

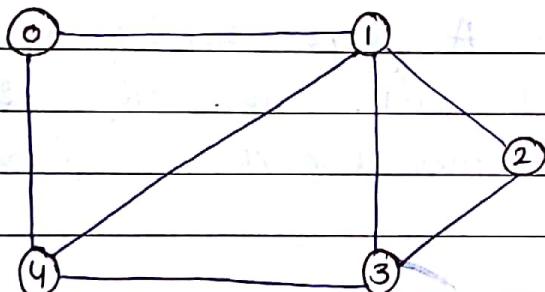
Unit 4

★ Graph:- A graph is simply a set of points together with a set of lines connecting various points. It is a non-linear data structure.

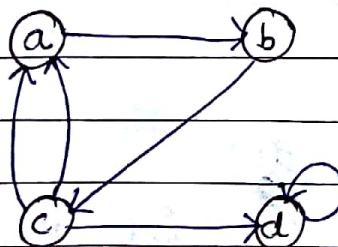
It is a pictorial representation of a set of objects where some pairs of objects are connected by links.

(a) Vertices :- The interconnected objects are represented by points.

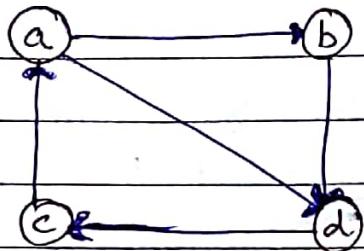
Edges :- The links that connect the vertices.



Directed graph:- In graph theory, a directed graph is a graph that is set of vertices connected by edges, where the edges have a direction associated with them. It is also called digraph.



Undirected graph :- Undirected graph have edges that do not have a direction. the edges indicate a two way relationship , in both directions .all the edges are bidirectional.



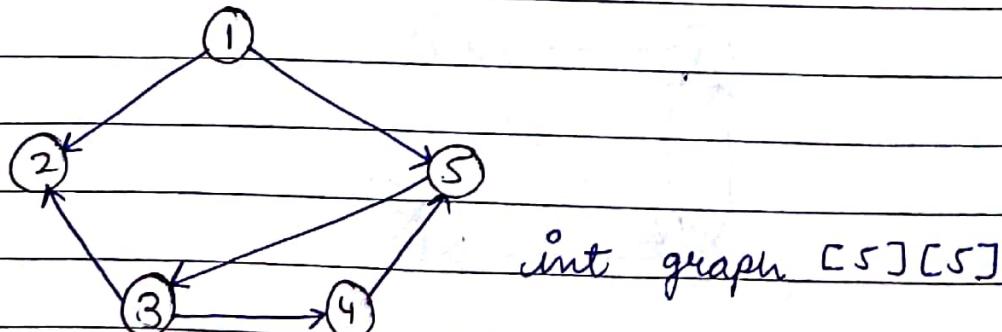
Directed acyclic graph :- A directed acyclic graph is a graph that have no cycles whereas in a cyclic graph it have direction.

Weighted graph :- A graph having a weight or number , associated with some edge. It is a graph in which each branch is given a numerical weight.

Representation of Graph :-

1. Adjacency Matrix (array)
2. Adjacency list (link list)

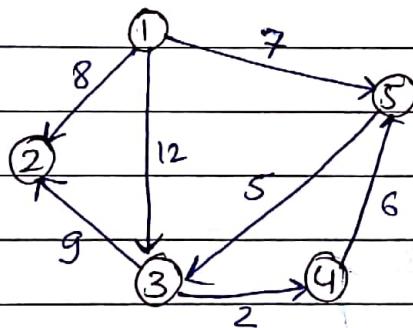
1. Adjacency Matrix :-



$a[i][j]$

vertices	1	2	3	4	5
1	0	1	1	0	1
2	0	0	0	0	0
3	0	1	0	1	0
4	0	0	0	0	1
5	0	0	1	0	0

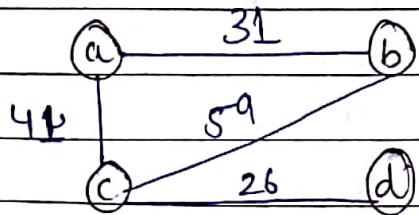
Adjacency matrix is a 2D array of size $V \times V$ where V is the number of vertices in a graph. We can also use weighted graph.

