Curriculum & Syllabus

of

M.E. Engineering Design

(For the batch admitted in 2007-08)



K.S.RANGASAMY COLLEGE OF TECHNOLOGY TIRUCHENGODE – 637 215

(An Autonomous Institution affiliated to Anna University of Technology Coimbatore and approved by AICTE New Delhi)

K.S.Rangasamy College Autonomous Re	R 2007						
Department	ent Mechanical Engineerin						
Programme Code & Name	31 : M.E. Engineer	ing Design					

	K.S.Rangas	samy College of Tech	nology	y, Tiru	cheng	ode - 637 2	215		
	Curricul	um for the Programme	s unde	r Auto	nomou	s Scheme			
Regulation		R 2007							
Department		Department of Mecha	anical I	Engine	ering				
Programme C	ode & Name	31 : M.E. Engineering	g Desig	gn					
		Seme	ster I						
Course Code	Cour	se Name		Hours, Week		Credit	Maximum Marks		
Code			L	L T P			CA	ES	Total
	THEORY								
07310101S	Advanced Mathem	natics	3	1	0	4	50	50	100
07310102S	Computer Applica	<u> </u>	3	0	0	3	50	50	100
07310103S	Finite Element An	•	3	1	0	4	50	50	100
07310104C	Concepts of Engir	neering Design	3	0	0	3	50	50	100
07310105C	Micro Electro Med Design	hanical Systems	3	1	0	4	50	50	100
073101**E	Elective I		3	0	0	3	50	50	100
	PRACTICAL								
07310107P	Computer Aided D	Design Laboratory	0	0	3	2	50	50	100
		Total	18	3	3	23		700	
		Seme	ster II						
Course	Cour	se Name		Hours, Week		Credit	Maximum Marks		
Code			L	Т	Р		CA	ES	Total
	THEORY								
07310201S	Mechanical Vibrat	ions	3	1	0	4	50	50	100
07310202C	Product Design ar	nd Development	3	0	0	3	50	50	100
07310203C	Advanced Mechai Kinematics	nisms and Robot	3	1	0	4	50	50	100
07310204C	Design for Manufa	acture and Assembly	3	0	0	3	50	50	100
073102**E	Elective II		3	0	0	3	50	50	100
073102**E	Elective III '		3	0	0	3	50	50	100
	PRACTICAL								
07310207P	Analysis and Simu	ulation Laboratory	0	0	3	2	50	50	100
07310208P	Technical Semina	r I	0	0	3	2	100	00	100
07310209P	Technical Report Presentation I	Preparation and	0	0	2	0	100	00	100
	Tota					24		900	

	K.S.Rangas	amy College of Tech	nology	y, Tiru	cheng	ode - 637 2	215		
	Curricul	um for the Programmes	s unde	r Auto	nomou	s Scheme			
Regulation		R 2007							
Department		Department of Mecha	nical I	Engine	ering				
Programme C	ode & Name	31 : M.E. Engineering	Desig	gn					
Semester III									
Course	Cour	se Name		Hours, Week		Credit	Ма	aximum l	Marks
Code	Code				Р		CA	ES	Total
073103**E	Elective IV		3	0	0	3	50	50	100
073103**E	Elective V		3	0	0	3	50	50	100
073103**E	Elective VI		3	0	0	3	50	50	100
07310304P	Project Work - Ph	ase I	0	0	12	6	100	00	100
07310305P	Technical Report Presentation II	Preparation and	0	0	2	0	100	00	100
		Total	9	0	14	15		500	
		Semes	ter IV						
Course	Cour	se Name		Hours, Week		Credit Max		aximum l	Marks
Code			L	Т	Р		CA	ES	Total
07310401P	Project Work - Phase II			0	40	20	50	50	100
		Total	0	0	40	20		100	•

	K.S.Rangas	amy College Of Tech	nology	y, Tiru	cheng	ode - 637	215			
	Curricul	um for the programme	s unde	r Autor	nomou	s Scheme				
Regulation		R 2007								
Department		Department of Mecha	anical E	Engine	ering					
Programme Co	ode & Name	31 : M.E. Engineering	g Desig	jn						
		List of E	lectives	3						
				Hours			Maximum Marks			
Course Code	Cours	se Name		Week		Credit			1	
			L	Т	Р		CA	ES	Total	
Electives I										
07310141E	Rapid Prototyping		3	0	0	3	50	50	100	
07310142E	Tribology in Desig		3	0	0	3	50	50	100	
07310143E	Optimization Tech	<u> </u>	3	0	0	3	50	50	100	
07310144E	Advanced Strengt		3	0	0	3	50	50	100	
07310145E	Product Data Man	•	3	0	0	3	50	50	100	
	T	Electi	ves II	ı					1	
07310251E	Mechanics Of Cor	•	3	0	0	3	50	50	100	
07310252E	Applied Engineeri	ng Acoustics	3	0	0	3	50	50	100	
07310253E	Advanced Tool De	esign	3	0	0	3	50	50	100	
		Electiv	es III							
07310261E	Design Of Hydrau Systems	lic And Pneumatic	3	0	0	3	50	50	100	
07310262E	Applied Finite Eler	ment Analysis	3	0	0	3	50	50	100	
07310263E	Mechanics Of Fra	cture	3	0	0	3	50	50	100	
07310264E	Applied Object Or	ented Programming	3	0	0	3	50	50	100	
		Electiv	es IV							
07310371E	Design Of Materia Equipments	l Handling	3	0	0	3	50	50	100	
07310372E	Experimental Stre	ss Analysis	3	0	0	3	50	50	100	
07310373E	Vibration Control A Monitoring	And Condition	3	0	0	3	50	50	100	
		Electiv	ves V							
07310381E	Integrated Manufa	cturing Systems	3	0	0	3	50	50	100	
07310382E	Theory Of Plates	And Shells	3	0	0	3	50	50	100	
07310383E	Design Of Heat Ex	changers	3	0	0	3	50	50	100	
		Electiv	es VI							
07310391E	Productivity Mana Engineering		3	0	0	3	50	50	100	
07310392E	Mechatronics in M Systems	anufacturing	3	0	0	3	50	50	100	

	K.S.Ra	ngasamy College of Technolo	gy -	Autono	mous F	Regula	ition		R 20	007	
Depart	ment	Mechanical Engineering	Р	rogramn Na	ne Code me	e &	31 : N	Л.E. Eng	1.E. Engineering Design		
			Se	emester	l						
Course	Codo	Course Name		Hou	rs / We	ek	Credit	М	aximum I	Marks	
Course	Code	Course Name		L	Т	Р	С	CA	ES	Total	
07310	101S	ADVANCED MATHEMATICS	3 1 0 4 50 50								
At the end of the study of the paper Advanced Mathematics, the student will be able to sol linear systems by methods of elimination, triangularisation and iteration, method of fin differences and Rayleigh Ritz methods, Solve numerically partial differential equations parabolic, elliptic and hyperbolic types with appropriate boundary and initial condition encountered in engineering design.											
									9		
Simultar method.	neous Numer	Equations: Gauss elimination ical Integration: Trepezoidal rule	and	simpsor	n's 1/3 a	scheme and 3/8	e- Gauss 3 th rules- \	seidel Veddle's	methods	-relaxation	
2 BO	UNDAF	RY & CHARACTERISTIC VALUI	E PR	OBLEM	S	То	tal Hrs		9		
method. 3 CA Extremu	LCULU	Finding eigenvalues / vectors b S OF VARIATIONS nctionals involving one unknown rivatives- several independent va	func	tion- sev	/eral un	To knowr	tal Hrs		9	•	
		PARTIAL DIFFERENTIAL EQU			CHILICUI		tal Hrs		9		
Finite d	ifferenc y condi	e expressions for partial derivations- Poisson equation – Relax	atives ation	- Lapl method	•	equation	on – Liebi	mann m	ethod -	derivative	
	RABOL UATIO	IC AND HYPERBOLIC PARTIA NS	L DIF	FEREN	TIAL	То	tal Hrs		9		
		 Explicit method – Crank- Ni Solution by finite differences, 									
Total ho	urs to b	e taught							45		
Text boo	ok (s) :										
	jasekara tion.	an.S "Numerical method in Scier	nce a	nd Engii	neering	" – W	heeler Pub	olishing ,	1999, Se	cond	
Referen	` '										
	uglas J cond ed	Faires and Riched Burden, "Nition.	lumei	rical Me	thods"	Brooks	s / Cole P	ublishin	g Compa	any, 1998,	
		atraman, Higher mathematics for	_	•					•	any,2000	
3 Joh	nn H Ma	athews and Kurtis D Fink, "Nume	erical	Methods	s using	MATL	AB", Prent	ice Hall,	1998.		
		ney and David Kincaid, "Numerio Fourth Edition, 1999.	cal M	athemat	ics and	Comp	outing", Bro	ooks/Col	le Publish	ning	

K.S.Ra	ngasamy College of T	echnology -	Autono	mous	Regul	ation		R 20	07	
Department	Mechanical Engineering	Programm	e Code	& Name	Э	31 : M.E	E. Engin	eering De	esign	
		S	emester	l						
Course Code	Course Nar	ma	Hou	rs / We	ek	Credit	М	aximum N	Marks .	
Course Code			L	T	Р	С	CA	ES	Total	
07310102S	COMPUTER APPLIC DESIGN		3	0	0	3	50	50	100	
Objective(s)	components. To develop the students the ability to utilize the computers in managing product design data.									
1 INTRODUCTION TO COMPUTER APPLICATIONS IN NEW PRODUCT DESIGN Total Hrs								<u> </u>		
	Concept design – parametric sketching – constraints – computer graphics principles-2D transformation, scaling,									
	owing, view ports – clipp ERS IN DESIGN	oing – data ex	change	formate			I	9		
			!-4:	£ 4		tal Hrs		-		
development -	of Mechanical compo plastic parts with dra ts – tolerance analysis	ift and shrink	kage allo	owance	- Re					
	ERS IN TOOLING DES					tal Hrs		9		
Mould design - tooling	jigs and fixtures desig	gn – check fo	r interfe	rences	– med	chanism de	sign an	d analysi	s – Rapid	
4 COMPUTE	ERS IN DESIGN PROD	UCTIVITY			To	tal Hrs		9		
design of shafts			, pro/Pro	gramm	es, sc	ript, LISP ϵ	etc to wr	ite applic	ations like	
5 MANAGIN	G PRODUCT DESIGN	DATA			To	tal Hrs		9		
	 library creation – ca 							itive desig	gn among	
peer groups – L Total hours to b	Design optimization for g	geometry – D	esign ch	еск, ар	proval	and valida	ition.	45		
Text book (s):	e taugnt							43		
1 William M.	Neumann and Robert	Sproul "Princi	iples of (Comput	er Gra	phics "McC	Graw Hill	Book Co).	
Singapore 2 Ibrahim Ze	<u>1989.</u> eid "CAD/CAM – Theory	and Practice	" _ McG	iraw Hil	l Inter	national Fo	lition 10	98		
Reference(s):	JA OND/ONIVI THEOLY	, and i rabilité	, ivioC		.,	national Et	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	 		
` '	CAD/CAM: Principles a	nd Application	ns" Tata	McGra	w Hill	Second Fo	lition 20	004		
	ndahl, E. G, CAD – Dat									
_	earn and M Pauline Bak					•				
3 Donaid He	an and wir admit bak	.c. Compater	Tapriid	,	THOC I I	un 11101332				

K.S.Ra	angasamy College of	Technology	- Autono	omous	Regula	ation		R 20	007	
Department	Mechanical Engineering	Programm	e Code 8	& Name		31 : M.	E. Engin	eering D	esign	
			Semeste	er I						
Course Code	Course Na	ame	Hou	rs / We	ek	Credit	М	aximum I	Marks	
Course code	000130110		L	T	Р	С	CA	ES	Total	
07310103S	FINITE ELEMENT A		3	1	0	4	50	50	100	
Objective(s)	To teach students problems and workin design.	g knowledge	of compu	uter-aide					engineering their use in	
	OUCTION & ONE-DIME					tal Hrs		9		
Relevance of finite element analysis in design - Variational principles and methods –Weighted-Integral statements – Weak formulations – Ritz method – Method of weighted residuals Applications of FEA - Finite element modeling – Co-ordinates and shape functions - Potentialenergy approach – Galerkin's approach – One dimensional finite element models in Solidmechanics and Heat transfer – Finiteelement model for beams										
	MENSIONAL PROBLE			1 1		tal Hrs		9		
Evaluation of heat transferPlanestress –	ion – Laplace equation of integrals – Assembl – Torsional cylindrica Axi-symmetric problen	y – Axi-symm Il member – ns – Principle	netric pro Transier	blems - nt analy	– Appl sis - ement	ications – Theory of	Conduc	tion and ty – Plar	convection	
	AMETRIC ELEMENTS					tal Hrs		9		
integration – G of 2D and 3D	Bilinear quadrilateral Gauss quadrature – Sta applications FURAL DYNAMICS AF	atic condensa	ation – Lo		sidera					
DOF-response	itions – Mass and dan e history – Model meth tion techniques –Exp	nods – Ritz ve	ectors –C	Compon	ent me	ode synthe	esis – Ha	armonic ı	response -	
	NEAR PROBLEMS & E					tal Hrs		9		
Large displace	Material non-linearity ment – Error norms ar							daptive re		
Total hours to								45		
Text book (s) :		41 E1 14 E1		41 III B		1 2 2 1 4		LE DO	1000	
_	.N., "An Introduction to									
	L, "A First Course in t	ne Finite Elem	nent Meti	nod", Ih	ird Ed	ition, Thon	nson Lea	arning, 20	002.	
Reference(s) :			l'aat'	-4 F' - ''		A L	:-"			
Wiley, Jo	obert Davis et al "Conc ohn & Sons, 1999.						sis",			
	d L.J., "Applied Finite I			n Wiley	, 1984					
3 S.S.Rao, "Finite Element Analysis", 2002 Edition.										
Zienkiewicz, O.C. and Taylor, R.L., "The Finite Element Method", Fourth Edition, Volumes 1 & 2, McGraw Hill International Edition, Physics Services, 1991.										
5 Bathe K	.J., "Finite Element Pro	cedures in Er	ngineerin	g Analy	sis", P	rentice Ha	II, 1990.			

