

Basic rules for sketching the root locus

1. **No. of branches:** The number of branches of the root locus equals to the number of closed-loop poles.

Ex. $1 + K \frac{(s+2)}{(s+3)(s+4)} = 0$

Ch. eqⁿ: $\frac{(s+3)(s+4)}{(s+3)(s+4)} + K \frac{(s+2)}{(s+3)(s+4)} = 0$

$K=0$
 $K \geq 0$

No. of closed-loop poles = 2

Open-loop poles: -3, -4

Zero: -2

✓ $K=0$ ✓
when $K=0$, $s=-3$ and $s=-4$ are two roots of the Ch. eqⁿ.

$K=\infty$

$$\frac{1}{K} + \frac{s+2}{(s+3)(s+4)} = 0$$
$$\frac{1}{K} + \frac{\frac{1}{s} + \frac{2}{s+2}}{\left(1 + \frac{3}{s}\right)\left(1 + \frac{4}{s}\right)} = 0$$

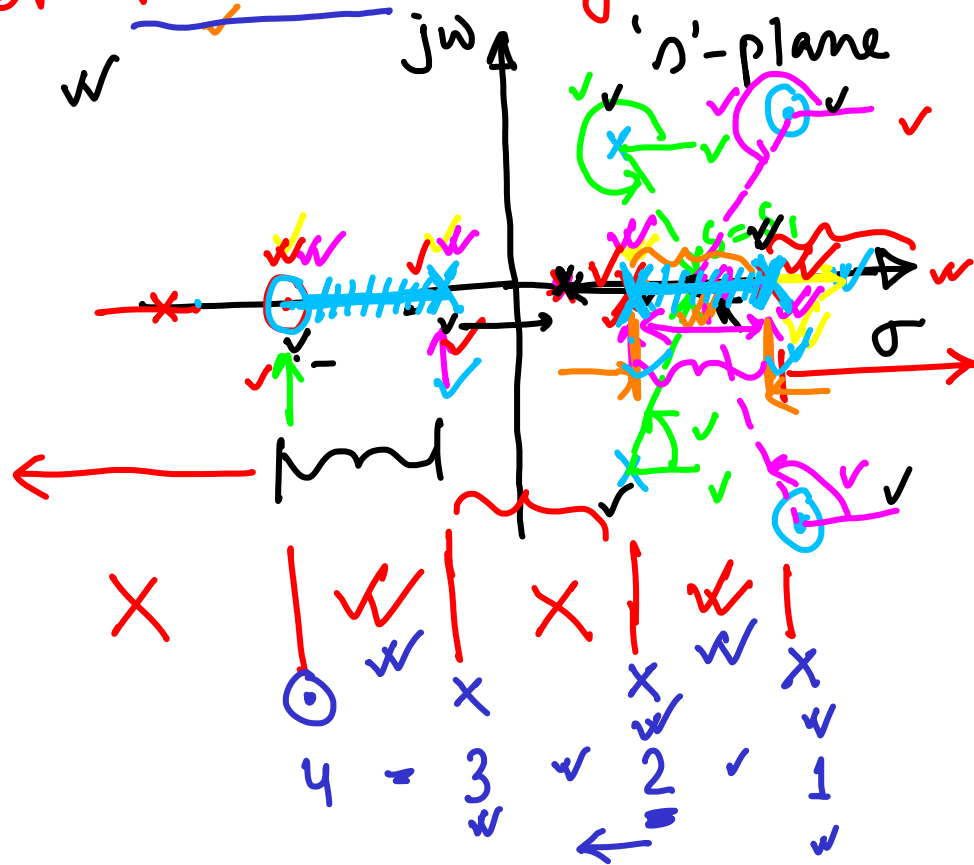
$\frac{1}{s} + \frac{2}{s+2} = 0$

When $K \rightarrow \infty$, $s=-2$ is a root of Ch. eqⁿ.

$K \rightarrow \infty$, $s=\infty$ is a root of Ch. eqⁿ.

