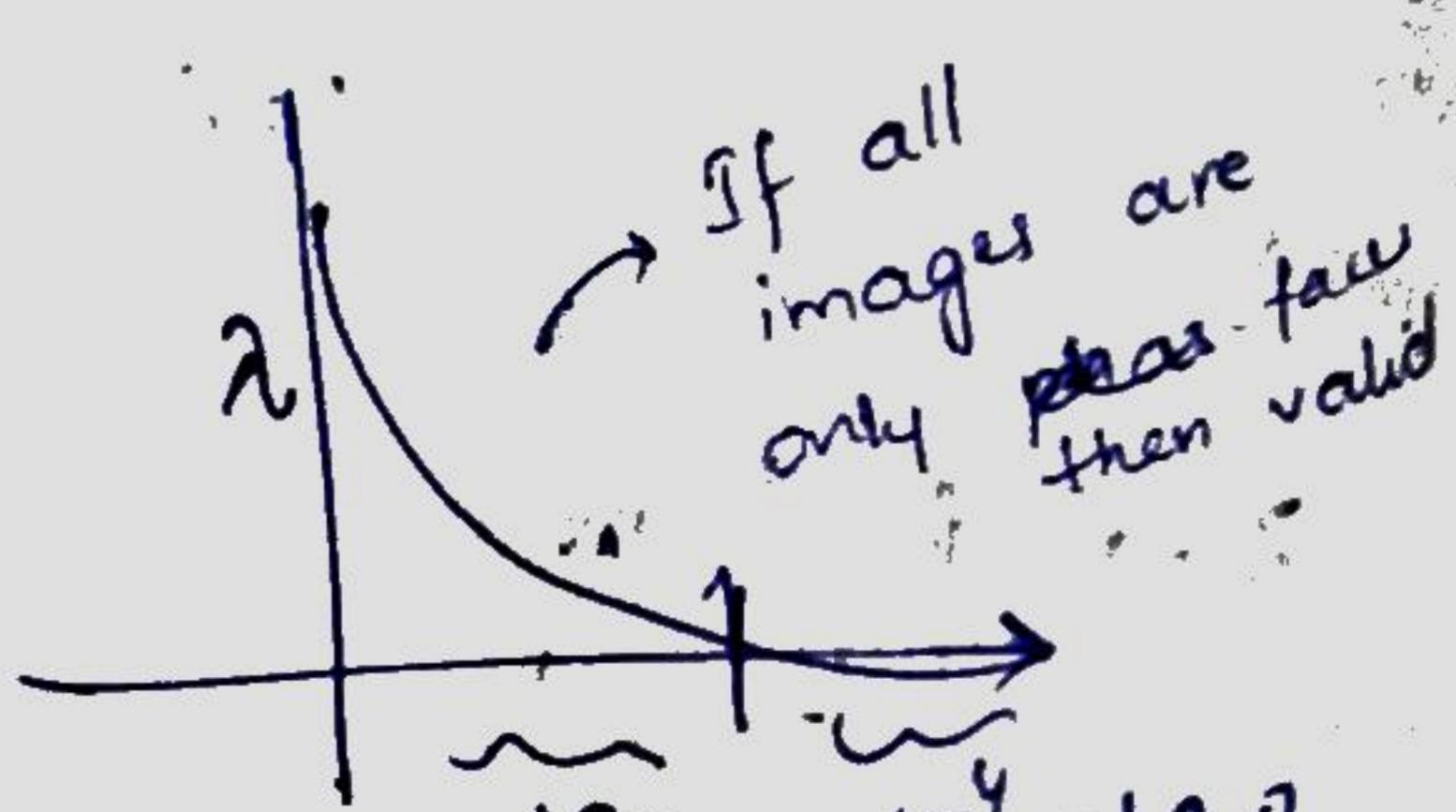
same,

a few eigen vectors

$$z = x^T u$$

$$z = \begin{bmatrix} x^T u_1 \\ x^T u_2 \\ \vdots \\ x^T u_k \end{bmatrix} \rightarrow \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

$\dim(10^4 \times 1)$



So  $\dim(z) = 100 \times 1$

$$x = \sum_{i=1}^{100} \alpha_i u_i \rightarrow \text{eigen face}$$

↓

$A$  protection  $x^T u_i$

$$\text{New face} = \sum_{i=1}^{100} \alpha_i u_i + \sum_{i=\text{rest}} \alpha_i u_i \rightarrow \text{useless}$$

Almost similar  
for every photo

Practical eg: A video conference: If only the 100 numbers are sent, your ~~features~~ face can be drawn, but why don't we use?