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Department	Mechanical Engineering	Programm	e Code 8	& Name		31 : M.	.E. Engir	neering D	esign
			Semeste	er I					
Course Code	Course No	Course Name L T P C CA E				aximum N	Marks		
Course Code	Course iva	anie	L	Т	Р	С	CA	ES	Total
07310104C	CONCEPTS OF ENGINEERING DE		3	0	0	3	50	50	100
Objective(s)	To Import knowled geometric modeli Environmental and			modeling, processing,					
1 THE DESIGN PROCESS Total Hrs 9									
steps of Produc - CAD & CAM,	ocess - need identific et Design – Conceptu Human factors in De I ENGINEERING DE	al Design, Em sign.			n, deta				
Creativity and problem solving, Decision Theory, Modeling – Role of models in Engineering Design, Mathematical modeling, Geometric modeling, finite element modeling, Rapid Prototyping – Simulation Finite Difference method, Monte Carlo method – Optimization – Search methods, Geometric Programming, Structural and shape optimization.									
	L SELECTION AND	MATERIALS	IN DESIG	ΞN	To	tal Hrs		9	
selection Chart,	on – Ashby Chart an , Pugh selection methue failure, Design for	nod, selection	with cor	nputed					
4 MATERIA Classification of	L PROCESSING AN f manufacturing proc	D DESIGN esses and the	eir role ir	n design	To:	tal Hrs ors determ		9 e process	s selection,
4 MATERIAL Classification of use of process sheet metal for	L PROCESSING AN f manufacturing proc selection chart and c ming, Design for ca	D DESIGN esses and the computerized	eir role ir database	n design e – Desi	To , Fact gn for	tal Hrs ors detern manufacti	uring, De	9 e process	s selection, orging and
4 MATERIAL Classification of use of process sheet metal for stresses and he 5 LEGAL, E	L PROCESSING AN f manufacturing proc selection chart and c ming, Design for ca	D DESIGN esses and the computerized esting, Design	eir role ir database for mad SAFETY	n design e – Desi chining,	To , Fact gn for weldir	tal Hrs ors detern manufacti	uring, De	9 e process	s selection, orging and
4 MATERIAL Classification of use of process sheet metal for stresses and he ISSUES IN The origin of la Codes of ethics and remanufact reliability failure	L PROCESSING AN f manufacturing proc selection chart and c ming, Design for ca eat – treatment. THICAL ENVIRONM N DESIGN AND QUA aws, Contracts, - Lia s, solving ethical conf ture, Design for safe mode effect analysis	D DESIGN esses and the computerized esting, Design ENTAL AND SALITY ENGINE ability – Tort I licts. Design fety – Potentia	eir role ir database for mad SAFETY EERING Law- Pro or enviro	n design e – Desi chining, oduct Li onment -	To To yelding To ability	tal Hrs ors determ manufactu ng and as tal Hrs - Design Cycle asse	aspects	9 e process esign for f design for 9 of produ – Materia r safety,	s selection, orging and or residual act liability, al recycling
4 MATERIA Classification of use of process sheet metal for stresses and he 5 LEGAL, E ISSUES IN The origin of la Codes of ethics and remanufact reliability failure Total hours to b	L PROCESSING AN f manufacturing proc selection chart and c ming, Design for ca eat – treatment. THICAL ENVIRONM N DESIGN AND QUA aws, Contracts, - Lia s, solving ethical conf ture, Design for safe mode effect analysis	D DESIGN esses and the computerized esting, Design ENTAL AND SALITY ENGINE ability – Tort I licts. Design fety – Potentia	eir role ir database for mad SAFETY EERING Law- Pro or enviro	n design e – Desi chining, oduct Li onment -	To To yelding To ability	tal Hrs ors determ manufactu ng and as tal Hrs - Design Cycle asse	aspects	9 e process esign for fordesign for fo	s selection, orging and or residual act liability, al recycling
4 MATERIAL Classification of use of process sheet metal for stresses and he 5 LEGAL, E ISSUES IN The origin of la Codes of ethics and remanufact reliability failure Total hours to b Text book (s):	L PROCESSING AN f manufacturing proc selection chart and c ming, Design for ca eat – treatment. THICAL ENVIRONM N DESIGN AND QUA aws, Contracts, - Lia s, solving ethical conf ture, Design for safe mode effect analysis ie taught	D DESIGN esses and the computerized esting, Design ENTAL AND S ALITY ENGINE ability – Tort I licts. Design f ety – Potentia s, robust Design	eir role ir database for mad SAFETY EERING Law- Pro or enviro al Dange gn.	n design e – Desi chining, oduct Li onment - rs and	To To yeldin To ability Life Guidel	tal Hrs ors determ manufactung and as tal Hrs - Design Cycle asselines for d	aspects essment esign fo	9 e process esign for f design for 9 s of produ – Materia r safety, 45	s selection, orging and or residual act liability, al recycling
4 MATERIAL Classification of use of process sheet metal for stresses and he is supported by the stresses and he is supported by the supported	L PROCESSING AN f manufacturing proc selection chart and c ming, Design for ca eat – treatment. THICAL ENVIRONM N DESIGN AND QUA aws, Contracts, - Lia s, solving ethical conf ture, Design for safe mode effect analysis te taught orge E, Engineering	D DESIGN esses and the computerized esting, Design ENTAL AND SALITY ENGINE ability – Tort I licts. Design fety – Potentia s, robust Design Design –"A m	eir role ir database for mad SAFETY EERING Law- Pro or enviro al Dange gn.	n design e – Desi chining, oduct Li onment - rs and	To To yeldin To ability Life Guidel	tal Hrs ors determ manufactung and as tal Hrs - Design Cycle asselines for d	aspects essment esign fo	9 e process esign for f design for 9 s of produ – Materia r safety, 45	s selection, orging and or residual act liability, al recycling
4 MATERIAL Classification of use of process sheet metal for stresses and he S LEGAL, E ISSUES IN The origin of la Codes of ethics and remanufact reliability failure Total hours to b Text book (s): 1 Dieter, Ge Internation	L PROCESSING AN f manufacturing proc selection chart and c ming, Design for ca eat – treatment. THICAL ENVIRONM N DESIGN AND QUA aws, Contracts, - Lia s, solving ethical conf ture, Design for safe mode effect analysis te taught orge E, Engineering hal Edition, Singapore ich and Steven D. Ep	D DESIGN esses and the computerized esting, Design ENTAL AND SALITY ENGINE ability – Tort I licts. Design f ety – Potentia s, robust Design Design –"A me e 2000.	eir role ir database for mad SAFETY EERING Law- Pro or enviro al Dange gn.	n design e – Desi chining, oduct Li onment rs and	To n, Fact gn for weldin To ability - Life Guidel	tal Hrs ors determ manufactu ng and as tal Hrs - Design Cycle asse lines for d	aspects essment esign fo	9 e process esign for fr design for 9 s of produ – Materia r safety, 45 raw Hill,	s selection, orging and or residual act liability, al recycling Design for
4 MATERIAL Classification of use of process sheet metal for stresses and he 5 LEGAL, E ISSUES IN The origin of la Codes of ethics and remanufact reliability failure Total hours to b Text book (s): 1 Dieter, Ge Internation 2 Karl T. Viri	L PROCESSING AN f manufacturing proc selection chart and c ming, Design for ca eat – treatment. THICAL ENVIRONM N DESIGN AND QUA aws, Contracts, - Lia s, solving ethical conf ture, Design for safe mode effect analysis te taught orge E, Engineering hal Edition, Singapore ich and Steven D. Ep	D DESIGN esses and the computerized esting, Design ENTAL AND SALITY ENGINE ability – Tort I licts. Design f ety – Potentia s, robust Design Design –"A me e 2000.	eir role ir database for mad SAFETY EERING Law- Pro or enviro al Dange gn.	n design e – Desi chining, oduct Li onment rs and	To n, Fact gn for weldin To ability - Life Guidel	tal Hrs ors determ manufactu ng and as tal Hrs - Design Cycle asse lines for d	aspects essment esign fo	9 e process esign for fr design for 9 s of produ – Materia r safety, 45 raw Hill,	s selection, orging and or residual act liability, al recycling Design for
4 MATERIA Classification of use of process sheet metal for stresses and he 5 LEGAL, E ISSUES IN The origin of la Codes of ethics and remanufact reliability failure Total hours to b Text book (s): 1 Dieter, Ge Internation 2 Karl T. Viri Edition, 20 Reference(s): 1 Pahlgand	L PROCESSING AN f manufacturing proc selection chart and c ming, Design for ca eat – treatment. THICAL ENVIRONM N DESIGN AND QUA aws, Contracts, - Lia s, solving ethical conf ture, Design for safe mode effect analysis te taught torge E, Engineering nal Edition, Singapore ich and Steven D. Ep 2000. Beitz W "Engineering	D DESIGN esses and the computerized esting, Design ENTAL AND SALITY ENGINE ability — Tort I licts. Design fety — Potentias, robust Design Design —"A me 2000. ppinger "Product of Design" Spri	eir role ir database for mad SAFETY EERING Law- Pro or enviro al Dange gn. aterials a act design	n design e – Desi chining, oduct Li onment rs and and proc	To To yelding To ability Life Guidel cessing evelop	tal Hrs ors determ manufactu ng and as tal Hrs - Design Cycle asse lines for d g Approact oment", Mo	aspects essment esign fo	9 e process esign for fr design for 9 s of produ – Materia r safety, 45 raw Hill,	s selection, orging and or residual act liability, al recycling Design for
4 MATERIAL Classification of use of process sheet metal for stresses and here 5 LEGAL, E ISSUES IN The origin of la Codes of ethics and remanufact reliability failure Total hours to b Text book (s): 1 Dieter, Ge Internation 2 Karl T. Viriedition, 20 Reference(s): 1 Pahlgand 2 Ray M.S.	L PROCESSING AN f manufacturing proc selection chart and c rming, Design for ca eat – treatment. THICAL ENVIRONM N DESIGN AND QUA aws, Contracts, - Lia s, solving ethical conf ture, Design for safe mode effect analysis te taught orge E, Engineering hal Edition, Singapore ich and Steven D. Ep 2000.	D DESIGN esses and the computerized of esting, Design ENTAL AND SALITY ENGINE ability — Tort I licts. Design f ety — Potentia s, robust Design Design —"A me e 2000. ppinger "Production of the production of the	eir role ir database for mad SAFETY ERING Law- Proor environt Dange gn. aterials a lict design printice	n design e – Desi chining, oduct Li onment - rs and and proc n and D rlag NY-	To: I, Fact gn for weldin To: ability Life Guidel cessing evelop 1984	tal Hrs ors determ manufactu ng and as tal Hrs - Design Cycle asselines for design g Approact oment", Mo	aspects essment esign fo	9 e process esign for fr design for 9 s of produ – Materia r safety, 45 raw Hill,	s selection, orging and or residual act liability, al recycling Design for

	K.S.Ra	ngasamy College of T	echnology - Au	tonom	ous R	egulat	ion		R 20	07
De	partment	Mechanical Engineering	Programme C	Code &	Name		31 : M.I	E. Engir	neering D	esign
			Seme	ster I						
Col	ırse Code	Course Na	ame	Но	urs / W	eek	Credit	Ma	aximum l	Marks
	disc oddc			L	Т	Р	С	CA	ES	Total
07	310105C	MICRO ELECTRO MI SYSTEMS DESIGN		3	1	0	4	50 50 100		
Ob	jective(s)	manufacturing and mi	als and fabric	ation		ss, n	nicro me			echanical system
1 INTRODUCTION Total Hrs 9										
micr scal	Overview-Microsystems and microelectronics - Working principle of Microsystems -micro actuation techniques- micro sensors-types-microactuators-types-micropumpmicromotors-micro-valves-microgrippers-scaling laws- scaling in geomentry-scaling in rigid body dynamics- scaling in electrostatic forces- scaling in electricity- scaling in fluid mechanics- scaling in heat transfer.									
2	MATERIAL	S AND FABRICATION	PROCESS			To	tal Hrs		9	
piez - Ox 3 Intro and theo	oelectric cry kidation –CV MICROME duction-stat square plat ry and dar	o2, SiC, Si3N4 and poly stals polymers for MEN /D - Physical vapor dep CHANICS ic bending of thin plate e with all edges fixed - nping coefficients- the toughness and interfac	MS -conductive prosition - Depositions-circular plates - Mechanical vibermo mechanics	on by one b	s – Pho epitaxy dge fixe resona	otolitho - etch To ed – re nt vibr	ography - ing procestal Hrs ectangular ation- mic	Ion imp ss plate v	lantation 9 with all edeleromete	-Diffusion dges fixed ers-design
4		STEM MANUFACTUR		arnoo		To	tal Hrs		9	
pack		chnology-Bulk Micro ı rials-die level-device le aling								
5		STEM DESIGN				To	tal Hrs		9	
		ations-process design- stry-bio medical –aero s				al des	ign applic	ations o	f micro s	ystem in -
Tota	I hours to be	e taught							45	
Text	book (s):									
1		Gad-el-Hak, The MEMS								
2		ardner, Vijay K.Varadaı & sons Ltd.,2001.	n, Osama O.Awa	del Ka	rim, Mi	croser	sors MEN	/IS and	Smart De	evices,
Refe	erence(s):									
1	1997.	U.Rembold, Microsyste							rlin Heide	elberg
2		u,MEMS & Microsyster								<u> </u>
3	Francis E.H Tay and W.O Choong, Microfludics and BioMEMS Applications, Springer, 2002.									

