

# SPRING MASS OSCILLATIONS

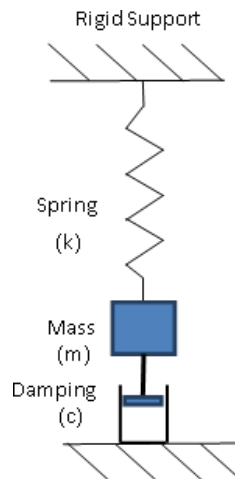
## Experiment No. 1 (Theory)

**Title:** - Free damped oscillation of mass-spring system

**Aim:** - To obtain damped time period, angular frequency, frequency, logarithmic decrement, damping ratio, natural frequency, initial displacement, initial velocity, initial phase, amplitude, exponentially decaying envelop,  $u(t)$ ,  $v(t)$  and  $a(t)$ .

**Apparatus:** - Slotted masses on holder, clamp and stand, spring, etc.

**Diagram:** -



**Theory:** - The displacement of a free damped spring mass system is given by

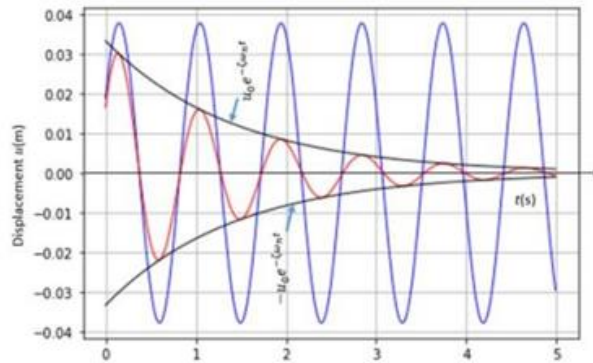
$$u(t) = e^{-\zeta \omega_n t} (u_0 \sin(\omega_D t - \Phi_0))$$

where, the amplitude  $u_0$  and phase  $\Phi_0$  are given by

$$u_0 = \sqrt{\left(\frac{\dot{u}(0)}{\omega_n}\right)^2 + (u(0))^2}$$

$$\Phi_0 = \tan^{-1} \left( \frac{-u(0)}{\frac{\dot{u}(0)}{\omega_n}} \right)$$

The typical displacement versus time curve looks like this:



The velocity and acceleration are  $v(t) = \dot{u}(t)$  and  $a(t) = \dot{v}(t)$ . The logarithmic decrement is,

$$\delta = \left(\frac{i}{j}\right) \ln \left( \frac{u_i}{u_{i+j}} \right)$$

And the damping ratio can be calculated from the logarithmic decrement from the relation:

$$\delta = \frac{2\pi\zeta}{\sqrt{1-\zeta^2}}$$

The angular frequency  $\omega_D$  of a damped system is related with the natural angular frequency  $\omega_n$  as

$$\omega_b = \omega_n \sqrt{1-\zeta^2}$$