This method is valid iff the images we capture only faces and not other objects like cars, ... So not useful

In the photo example,  $10^4 > 10^3$   
 $d > N$ .

think of  $xx^T$  and  $x^Tx$

$$x = N \times d, x^T = d \times N$$

$\sum_{i=1}^d$

$$xx^T = N \cdot N$$

$$x^Tx = d \cdot d$$

$\|x\|^2$  decay  
affect for line

$x^T x \Rightarrow \lambda_2 \text{ need not be small}$

If identical faces  $\Rightarrow$  steeper curve

$$xx^T u = \lambda_1 u$$

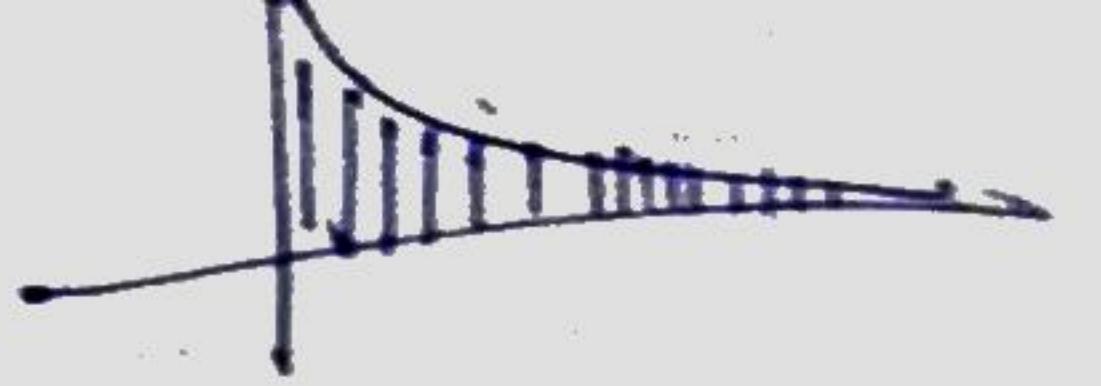
$$x^Tx v = \lambda_2 v$$

$$\cancel{x^T x} x^T u = \lambda_1 x^T u$$

$$x^T x v = \lambda_2 v$$

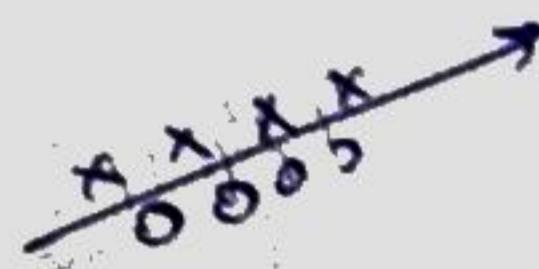
Compute eigen vectors of  $N \times N$  matrix  $x$   
 $= 10^3$   
 and convert  $d \times d \rightarrow 10^4$