K.S.Rar	K.S.Rangasamy College of Technology - Autonomous Regulation R 2007										
Department	Mechanical Engineering	Programme Code & Name 31 : M.E. E					E. Engin	ngineering Design			
	Semester I										
Course Code	Course Name		Hou	ırs / We	ek	Credit	M	laximum N	Marks		
Course Code	Course	ivame	L	Т	Р	С	CA	ES	Total		
07310107 P	CAD LABORATO	DRY	0	0	3	2	50	50	100		
Objective(s) To develop the students to work in solid modeling, sheet metal and mechanism design of mechanical components and feature based packages like pro-E, solid works etc											

Exercises in Sketching, Solid Modeling, Surface modeling, Sheet metaland mechanism design of Mechanical Components and assembly using Parametric and Feature Based Packages like PRO-E / SOLID WORKS /SOLID EDGE/CATIA / NX / ANSYS / NASTRAN etc.

K.S.Rangasamy College of Technology - Autonomous Regulation R 2007										
Department	Mechanical Engineering	Progran	nme Co	de & Na	ame	31	: M.E. E	ngineerii	ng Design	
			Semes	ster II						
Course Code	Course Nan	20	Hou	rs / We	ek	Credit		Maximur	n Marks	
Course Code	Course Mail	16	L	Т	Р	С	CA	ES	Total	
07310201S	MECHANICAL VIBI		3	1	0	4	50	50	100	
Objective(s) To impart knowledge on mechanical vibrations of single, multiple degrees of freedom and continuous systems, design systems to achieve the vibratory response, analyze and predict vibratory behavior of mechanical systems.										
forced vibration Support motion Transient Vibrat		oled viscou – Impulse	ıs damp	pers, S	ystem action	Identifica – Virtual	ition fro	m freque Lagrang	ency response, le's equation	
	REE FREEDOM SYS					tal Hrs		g	•	
	f spring-coupled syst				m – V	ibration o	f two de	gree free	edom system –	
	 Vibration Absorber GREE FREEDOM SY 		i isolatio	n.	To	tal Hrs		Ç	1	
orthogonal prop in forced vibration	of vibration – Flexib erties – Modal matrix on – Numerical metho	-Modal Ana ds for funda	alysis – amental	Forced	Vibrat					
	N OF CONTINUOUS					tal Hrs		g	•	
Effect of Rotary	ned by wave equation inertia and shear defo	rmation -	Vibration	n of plat	tes.		s – Eule	r Equation	on for Beams –	
	ENTAL METHODS IN					tal Hrs		9		
	ments – Vibration exc Examples of Vibration					ysis – Vib	ration T	ests – Fr	ee and Forced	
Total hours to be	e taught							4	5	
Text book (s):										
1990.	W.T., "Theory of Vib									
Rao, J.S. and Gupta, K., "Introductory Course on Theory and Practice Mechanical Vibration", New Age International (P) Ltd., New Delhi, 1999.										
Reference(s):										
-	g, J.P, "Mechanical Vi					-				
2 Rao, S.S., "Mechanical Vibrations", Addison Wesley Longman, New York, 1995.										

	K.S.Ranga	samy College of Te	chnology	- Auton	omous	Regu	lation		R	2007
De	partment	Mechanical Engineering	Progra	amme Co Name	ode &		31 :	M.E. En	gineering	g Design
				Semes	ter II					
Co	uraa Cada	Course Nor	~	Hou	rs / We	ek	Credit		Maximu	m Marks
Co	urse Code	Course Nar	ne	L	Т	Р	С	CA	ES	Total
07	7310202C	PRODUCT DESIG DEVELOPMENT		3	0	0	3	50	50	100
Objective(s) To Impart knowledge on product development process and challenges in product specifications, concept selection and product architecture.										
1	INTRODUC	TION				То	tal Hrs		Ç	9
Dev Dev Dev	elopment- C elopment P elopment P anization.	of Successful Production hallenges of Production rocess-Concept Devicess- The AMF	t Developn /elopment:	nent –D The F	evelopr ront-E	ment I nd Pr oduct	Processes ocess A Develop	s and C dapting	Organizat the Ge Organizat	ions-A Generic eneric Product ions-The AMF
2	PRODUCT	PLANNING				To	tal Hrs		ć	9
Hier 3 Prod Spe	archy- Estab PRODUCT duct specific	omers- Interpreting I lishing the Relative Ir SPECIFICATIONS cations- Stages of oncept Generation-T	nportance of Specification	of the Ne	eeds-Re tablishi	eflectir To ng Ta	ng on the tal Hrs arget Spe	Results ecification	and the sons- Set	Process.) ting the Final
4	CONCEPT	SELECTION				To	tal Hrs		()
Con Mea 5 Prod	cept Test- (ssuring Custo PRODUCT duct Archited	on- Overview of Methor Choosing a Surveyoner Response- Inter ARCHITECTURE Citure-Implications of Cig-Related System-Le	Population- preting the the Archite	Choos Results- ecture-E	ing a S Reflec	Survey ting o To	/ Format- n the Res tal Hrs	Commults and	unicating the Prod	the Concept- ess.
	al hours to be	·	voi Boolgii	100000.					4	5
	t book (s):							I .	<u> </u>	-
1	Ulrich, Karl 1999.	T. and Eppinger, S								Hill, New York,
2		n and Wood, Kristin, '	Product De	esign" Pe	earson	Public	ation, Nev	w Delhi,	2004.	
	Reference(s): Rosenthal, Stephen, "Effective Product Design and Development", Business One Orwin, Homewood,									
1 1992. Stuart Pugh., "Tool Design – Integrated Methods for successful Product Engineering", Addison Wesley										
2	Publishing,	New York, 1991.								
3	Kemnneth Crow., "Concurrent Engineering / Integrated Product Development", DRM Associates, 26/3, Via Olivera, Palos Verdes, Workshop Book.									

	N.S.Kang	gasamy College of Tec	hnology - A	Autonoi	nous I	Regul	ation		R	2007
De	partment	Mechanical Engineering	Ů	mme Co Name			31 : I	M.E. En	gineering	g Design
				Semeste	r II					
Col	urse Code	Course Nam	۵	Hou	rs / We	ek	Credit		Maximur	m Marks
	uise code	Course Ivaiii		L	Т	Р	С	CA	ES	Total
07	310203C	ADVANCED MECHAN AND ROBOT KINEMA	ATICS	3	1	0	4	50	50	100
-	jective(s)	To Impart knowledge of static force analysis, d				robot	kinematio			
1	INTRODU						tal Hrs		9	
		amentals of kinematics -		nalysis –	format	tion of	one D.O	.F. mult	i loop kin	ematic chains
2		a – Gross motion conce C ANALYSIS	pis.			Tot	tal Hrs		C)
		Velocity and acceleratio	n analysis c	of simple	mech			centres	kinemat	tics analysis c
		inisms, Goodman analy					o, motant	00111100	, Killollia	noo anaryoto c
3		RVATURE THEORY		•			tal Hrs		g)
4	SYNTHES	ose positions of the mor	<u> </u>			To	tal Hrs		ç	<u> </u>
gen	eration, pa	s – Number synthesis th generation, motion	generation	. Grapl	nical n	netho	ds. Cogn	ate lin	synthes	sis – functio Coupler curv
gen synt	eration, pa hesis, desiç	th generation, motion gn of six-bar mechanisı	generation ms. Algebra	. Grapl ic meth	nical n ods. A	netho	ds. Cogn	ate lin	synthes	sis – functio Coupler curv
gen synt Can 5	eration, pa hesis, design Mechanism DYNAMIC MECHANI	th generation, motion gn of six-bar mechanisi ms – determination of op S OF MECHANISMS AI SMS AND ROBOTICS	generation ms. Algebra otimum size ND SPATIA	. Grapl lic meth of Cam L	nical n ods. A s.	nethoo pplica To	ds. Cogn tion of in: tal Hrs	ate lin stant ce	I synthe: kages -(enter in li	sis – functio Coupler curv inkage desigr
gen- synt Can 5 Stat force Spa	eration, par thesis, design Mechanism DYNAMICS MECHANIST ic force anale, Kinetostatial RSSR r	th generation, motion gn of six-bar mechanisi ms – determination of op S OF MECHANISMS AI	generation ms. Algebra otimum size ND SPATIA rtia force ar on to force - Hartenber	. Graphic methor of Cam L nalysis - and morg Parar	nical nods. As comboment neters.	nethoo pplica Tot ined s baland Forw	ds. Cogn tion of instal Hrs static and cing of lingard and	inertia	I synthes kages enter in li	sis – functio Coupler curv inkage design O alysis, shakin tic Analysis o
gen- synt Can 5 Stat force Spa Man	eration, par thesis, design Mechanism DYNAMICS MECHANIST ic force anale, Kinetostatial RSSR r	th generation, motion gn of six-bar mechanisms – determination of op S OF MECHANISMS AISMS AND ROBOTICS alysis with friction – Inelatic analysis. Introduction echanism – Denavit - tudy and use of Mechanism	generation ms. Algebra otimum size ND SPATIA rtia force ar on to force - Hartenber	. Graphic methor of Cam L nalysis - and morg Parar	nical nods. As comboment neters.	nethoo pplica Tot ined s balance Forw	ds. Cogn tion of instal Hrs static and cing of lingard and	inertia	I synthes kages enter in li	sis – functio Coupler curv inkage design o alysis, shakin tic Analysis o tics of Roboti
gen- synt Can 5 Stat forc Spa Mar Tota	eration, par thesis, design Mechanism DYNAMIC MECHANIST ic force anale, Kinetostatial RSSR r sipulators. S	th generation, motion gn of six-bar mechanisms – determination of op S OF MECHANISMS AISMS AND ROBOTICS alysis with friction – Inelatic analysis. Introduction echanism – Denavit - tudy and use of Mechanism	generation ms. Algebra otimum size ND SPATIA rtia force ar on to force - Hartenber	. Graphic methor of Cam L nalysis - and morg Parar	nical nods. As comboment neters.	nethoo pplica Tot ined s balance Forw	ds. Cogn tion of instal Hrs static and cing of lingard and	inertia	synthes kages - 6 enter in li g force and Kinema	sis – functio Coupler curv inkage design o alysis, shakin tic Analysis c
genesynt Can 5 Stat force Spa Man Tota	eration, parthesis, design Mechanism DYNAMICS MECHANIST ic force anale, Kinetostatial RSSR rappulators. Sal hours to be took (s): Sandor G. 1984.	th generation, motion gn of six-bar mechanisms – determination of op S OF MECHANISMS AISMS AND ROBOTICS alysis with friction – Inelatic analysis. Introduction echanism – Denavit tudy and use of Mechanie taught N., and Erdman A.G.,	generation ms. Algebra otimum size ND SPATIA rtia force ar on to force - Hartenber nism using S	. Graphic methof Cam L nalysis - and morg Parar Simulation	nical nods. A s. - comboment neters. on Soft-	Totined sbaland Forware	ds. Cognition of instal Hrs static and cing of linerard and packages Analysis	inertia ahkages. inverse s.	I synthemate in line i	sis – functio Coupler curv inkage design alysis, shakin tic Analysis of tics of Roboti
gen- synt Can 5 Stat forc Spa Mar Tota Tex 1	eration, parthesis, design Mechanism DYNAMIC: MECHANISTIC MECHANISTIC FORCE and e, Kinetostatial RSSR raipulators. Sal hours to but book (s): Sandor G. 1984. Shigley, J.	th generation, motion gn of six-bar mechanisms – determination of open SOF MECHANISMS AISMS AND ROBOTICS alysis with friction – Inelatic analysis. Introduction echanism – Denavit tudy and use of Mechanie taught	generation ms. Algebra otimum size ND SPATIA rtia force ar on to force - Hartenber nism using S	. Graphic methof Cam L nalysis - and morg Parar Simulation	nical nods. A s. - comboment neters. on Soft-	Totined sbaland Forware	ds. Cognition of instal Hrs static and cing of linerard and packages Analysis	inertia ahkages. inverse s.	I synthemate in line i	sis – functio Coupler curv inkage design alysis, shakin tic Analysis of tics of Roboti
gen- synt Can 5 Stat forc Spa Mar Tota Tex 1 2	eration, parthesis, design Mechanism DYNAMIC: MECHANII: ic force anale, Kinetostatial RSSR raipulators. Sal hours to be took (s): Sandor G. 1984. Shigley, J.I. erence(s):	th generation, motion on of six-bar mechanisms – determination of open of MECHANISMS AISMS AND ROBOTICS alysis with friction – Ineletic analysis. Introduction mechanism – Denavitatedy and use of Mechanie taught N., and Erdman A.G., E., and Uicker, J.J., "The	generation ms. Algebra otimum size ND SPATIA rtia force ar on to force Hartenber mism using \$ "Advanced eory of Mac	. Graphic methof Cam L nalysis - and more Parar Simulation Mechan	ods. A s. comb ment I neters. on Soft	Toolined standard Forware	ds. Cognition of instal Hrs static and cing of lirerard and packages Analysis ms", McG	inertiankages.inverses.and Sy	force and Kinemat Kinemat Kinemat 4.	sis – functio Coupler curv inkage design alysis, shakin tic Analysis of tics of Roboti
gen- synt Can 5 Stat forc Spa Mar Tota Tex 1 2	eration, parthesis, design Mechanism DYNAMIC: MECHANISTIC MECHANISTIC FORCE and etail RSSR mipulators. Sal hours to be took (s): Sandor G. 1984. Shigley, J. Herence(s): Ghosh, American Mechanism of the sal force in the sal forc	th generation, motion on of six-bar mechanisms – determination of open SOF MECHANISMS AISMS AND ROBOTICS alysis with friction – Inelatic analysis. Introduction mechanism – Denavit tudy and use of Mechanie taught N., and Erdman A.G., E., and Uicker, J.J., "The mitabha and Mallik, Asok	generation ms. Algebra otimum size ND SPATIA rtia force ar on to force - Hartenber nism using S "Advanced eory of Mac Kumar., "T	. Graphic methof Cam L nalysis - and morg Parar Simulation Mechan hines ar	ods. A s. comboment oneters. on Soft-	Totined sibaland Forware esign	ds. Cognition of instal Hrs static and cing of lirerard and packages Analysis ms", McG	inertiankages.inverses.and Sy	force and Kinemat Kinemat Kinemat 4.	sis – function Coupler curvinkage design alysis, shakin tic Analysis of tics of Robot Prentice Hal
gen- synt Can 5 Statt force Spa Mar Tota 1 2 Refe	eration, parthesis, design Mechanism DYNAMIC: MECHANISTIC MECHANISTIC FORCE and etail RSSR mipulators. Sal hours to be took (s): Sandor G. 1984. Shigley, J. Herence(s): Ghosh, American Mechanism of the sal force in the sal forc	th generation, motion on of six-bar mechanisms – determination of open of MECHANISMS AISMS AND ROBOTICS alysis with friction – Ineletic analysis. Introduction mechanism – Denavitatedy and use of Mechanie taught N., and Erdman A.G., E., and Uicker, J.J., "The	generation ms. Algebra otimum size ND SPATIA rtia force ar on to force - Hartenber nism using S "Advanced eory of Mac Kumar., "T	. Graphic methof Cam L nalysis - and morg Parar Simulation Mechan hines ar	ods. A s. comboment oneters. on Soft-	Totined sibaland Forware esign	ds. Cognition of instal Hrs static and cing of lirerard and packages Analysis ms", McG	inertiankages.inverses.and Sy	force and Kinemat Kinemat Kinemat 4.	sis – function Coupler curvinkage design alysis, shaking tic Analysis of Robot Prentice Ha

