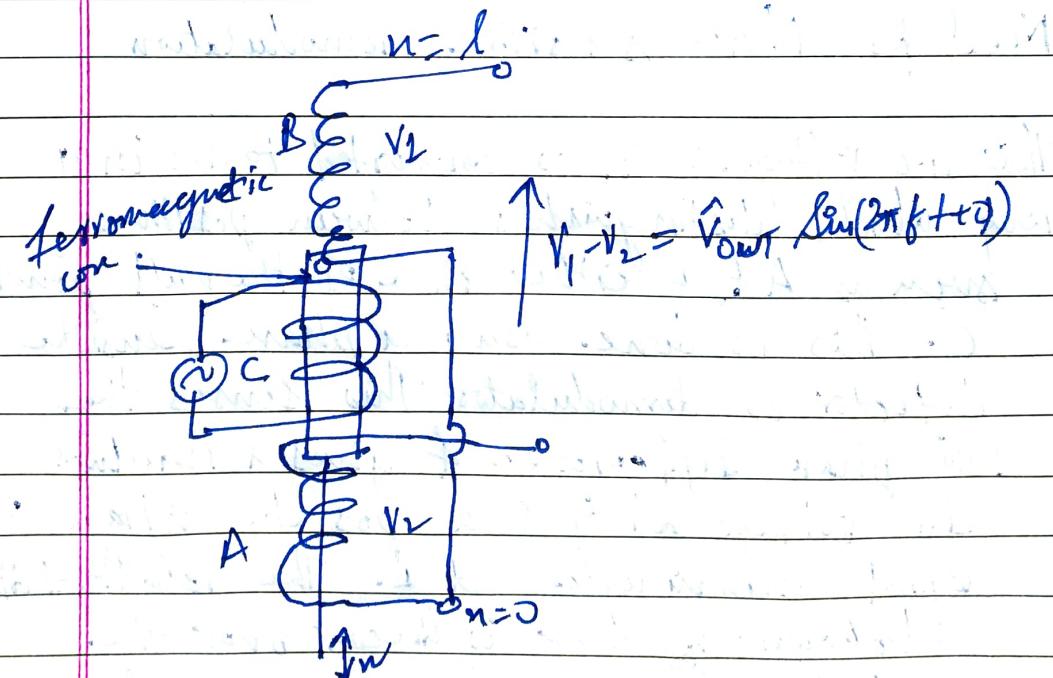


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18FE3 SD14

A1-(a) LVDT (Linear Variable Differential Transformer) sensor converts linear movement of the object it is coupled to and converts to electrical signal proportional to the movement.

### Operation:

It is a transformer with a single primary & two identical secondary windings wound on a tubular ferromagnetic former.



The primary winding is energized by an a.c. voltage of amplitude  $V_1$  & freq  $f \text{ Hz}$ ,

The two secondaries are connected in series opposition so that the output voltage

$V_{\text{out}} \sin(2\pi f t + \phi)$  is the difference of  $(V_1 - V_2)$  of the voltages induced in the secondary coils. A ferromagnetic core moves in & out the former; this alters the mutual inductance between the primaries & secondaries. With the core in the former,  $V_1$  &  $V_2$  change with core position  $x$ , causing amplitude  $V_{\text{out}}$  & phase  $\phi$  to change.

### Need for Phase sensitive demodulation

The a.c. voltage  $V_1 - V_2$  is converted to d.c. in a way which distinguishes between positions such as A & B either side of the null point C. This is done using a phase sensitive detector or demodulator. This senses the  $180^\circ$  phase difference & gives a negative d.c. voltage at A & a pos d.c. voltage of equal magnitude at B. The relationship between  $V_{\text{dc}}$  &  $x$  is linear over the central portion of the range 0 to  $L$ , but non-linear effects occur at either end (D & E) as the core moves to the edge. This non-linearity can be reduced by using central portion.

(b) Clearly  $V_D = V_B$  when  $V_c = \text{High} \rightarrow (i)$ .

Assuming the terminal of  $A_2$  to be at  $V_{bias}$  & the gain resistors to be  $R_p$ . Also, assuming the number of turns in all the coils the same.

For ideal opamp,

$$\frac{V_B}{V_A} = -\frac{R_2}{R_A} \quad [ \because \text{it is an inverting amp} ] \quad - (ii)$$

Since  $A_1$  is in open loop configuration it acts as a comparator.

When  $V_s > 0 : V_c = \text{Low or ground } (V_s)$

$V_s < 0 : V_c = \text{High or } V_{cc} \rightarrow (iii)$

From (ii)  $\therefore V_D = V_B$  when  $V_s < 0$ . (iv)

$V_D = V_{bias}$  when  $V_s > 0$

When  $V_D = V_{bias}$ , as  $V_D$  is open circuit, no current flows through  $R_p$  &  $R_f$  &  $R_g$  too.

Thus,  $\frac{V_D}{V_E}$  is open circuited & pulled to ground by  $\alpha_{C2}$ .

