Assignment -2

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(a)
$$e(n) = d(n) - \sum_{k>0}^{n-1} \omega_{k}^{n} u(n \cdot k)$$

where:

 $u \rightarrow confint$
 $e \rightarrow error$
 $d \rightarrow chrined output$
 $\omega_{k} \rightarrow color f$ pilons

 $f = f(n) e^{n}(n)$
 $f = f$

$$J = \frac{6a^{2} - \sum_{k=0}^{N-1} \omega_{k} p(-k) - \sum_{k=0}^{N-1} \omega_{k} p^{*}(-k)}{k=0}$$

$$+ \sum_{k=0}^{N-1} \sum_{i=0}^{N-1} \omega_{i} \omega_{i}^{*} \mu(i-k)$$

$$+ \sum_{k=0}^{N-1} \sum_{i=0}^{N-1} \omega_{i}^{*} \omega_{i}^{*} \mu(i-k)$$

This supresserts the error performance surface of the FIR filder and the analytical engineering is given here.

According to the give R&P, we unhatitute various times.

Ahn, Wo = R-P 602 = (R-P)MR. (R-P) = PMR-1.P.

$$R = \begin{bmatrix} 1 & 0.4045 \\ 0.4045 & 4 \end{bmatrix}, \quad D = \begin{bmatrix} 0 \\ 0.2339 \end{bmatrix}$$

 ve_{1}, ve_{2}, ve_{3} ve_{4}, ve_{5} ve_{6}, ve_{6}, ve

The cost function T is bood spaped curve characterized by filter tap weight $\omega_0, \omega_1 - \omega_{M-2}$ رطی Since the error surface is bout shaped, it is characterized by a unique minimum. J Menimum I point At the minimum, the gradient vector is 0. Here. \$\forall J_L J = 0 , b = 0, \lambda, - M-1

let wa = ant jbk.

 $\nabla_{b}J = \frac{\partial T}{\partial a_{h}} + \int \frac{\partial T}{\partial b_{h}}$ $T = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial T}{\partial b_{h}}$ $T = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial T}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial T}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \int \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial b_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ $V_{b}J = \frac{\partial U}{\partial a_{h}} + \frac{\partial U}{\partial a_{h}}$ V_{b

 $\frac{1}{\sqrt{4}} = 0 - \rho r(a) + -\rho^{*}(-b) + \frac{1}{\sqrt{2}} bin (red)$

$$R^{-} = \frac{1}{0.8363} \begin{bmatrix} 1 & -0.4045 \\ -0.4045 \end{bmatrix}$$

$$R^{-} = \begin{bmatrix} 0 \\ 0.1939 \end{bmatrix}$$

$$R^{-} = \begin{bmatrix} 1 & -0.4045 \\ -0.4045 \end{bmatrix} \begin{bmatrix} 0 \\ 0.2939 \end{bmatrix}$$

$$R^{-} = \begin{bmatrix} -0.44.215 \\ 0.3514 \end{bmatrix}$$

Lo Wiener-Hopf Solution

(e) The stepsize parameter
$$\mu$$
 $0 \le \mu \le \frac{2}{d mox}$ (from stability)

 $d max \ge 3$ the largest value of Routine

 $RX = dX \Rightarrow (R - dI)X = 0$
 $\Rightarrow R - dI = 0$
 $\begin{vmatrix} 0 - dI \end{vmatrix} = 0$
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>> 10cm < 1.4289