	K.S.Raı	ngasamy College of	f Technology	- Auton	omous F	Regula	ation		R	2007
Dep	partment	Mechanical Engineering	Programm	e Code	& Name		31 : N	M.E. Er	gineerin	g Design
				Semes	ter II					
Cou	rse Code	Course Na	amo	Но	urs / Wee	ek	Credit		Maximu	m Marks
Cou	ise Code	Course in	airie	L	Т	Р	С	CA		Total
073	310204C	DESIGN FOR MAN AND ASSEMBLY		3	0	0	3			100
Obj	ective(s)									
1	PROCES	S CAPABILITY AND	TOLERANCE	S		To	tal Hrs		Ç	9
eval Asse 2 Influ	uation me embly limits FACTORS ence of ma	thod, Process capals -Datum features - S INFLUENCING FO aterials on form desi	bility - Feature Tolerance stace RM DESIGN gn - form desi	e tolera cks.	nces - G	To	tric tolera	ances -	-Worst o	ease method -
form 3		welded members, fo ENT DESIGN - MAC		SIDERA	ATION	То	tal Hrs		(9
Red rede group 5 Intro Des	chinability - COMPON esign of caup technolo DESIGN Foduction — ign guide I	Design for economy ENT DESIGN - CAS astings based on Past members to obvious - Computer Application - CAS Environmental objectives - Example application - Example application - Example application - CAS -	- Design for of TING CONSIDERATING LINE CONSIDERATION OF THE CONSIDERATI	clampab DERATI sideration entificati MA I issues cycle as	ility - Des ON ons - Mir on of un - Region	sign for To himizin econo To hal and and to Battern to the Battern	r accessit tal Hrs g core re mical des tal Hrs d local iss asic meth	equirementsign - I	Design fo	r assembly. achined holes, g the design - FE methods - nvironmentally
Tecl Des stan	hniques to ign for recy dards.	reduce environment yclability – Design fo	tal impact - D	esign to	minimize	e mate	erial usag	e – De	sign for	disassembly -
	al hours to l	be taught							4	5
	t book (s):									
1		ry., "Designing for M								
2		esign for Manufactui	re Handbook",	McGrav	v-Hill, Ne	w Yorl	k, 1999.			
Refe	erence(s) :									
1	London 2	I, G, Heartz and Nik 002.		· ·						el Dekker Inc.,
2		en and Wood, Kristir							2004.	
3	London, 1	, "Engineering Desgr 974.	•	• •						
4		edel T., "Design for t						996.		
5	Fixel, J., "	Design for the Enviro	onment", McGr	aw-Hill,	New Del	hi, 199	96.			

K.S.Ran	gasamy College of T	echnology	- Auton	omous	Regu	ation		R 20	07
Department	Mechanical Engineering	Programn	ne Code	& Nam	е	31 : M.E. Engineering Design			
		9	Semeste	r II					
Course Code	Course Nar	~ ^	Hou	ırs / We	ek	Credit	М	aximum N	Marks
Course Code	Course war	ne	L	Т	Р	С	CA	ES	Total
07310207P	ANALYSIS AND SIMULATION LABO	RATORY	0	0	3	2	50	50	100
Objective(s)	To develop the stud software.	ents to perfo	rm Anal	ysis of	beams	, trusses ar	nd fins u	sing analy	ysis

Analysis of mechanical machine components using analysis software

Introduction of CAE software, STRUCTURAL Analysis: Static analysis 2D, 3D, Beam, Truss. THERMAL Analysis: 2D Conduction, 3D Convection. DYNAMICS Analysis: Modal analysis, Transient analysis.

K.S.Ra	ngasamy Co	ollege of					ıs Regula	tion		R 20	07
Department	Mechan Enginee		Program N	me (lame	Code &	ı	3	1 : M.E.	Engin	eering Desigr	1
				S	emest	er II					
Course Code	Cou	ırse Nam	•	Но	urs / W	/eek	Credit		Ма	ximum Marks	3
Course Code	Cou	irse nam	Е	L	Т	Р	С	CA		ES	Total
07310208P	TECHNICA	L SEMIN	IAR I	0	0	3	2	100		00	100
Objective(s)	To make the								relate	d to the prog	gram – To
Methodology	sub • Ma • Usi by	oject stud terials rel ing OHP 5-10 mini	ied in the ated to ea / Power F utes for qu	seme ach to Point uestio	ester opic ha the Sto on & Ai	ve to udent nswer	· be collect	ed from sent for ussions.	variou: about	erging areas s sources 10-15 minute	
	Week						Activity				
	I	Fixing th	ne topics	in coi	nsultat	ion wi	th Faculty				
	II	Collecti	ng Materia	als							
	III-IV	Present	ation of th	ne firs	st topic	s by s	tudent (1/	3 stude	nts per	week)	
	VI-VIII	Present	ation of S	econ	d topic	s by s	student (1/	/3 stude	nts per	week)	
	IX-XI	Present	ation of T	hird t	opics l	oy stu	dent (1/3 :	students	s per w	eek)	
Execution			uous asse and 2 cre		ent and	d No E	nd Seme	ster exa	ıminatio	on	
		C	omponent	t					We	ightage	
	Presentatio	n of Topi	c –l						;	30%	
	Presentatio	n of Topi	c – II						;	30%	
	Presentatio	n of Topi	c – III						;	30%	
	Submission of 46 page write u topics				the thr	ee				10%	
						Tot	al		1	00%	

K.S.Ra	ngasamy College o	of Technolo	gy -	Auton	omo	ıs Regula	ation	F	R 2007
Department	Mechanical Engineering	Program N	nme C lame	Code &		3	1 : M.E.	Engineering De	sign
			S	emest	er II				
Course Code	Caura a Na		Но	urs / W	/eek	Credit		Maximum M	arks
Course Code	Course Na	me	L	Т	Р	С	CA	ES	Total
07310209P	TECHNICAL REP PREPARATION A PRESENTATION	ND I	0	0	2	0	100	00	100
Objective(s)	To provide exposuments and confection to improve the tectors.	rence proce	edin	gs.					cles in referred
Methodology	By mutual to the stude published The stude published The stude last 5 year Using OHI followed b The stude of the sem The stude page Abs Remarks a	ent. Ints have to literature. Int is expect s. Int is expect s. Int is expect s. Int is expect s. Int has make ester. Int has to we tract, Reviewed the set of F	refer ed to int, the s disc e two write a ew of Refere	the Jo collect ne stud cussion presen a Tech Rese ences)	y guid urnals t at lea lent ha n. ntatior nical arch . The	e will assi and Con ast 20 suc as to make as, one at Report fo paper und technical	gn a top ference th Reser the mid r about der vari report h	proceedings and arch Papers publication for 15-20 dle and the other and subheading as to be submitted of the faculty grant in the grant in the faculty grant in the faculty grant in the grant in the faculty grant in the	d collect the lished in the minutes r near the end itle page, One is, Concluding ed to the HOD
	Week					Activit	у		
	I Allotn	nent of Facu	ılty G	uide b	y the I	HoD			
	II Finali	zing the top	ic wit	h the a	approv	al of Facu	ulty Guid	le	
Execution	III-IV Collec	ction of Tec	hnica	I pape	rs				
Execution	V-VI Mid s	emester pre	senta	ation					
	VII-VIII Repo	t writing							
	IX Repo	t submissic	n						
	X-XI Final	presentatio	า						
	3 Hrs/week	and 2 cred	its	ment a	nd 50	% by End	Semes	ter examination	
		Component	t					Weightage	
Frakatian	Mid semester pres							25%	
Evaluation	Final presentation							25%	
	End Semester Exa	mination R	eport					30%	
	Presentation							20%	
					Tot	al		100%	

K.S.Rai	ngasamy Colleg	e of Technology	- Auton	omous	Regu	lation		R 20	08
Department	Mechanical Engineering	Programme	Code &	Name		31 : M.E. Engineering Design			sign
			Semeste	er III					
Course Code	Course	· Name	Hou	rs / We	ek	Credit	М	aximum N	/larks
Course Code	Course	: Name	L	Т	Р	С	CA	ES	Total
08310304P	PROJECT WO	RK - PHASE I	0	0	12	6	100	00	100
Objective(s)	technical proce	oractical knowled dures in their pr w the research a d placing this as	oject wo rticles, jo	rk. To p ournals	orovide and co	e an exposi onference p	ure to th proceedir	e student ngs releva	s to refer,
Methodology	one of v Probler Studen Report Prelimin	eviews have to be which should be soled in should be select that the select has to be prepared and implementation has to be select that the se	the guide cted about 20 ed by the tion can b	e. O papers e studer done	s relate ats as p	ed to their w per the form sible	/ork		

K.S.Ra	ngasamy College	of Technolo	ogy -	Auton	omou	ıs Regula	ation		R 20	007
Department	Mechanical Engineering	Program N	nme (Name			3	1 : M.E	. Engir	neering Desig	n
			S	emeste	er III					
Course Code	Course Na	me	Но	urs / W	/eek	Credit		Ma	aximum Mark	S
Course Code	Course No	une	L	Т	Р	31 : M.E. Engineering Design Credit Maximum Marks C CA ES To			Total	
07310305P	TECHNICAL REF PREPARATION A PRESENTATION	ND II	0	0	2					100
Objective(s)	journals and confe	erence proce	eedin	gs.						in referred
Methodology	By mutual to the stude published The stude published The stude last 5 year Using Ohmore followed the sere of the sere and page Abstrans.	I discussionate dent. Internature. Interna	s, the refer sed to bint, the discertise two of Refer	the Jo collectine studicussion preserva Tech Rese ences)	y guid urnals t atlea lent han. ntatior nical arch . The	e will assi and Con st 20 such as to make as, one at Report for paper und technical	gn a top ference h Resea e prese the mid r about der vari report h	procentation arch Pantation delean 30-50 ious sinas to b	ne general / sedings and compers published for 15-20 min	ed in the nutes ear the end page, One Concluding to the HOD
	Week				,	Activity			- randamy game	<u> </u>
	I Allotr	nent of Fact	ulty G	uide b	y the I	HoD				
	II Final	zing the top	ic wit	h the a	pprov	al of Facu	ılty Guid	de		
	III-IV Colle	ction of Tec	hnica	l pape	rs					
Execution	V-VI Mid s	emester pre	esent	ation						
	VII-VIII Repo	rt writing								
	IX Repo	rt submissio	on							
	X-XI Final	presentatio	n							
		ntinuous As and 2 cred		ment a	nd 50	% by End	Semes	ter exa	amination	
		Componen	t					We	eightage	
Frankrati	Mid semester pre								25%	
Evaluation	Final presentation								25%	
	End Semester Ex	amination R	eport						30%	
	Presentation								20%	
					Tota	al			100%	

