SCHOOL OF COMPUTER SCIENCE & ENGINEERING SRM UNIVERSITY,

SRM NAGAR, KATTANKULATHUR-603203.

SUBJECT: MICROPROCESSORS AND MICROCONTROLLERS

SUBJECT CODE: 15CS205J SEMESTER: VI

CLASS : III CSE HOURS/WEEK : 2 HOURS

EX. NO	NAME OF THE EXPERIMENTS		
Sl. No.	Description of experiments		
	Assembly Language Programs Using TASM/MASM		
1	Program involving Arithmetic Instructions on 16 bit data		
	i. Addition & Subtraction ii. Multiplication & Division iii. Factorial of a given number		
2	Program involving Data Transfer Instructions on 16 bit data		
	 i. Byte and Word data transfer in different addressing modes ii. Block Data Transfer 		
3	Program involving Bit Manipulation Instructions on 16 bit data -Given data is positive or negative		
4	Implementation of Bubble Sort Algorithm		

5	 i. Reverse a given string and check whether it is a palindrome ii. String Display using Display Interrupt (Read your name from the keyboard and displays it at a specified location on the screen after the message "What is your name?" You must clear the entire screen before display) 	
6.	Time display using Interrupt (Read the current time from the system and display it in the standard format on the screen)	
	Basic 8051 programming using C	
7	Port Programming	
8	Timer-Counter Programming	
9	Serial Programming	
10	Interrupt Programming	

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(HOD / CSE)

Steps to use MASM

MASM:

- 1. TYPE IN NOTEPAD AND SAVE IT AS FILENAME.ASM(CLICK ALL FILES).
- 2. EDIT: EDIT FN.ASM
- 3. MASM FN.ASM
- 4. LINK FN.OBJ
- 5. DEBUG FN.EXE
- -R
- -T
- -T

8086 PROGRAM:

ExNo:1 i) Program involving Arithmetic Instructions on 16 bit data

Addition

AIM: To implement assembly language program for addition of two 16-bit numbers.

APPARTUS: MASM Software, P.C.

PROGRAM:

DATA SEGMENT N1 DW 1234H

N2 DW 2134H

RES DW?

DATA ENDS

CODE SEGMENT

ASSUME CS: CODE, DS: DATA

START: MOV AX, DATA

MOV DS, AX

MOV AX, N1

MOV BX, N2

ADD AX, BX

MOV RES, AX

INT 21H

CODE ENDS

END START

RESULT:

AX = 3368h

ExNo:1 i) Program involving Arithmetic Instructions on 16 bit data

Subtraction

AIM: To implement assembly language program for subtraction of two 16-bit numbers.

APPARTUS: MASM Software, P.C.

PROGRAM:

DATA SEGMENT
N1 DW 4444H
N2 DW 2121H
RES DW ?
DATA ENDS
CODE SEGMENT
ASSUME CS:CODE, DS:DATA
START: MOV AX,DATA
MOV DS,AX
MOV AX,N1
MOV BX,N2
SUB AX,BX
MOV RES,AX

RESULT:

INT 21H CODE ENDS END START

AX = 2323h

ExNo:1 ii) Program involving Arithmetic Instructions on 16 bit data

Multiplication

AIM: To implement assembly language program for Multiplication of two 16-bit numbers.

APPARTUS: MASM Software, P.C.

PROGRAM:

ASSUME CS: CODE, DS: DATA **CODE SEGMENT** MOV AX, DATA MOV DS, AX MOV AX, OPR1 MUL OPR2 MOV RESLW, AX MOV RESHW, DX HLT CODE ENDS **DATA SEGMENT OPR1 DW 2000H** OPR2 DW 4000H **RESLW DW?** RESHW DW? **DATA ENDS END** (DX)

Input:

OPR1 = 2000H OPR2 = 4000H

Output:

RESLW = 0000H (AX) RESHW = 0800H (DX)

ExNo:1 ii) Program involving Arithmetic Instructions on 16 bit data

Division

AIM: To implement assembly language program for Division of two 16-bit numbers.

