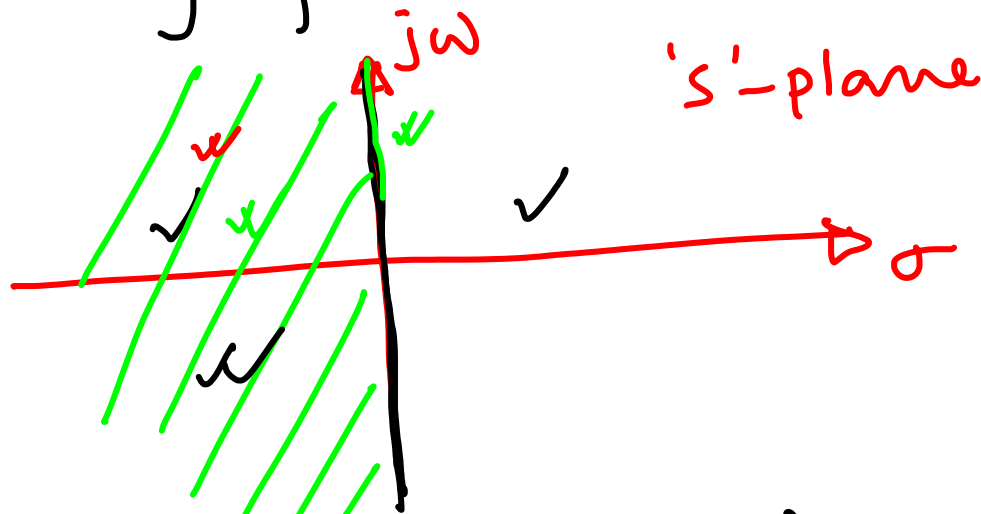


Routh-Hurwitz Criterion ✓✓

$$F(s) = \underbrace{a_n}_{-} s^{\underbrace{n}} + \underbrace{a_{n-1}}_{-} s^{n-1} + \dots + \underbrace{a_1}_{-} s + \underbrace{a_0}_{-} = 0 \quad \checkmark \checkmark \checkmark$$

- A method of determining the location of zeros of a polynomial with constant real co-efficients with respect to the left and right-half of the 's'-plane without actually solving for the zeros.



- The necessary and sufficient condition that all roots of a constant co-efficient polynomial lie in the left-half of the 's'-plane is that - the equation's Hurwitz determinant, D_k , $k=1, 2, \dots, n$ must all be positive.

$$D_1 = a_{n-1}, \quad D_2 = \begin{vmatrix} a_{n-1} & a_{n-3} \\ a_n & a_{n-2} \end{vmatrix}, \quad D_3 = \begin{vmatrix} a_{n-1} & a_{n-3} & a_{n-5} \\ a_n & a_{n-2} & a_{n-4} \\ 0 & a_{n-1} & a_{n-3} \end{vmatrix}$$

$$D_n = \begin{vmatrix} a_{n-1} & a_{n-3} & a_{n-5} & \dots & 0 \\ a_n & a_{n-2} & a_{n-4} & \dots & 0 \\ 0 & a_{n-1} & a_{n-3} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & a_0 \end{vmatrix}$$

where the coefficients with indices larger than n or negative need to be replaced by zero.

Routh table

$$a_6 s^6 + a_5 s^5 + a_4 s^4 + a_3 s^3 + a_2 s^2 + a_1 s + a_0 = 0$$

s^6	a_6	a_4	a_2	a_0
s^5	a_5	a_3	a_1	0
s^4	$A = \frac{a_5 a_4 - a_3 a_6}{a_5}$ $B = \frac{a_5 a_2 - a_1 a_6}{a_5}$ $C = \frac{a_5 a_0 - 0}{a_5} = a_0$			
s^3	$D = \frac{A a_3 - B a_5}{A}$ $E = \frac{A a_1 - a_0 a_5}{A}$			
s^2	$F = \frac{D B - E A}{D}$			

A	B
C	D
$\frac{CB - DA}{C}$	

$$G = \frac{FE - a_0 D}{F}$$

$$a_0$$

s^1
 s^0

For identification purpose

- The roots of the equation are all in the left half of the s -plane if all the elements of the first column are of the same sign.

- The number of changes of sign in the first column is equal to the number of roots with positive real part.

Ex.