K.S.Raı	ngasamy Colleg	e of Technology	- Auton	omous	Regu	lation		R 20	08
Department	Mechanical Engineering	Programme	Code &	Name		31 : M.	E. Engin	eering De	esign
			Semeste	er IV					
Course Code	Course	Nama	Hou	rs / We	ek	Credit	М	aximum N	Marks
Course Code	Course	: Name	L	Т	Р	С	CA	ES	Total
08310401P	PROJECT WO	RK - PHASE II	0	0	40	20	50	50	100
Objective(s)	implement their	and strengthens innovative idea le assessment m	s to fore	front th	e risk	issues and	to retri		
Methodology	one of v Each re Attenda valid re They sh Final re membe examin	eviews have to be which should be a ciview has to be earnce is compulso ason, one or more about publish the eview will be durs one of which er with in the collection should be su	the guide valuated bry for all tre chance paper prone by should lege)	fro 100 reviews se may be referably the cor	marks s. If a pe give y in the mmitted guide(I	student fail n journals/co that con f possible	Is to atte onference sists of include	end reviev es minimun one exter	v for some

K.S.Ra	ngasamy College of Ted	chnology	/ - Autor	nomous	Regu	lation		R 20	07
Department	Mechanical Engineering	Progra	amme Co	de & N	ame	31 : 1	M.E. Eng	jineering	Design
			Electi	ve					
Course Code	Course Nome		Hou	rs / We	ek	Credit	М	aximum N	/larks
Course Code Course Name Code & Name 31 : M.E. Engineering Design Elective Course Name Code &									Total
07310141E	TOOLING		_	_					100
	manufacturing industries		software	e for Ra	•	,, o	d rapid p	rototypin	g in
								•	
			t, History	of RP	system	ns, Survey c	of applica	itions, Gr	owth of
					То	tol Uro		E	
			2010 000				loobino d		nliaatiana
SELECTIVE L	ASER SINTERING - Ty								
		3			To	tal Hrs		9	
Principle, Proc	ess parameters, Path gen	eration,	Application	ons. SO	LID GF	ROUND CU	RING: P	rinciple o	f
operation, Mac	hine details, Applications.								
Thermo jet pri System. LASE	nter, Sander's model ma R ENGINEERED NET SH	arket, 3-	D printer	, Genis	sys Xs	printer, JF		5, Obje	
								•	
Rapid Tooling tooling, Lamina	Direct AIM, Quick cast plate tooling, soft tooling vs	rocess, C hard tool	Copper p		le, Rap	id Tool, DM			
6 SOFTWA	RE FOR RAPID PROTO	TYPING			To	tal Hrs		9	
Collaboration t Data preparation PROCESSES	erview of Solid view, Marools. RAPID MANUFACTON errors, Part building errors acting, Surfactor to solid models.	TURING ors, Erro	PROCE ors in finis	SS OF shing, Ir	TIMIZ/ nfluenc	ATION - Fa e of part bu	actors in ild orient	fluencing ation. AL	accuracy LIED
Total hours to I	oe taught							45	
Text book (s):									
1 Paul. F. J	acobs, "Stereo lithograph	y and oth	ner RP &	M Tech	nnologi	es", SME, N	NY, 1996		
2 Pham. D.	T. & Dimov. S. S., "Rapid	d Manufa	cturing",	Verlag,	Londo	n, 2001.			
Reference(s):	· · · · · · · · · · · · · · · · · · ·								
1 Terry Wo	hlers, "Wohlers Report 20	06", Wol	nlers Ass	ociates	, 2006.				

K.S.R	angasamy College of T	echnology -	Autonoi	nous R	egula	ntion		R 20	07
Department	Mechanical Engineering	Programm	e Code	& Name	:	31 : M.E	E. Engin	eering De	esign
		E	Elective						
Course Code	Course Nam		Hou	rs / Wee	k	Credit	Ma	aximum N	Marks
Course Code	Course Main	ie	L	T	Р	С	CA	ES	Total
07310142E	TRIBOLOGY IN DESIG		3	0	0	3	50	50	100
Objective(s)	To create awareness o elements.	·	nce of Tr	ibology			election		ne
	ES, FRICTION AND WEA					tal Hrs		9	
Properties of mapping, mea coatings. Com 2 LUBRICA Lubricants —	ction – Mechanism of fric metallic and non metallic surements, wear resista puter Simulations of friction ATION THEORY selection criteria – lub sic equations, Reynold's	materials, fr nce materials on, lubrication rication regin	riction in s – surfa n and we nes – I	extrem ace trea ar. Hydrody	e cor atmen	nditions. W t, surface otal Hrs	ear – T modifica and pla	ypes, meations an	echanism, d surface
3 DESIGN Dynamic analypivoted – ma	operties. Hydrostatic lubr OF FLUID FILM BEARIN ysis of hydrodynamic be ss flow rate, friction, poness of squeeze film and	GS earing perform ower loss, he	nance, t	rust and	d jour	difference	e, dynar	9 partial, nic load	fixed and s, oil film
	RIAL COMPONENTS AN		ZITIOIOTIC	Tiyaroc		tal Hrs	oigii.	9	
mechanics, be life prediction,	s – self acting finite beari earing internal load distrib torque calculation, tempe ND AUTOMOTIVE TRIB	oution, lubrica erature analys	tion - B	earing g	geome sting	etry and ki	nematic	s, load ra	
mechanism. Flubrication reg normal pressu	Mechanism, components Principles of Aerospace limes, engine bearings, re distribution, brakes, e cro tribology of MEMS ma be taught	eccentric be wheel bearin ffects of serv	earing t igs, tire. ice on e	est me Mecha ngine o	chani nics il pro	sm. Engin of load tra perties. Tri	e Tribo insfer – bology i	logy –im contact in manufa	nportance, area and
Text book (s):							ı		
1 Cameron	, A. "Basic Lubrication Th	eory", Ellis He	erward L	td., UK,	1981				
2 Hulling, J	.(Editor) – " Principles of	Tribology", Ma	acMillan	, 1984.					
Reference(s):									
1 Williams,	J.A. "Engineering Tribolo	gy", Oxford U	Iniversity	Press,	1994				
2 Neale, M	.J. "Tribology Handbook",	Butterworth I	Heinema	nn, 199	5.				
3 Bharat Bl	nushan, "Modern Tribolog	y Handbook"	Vol. – I	& II.					

	K.S.R	angasamy College of Tec	hnology -	Autonoi	mous F	Regula	ition		R 20	07
Departi	ment	Mechanical Engineering	Programn	ne Code	& Nam	ne	31 : M.E	E. Engin	eering De	esign
	•		E	lectives		•				
Course	Codo	Course Name		Hou	rs / We	ek	Credit	M	aximum I	Marks
Course	Code	Course marrie		L	Т	Р	С	CA	ES	Total
07310	143E	OPTIMIZATION TECHNIC DESIGN		3	0	0	3	50	50	100
Objecti	. ,	To Impart knowledge techniques in design.	on static,	dynami	c con			nconstra	ained op	timization
1 IN	TRODL	JCTION				To	tal Hrs		9	
formulat	tion of o	acteristics of mechanical entire objective function, design c	onstraints -						es of opt	timization,
2 UN	CONS	TRAINED OPTIMIZATION				To	tal Hrs		9	
		e and multivariable optimiz adient search methods – In				onstra	ined minin	nization	Golde	n section,
		AINED OPTIMIZATION	•			To	tal Hrs		9	
	ers; Ge	vith equality and inequality ometric Programming - Co								
		APPLICATIONS				To	tal Hrs		9	
		lications - Design of sim								
		ded members for minimur	n cost, ma	ximum v	weight	– Des	sign of sha	afts and	torsiona	lly loaded
		sign of springs. C APPLICATIONS				To	tal Hrs		9	
		cations – Optimum design	of single tw	n deare	e of fre			ibration		'S
		Mechanisms – Optimum de								
Total ho	ours to I	oe taught							45	
Text boo	ok (s) :									
l Pu	ıblisher	S.Rao., "Engineering Opt s 1996.		•					`) Limited,
2 Jol	hnson I	Ray, C., "Optimum design o	of mechanic	al eleme	ents", V	۷iley, د	John & Sor	ıs, 1990		
Referen	. ,					-				
	ilyanam t. 1995	noy Deb, "Optimization for .	Engineerin	g design	algori	thms a	and Examp	les", Pro	entice Ha	all of India
	oldberg. ork, 198	, D.E., "Genetic algorithms 9.	in search,	optimiza	tion an	d mad	hine", Barr	nen, Ado	dison-We	sley, New

K	.S.Rar	ngasamy College of	Technology	/ - Autor	nomous	s Regu	lation		R 20	007
Departm	ent	Mechanical Engineering	Program	me Code	& Nam	ne	31 : M.	E. Engin	eering De	esign
				Electi	ve					
Cauras	· o al o	Caura Mare		Hou	ırs / We	ek	Credit	M	laximum l	Marks
Engineering Programme Code & Name 31 : M.E. Engineering Design			Total							
0731014	4E	MATERIALS			_					100
Objective	e(s)	techniques from er mechanics of materia	ngineering als to more	mechani advance	ics and	d appl	ied mathe	matics,	basic co	oncepts in
1 ELA	STICI					To	otal Hrs		9	
dimensior – Airy's st flow.	nal stre ress fu	ess of a tension – ger unction. hear Centre:L	neralized Ho	oke's lav	v − St.\	ennan arious	t's principle sections –	– Plane		
2 UNS	SYMM	ETRICAL BENDING				To	tal Hrs		9	
members closed rin	 circ g subj 	umferential and radia ected to concentrated	al stresses - load and ur	 deflect niform loa 	ion and	l radial ain link	curved be and crane	eam with	re-strair	
Radial an speed. – I	d tanç Rotatir	gential stresses in so ng shafts and cylinder	lid disc and s.	ring of		thickn	ess and va		ickness -	
function -	Torsi	onal stresses in hollow			ory – e			analogy		dtl's stress
plates. Th	eory o	of contact stresses - r								
Total hour	rs to b	e taught							45	
Text book	(s):									
Edu	cation	1985.	•						•	
		Cook, Wareen.C.Your	nd, "Advance	ed Mecha	anics of	Materi	als", Macm	illon Pub	lishers C	ompany,
	` '									
2003	3.									
		S., Advanced Mechan	ics of Solids	s, Tata M	cGraw	Hill Pub	olishing Cor	mpany L		003
3 1997	7.	ju, N., Gururaja,D.R., , "Advanced Topics of								

	K.S.Ran	gasamy College of Ted	chnology -	· Autono	mous	Regul	ation		R 20	07
De	partment	Mechanical Engineering	Prograi	mme Co	de & Na	ame	31 : N	И.Е. Eng	jineering	Design
				Elective						
Č	rse Code	Course Name		Hou	rs / We	ek	Credit	М	aximum N	Marks .
Coc	iise Code		,	L	Т	Р	С	CA	ES	Total
073	310145E	PRODUCT DATA MANAGEMENT		3	0	0	3	50	50	100
Ob	jective(s)	To Impart knowledge of product data, projects a			nent, co	Ū		agement	, compon	ents on
1	INTRODUC						otal Hrs		9	
		DM-present market con	straints-ne	ed for c	ollabora	ation -	internet ar	nd devel	opments	in server-
2	computing.	ENTS OF PDM				To	tal Hrs		9	
_		a typical PDM setup-ha	rdware and	d softwa	re-doci	_		l ent-creat	•	viewing of
	ments-creat	ing parts-versions and v	ersion conf							
3	CONFIGU	RATION MANAGEMENT	Γ			To	tal Hrs		9	
Base	lines-produ	ct structure-configuration	n managen	nent-cas	e studie	es.				
4	PROJECTS	S AND ROLES				To	tal Hrs		4	
		cts and roles-life cycle						ating inf	ormation	flow-work
flows 5		f work flow templates-life MANAGEMENT	e cycle wor	k flow int	egratio		e studies. Ital Hrs	T	5	
·			n. rooti noti o	م مام م				41		
		nange request- change i PRODUCTS AND VARI		n- chang	je propo		change ac tal Hrs	livity - Ca		98.
6					- C				9	
and p	product conf	nt Systems for FEA data igurator-generic product ng of variants in product	modeling	in config	uration					
Total	hours to be	taught							45	
Text	book (s):									
1		, Kristin Wood, "Product	•							
2	Daniel Am	or, "The E-Business Re	volution", F	Prentice-l	Hall, 20	00.				
Refe	rence(s):									
1	McGraw Hi		·			Ū	`	-		ring ".
2	•	rain. "Visual Modeling wi		I Rose a	nd UML	_ ". Ad	dison Wesl	ey199	8.	
3	Wind-Chill	R5.0 Reference Manuals	s 2000.							