2. Symmetry: The root locus is symmetrical about the real-axis since the polynomial is a real co-efficient polynomial.

3. Real-axis segment:



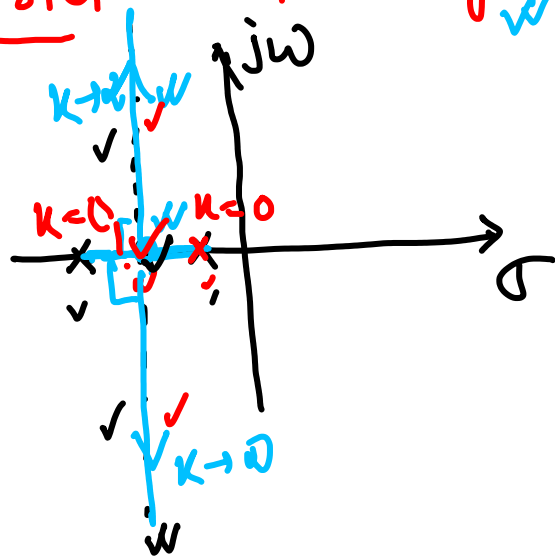
$$\underline{360^\circ + 180^\circ} \quad \underline{0^\circ}$$

$$\angle K G(s) H(s) = (2k+1)180^\circ$$

Resultant Contribution of Complex pole and/or zero is $360^\circ / 0^\circ$.

On the real-axis, for $k > 0$, the root locus exists to the left of an odd number of real axis finite open-loop poles and/or finite open-loop zeros.

4. Centroid and asymptotes:



The root locus approaches straight lines as asymptotes as the locus approaches infinity.

The real-axis intercept

$$\sigma = \frac{\sum \text{finite poles} - \sum \text{finite zeros}}{(\text{no. of finite poles}) - (\text{no. of finite zeros})}$$

Angle of asymptotes

$$\theta = \frac{(2k+1)\pi}{(\text{no. of finite poles}) - (\text{no. of finite zeros})}$$

$k=0, \pm 1, \pm 2, \dots$

It is needed when some zeros are at infinity.

Ex.

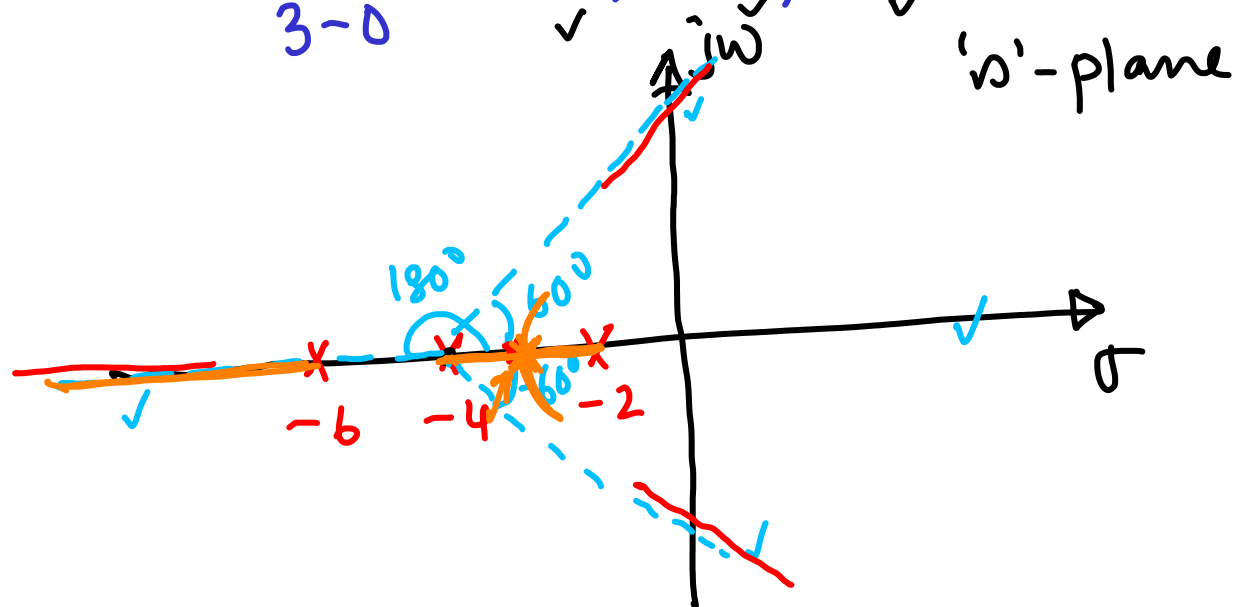
$$G(s) = \frac{k}{(s+2)(s+4)(s+6)} = k G(s) H(s)$$