When  $V_D = V_B$ ,

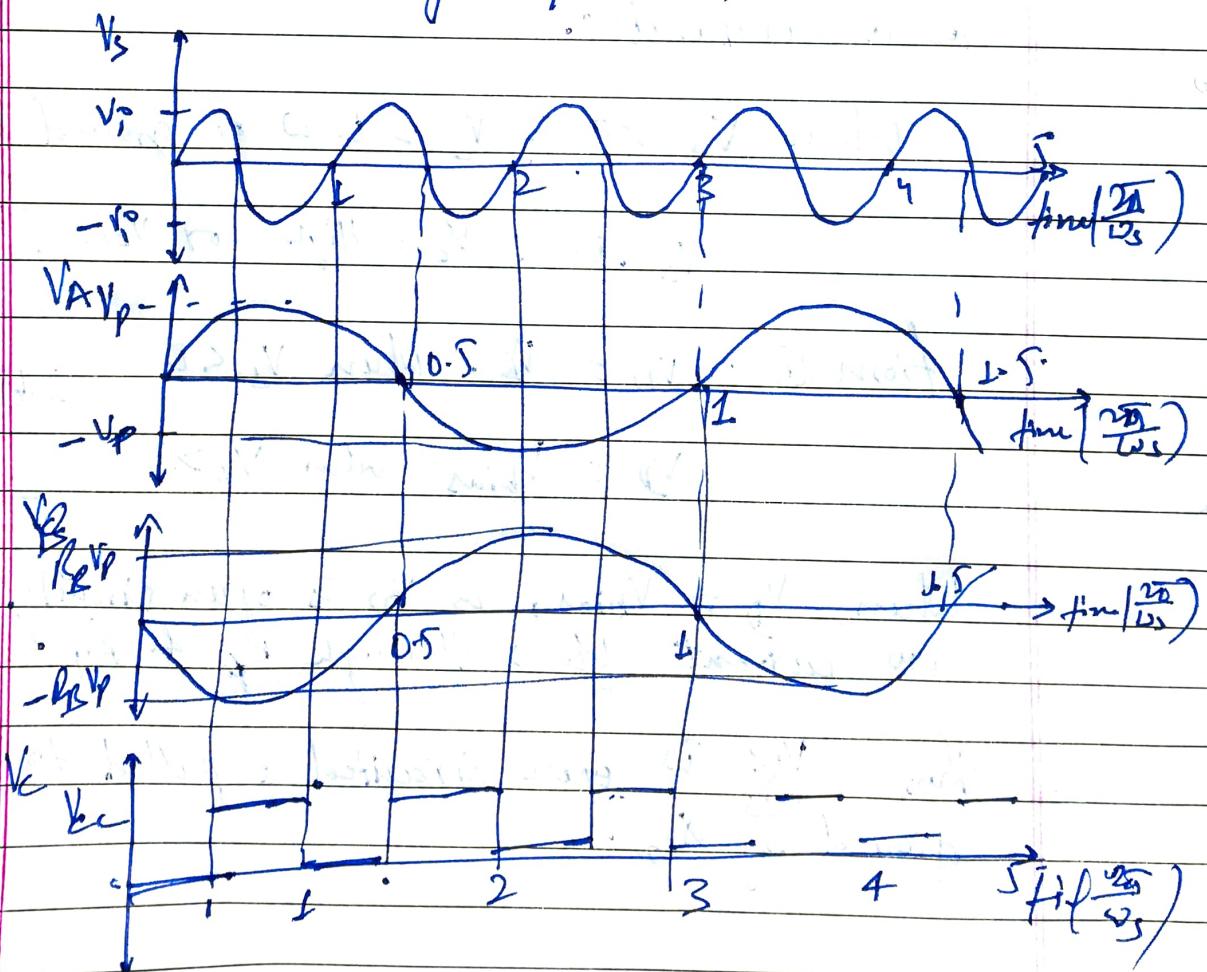
$$V_{C1} = \left(1 + \frac{R_1}{R_2}\right) V_{INAS} - \frac{R_P}{R_{IN}} V_B - (W)$$

as  $A_2$  is in difference amplifier configuration.