	K.S.R	angasamy College of T	echnology - A	utonom	ous R	egula	tion		R 20	07
Dep	artment	Mechanical Engineering	Programme	Code &	Name	•	31 : M.E	E. Engin	eering De	esign
			Sem	ester II						
Cour	se Code	Course Nam		Hou	s / We	ek	Credit	Ma	aximum N	Marks
Cour	se Code			L	Т	Р	С	CA	ES	Total
073	10251E	DESIGN OF HYDRAUL PNEUMATIC SYSTEMS	3	3	0	0	3	50	50	100
Obje	ective(s)	To Impart knowledge of Hydraulic & pneumatic circuits and their installa	actuators, thei	control						
1	ACTUATORS									
volun	netric, me	er Generators – Selectior chanical and overall effic cification and characterist	iencies of posit							
2	CONTRO	L AND REGULATION EL	EMENTS			То	tal Hrs		9	
		ection and flow control varietion and flow control values, relays					d safety va	alves - A	Actuation	systems.
		LIC CIRCUITS	,				tal Hrs		9	
press	s circuits -	 Quick return, sequence Hydraulic milling maching f components - Safety are 	ne - Grinding,	planning	, copyi					
4	PNEUMA	TIC SYSTEMS AND CIR	CUITS			То	tal Hrs		9	
Fring	e conditio	damentals - Control elem ons modules and these in nethod - Compound circu	itegration - Se	quential	circuits	s -Cas	cade meth			
		ATION, MAINTENANCE					tal Hrs		9	
		uipments - Selection of cuits - Use of microproces								
	hours to								45	
Text	book (s):									
1	Espossito	, Antony., "Fluid Power w	ith Application	s", Prent	ice Ha	II, New	/ York, 198	30.		
	Pease, D New Delh	udleyt, A. and Pippenger, ii, 1985.	John J., "Indu	strial Hy	draulic	s", Tat	a McGraw	-Hill,		
Refe	rence(s) :									
1	Parr, And	rew, "Hydraulic and Pneu	matics", Jaico	Publishi	ng Hou	ıse, N	ew Delhi, 2	2004.		
2	Bolton. W	., "Pneumatic and Hydra	ulic Systems", I	Butterwo	rth –H	einem	ann, 19 <mark>97</mark>			

	K.S.Ra	ngasamy College o	f Technology	y - Autor	nomous	Regu	lation		R 20	07
De	partment	Mechanical Engineering	Progra	amme Co	ode & N	ame	31	: M.E. Eı	ngineerinç	g Design
				Semest	er II					
Col	ırse Code	Course Na	ımo	Hou	ırs / We	ek	Credit	M	aximum N	Marks
COL	iise Code		-	L	Т	Р	С	CA	ES	Total
07	310252E	APPLIED ENGINE ACOUSTICS		3	0	0	3	50	50	100
Ob	jective(s)	To Impart knowledge transmission pheno	mena and co					tion of so	ound and t	their
1		DNCEPTS OF ACOL					tal Hrs		9	
Alte	ration of wanding waves	stics – Sound pressu we paths –Measurer s – Acoustic energy o	nent of sound density and in	waves -	- sound	spectra	a– Sound f	ields – In		
2		TERISTICS OF SOL					tal Hrs		9	
		sional wave equation								Velocity
		ssive sound wave th /e propagation along								on
3		ISSION PHENOMEN		onea and	aci terio		ital Hrs	lon in two	9	011.
	nges in me	dia — Tranemieeion f								
thro	ection at the	e surface of a solid, nedia.	normal incide	nce, obli		dence-			ttern – Tra	
thro 4	ection at the ugh three m AN INTRO MEASUR	e surface of a solid, nedia. DDUCTION TO THE EMENT OF SOUND	normal incide	nce, obli	que inci	dence- To	- Standing otal Hrs	wave pat	tiern – Tra	ansmission
4 Intro	ection at the ugh three many AN INTRO MEASUR oduction – Tesure level -	e surface of a solid, i nedia. DDUCTION TO THE	ASSESSMEI the measurer ntours – Perc	NT AND ment of serived no	ound position	To ower – –Loud	- Standing stal Hrs Sound leveness, Loud	wave pat	ttern – Tra 9 -Weighted el, perceiv	d sound yed noise,
4 Intropress	ection at the ugh three many AN INTRO MEASUR oduction – To sure level - teived noise BASIC CO	e surface of a solid, inedia. DDUCTION TO THE EMENT OF SOUND The decibel scale for Equal Loudness co elevel – Equivalent so	ASSESSMEI the measurer ntours – Percound level– I E CONTROL	NT AND ment of served no	ound poisiness level –	To ower – –Loud Freque	- Standing otal Hrs Sound leveness, Loudency and Autal Hrs	wave pat	9 -Weighteel, perceives measurer	d sound yed noise, ment.
4 Intro pres perc 5 Nois of m	ection at the ugh three m AN INTRO MEASUR oduction – T sure level - ceived noise BASIC CO se Control a	e surface of a solid, nedia. DDUCTION TO THE EMENT OF SOUND The decibel scale for Equal Loudness control Education Education Source Person Noise to the source, path, and revolved — Determinat	ASSESSMEI the measurer ntours – Percound level– I E CONTROL eceiver – Noi	NT AND ment of served nodentified se control	ound positions and the control of th	Toower – Loud Freque Too	standing stal Hrs Sound leveness, Loudency and Aletal Hrs I treatment	wave pat el meter - ness leve mplitude - Machin	Weighted el, perceive measurer 9 nery noise	d sound yed noise, ment.
Intro pres perc 5 Nois of m Aco	ection at the ugh three many thre	e surface of a solid, nedia. DDUCTION TO THE EMENT OF SOUND The decibel scale for Equal Loudness continued by Elevel — Equivalent source, path, and revolved — Determinat sures.	ASSESSMEI the measurer ntours – Percound level– I E CONTROL eceiver – Noi	NT AND ment of served nodentified se control	ound positions and the control of th	Toower – Loud Freque Too	standing stal Hrs Sound leveness, Loudency and Aletal Hrs I treatment	wave pat el meter - ness leve mplitude - Machin	Weighted el, perceive measurer 9 nery noise	d sound yed noise, ment.
Intro pres perc 5 Nois of m Aco Tota	ection at the ugh three many thre	e surface of a solid, in edia. DDUCTION TO THE EMENT OF SOUND. The decibel scale for Equal Loudness control to Elevel — Equivalent source, path, and revolved — Determination is the source.	ASSESSMEI the measurer ntours – Perc ound level– I E CONTROL eceiver – Noi ion of sound p	nce, oblice NT AND ment of served noted to the control of the cont	ound positions ound positions ound positions ound positions ound ound ound ound ound ound ound ound	To ower – -Loud Freque To oustica	- Standing stal Hrs Sound leve ness, Loud ency and A stal Hrs I treatment r level – No	wave patel meter - ness levemplitude - Machinise redu	9 -Weighter el, perceiv measurer 9 nery noise	d sound yed noise, ment.
Intro pres perc 5 Nois of m Aco Tota	ection at the ugh three many thre	e surface of a solid, nedia. DDUCTION TO THE EMENT OF SOUND The decibel scale for Equal Loudness complete level — Equivalent sonce, path, and revolved — Determinate sures. De taught awrence E. and Frey York, 1986.	ASSESSMEI the measurer intours – Perc cound level– I E CONTROL eceiver – Noi ion of sound p	nce, oblice NT AND ment of second notes of the control of the cont	ound positioness level –	Toower – —Loud Freque Too Dustical powe	standing stal Hrs Sound leveness, Loudency and Aletal Hrs I treatment r level – Notal Hrs tics", John	el meter - ness leve mplitude - Machin bise redu	Weighted el, perceiv measurer 9 nery noise ction proc	d sound yed noise, ment. e – Types edures –
thro 4 Intro pressperce 5 Nois of m Aco Tota Text 1	ection at the ugh three man in three	e surface of a solid, nedia. DDUCTION TO THE EMENT OF SOUND The decibel scale for Equal Loudness complete level — Equivalent sonce path, and revolved — Determinate sures. De taught Enter Solid So	ASSESSMEI the measurer intours – Perc cound level– I E CONTROL eceiver – Noi ion of sound p	nce, oblice NT AND ment of second notes of the control of the cont	ound positioness level –	Toower – —Loud Freque Too Dustical powe	standing stal Hrs Sound leveness, Loudency and Aletal Hrs I treatment r level – Notal Hrs tics", John	el meter - ness leve mplitude - Machin bise redu	Weighted el, perceiv measurer 9 nery noise ction proc	d sound yed noise, ment. e – Types edures –
thro 4 Intro pressperce 5 Nois of m Aco Tota Text 1	ection at the ugh three many thre	e surface of a solid, nedia. DDUCTION TO THE EMENT OF SOUND The decibel scale for Equal Loudness control level — Equivalent source, path, and revolved — Determinate sures. De taught Enwrence E. and Frey York, 1986. In A. and Hansen, Control level in the solid in the solid in the surface	ASSESSMEI the measurer intours – Perc cound level– I E CONTROL eceiver – Noi ion of sound p	nce, oblice NT AND ment of second notes of the control of the cont	ound positioness level –	Toower – —Loud Freque Too Dustical powe	standing stal Hrs Sound leveness, Loudency and Aletal Hrs I treatment r level – Notal Hrs tics", John	el meter - ness leve mplitude - Machin bise redu	Weighted el, perceiv measurer 9 nery noise ction proc	d sound yed noise, ment. e – Types edures –

K.	S.Ra	ngasamy College of Tec	hnology -	Autonor	nous F	Regula	ition		R 20	07
Departme	nt	Mechanical Engineering	Programm	ne Code	& Nam	ie	31 : M.E	E. Engin	eering De	esign
			Ser	mester I						
Course Co	odo	Course Name		Hou	rs / We	ek	Credit	M	aximum I	Marks
Course Co	Jue	Course Mairie		L	Τ	Р	С	CA	ES	Total
07310253	3E	ADVANCED TOOL DES	IGN	3	0	0	3	50	50	100
Objective	(s)	To Impart knowledge on of drill jigs, design of fixture.							t Treatme	ent design
1 TOOL	-DES	SIGN METHODS				To	tal Hrs		9	
Ideation – drawings –	Tent Scre	The Design Procedure – ative Design Solutions – ews and Dowels – Hole le cture – Electro-discharge	The Finish ocation – J	ed Desi ig-boring	gn – D g practi	raftino ce – I	g and Des nstallation	ign Tecl of Drill	hniques Bushings	in Tooling
2 TOOL	ING	MATERIALS AND HEAT	TREATMEN	NΤ		To	tal Hrs		9	
Steel – No cutting too selection or	onme ls – f cark	roperties of Materials – Fe tallic Tooling Materials – Milling cutters – Drills ar bide cutting tools – Determ	Nonferround Drilling	s Toolin - Ream	g Mate er clas	erials sificat or car	- Metal cu on - Taps oide tools	itting To	ools – Si classific	ngle-point
		F DRILL JIGS					tal Hrs		9	
Automatic Chip forma	gage ation	Fixed Gages – Gage Tole s – Principles of location - in drilling – General con orill jigs and modern manu	 Locating is siderations 	methods	and de	evices	- Principle	es of cla	mping –	Drill jigs –
4 DESIG	GN C	F FIXTURES AND DIES				То	tal Hrs		9	
Broaching - Blanking layout -She TOOL	Fixtu and ort-ru DES	ixtures and economics – 7 res – Lathe Fixtures – Gri Piercing die construction n tooling for Piercing – Be SIGN FOR NUMERICALL	nding Fixtu – Pilots – ending dies	res –Typ Strippers – Formir	oes of [s and p	Die co ressu – Dra	nstruction - re pads- P	– Die-de resswor	esign fund	damentals
MACE										
systems in	use Tool h	The need for numerical of today – Fixture design for nolding methods for numeroduction – General explar	or numerica erical contr	ally contr ol – Aut	olled n	nachin tool c	e tools – c hangers a	Cutting nd tool	tools for positione	numerical ers – Tool
presetting -		e taught							45	
presetting - Machines	s to b	e taught							45	
presetting Machines Total hours Text book	s to b	e taught , Cyrll., LeCain, George H	. and Goold	d, V.C., "	Tool D	esign"	, Tata McG	Fraw- Hi		ork, 2000.
machines Total hours Text book (s to be (s) :							Braw- Hi		ork, 2000.
machines Total hours Text book (s to b (s) : Idson , Prak	, Cyrll., LeCain, George H						∂raw- Hi		ork, 2000.