No. of finite poles = 3 (-2, -4, -6)

No. of finite zeros = 0

$$\sigma = \frac{(-2-4-6) - (0)}{3-0} = \frac{-12}{3} = -4$$

$$\theta = \frac{180^\circ}{3-0} = 60^\circ, 180^\circ, 300^\circ$$



5. Real-axis breakaway or break-in points:

$$1 + K G(s) H(s) = 0 \quad \checkmark$$

$$K = -\frac{1}{G(s)H(s)} \quad \checkmark$$

Calculate $\frac{dK}{ds}$ and find the value of s so that $\frac{dK}{ds} = 0$.

Ex.

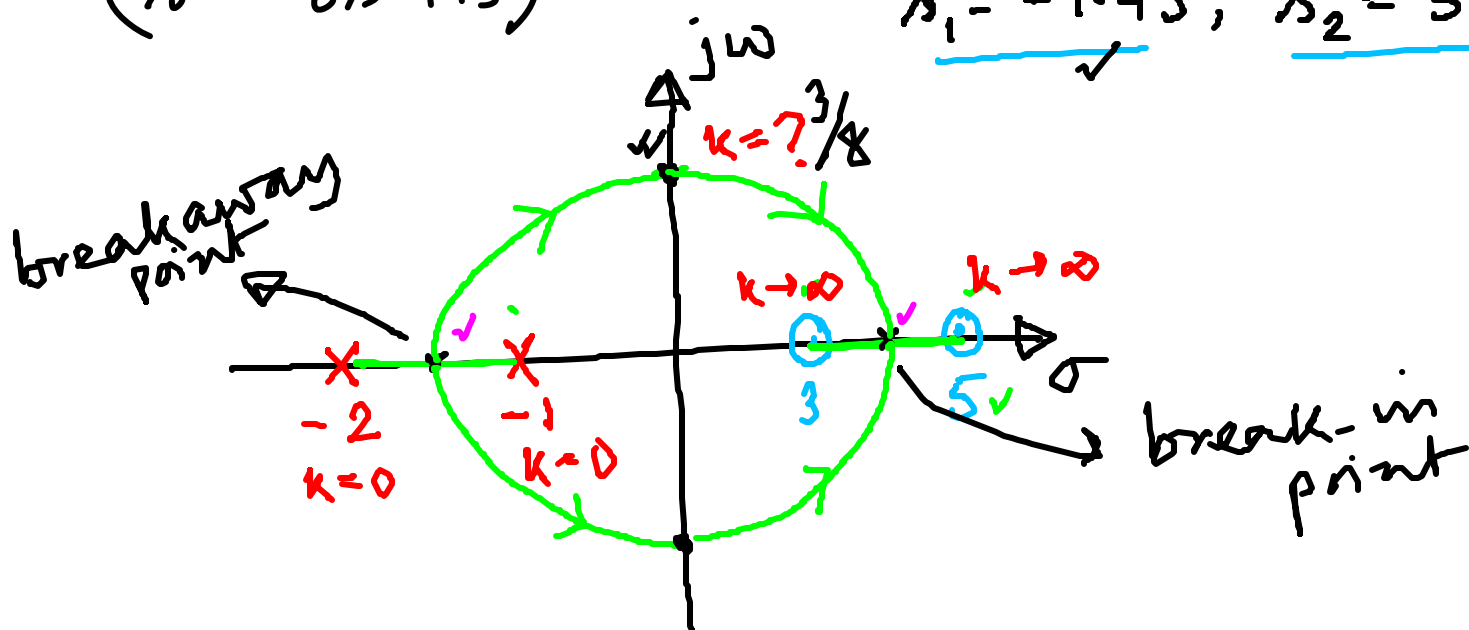
$$1 + K \frac{(s-3)(s-5)}{(s+1)(s+2)} = 0 \quad \checkmark \quad \checkmark \quad \checkmark \quad \checkmark \quad \checkmark \quad \checkmark \quad \checkmark \quad \checkmark$$