$$s^3 - 4s^2 + s + 6 = 0$$

$$(s-2)(s+1)(s-3) = 0$$

\Rightarrow necessary condition fails \Rightarrow unstable polynomial

$$s^3 \quad 1 \quad 1$$

$$s^2 \quad -4 \quad 6$$

$$s \quad \frac{-4-6}{-4} = 2.5 \quad 0$$

$$s^0 \quad \frac{2.5 \times 6 - 0 \times -4}{2.5} = 6$$

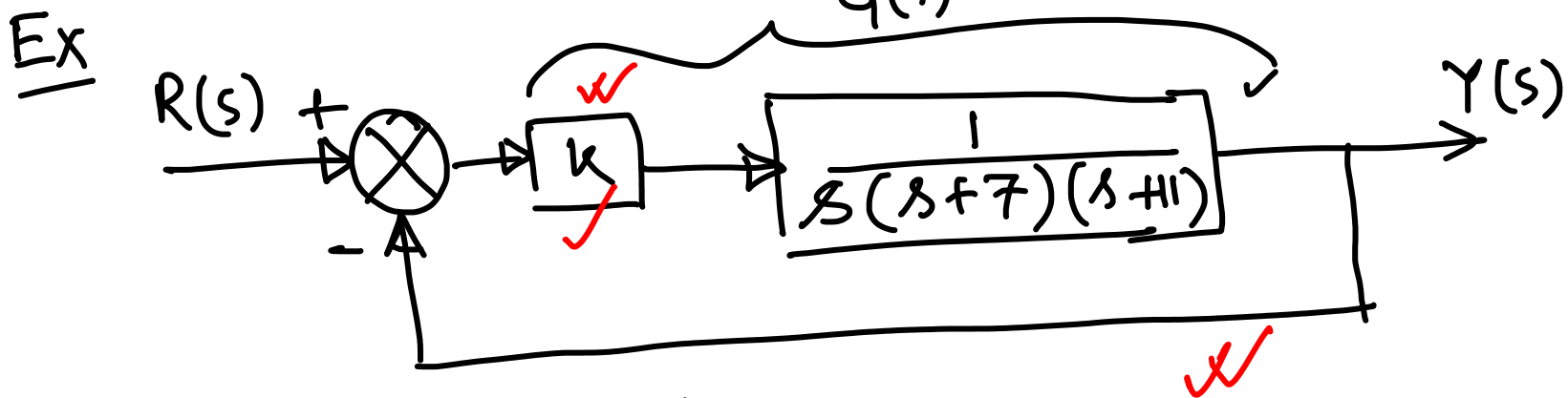
$+1$
 -4
 $+2.5$

$+ve$ to $-ve$
 $-ve$ to $+ve$

no. of changes of sign
 $= 2$

$+6$
First column

Two roots are in RHP



Assume $k > 0$.

Closed-loop TF = $\frac{Y(s)}{R(s)} = \frac{G(s)}{1+G(s)}$

$$= \frac{k}{s^3 + 18s^2 + 77s + k}$$

stable

$s^3 + 18s^2 + 77s + k = 0$

1386

s^3	1	\swarrow	77
s^2	18	\swarrow	k
s	$\frac{1386-k}{18}$	\swarrow	0
s^0	k		

The closed-loop is to be stable, if- $1386 - k > 0$
 $\Rightarrow k < 1386$

$0 < k < 1386$

If $k = 1386$, then

$$s^3 + 18s^2 + 77s + 1386 = 0$$

no change of sign

all elements in a row become zero.

s^3 1
 s^2 18
 s 77
 s^0 1386

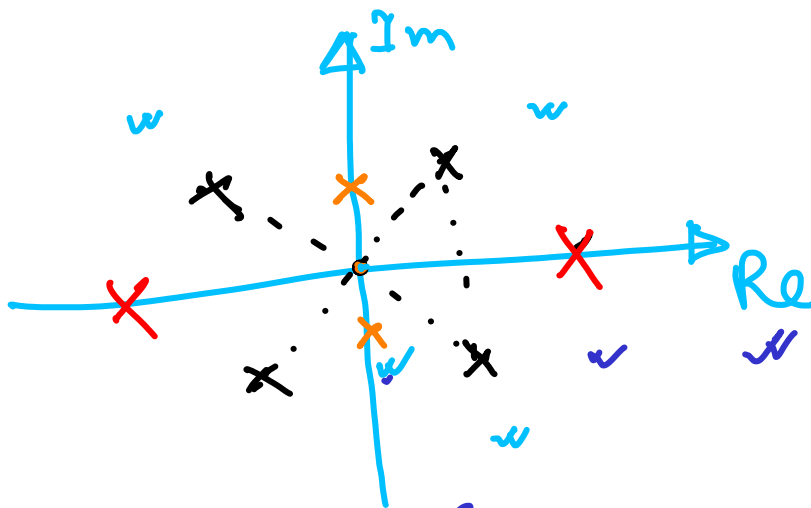
$1386 - 1386 = 0$
 $\frac{1386 - 1386}{18} = 0$
 36

$A(s) = 18s + 1386$ (Auxiliary polynomial)
 $\frac{dA(s)}{ds} = 36s$

An even polynomial (i.e. $s^4 + 2s^2 + 5$) is a factor of the original polynomial.

↳ when a row is completely zero

Even polynomial has roots symmetric to the origin.



- NO roots in the RHP. So no roots in the LHP since they should be symmetric w.r.t. origin.

— Two roots on the imaginary axis.

$$18s^2 + 1386 = 0$$

$$s^2 = -\frac{1386}{18} = -77$$

$$s_{1,2} = \pm 8.77j \quad \checkmark$$

$$\omega = \frac{2\pi}{T} = 8.77 \text{ rad/s.}$$

$$T = \frac{2\pi}{8.77} = \underline{0.716 \text{ s.}} \quad \checkmark$$

Ex. Determine the stability of the closed-loop

TF

$$T(s) = \frac{10}{s^5 + 2s^4 + 3s^3 + 6s^2 + 5s + 3} \quad \checkmark$$

Root locus diagram for the closed-loop system. The poles are at $s = -1, -2, -3, -4, -5$ and the zero is at $s = -3$. The root locus branches are shown with arrows. A green box highlights the region around the zero at $s = -3$.

[Zero appears only in the first column]

Label	$\epsilon = +ve$	$\epsilon = -ve$
s^5	+ve	+ve
s^4	+ve	+ve
s^3	+ve	-ve
s^2	-ve	+ve
s^1	+ve	+ve
s^0	+ve	+ve

Two poles in RHP.

E-method \rightarrow when the element in
the first column becomes
Zero.