	K.S.Ra	ngasamy College o	of Technology	y - Autor	nomous	s Regu	lation		R 20	07
De	partment	Mechanical Engineering	Progran	nme Cod	le & Na	me	31 : 1	M.E. En	gineering	Design
				Semest	er II					
_	0 1	0 11		Hou	ırs / We	ek	Credit	N	laximum N	/Jarks
Col	ırse Code	Course Na	ame	L	Т	Р	С	CA	ES	Total
07	310261E	MECHANICS OF COMPOSITE MAT		3	0	0	3	50	50	100
Ob	jective(s)	To Impart knowled materials their des					al Mechani	cs, mec	hanics of o	composite
1	INTRODU	JCTION				To	tal Hrs		9	
fibe	s - Matrices r surface tr	ed – General Charad s – Polymer, Graphi eatments - Fillers a	te, Ceramic ar	nd Metal	Matrice	s – Cha	aracteristics	of fiber		
2	MECHAN	ICS				То	tal Hrs		9	
You	ng's modul	materials approach lus – major Poisso cteristics of Fiber -Ro	n's ratio - In-	plane sh	near mo	odulus, –Lamir	Ultimate s	strengths	of a un	idirectional
		cal Properties – Fat	ique and Impa	oct Drone	ortice _			octe – I	Ū	nronartias
		rior and Damage Tol		act i tope	- III	LIIVIIO	illiciliai elli	ccis – L	ong term	properties,
4		CTURING				То	tal Hrs		9	
		 Compression Moution methods - Proce 								
5		OF STRUCTURES					tal Hrs		9	
Join com	t design-Bo pression m	ons - Laminate Des olted and Bonded of nember – Design of inated composites.	Joints - Desig	gn Exam	ples -	Design	of a tens	ion mer	nber - D	esign of a
Tota	al hours to b	e taught							45	
Tex	book (s):									
1	Mallick, P 1993.	.K., "Fiber Reinforce	d Composites	: Materia	als, Man	ufactur	ing and De	sign", M	arcel Dek	ker Inc,
2	Autar K. k	Caw, "Mechanics of C	Composite Ma	terials" C	CRC Pre	ess, 20	06.			
Ref	erence(s):									
1		B.D., and Broutman w York, 1990.	L.J., "Analysis	and Per	rforman	ce of F	iber Compo	sites", J	lohn Wiley	and and
2	Ronald G	ibson, "Principles of	Composite Ma	aterial M	echanic	s", Tata	a McGraw I	Hill, 199	4.	
3	Chawla K	.K., "Composite mat	erials", Spring	er – Verl	ag, 198	7.				

	K.S.R	angasamy College of T	echnology -	Autono	mous	Regul	ation		R 20	007	
De	partment	Mechanical Engineering	Program	me Code	e & Nar	ne	31 : N	1.E. Eng	ineering	Design	
			Se	emester	II						
Cou	rse Code	Course Nam	0	Hou	rs / We	ek	Credit	М	aximum l	Marks	
<u> </u>	ise Code			L	Т	Р	С	CA	ES	Total	
073	310262E	APPLIED FINITE ELEN ANALYSIS		3	0	0	3	50	50	100	
Obj	ective(s)	To Teach students the problems involving fluid To provide students wand their use in design.	l mechanics, ith a working	linear ar	nd non-	linear.			· ·		
1	BENDING	OF PLATES AND SHE	LLS			To	otal Hrs		9		
Eler	Review of Elasticity Equations – Bending of Plates and Shells – Finite Element Formulation of Plate and Shell Elements - Conforming and Non Conforming Elements – C ₀ and C ₁ Continuity Elements – Application and Examples.										
2		EAR PROBLEMS					tal Hrs		9		
Geo		Iterative Techniques – M n linearity – large displac									
3	DYNAMIO	C PROBLEM				To	tal Hrs		9		
		tion – Free, Transient ar oubolt, Wilson, Newmarl				on Pro	ocedures –	Subspa	ce Iterativ	re	
4	_	ECHANICS AND HEAT	_				tal Hrs		9		
		lations of Fluid Mechanion Flow – Metal and Polyr									
5		ESTIMATES AND ADAP					tal Hrs		9		
Erro	r norms ar	nd Convergence rates – I	h-refinement	with ada	ptivity -	- Adap	tive refiner	ment.			
Tota	al hours to	be taught							45		
Tex	t book (s) :										
1	Cook, R.D., "Concepts and Applications of Finite Element Analysis", John Wiley & Sons Inc., New York, 1989.										
2	Bathe, K.J., "Finite Element Procedures in Engineering Analysis", Prentice Hall, New Jersey, 1990.										
Refe	erence(s):										
1	-										

	K.S.R	angasamy College of Tec	hnology -	Autono	nous F	Regula	ition		R 20	07
Dep	artment	Mechanical Engineering	Programm	ne Code	& Nam	ie	31 : M.E	E. Engin	eering De	esign
			Ser	mester						
Cou	rse Code	Course Name		Hou	rs / We	ek	Credit	Ma	aximum l	Marks
Cou	ise Code	Course Name		L	Т	Р	С	CA	ES	Total
073	310263E	MECHANICS OF FRACT	URE	3	0	0	3	50	50	100
Obj	ective(s)	To prove in depth study o To analyse crack Growth								
1	ELEMEN'	TS OF SOLID MECHANIC	S			To	tal Hrs		9	
The	geometry	of stress and strain - Elasti	ic deformati	on - Pla	stic and	elast	o-plastic de	eformation	on - Limit	analysis.
2	STATION	IARY CRACK UNDER STA	TIC LOADI	NG		To	tal Hrs		9	
		nal elastic fields – Analytica Igdaale model – J integral a							oximation	ı - Plastic
3	ENERGY	BALANCE AND CRACK C	ROWTH		·	То	tal Hrs		9	
	ith analysis k arrest.	s – Linear Fracture Mechar	nics - Crack	Openin	g displa	ceme	nt – Dynam	nic ener	gy baland	ce –
4	FATIGUE	CRACK GROWTH CURV	E			То	tal Hrs		9	
		tion describing crack growt oad spectrum – Effects of E			calculat	tions fo	or a given l	oad am	plitude –	Effects of
5	ELEMEN'	TS OF APPLIED FRACTUI	RE MECHA	NICS		То	tal Hrs		9	
		rack-growth Analysis for cy kness as a Design paramet								arge scale
Tota	I hours to I	be taught							45	
Text	book (s):									
1	Broek, Da 1978.	avid. "Elementary Engineeri	ing Fracture	Mecha	nics", F	ifthoff	& Noerdho	ff Intern	ational P	ublisher,
2	Hellan, Ka	are., "Introduction of Fractu	re Mechani	cs", McC	3raw-H	ill, Nev	w York, 198	35.		
Refe	erence(s):									
1	Preshant	Kumar., "Elements of Fract	ture Mechar	nics", W	heeler l	Publisl	ning, Allaha	abad, 19	99.	_

	K.S.Ra	angasamy College of Tecl	hnology -	Autono	mous F	Regula	ation		R 20	07
De	partment	Mechanical Engineering	Progra	amme C Name	ode &		31 : M.E	E. Engin	eering De	esign
			Sei	mester						
Co	urse Code	Course Name		Hou	rs / We	ek	Credit	Ma	aximum l	Marks
Co	urse Code	Course Name		L	Т	Р	С	CA	ES	Total
07	7310264E	APPLIED OBJECT ORII PROGRAMMING		3	0	0	3	50	50	100
OI	ojective(s)	To Impart some fundame class derivation and app	lications of		ented p	rogran	nming, C+	⊦ data ty	pes, C++	- classes,
1	PROGRAMMING									
	Elements of OOP, classes, subjects, messaging, inheritance, polymorphism, OOP paradigm versus Procedural paradigm, object-oriented design.									
2	C++ DATA	A TYPES				To	tal Hrs		9	
		statements, operators, pro		type coi	nversio	n, flow	control, A	rrays stı	uctures,	argument
		nce argument, overloaded t	function.				4-111			
3 Dofi	C++ CLAS	s objects, member function	ne pointor	frionde	class		otal Hrs	scope	9 unions	hit fields
clas		and ellises - Class me								
4	CLASS DI	ERIVATION				To	tal Hrs		9	
		cification, Information hid der derivation, class scope							classes,	standard
5	APPLICA	TION				To	tal Hrs		9	
00	P's applicati	ions in linear programming,	integer pro	ogramm	ing, sim	nulatio	n, etc.			
Tota	al hours to b	e taught							45	
Tex	t book (s):									
1	Wiener, R ", 1999.	ichard, S. and Pinson, Lew	is, J. "An ir	ntroducti	on to ol	ojectiv	e oriented	prog	ramming	and C++
2	Stanley B.	Lippman, "C++ primer ", Ad	ddison - W	esley Pu	ıb. Co.,	1989.				
Ref	erence(s):									
1	Robert La	fore, "Object Oriented prog	ramming in	Turbo (C++ ", (Salgot	ia Publicati	on, 1992	2.	
2	Strousstru	p, Bjarne, The "C++ progra	mming lan	guages	", Addis	son W	esley, 1986	6.		

	K.S.Rar	ngasamy College of Techr	nology - A	Autonor	nous F	Regula	ition		R 20	07
D	epartment	Mechanical Engineering	Progra	amme C Name	ode &		31 : M.E	E. Engin	eering De	esign
			Sen	nester II						
Co	urse Code	Course Name		Hou	rs / We	ek	Credit	Ma	aximum N	Marks
Co	urse Code	Course Name		L	Т	Р	С	CA	ES	Total
07	7310371E	DESIGN OF MATERIAL HANDLING EQUIPMENT		3	0	0	3	50	50	100
O	bjective(s)	To give a comprehensive	insight or	design	of hois	ts, Ho	sting gear,	convey	ors and E	Elevators.
1	MATERIAL	S HANDLING EQUIPMENT	-			To	tal Hrs		9	
Тур	es of materia	l handling equipments - Sel	ection an	d applic	ations.					
2	DESIGN OF						tal Hrs		9	
syst	ems, sprocke	g elements - Welded and ro ets and drums, Load handl agnets - Grabbing attachme	ing attac	hments	- Desig	n of f	orged hool	ks and e	eye hook	s - Crane
3	DRIVES OF	HOISTING GEAR				To	tal Hrs		9	
		drives - Traveling gear - R				- Cant	ilever and	monorai	l cranes	- Slewing,
-		ar - Cogwheel drive - Selec	ting the m	otor rati	ngs.			<u> </u>		
4	CONVEYO	หร ion - Design and applicatio	no of Dol				tal Hrs	nd 0000	9)
		ew conveyors - Vibratory co		convey	ors, ap	oron co	niveyors a	na esca	iators - F	neumatic
5	ELEVATOR						tal Hrs		9	
		s: design - Loading and b hoisting machine, safety de						Shaft v	vay, guic	les,
	al hours to be								45	
Tex	t book (s):									
1	Rudenko, N	I., Materials handling equipr	ment, ELr	vee Pul	olishers	, 1970).			
2	Spivakovsy	, A.O. and Dyachkov, V.K.,	LConvey	ing Macl	nines, \	/olume	es I and II,	MIR Pul	blishers,	1985.
Ref	erence(s):									
1	Alexandrov	, M., Materials Handling Equ	uipments,	MIR Pu	blisher	s, 198	1.			
2	Boltzharol,	A., Materials Handling Hand	dbook, Th	e Ronal	d Press	Com	pany, 1958	3.		
3	P.S.G. Tech	n, "Design Data Book", Kala	ikathir Ac	hchagai	m, Coir	nbator	e, 2003.			
4	Lingaiah. K. Bangalore,	. and Narayana Iyengar, "M 1983.	achine D	esign Da	ata Han	d Boo	k", Vol. 1 8	k 2, Sum	a Publisl	ners,

	K.S.Ra	ngasamy College of	Technology	y - Autor	nomous	Regu	lation		R 20	07
Del	partment	Mechanical Engineering	Programn	ne Code	& Name	е	31 : M.	E. Engin	eering De	sign
				Semeste	er III					
Cou	rse Code	Course Nan	20	Hou	ırs / We	ek	Credit	М	aximum N	/larks
Cou	ise Code	Course Man	ile	L	Т	Р	С	CA	ES	Total
073	310372E	EXPERIMENTAL ST ANALYSIS	RESS	3	0	0	3	50	50	100
Obj	ective(s)	To prove in depth principles of Acoustic								
1	FORCES	AND STRAIN MEASU	JREMENT			To	otal Hrs		9	
Fring		principle, types, perfo ulic jacks and pressur								
2		ON MEASUREMENTS of Structural Vibratio					otal Hrs		9	
	rding of si ems.	celeration measureme gnals – Cathode Ra CS AND WIND FLOW	y Oscillosco	ppe – X		er – Cl				
		essure and flow meas			n tranca			(al matar	•	imotor and
	meters - V	Wind tunnel and its us								
4	DISTRES	S MEASUREMENTS				To	tal Hrs		9	
		istress in structures - -cell, construction and								
5		TRUCTIVE TESTING					otal Hrs		9	
testi	ng principle	structures, buildings, es and application – H								Ultrasonic
	I hours to b	e taught							45	
Text	book (s):									
1		and WF Riley, Exper								
2	L.S.Srinat	h et al, Experimental	Stress Analy	/sis, Tata	McGra	w Hill (Company, N	New Delh	ni, 1984.	
Refe	rence(s):									
1	Sadhu Sir	ngh – Experimental St	ress Analysi	is, Khanr	na Publi	shers,	New Delhi,	1996.		
2	R.S.Siroh	i, HC Radhakrishna, N	1echanical N	/leasurer	nents, N	lew Aç	ge Internation	nal (P) L	_td. 1997.	
3	F.K Garas	s, J.L. Clarke and GST	Armer, Stru	uctural as	ssessme	ent, Bu	itterworths,	London,	1987.	
4	D.E. Bray	& R. K.Stanley, Non-	destructive E	Evaluatio	n, McGi	raw Hil	l Publishing	Compa	ny, N.Y.19	989.