Image - is Positive Semi - Definite



Classification + Dimensionality Reduction :-

If



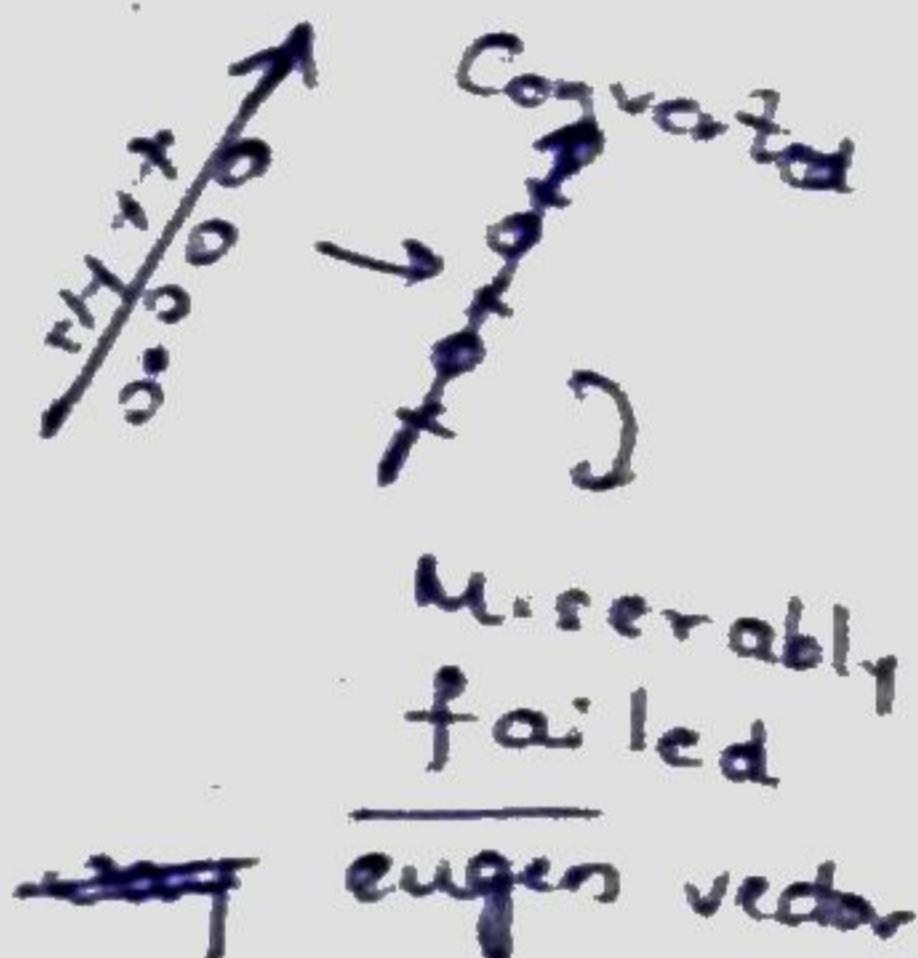
→

xxxxoo

Perpendicular

Don't → (But  $\perp^{\text{av}}$  need not  
PRESUME always be best soln, ~~##~~)

Unsupervised → You don't care, which ~~any~~ eigenvector was used.



Supervised →

LDA | Fisher

Where class info is used

10/9/18

## Lec-11

- $(x_i, y_i) \quad i=1..N$
- $x_i \in \mathbb{R}^d$

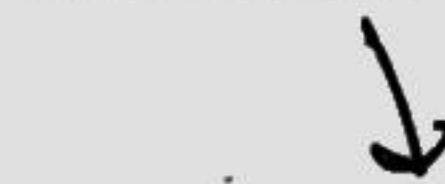
$\boxed{\text{Q: Is } N > d \text{ or } d > N \Rightarrow \text{if } d \text{ is large, in the starting, need not be the best or right } x.}$

### A need for feature Selection/Extraction:-



#### Subset Selection

- Can you find a subset of selections, that can do almost as good as the original set.
- To reduce cost.  
↳ Example he took is, doing medical tests to get info abt patient
- Subset selection is a hard prob and so, finding the best subset would be hard



$z = Ux$  [A unitary transformation]

$$k < d$$

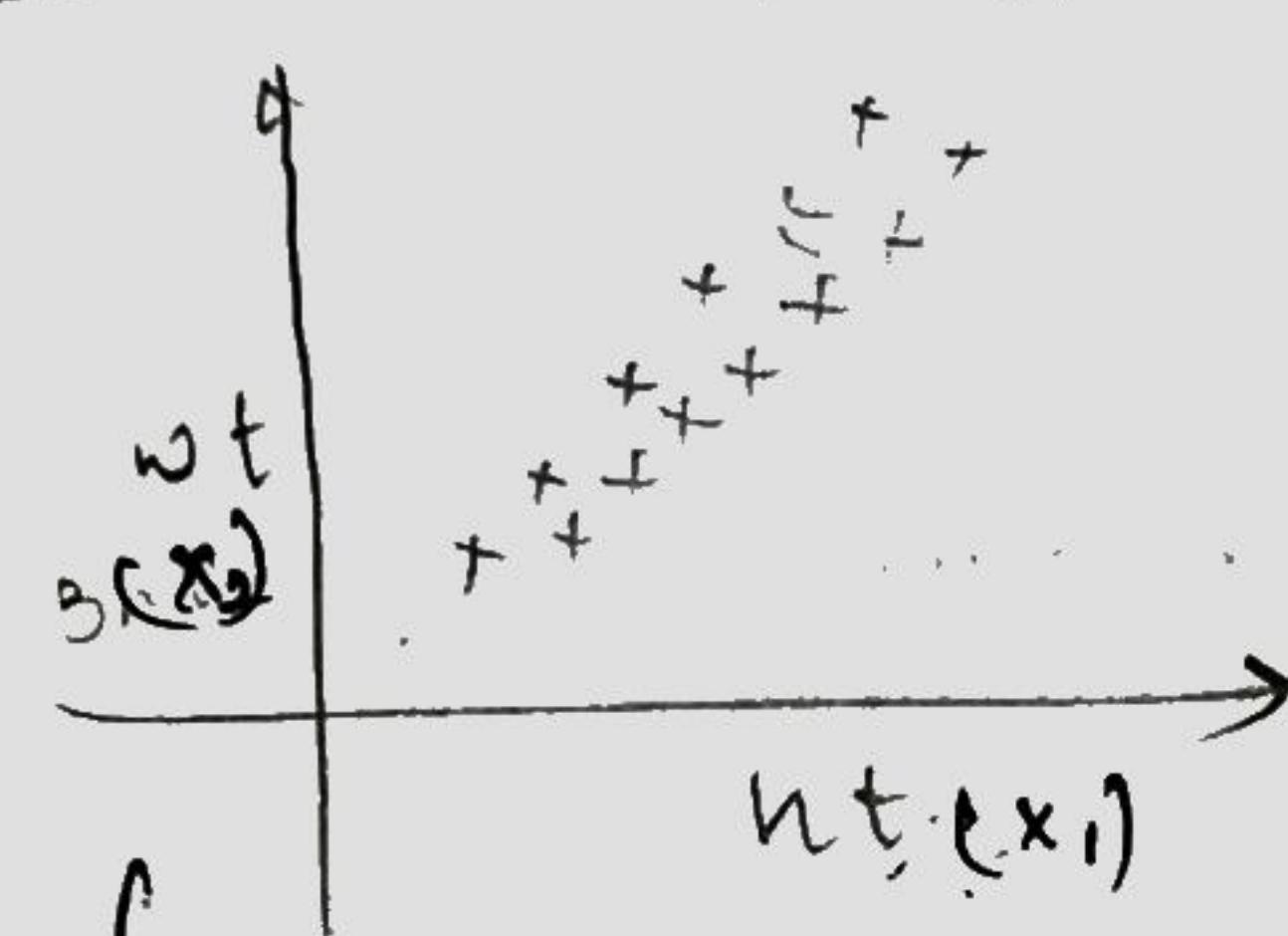
- Sort, of like combining medical tests, to ~~get~~ reduce the ~~next~~ dimensions