APPARTUS: MASM Software, P.C.

Program:

ASSUME CS: CODE, DS: DATA

CODE SEGMENT

MOV AX, DATA

MOV DS, AX

MOV AX, OPR1

DIV OPR2

MOV RESQ, AL

MOV RESR, AH

HLT

CODE ENDS

DATA SEGMENT

OPR1 DW 2C58H

OPR2 DB 56H

RESQ DB?

RESR DB?

DATA ENDS

END

Input:

OPR1 = 2C58H (DIVIDEND)

OPR2 = 56H (DIVISOR) Output: RESQ = 84H (AL) RESR = 00H (AH)

ExNo:1 iii) Factorial of a given number

AIM: To implement assembly language program to find factorial of a given number

APPARTUS: MASM Software, P.C.

Program:

DATA SEGMENT

X DW 06H

FACT DW?

DATA ENDS

CODE SEGMENT

ASSUME CS:CODE,DS:DATA

START: MOV AX, DATA

MOV DS,AX

MOV AX,01H

MOV CX,X

UP: MUL CX

LOOP UP

MOV FACT, AX

MOV AH,4CH

INT 21H

CODE ENDS

END START

Input: 06

Output: 2D0H

ExNo:2 i) Byte and Word data transfer in different addressing modes

AIM: To implement assembly language program for Byte and Word data transfer in different addressing modes

APPARTUS: MASM Software, P.C.

Program:

DATA SEGMENT

DATA1 DB 23H

DATA2 DW 1234H

DATA3 DB 0H

DATA4 DW 0H

DATA5 DW 2345H,6789H

DATA ENDS

CODE SEGMENT

ASSUME CS:CODE,DS:DATA

START: MOV AX,DATA; //Initialize DS to point to start of the memory

MOV DS,AX; //set aside for storing of data

MOV AL,25X; //copy 25H into 8 bit AL register

MOV AX,2345H;// copy 2345H into 16 bit AX register

MOV BX,AX;// copy the content of AX into BX register(16 bit)

MOV CL,AL;// copy the content of AL into CL register

MOV AL,DATA1 ;// copies the byte contents of data segment memory location DATA1 into 8 bit AL

MOV AX,DATA2 ;// copies the word contents of data segment memory ;location DATA2 into 16 bit AX

MOV DATA3,AL;// copies the AL content into the byte contents of data ;segment memory location DATA3

MOV DATA4,AX ;//copies the AX content into the word contents of ;data segment memory location DATA4

MOV BX,OFFSET DATA5;// The 16 bit offset address of DS memeory location

; DATA5 is copied into BX

MOV AX,[BX]; //copies the word content of data segment ;memory location addressed by BX into ;AX(register indirect addressing)

MOV DI,02H; address element

MOV AX,[BX+DI]; copies the word content of data segment

;memory location addressed by BX+DI into

;AX(base plus indirect addressing)

MOV AX,[BX+0002H]; copies the word content of data segment

;(16 bit)

MOV AL,[DI+2]; register relative addressing

MOV AX,[BX+DI+0002H]; copies the word content of data

segment

;memory location addressed by BX+DI+0002H

;into AX(16 bit)

MOV AH,4CH; Exit to DOS with function call 4CH

INT 21H

CODE ENDS; Assembler stop reading

END START

ExNo:2 ii) Block Data Transfer

AIM: To implement assembly language program for Block Data Transfer

APPARTUS: MASM Software, P.C.