	K.S.R	angas	amy College of Tech	nology -	Autono	mous F	Regula	ation		R 20	07
Dep	partment	Mec	hanical Engineering	Prograr	nme Co	de & Na	ame	31 : N	I.E. Eng	ineering	Design
				Ser	mester I	II		•			
-	Course Coo	40	Course Nam	^	Hou	rs / We	ek	Credit	Ma	aximum I	Marks
(Jourse Coc	эе	Course Name	Е	L	Т	Р	С	CA	ES	Total
	07310373E		VIBRATION CONTR CONDITION MONIT	ORING	3	0	0	3	50	50	100
(Objective(s	s)	At the end of the cou design and principles								
1	INTRODU	JCTIO	N				To	tal Hrs		9	-
Free		em - C	ntals of Single Degree Continuous system - D Analysis.								
2	VIBRATIO	ON CC	NTROL				To	tal Hrs		9	
Sele			tion of Vibration at the I additions – Artificial c								
3			TION CONTROL					tal Hrs		9	
			pts and applications -						naracter	stics - R	eview of
4		ON BA	naracteristics Active vi ASED MAINTENANCE S					es. tal Hrs		9	
mon tech	itoring - Ma niques – M	achine Iachin	on Monitoring Method condition monitoring e condition monitoring monitoring parameter	and diagno technique	osis – Vi	ibration	sever	ity criteria -	– Machii	ne mainte	enance
5	DYNAMIC	BAL	ANCING AND ALIGN	MENT OF	MACHIN	NERY	To	tal Hrs		9	
Mac	hinery Alig	nment	nic Balancing of Rotors - "Rough" Alignment naft-to-coupling spool	Methods -							
Tota	I hours to	be tau	ght							45	
Text	book (s):										
1	Bathe K.J Delhi, 197		Wilson, F.I., "Numerica	al Methods	s in Finit	e Elem	ent An	alysis", Pre	entice Ha	all of Indi	a, New
2	Hartog, J.	O. De	n., "Mechanical Vibrat	ions", McC	3raw-Hil	I, New	York, 1	1985.			
Refe	erence(s):										
1	Rao, J.S.	, "Vibra	atory Condition Monito	ring of Ma	chines",	CRC F	Press,	London, 20	000.		
2	Science E	Isevie	r, "Hand Book of Cond	dition Mon	itoring",	Elsevie	r Scie	nce, Amste	erdam, 1	996.	

K.S.Ra	ngasamy College of T	echnology -	Autono	mous l	Regul	ation		R 20	07
Department	Mechanical Engineering	Programm	e Code	& Name	Э	31 : M.E	E. Engin	eering De	esign
		Se	mester	Ш					
Course Code	Course Nan	20	Hou	rs / We	ek	Credit	M	aximum l	Marks
Course Code	Course Nan	ie	L	Т	Р	С	CA	ES	Total
07310381E	INTEGRATED MANUFACTURING S		3	0	0	3	50	50	100
Objective(s)	To enlighten the basi computer aided plai integrated manufactu	nning and d							
1 INTRODUC	CTION				To	tal Hrs		9	
	a manufacturing syst ems-linking manufacturi								
	ECHNOLOGY AND CO PLANNING	MPUTER AID	DED		To	tal Hrs		9	
	t families-parts classific ocess planning function							s-benefits	s of group
3 COMPUTE	R AIDED PLANNING A	ND CONTRO)L		To	tal Hrs		9	
planning (MRP	nning and control-cost)-shop floor control-Fa omated data collection	ctory data c							
	R MONITORING					tal Hrs		9	
strategies- dire	uction monitoring sys ct digital control-superv pection method - compu	isory comput	ter conti	ol-com	puter	in QC - co	ntact in	spection	
5 INTEGRAT	ED MANUFACTURING	SYSTEM			To	tal Hrs		9	
system- comput (FMS) - the FM - CAD/CAM sys	olication - features - t Iter control system - E S concept-transfer syst Item - human labor in th prototyping - Artificial Ir	DNC systems ems - head c le manufactu	s manuf changing ring sys	acturing FMS - tem-cor	g cell. varial npute	Flexible role mission integrated	manufac manufa	turing sy acturing s	rstems system
Total hours to b	e taught							45	
Text book (s):									
1 Groover, M	.P., "Automation, Produ	ction System	and CI	M", Pre	ntice-l	Hall of India	a, 1998.		
2 David Bedy	vorth, "Computer Integr	ated Design a	and Mar	ufactur	ing", T	MH, New	Delhi, 1	1998	
Reference(s):									
1 Yorem Kor	en, "Computer Integrate	d Manufactu	ring Sys	tems", l	McGra	w Hill, 198	3.		
İ	ıl G., "Computer Integra								
3 R.W. Yeom Amsterdam	namas, A. Choudry and n, 1985.	P.J.W. Ten F	lagen, "	Design	rules	or a CIM s	ystem",	North Ho	lland

K.S.Rangasamy College of Technology - Autonomous Regulation R 2007										07
Department		Mechanical	Programme Code &				31 : M.E. Engineering Design			
	Engineering Name ST. W.E. Engineering Design Semester III									
	Hours / Week Credit Maximum Marks									
Course Code		Course Name		L	T T	eek P	Credit	CA	ES	Total
07	310382E	AND	3	0	0	3	50	50	100	
Ob	Objective(s) SHELLS SHELLS Objective(s) Objective(s) SHELLS Objective(s) Objective(s) Objective(s) SHELLS Objective(s)									
1		ES & GOVERNING DIFF					tal Hrs		9	
	Plates with dary condition	small deflection - Late ons.	rally loaded	thin pla	tes -	- Gove	erning diffe	erential (equation	- Various
2	BENDING C	OF RECTANGULAR & CI	RCULAR P	LATES		To	tal Hrs		9	
	Rectangular plates - Simply supported rectangular plates - Navier solution and Levy's method - Rectangular plates with various edge conditions - Plates on elastic foundation - Symmetrical bending of circular plates.									
3	ANALYSIS	OF PLATES				To	tal Hrs		9	
Ener	gy methods	- Finite difference and Fir	nite element	methods	S.					
4	4 SHELLS & FOLDED PLATES STRUCTURE Total Hrs 9									
trans	slation, exam	shells - Types of shells, s ples, and limitations of m SCE Task Committee m	embrane the							
5	SPACE FRAMES Total Hrs 9									
Space	ce frames - C	Configuration - Types of n	odes - Gene	eral princ	iples	of des	ign Philoso	phy - Bo	ehavior.	
Tota	I hours to be	taught							45	
Text	book (s):									
1		Theory and Analysis of P								
2	Timoshenko, S. and Krieger S.W. Theory of Plates and Shells, McGraw Hill Book Company, New York 1990.									
Refe	rence(s):									
1	1 Wilhelm Flügge, stresses in shells, Springer – Verlag.									
2	Timoshenko, S. Theory of Plates and Shells, McGraw Hill, 1990.									
3	Ramasamy, G.S., Design and Construction of Concrete Shells Roofs, CBS Publishers, 1986.									
4	Dr.N.Subramanian, Principles of Space Structures , Wheeler Publishing Co. 1999.									
5	Proceedings of International Conference on Space Structures, Anna University, November 1997.									

K.S.Rangasamy College of Technology - Autonomous Regulation R 2007										
De	Department Mechanical Engineering Programme Code & N					ame	31 : M.E. Engineering Design			
	Semester III									
C -	uraa Cada	Course Name		Hours / Week		ek Credit		Maximum Marks		
_ C0	urse Code			L	Т	Р	С	CA	ES	Total
07310383E DESIGN OF HEAT EXCHANGERS		EXCHANGERS		3	0	0	3	50	50	100
Ok	Objective(s) To educate the ways and means of flow distribution and stress analysis, constructional details of Heat Exchangers, Design aspects of heat exchangers, condensers, evaporators and cooling towers.									
1	CONSTRUC	TIONAL DETAILS AND H	IEAT TRAN	NSFER		To	tal Hrs		9	
	Types - Shell and Tube Heat Exchangers - Regenerators and Recuperates Industrial Applications Temperature Distribution and its Implications - LMTD - Effectiveness									
2		RIBUTION AND STRESS		-			tal Hrs		9	
		nce - Friction Factor - Pressels - Thermal Stresses -						in Tube	es - Heat	ter sheets
3										
		d Pressure Loss - Flow C Liquid - Gas-Gas-Liquid I			ct of B	affles	- Effect of	Deviation	ons from	Ideality -
4										
Desi	gn of Surface	and Evaporative Conder	sers - Des	ign of St	nell and	d Tube	- Plate Ty	pe Evap	orators	
5	5 COOLING TOWERS Total Hrs 9									
	king - Spray nods.	Design - Selection of Pu	mps - Fan	s and P	ipes -	Testir	ig and Ma	intenand	ce – Exp	erimental
Tota	Total hours to be taught 45									
Text	Text book (s):									
1	T. Taborek, G.F. Hewitt and N.Afgan, Heat Exchangers, Theory and Practice, McGraw Hill Book Co., 1980.									
2	Walker, Industrial Heat Exchangers - A Basic Guide, McGraw Hill Book Co., 1980.									
Refe	Reference(s):									
1	1 Nicholas Cheremisioff, Cooling Tower, Ann Arbor Science Pub 1981.									
2	2 Arthur P. Fraas, Heat Exchanger Design, John Wiley & Sons, 1988.									

	K.S.Ra	ingasamy College of Tech	nology - /	Autonon	nous R	egula	tion		R 20	07
De	Department Mechanical Engineering Programme Cod Name			ode &	31 : M.E. Engineering Design					
Semester III										
Course Code		Course Name		Hours / Wee		ek Credit		Maximum Marks		
				L	Т	Р	С	CA	ES	Total
07310391E PRODUCTIVITY MANAGEMENT AND RE-ENGINEERING				3	0	0	3	50	50	100
Obj	ective(s)	To Integrate the conce engineering process, Re-e						onal tra	ansforma	tion, Re-
1	INTRODU						tal Hrs		9	
Prod	luctivity cor	cepts - Macro and Micro fac	ctors of pro	oductivity	, Prod	uctivity	y benefit m	odel, pro	oductivity	cycle.
2	PRODUCT	TIVITY MODELS				To	tal Hrs		9	
Prod	luctivity ma	easurement at Internationa anagement in manufacturing odels and techniques.								
3	3 ORGANIZATIONAL TRANSFORMATION Total Hrs 9									
	aring the v	organizational transformation vorkforce for transformation								
4										
PMI mod		dosomwan model, Moen an	d Nolan s	trategy f	or proc	ess in	nprovemer	nt, LMIC	IP model	, NPRDC
5	RE-ENGINEERING TOOLS AND IMPLEMENTATION Total Hrs 9									
RE-d	pportunitie	process tools and technique is, process redesign - case ng, user interfaces, maintair	es. Softwa	are meth	ods in					
Tota	l hours to b	e taught							45	
Text	book (s):									
1	Sumanth, D.J., " Productivity engineering and management ", TMH, New Delhi, 1990.									
Edosomwan, J.A., "Organizational transformation and process re-engineering ", British Library cataloging in pub. Data, 1996.										
Reference(s):										
1	Rastogi, P.N. "Re-Engineering and Re-inventing the enterprise ", Wheeler pub. New Delhi, 1995.									
2	Premvrat, Sardana, G.D. and Sahay, B.S, "Productivity Management - A systems approach ", Narosa Pub. New Delhi, 1998.									

	K.S.R	angasamy College of Tecl	nnology -	Autono	nous F	Regula	ition		R 20	07	
De	partment	Mechanical Engineering	Programme Code & Name				31 : M.E. Engineering Design			esign	
	Semester III										
Car	waa Cada	Course Name			Hours / Week		Credit	Maximum Marks			
Cou	ırse Code	Course Name		L	Т	Р	С	CA	ES	Total	
073	310392E	MECHATRONICS IN MANUFACTURING SYST		3	0	0	3	50	50	100	
Ob	jective(s)	To understand the functions of mechatronic systems, sensors and transducers, microprocessor									
1	INTRODU	in mechatronics, programmable logic controllers and design. UCTION Total Hrs							9		
-	_	Mechatronics - Systems - I	Mechatroni	ce in Pr	nducte			Svetame		l Svetame	
		esign and Mechatronics Des		03 111 11	Juucis	IVICA	surcincin (Јузісті із	Contro	i Oystoilis	
2		S AND TRANSDUCERS				To	tal Hrs		9		
		Performance Terminology -									
		nperature sensors - Light se		ection o	f senso			ssing - S	Servo sys	tems.	
3		ROCESSORS IN MECHATI					tal Hrs		9		
instı	Introduction - Architecture - Pin configuration - Instruction set - Programming of Microprocessors using 8085 instructions - Interfacing input and output devices - Interfacing D/A converters and A/D converters —Applications - Temperature control - Stepper motor control - Traffic light controller.										
4		MMABLE LOGIC CONTRO		og o	71111 01110		tal Hrs		9		
		Basic structure - Input / Ou Data handling - Analog inpu					-Mnemon	ics Time	ers, Inter	nal relays	
5	DESIGN AND MECHATRONICS Total Hrs 9										
Des	igning - Po	ssible design solutions - Ca	se studies	of Mech	atronic	s syst	ems.				
Tota	al hours to	be taught							45		
Tex	t book (s):										
1	Michael B Histand and David G. Alciatore. "Introduction to Mechatronics and										
2 Bradley, D.A., Dawson, D, Buru, N.C. and Loader, AJ., "Mechatronics ", Chapman and Hall, 1993.											
Ref	erence(s) :										
1	Ramesh.S, Gaonkar, " Microprocessor Architecture, Programming and Applications "Wiley Eastern, 1998.										
2	Laurence I Komm "I la destanding Flactra Machanial Facing aring An Introduction to Machanaga"										
3	Ghosh, P.K. and Sridhar, P.R., 0000 to 8085, "Introduction to Microprocessors for Scientists", Second Edition, Prentice Hall, 1995.										