#### II A Dimensionality Reduction

- Can be thought as extracting new features for the task
- Sensing cost  $\rightarrow$  no change  
But downstream  $\rightarrow$  Less of feature extraction

$$=$$

Soln: PCA



#### problem:-

↳ ~~Intelligence~~ Intelligence vs ht & wt  
↳ Suppose this ht & wt of a single child, & plotting

↳ We observe ht, wt are linearly correlated

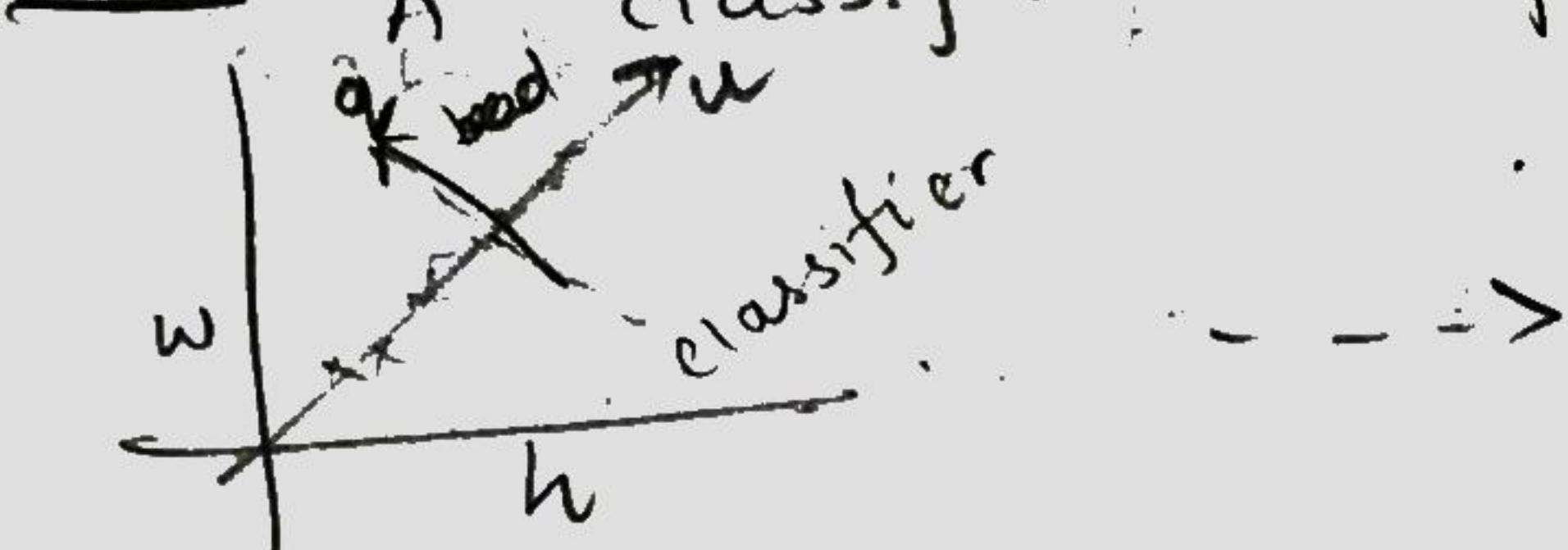
R<sup>d</sup> of dimensions  $\xrightarrow{x_1 x_2 x_3 x_4} (z)$   
age

Comb of wt + ht

$z \rightarrow$  is practically capturing  $x_1$  and  $x_2$

A classifier  $\rightarrow$  Capability of driving

If projected in q(bad) direction



$\xrightarrow{0000} z$   
Badd! / good  
drivers

No age separ.