Block move (with and with out overlapping)

Without overlapping

Program:

DATA SEGMENT

X DB 01H,02H,03H,04H,05H; Initialize Data Segments Memory

Locations

Y DB 05 DUP(0) DATA ENDS

CODE SEGMENT

ASSUME CS:CODE,DS:DATA

START:MOV AX,DATA; Initialize DS to point to start of the

memory

MOV DS,AX; set aside for storing of data

MOV CX,05H; Load counter

LEA SI,X+04; SI pointer pointed to top of the memory block LEA DI,X+04+03; 03 is displacement of over lapping, DI pointed to

;the top of the destination block

Before execution

00

00

00

00

00

05

04

03

02

01

After execution

05 04 03 02 01 05 04 03 02 01 Y,DI X, SI With Overlapping Program: **DATA SEGMENT** X DB 01H,02H,03H,04H,05H; Initialize Data Segments Memory Locations **DATA ENDS CODE SEGMENT** ASSUME CS:CODE,DS:DATA START:MOV AX,DATA; Initialize DS to point to start of the memory MOV DS,AX; set aside for storing of data MOV CX,05H; Load counter SI pointer pointed to top of the memory block LEA SI,X+04; 03 is displacement of over lapping, DI pointed LEA DI,X+04+03;

;the top of the destination block

UP: MOV BL,[SI]; Move the SI content to BL register

MOV [DI],BL; Move the BL register to content of DI

DEC SI; Update SI and DI

DEC DI

to

DEC CX; Decrement the counter till it becomes zero

JNZ UP

MOV AH,4CH

INT 21H CODE ENDS

END START DS Before execution XX XX XX XX XX 05 04 03 02 01 DI SI Χ DS After execution XX XX 05 04 03 - 02 01

03 02 01

ExNo:3 Program involving bit manipulation instruction

AIM: To implement assembly language program involving bit manipulation instruction If given data is positive or negative

APPARTUS: MASM Software, P.C.

Program:

DATA SEGMENT NUM DB 12H

MES1 DB 10,13,'DATA IS POSITIVE \$'

MES2 DB 10,13, DATA IS NEGATIVE \$'

DATA ENDS

CODE SEGMENT

ASSUME CS:CODE,DS:DATA

START: MOV AX, DATA

MOV DS,AX

MOV AL, NUM

ROL AL.1

JC NEGA

;Move the Number to AL.

;Perform the rotate left side for 1 bit position.

;Check for the negative number.

MOV DX,OFFSET MES1 ;Declare it positive.

JMP EXIT ;Exit program.

NEGA: MOV DX,OFFSET MES2;Declare it negative.

EXIT: MOV AH,09H

INT 21H

MOV AH,4CH

INT 21H

CODE ENDS

END START

Output: Data is positive Positive Numbers: 00-7F Negative numbers: 80-FF

ExNo:4 Bubble sort using MASM

AIM: To implement assembly language program for Bubble Sort

APPARTUS: MASM Software, P.C.

Program:

Ascending Order:

model small

```
.data
arr db 5h,7h,6h,4h,10h,09h
len db $-arr
```

.code

start: mov ax,@data mov ds,ax mov cl,len lp1: mov bx,cx lea si,arr

lp2: mov al,[si]

inc si

cmp [si],al

jb lp3

xchg [si],al

mov [si-1],al

lp3: dec bx jnz lp2

loop lp1

mov ah,4ch

int 21h

end start

Descending Order:

```
.model small
.data
arr db 5h,7h,6h,4h,10h,09h
len db $-arr
.code
start: mov ax,@data
     mov ds,ax
     mov cl,len
lp1: mov bx,cx
     lea si,arr
lp2: mov al,[si]
     inc si
     cmp [si],al
     jb lp3
     xchg [si],al
     mov [si-1],al
lp3: dec bx
     jnz lp2
     loop lp1
     mov ah,4ch
     int 21h
end start
```

ExNo:5 i) Reverse a given string and check whether it is a palindrome

AIM: To implement assembly language program to check whether the string is a palindrome.

APPARTUS: MASM Software, P.C.