$$\Rightarrow \frac{K(s-3)(s-5)}{(s+1)(s+2)} = -1$$

$$\Rightarrow K = -\frac{(s^2 + 3s + 2)}{(s^2 - 8s + 15)} \quad \checkmark$$

$$\frac{dK}{ds} = \frac{11s^2 - 26s - 61}{(s^2 - 8s + 15)^2} = 0 \quad \checkmark \quad \checkmark$$

$$s_1 = -1.45, \quad s_2 = 3.82$$



6. The jw-axis crossing: The Routh-Hurwitz criterion is used to find the jw-axis crossing point and the corresponding gain K .

$$s^2 + 3s + 2 + K(s^2 - 8s + 15) = 0$$

$$s^2(K+1) + s(3-8K) + (2+15K) = 0$$

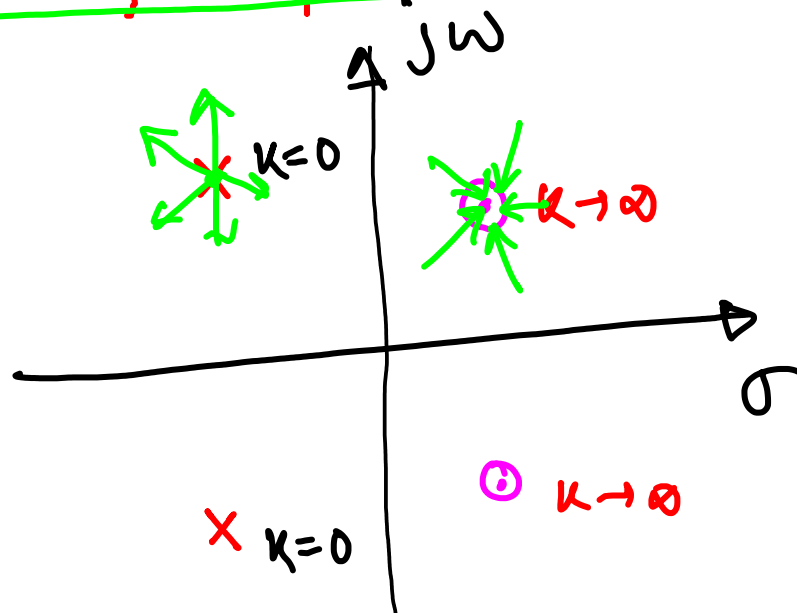
$$\begin{array}{l} s^2 (K+1) \quad (2+15K) \\ s (3-8K) \leftarrow \\ s^0 (2+15K) \end{array}$$

$$\begin{aligned} 3-8K &= 0 \\ \Rightarrow K &= \frac{3}{8} \checkmark \end{aligned}$$

Auxiliary eqⁿ:

$$A(s) = \frac{11}{8}s^2 + \frac{61}{8} = 0$$

7. Angle of departure and Arrival:

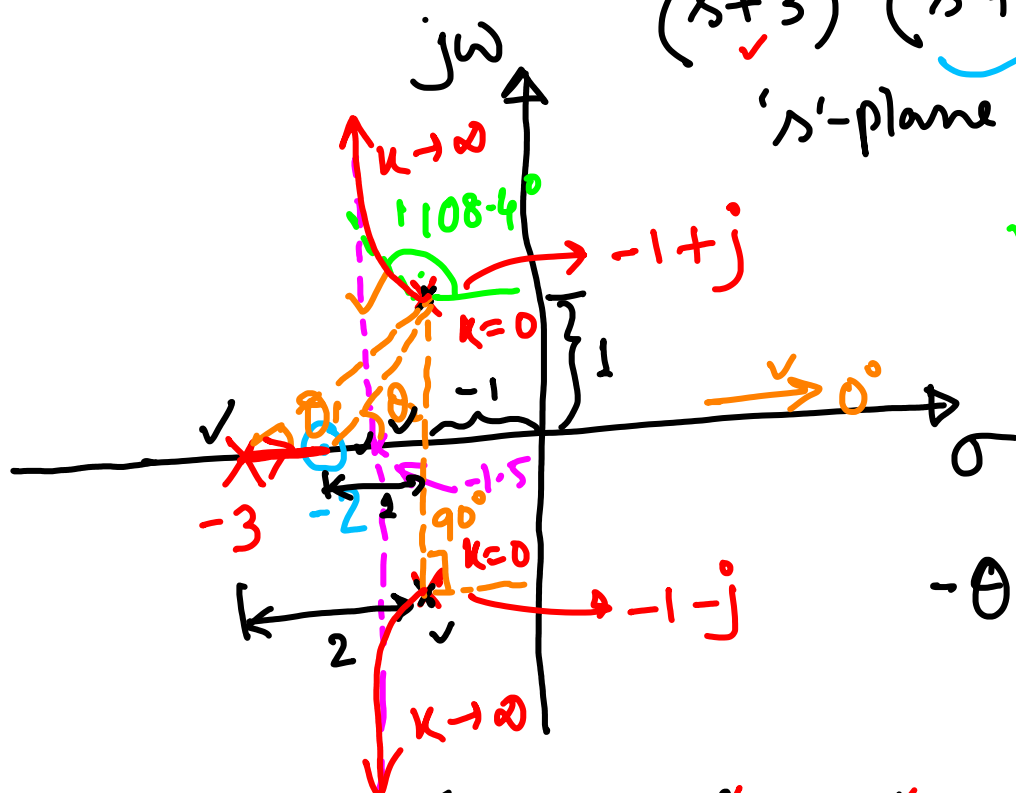


When complex conjugate pole and/or zero exist, we need to find angle of departure or arrival.