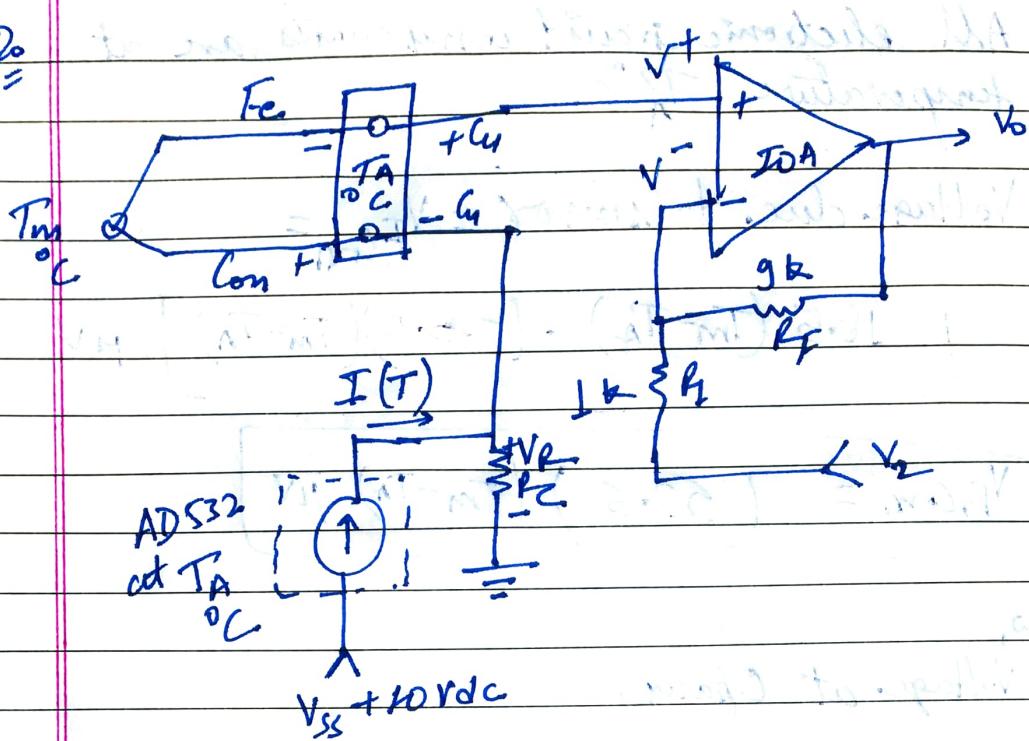
Finally  $V_E$  is passed through the low pass filter comprising  $\alpha_{C2}$  &  $B_2$ ; with

$$\alpha_{C2} = \frac{1}{\omega_m C_2}; \quad V_E = b V_D e^{-\alpha t} \quad \text{with } \alpha \in (0, 1); \quad \theta > 0^\circ$$

from above theory & equations,



$\text{O}_2 =$



In question, information given,

$$\rightarrow I(T) = (T + 273) \times 10^{-6} \text{ A}$$

$$\rightarrow V_R = [I(T)] \times [R_2]$$

$\rightarrow$  Ideal Opamp.

$$\rightarrow R_f = g_b R, R_2 = L_b R$$

$\rightarrow$  Thermolectric Sensitivity

$$S_{Fe} = 18.5 \mu\text{V}/^\circ\text{C}$$

$$S_{con} = -35.0 \mu\text{V}/^\circ\text{C}$$

$$S_u = 6.5 \mu\text{V}/^\circ\text{C}$$

$\rightarrow$  Material Sensitivities constant over the range of measurement.

→ All electronic circuit components are at temperature  $T_A$  °C

(a) Voltage due to sensor =  $V_{E,com} =$

$$[18.5(T_m - T_A) - (-35.0)(T_m - T_A)] \text{ mV}$$

$$V_{E,com} = (53.5)(T_m - T_A) \text{ mV}$$

Now,

Voltage at Opamp,

$$V^+ = V_R + V_{E,com}$$

$$= [I(T_A) \times R_C] + (53.5)(T_m - T_A) \times 10^{-6} \text{ V}$$

Substituting value of  $I(T_A)$

$$V^+ = [R_C (T_A + 273) + 253.5 (T_m - T_A)] \text{ mV}$$

Since opamp is ideal,

$$V^+ = V^- \quad \text{at virtual ground}$$

$$\frac{V_O - V^-}{R_f} = \frac{V^- - V_2}{R_L}$$

$$\Rightarrow V_O = V^- \left( 1 + \frac{R_f}{R_L} \right) - \frac{R_f}{R_L} V_2$$

Putting values from above,

$$V_o = \left[ R_C (T_A + 273) + 53.5 (T_m - T_A) \right] \mu V \times \\ \left( 1 + \frac{9b\alpha}{1b\alpha} \right) \rightarrow \frac{9b\alpha}{1b\alpha} \times V_2$$

$$\Rightarrow V_o = \left[ 10 \left[ R_C (T_A + 273) + 53.5 (T_m - T_A) \right] \times 10^{-6} \right] \checkmark \\ - 9V_2$$

(b) Now,

$V_o$  can be written as,

$$V_o = \left[ 10 R_C \left[ (10) [R_C - 53.5] T_A + 53.5 T_m \right. \right. \\ \left. \left. + 2730 R_C \right] \times 10^{-6} \right] \checkmark - 9V_2$$

To make  $V_o$  independent of  $T_A$ .

$$R_C - 53.5 = 0$$

$$\boxed{R_C = 53.5 \Omega}$$

Also, to eliminate offset,

$$2730 \times R_C \times 10^{-6} - 9V_2 = 0 \\ \Rightarrow V_2 = \frac{2730 \times R_C \times 10^{-6}}{9}$$

$$\Rightarrow V_2 = \frac{2730 \times 520 \times 10^{-6}}{g} V$$

$$\Rightarrow V_2 = 0.016228 V$$

$V_2 = 16.228 mV$

(C)  $V_0 = 535 \times T_m \times 10^{-6} (V)$

Comparing it with,

$$V_0 = kT_m$$

We will get,

$k = 535 \times 10^{-6}$

unit will be

$$V/C$$