Program:

DATA SEGMENT

STR1 DB 'LIRIL'

LEN EQU \$-STR1

STR2 DB 20 DUP(0)

;start of data segment

MES1 DB 10,13, WORD IS PALINDROME\$'

MES2 DB 10,13, WORD IS NOT PALINDROME\$'

DATA ENDS

CODE SEGMENT

ASSUME CS:CODE,DS:DATA,ES:DATA

START: MOV AX, DATA

MOV DS,AX

MOV ES,AX

LEA SI,STR1

LEA DI,STR2+LEN-1

MOV CX,LEN

UP: CLD

LODSB

STD

STOSB

LOOP UP

LEA SI,STR1

LEA DI,STR2

CLD

MOV CX,LEN

REPE CMPSB

CMP CX,0H JNZ NOTPALIN LEA DX,MES1 MOV AH,09H **INT 21H** JMP EXIT NOTPALIN: LEA DX,MES2

MOV AH,09H

INT 21H

EXIT: MOV AH,4CH

INT 21H **CODE ENDS END START**

OUTPUT: WORD IS PALINDROME

ExNo:5 ii) Program to use DOS interrupt INT 21H function called for reading a character from keyboard, buffered keyboard input, display of character and string on console.

AIM: To implement assembly language program to display a String

APPARTUS: MASM Software, P.C.

Program:

DATA SEGMENT **INKEY DB?** BUF DB 20 DUP(0) MES DB 10,13, 'SRM UNIVERSITY \$' **DATA ENDS CODE SEGMENT** ASSUME CS:CODE, DS:DATA START: MOV AX, DATA MOV DS,AX MOV AH,01H **INT 21H**

;DOS function to read a character from keyboard ;with

echo. [AL = 8bit character]

MOV INKEY,AL ;Returns ASCII value of the pressed key.

MOV BUF,10

MOV AH,0AH

LEA DX,BUF

INT 21H

MOV AH,06H

MOV DL,'A'

INT 21H

MOV AH,09H

LEA DX,MES

INT 21H

MOV AH,4CH

INT 21H

CODE ENDS

END START

ExNo:6 Time display using Interrupt (Read the current time from the system and display it in the standard format on the screen)

AIM: To implement assembly language program to display a system time

APPARTUS: MASM Software, P.C.

Program:

DATA SEGMENT

HOUR DB?

MIN DB?

DATA ENDS

CODE SEGMENT

ASSUME CS:CODE, DS:DATA

DISCHAR MACRO CHAR

PUSH AX

PUSH DX

MOV DL, CHAR

MOV AH,02

INT 21H

POP DX

POP AX

ENDM

START: MOV AX, DATA

MOV DS,AX

CALL TIME

MOV AH,4CH

INT21H

TIME PROC NEAR

MOV AH,2CH ;function to read system time

INT21H

MOV HOUR, CH

MOV MIN,CL

CMP CH,12

JB DOWN

SUB CH,12

DOWN: MOV AL, CH

MOV AH,00H

AAM

MOV AX,3030H

DISCHAR AH

DISCHAR AL

DISCHAR':'

MOV AL,CL

MOV AH,00H

AAM

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ADD AX,3030H

DISCHAR AH

DISCHAR AL

DISCHAR''

CMP HOUR,12

JB AM

DISCHAR 'P'

JMP DOWN1

AM: DISCHAR'A'

DOWN1: DISCHAR'M'

RET

TIME ENDP

CODE ENDS

END START

ExNo:7 Port Programming

```
i)Write an 8051 C program to send values of -4 to +4 to port P1.
//Signed numbers
#include <reg51.h>
void main(void)
char mynum[]={+1,-1,+2,-2,+3,-3,+4,-4};
unsigned char z;
for (z=0;z<=8;z++)
P1=mynum[z];
ii)Write an 8051 C program to toggle bit D0 of the port P1 (P1.0)
50,000 times.
Solution:
#include <reg51.h>
sbit MYBIT=P1^0;
void main(void)
unsigned int z;
for (z=0;z<=50000;z++)
MYBIT=0;
MYBIT=1;
```

iii)Write an 8051 C program to toggle bits of P1 ports continuously with a 250 ms.