Ex

$$K G(s) H(s) = \frac{K (s+2)}{(s+3) (s^2 + 3s + 2)} \quad s_{1,2} = -1 \pm j$$

's'-plane



A point on root locus must satisfy

$$\angle K G(s) H(s) = (2k+1)180^\circ$$

$$-\theta_1 + \theta_2 - 90^\circ - \theta = 180^\circ$$

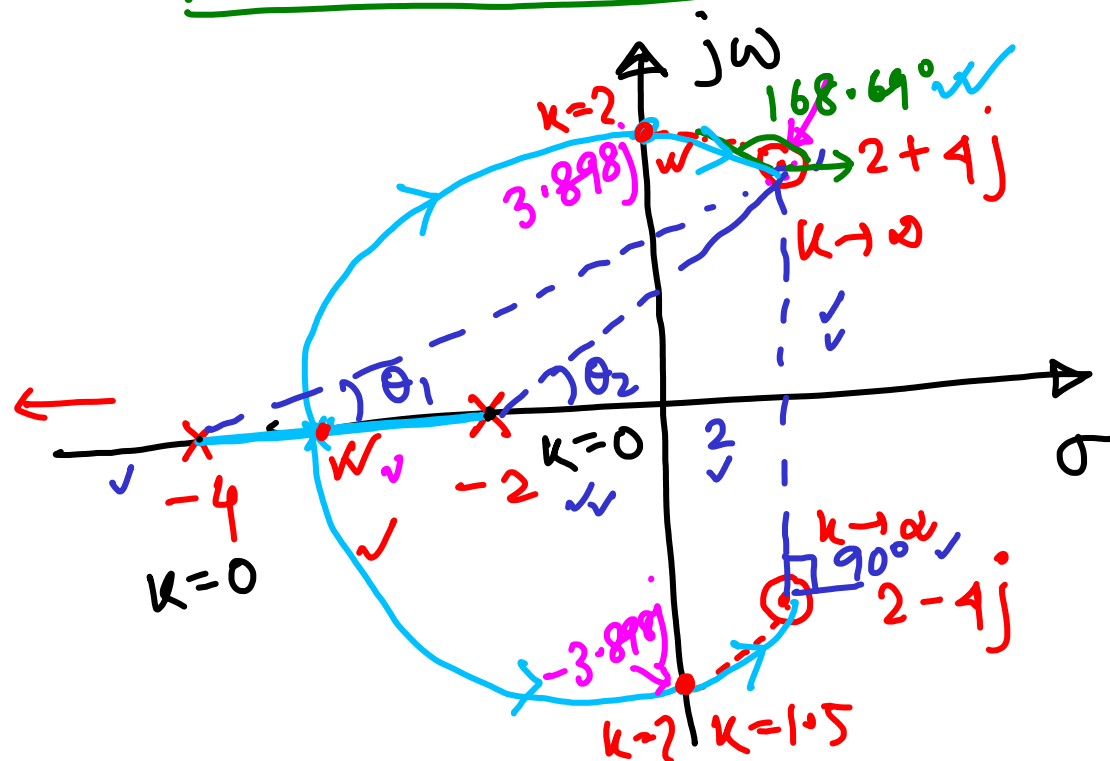
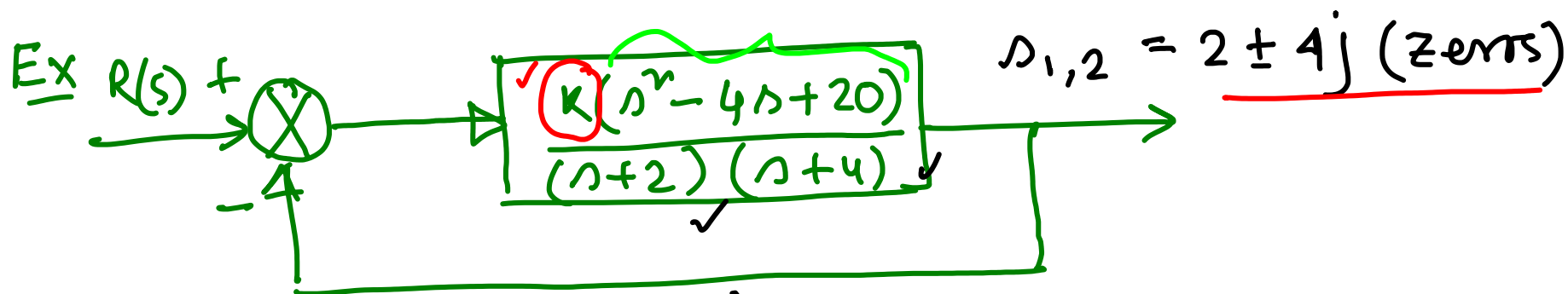
$$\text{Centroid } \sigma = \frac{(-3 - 1 + j - 1 - j) - (-2)}{3 - 1} = -\frac{3}{2} = -1.5$$

$$\text{Angle of asymptotes } \theta = \frac{180^\circ}{2} = 90^\circ, 270^\circ$$

$$\theta_1 = \tan^{-1}(1/2) \quad \theta_2 = \tan^{-1}(1/1)$$

$$-\theta = 180^\circ + 90^\circ + \theta_1 - \theta_2 = 270^\circ + 26.57^\circ - 45^\circ = 251.6^\circ$$

$$\theta = -251.6^\circ = 108.4^\circ$$



$$-\theta_1 - \theta_2 + 90^\circ + \theta = 180^\circ$$

$$-\tan^{-1}\left(\frac{4}{6}\right) - 45^\circ + 90^\circ + \theta = 180^\circ$$

$$-33.69^\circ - 45^\circ + 90^\circ + \theta = 180^\circ$$

$$\theta = 168.69^\circ$$

Angle of arrival

$$k = - \frac{(s^2 + 6s + 8)}{(s^2 - 4s + 20)}$$

$$\frac{dk}{ds} = 0, \quad 5s^2 - 12s - 76 = 0$$

$$s_{1,2} = -2.86, \quad 5.28$$

$$1 + k \frac{(s^2 - 4s + 20)}{s^2 + 6s + 8} = 0$$

$$s^2 + 6s + 8 + k s^2 - 4ks + 20k = 0$$

$$s^2(k+1) + (6-4k)s + (8+20k) = 0$$

$$s^2(k+1) \quad (8+20k) \quad k > 0 \quad \checkmark$$

$$s \quad (6-4k) \quad \text{---} \quad \text{---} \quad \text{---}$$

$$s^0 \quad (8+20k) \quad \checkmark$$

$$6-4k=0$$

$$\Rightarrow k = \frac{6}{4} = \underline{\underline{1.5}}$$

Auxiliary eqⁿ:

