Prateek Arora

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Research Interests: Computer Vision and Artificial Intelligence.

Education

- **University of Maryland** — College Park, MD
  Master of Engineering in Robotics — *August 2018 – Present*
- **GGSIPU University** — New Delhi, India
  Bachelors in Electrical and Electronics Engineering — *2012–2016*

Experience

- **Research Assistant** — *with Prof. Yiannis Aloimonos*
  Perception and Robotics group, University of Maryland — *August 2018 – Present*
  Quadrotors, 130 size
  Designed a hardware sensor and compute suite "PRGEye" consisting of a global shutter camera, an IMU and ToF distance sensors, a microcontroller and a microprocessor. Also, I implemented point to point trajectory on quadrotor using cascaded PID.
- **Research Associate** — *with Prof. Sujit and Sanjit Kaul*
  Indraprastha Institute of Information Technology (IIIT), Delhi, India — *July 2017 - July 2018*
  Self-driving car (ROS)
  Worked on traffic light detection in Indian traffic environment and system integration. Also, developed lane cost algorithm to replace binary cost map and integrated it with OMPL.
- **Research Assistant** — *with Prof. Gargi Mishra*
  Guru Gobind Singh Indraprastha University, India — *August 2014 - Jan 2016*
  Worked on Gaze controller robot that is controlled using movement of eyes for Quadriplegic patient.

Projects

- **Deep Homography Net, Supervised and Unsupervised**: Implemented Supervised and Unsupervised to estimate homography between two images using TensorFlow.
- **Structure from Motion (Monocular)**: Reconstruction of a 3D scene and simultaneously obtaining the camera poses of a monocular camera w.r.t. the given scene.
- **Video SnapCut**: Implemented object cutout in a video using set of local classifiers, a feature available in Adobe After Effects.
- **Face swap**: Implemented an end-to-end pipeline to swap faces in a video just like Snapchat's face swap filter using both **Delaunay Triangulation** and **Thin Plate Spline**.
- **Boundary detection using Pb-Lite**: Boundary detection in image using modified "Probability of Boundary" method. The probability is measured by computing changes in texture and brightness in the local neighborhood
- **Flying through gaps**: Implemented Gaussian-Mixture-Model to detect colored windows and used it as a feedback to autonomously fly drone through it.

Publications

- **Mobile Surveillance Spheroid Robot with Static Equilibrium Camera, Leaping Mechanism and KLT algorithm based Detection with Tracking**: Shamsheer Verma, Chahat Deep Singh, Sarthak Mittal, **Prateek Arora** and Arvind Rehalia.International Journal of Control Theory and Applications, 09(41) 2016, 473-488. ISSN: 0974-5572. (Link)
- **Control of wheelchair dummy for differently abled patients via iris movement using image processing in MATLAB**: **Prateek Arora**, Anshul Sharma, Anmoal Singh Soni, Aman Garg, IEEE INDICON 2015, doi: 10.1109/INDICON.2015.7443610 (Link)
- **Comparative study of different Gaits of a Hexapod Implemented using Inverse Kinematics and controlled via Bluetooth remote**: **Prateek Arora**, Anshul Sharma, Anmoal Singh Soni, Aman Garg, Gargi Mishra, International Conference on Quality, Productivity, Reliability, Optimization and Modeling 2017.

Relevant Courses

- **CMSC 426 - Computer Vision**: Fall 2018 — *by Prof. Yiannis Aloimonos*
- **CMSC 733 - Computer Processing of Pictorial Information** : Spring 2019 — *by Prof. Yiannis Aloimonos*
- **ENPM 667 - Control of Robotic Systems** : Fall 2018 — *by Prof. Waseem Malik*

Skills

Computer Languages: C++, Python, LaTeX
Operating System: Linux, Windows
Softwares/Libraries: Tensorflow, Numpy, Matlplotlib, Jupyter, Eagle, Matlab

References

Yiannis Aloimonos
Professor,
University of Maryland

Dr. P.B. Sujit,
Associate Professor,
IIIT-Delhi

Dr Gargi Mishra,
Asst Prof.
GGSIPU