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[arduino-bootcamp](#) / [Wii_Pan_Tilt](#) / [DualServoSweep](#) / [DualServoSweep.ino](#)**leeassam** modified dual servo sweep 1 contributor

41 lines (30 sloc) | 1.12 KB

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```
1  /*
2   Arduino Bootcamp
3
4   - Dual Servo Sweep
5
6   This project demonstrates how two servos can be controlled
7
8   created 10/30/2016
9   modified 10/30/2016
10  by: Lee Assam
11
12  */
13
14  #include <Servo.h>
15
16  Servo myservo1; // create servo object to control a servo
17  // twelve servo objects can be created on most boards
18
19  Servo myservo2;
20
21  int pos = 0;    // variable to store the servo position
22
23  void setup() {
24    myservo1.attach(9); // attaches the servo on pin 9 to the servo object
25    myservo2.attach(10); // attaches the servo on pin 10 to the servo object
26  }
27
28  void loop() {
29    for (pos = 0; pos <= 180; pos += 1) { // goes from 0 degrees to 180 degrees
30      // in steps of 1 degree
31      myservo1.write(pos);
32      myservo2.write(pos); // tell servo to go to position in variable 'pos'
```

```
33     delay(15);                // waits 15ms for the servo to reach the position
34 }
35 for (pos = 180; pos >= 0; pos -= 1) { // goes from 180 degrees to 0 degrees
36     myservo1.write(pos);        // tell servo to go to position in variable 'pos'
37     myservo2.write(pos);
38     delay(15);                // waits 15ms for the servo to reach the position
39 }
40 }
41
```