$$A(s) = \underline{2.5s^2 + 3.8s} = 0$$

$$\frac{dA(s)}{ds} = 5s$$

$$s_{1,2} = \pm \underline{\underline{3.898j}} \quad \checkmark$$

Root sensitivity (pole sensitivity)

The ratio of the fractional change in a closed-loop pole to the fractional change in a system parameter.

$$\zeta = \frac{\delta s/s}{\delta k/k} = \frac{k}{s} \frac{\delta s}{\delta k} \quad \checkmark \quad \checkmark \quad \frac{k}{s} \cdot \frac{\Delta s}{\Delta k} = \zeta$$

$$\Rightarrow \Delta s = \frac{s}{k} \zeta \Delta k$$

Ex Let ch. eqⁿ be

$$s^2 + 10s + k = 0$$

$$\Rightarrow 2s \frac{ds}{dk} + 10 \frac{ds}{dk} + 1 = 0$$

$$\text{Closed-loop TF} = \frac{K G(s)}{1 - K G(s) H(s)}$$

Poles of closed-loop system satisfy

$$1 - K G(s) H(s) = 0.$$

$$\Rightarrow K G(s) H(s) = 1 = \frac{1}{2K\pi} = \frac{1}{K 360^\circ}$$

$K = 0, \pm 1, \pm 2$

$$K = \frac{1}{|G(s)H(s)|}$$

$$|K G(s) H(s)| = \frac{K 360^\circ}{K} = 360^\circ, K = 0, \pm 1, \dots$$

1. No. of branches: NO change

2. Symmetry: NO change

3. Real-axis segment: On the real-axis, the root locus exists to the left of an EVEN number of real-axis, finite open-loop poles and/or finite open-loop zeros.

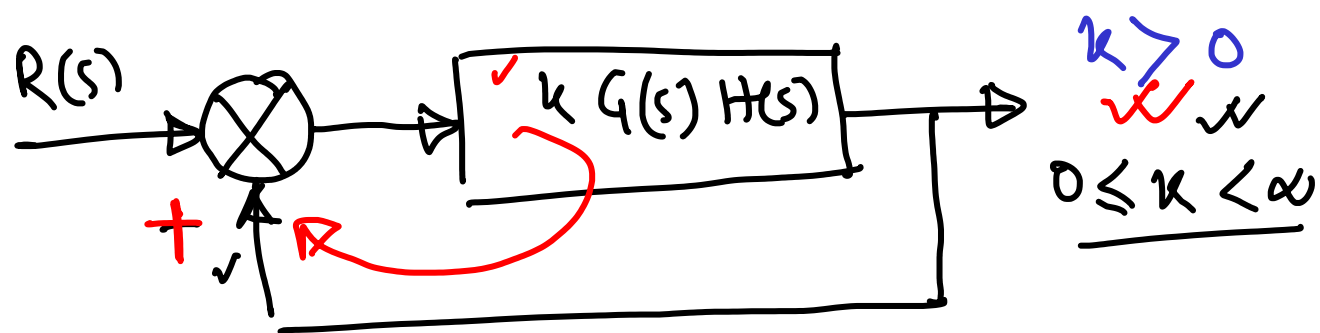
4. Starting and ending: NO change

5. Centroid and angle of asymptotes:

σ : NO change

$$\theta = \frac{2\pi K}{(\text{no of finite poles}) - (\text{no finite zeros})}$$

$K = 0, \pm 1, \dots$



If we
Consider
 $k < 0$ ✓
✓

$$\underline{-\infty < k \leq 0}$$

$$\begin{array}{c} k > 0 \\ \checkmark \quad \checkmark \\ \underline{0 \leq k < \infty} \end{array}$$