Solution:

```
#include <reg51.h>
void MSDelay(unsigned int);
void main(void)
{
  while (1) //repeat forever
{
  p1=0x55;
  MSDelay(250);
  p1=0xAA;
  MSDelay(250);
}
}
void MSDelay(unsigned int itime)
{
  unsigned int i,j;
  for (i=0;i<itime;i++)
  for (j=0;j<1275;j++);
}</pre>
```

ExNo:8 Timer-Counter Programming

i) Write an 8051 C program to toggle only pin P1.5 continuously every 250 ms. Use Timer 0, mode 2 (8-bit auto-reload) to create the delay.

Solution:

```
#include <reg51.h>
void T0M2Delay(void);
sbit mybit=P1<sup>5</sup>;
void main(void){
unsigned char x,y;
while (1) {
mybit=~mybit;
for (x=0;x<250;x++)
for (y=0;y<36;y++) //we put 36, not 40
T0M2Delay();
}
void T0M2Delay(void){
TMOD=0x02;
TH0=-23;
TR0=1;
while (TF0==0);
TR0=0;
TF0=0;
```

ii) Write an 8051 C program to create a frequency of 2500 Hz on pin P2.7. Use Timer 1, mode 2 to create delay.

Solution:

```
#include <reg51.h>
void T1M2Delay(void);
sbit mybit=P2^7;
void main(void){
unsigned char x;
while (1) {
mybit=~mybit;
T1M2Delay();
}
}
void T1M2Delay(void){
TMOD=0x20;
TH1=-184;
TR1=1;
while (TF1==0);
TR1=0;
TF1=0;
}
```

ExNo:9 Serial Programming

Write a program for the 8051 to transfer letter "A" serially at 4800 baud, continuously.

Solution:

```
MOV TMOD,#20H; timer 1,mode 2(auto reload)
MOV TH1,#-6;4800 baud rate
MOV SCON,#50H;8-bit, 1 stop, REN enabled
SETB TR1; start timer 1
AGAIN: MOV SBUF,#"A"; letter "A" to transfer
HERE: JNB TI,HERE; wait for the last bit
CLR TI; clear TI for next char
SJMP AGAIN; keep sending A
```

Write a program for the 8051 to transfer "YES" serially at 9600 baud, 8-bit data, 1 stop bit, do this continuously **Solution**:

MOV TMOD,#20H; timer 1,mode 2(auto reload) MOV TH1,#-3;9600 baud rate MOV SCON, #50H; 8-bit, 1 stop, REN enabled SETB TR1; start timer 1 AGAIN: MOV A,#"Y" ;transfer "Y" **ACALL TRANS** MOV A,#"E" ;transfer "E" **ACALL TRANS** MOV A,#"S"; transfer "S" **ACALL TRANS** SJMP AGAIN ;keep doing it :serial data transfer subroutine TRANS: MOV SBUF, A ; load SBUF HERE: JNB TI, HERE; wait for the last bit CLR TI; get ready for next byte RET

ExNo:10 Interrupt Programming

Write a program in which the 8051 reads data from P1 and writes it to P2 continuously while giving a copy of it to the serial COM port to be transferred serially. Assume that XTAL=11.0592. Set the baud rate at 9600.

Solution:

ORG 0000H

LJMP MAIN

ORG 23H

LJMP SERIAL ;jump to serial int ISR

ORG 30H

MAIN: MOV P1,#0FFH; make P1 an input port timer 1, auto reload MOV TH1,#0FDH; 9600 baud rate

MOV SCON,#50H; 8-bit,1 stop, ren enabled MOV IE,10010000B; enable serial int.

SETB TR1; start timer 1

BACK: MOV A,P1; read data from port 1 MOV SBUF,A; give a copy to SBUF

MOV P2,A; send it to P2

SJMP BACK; stay in loop indefinitely

;-----SERIAL PORT ISR

ORG 100H

SERIAL: JB TI,TRANS; jump if TI is high

MOV A,SBUF; otherwise due to receive CLR RI; clear RI since CPU doesn't

RETI; return from ISR

TRANS: CLR TI; clear TI since CPU doesn't

RETI; return from ISR

END

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