 $a[i][j]$

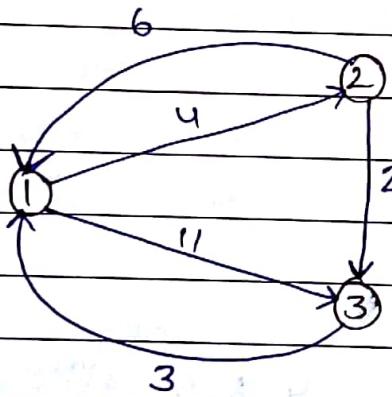
vertices	1	2	3	4	5
1	0	8	12	0	7
2	0	0	0	0	0
3	0	9	0	2	0
4	0	0	0	0	6
5	0	0	5	0	0

fig. for weighted graph it means cost is given.

Adjacency matrix of a given graph :-



vertices	1	2	3	4
1	∞	31	41	∞
2	31	∞	59	∞
3	41	59	∞	26
4	∞	∞	26	∞

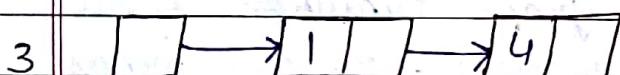
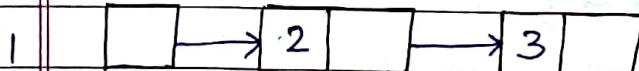
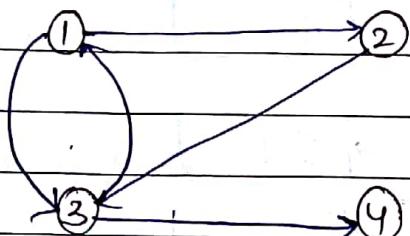


vertices	1	2	3
1	0	4	11
2	6	0	2
3	3	∞	0

cost adjacent matrix

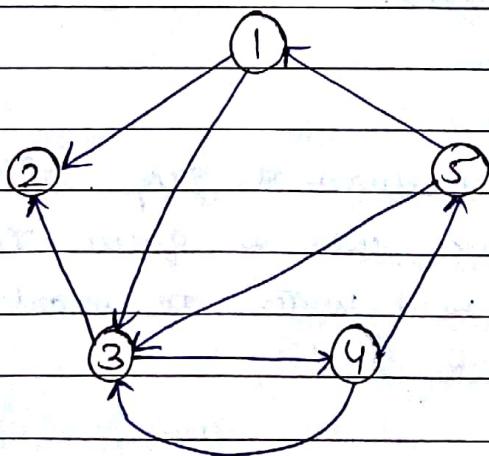
2. Adjacency list:- An array of linked list is used
 size of the array is equal to number of vertices
 In this representation, every vertex of graph contains
 list of its adjacent vertices. It is an array of
 separate lists.

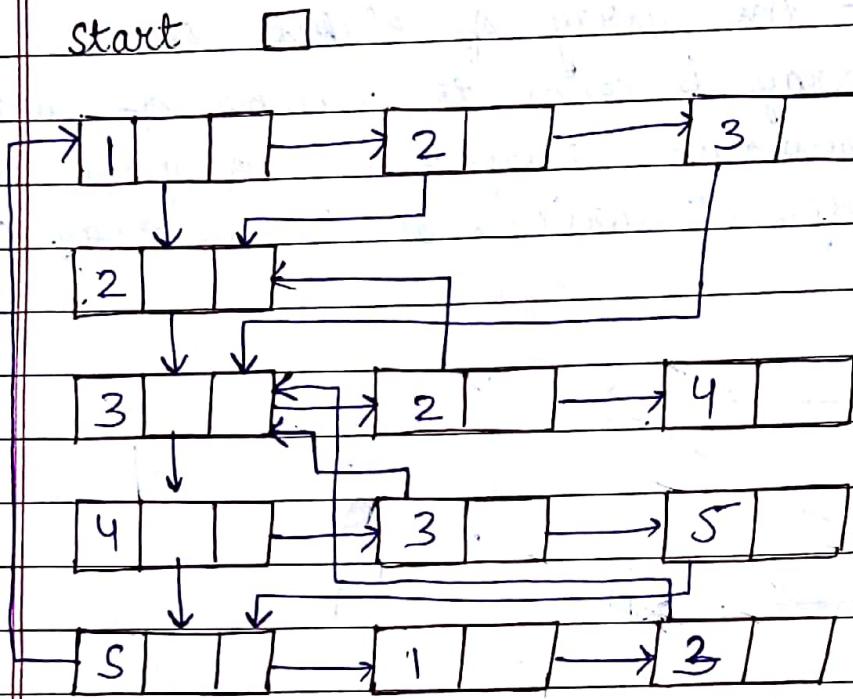
eg:- ①



Node list →

eg:- ②





Traversing in graph:-

In computer science, graph traversal is a form of traversal and refers to the process of visiting each node in a graph data structure exactly once.

It is classified in two ways:-

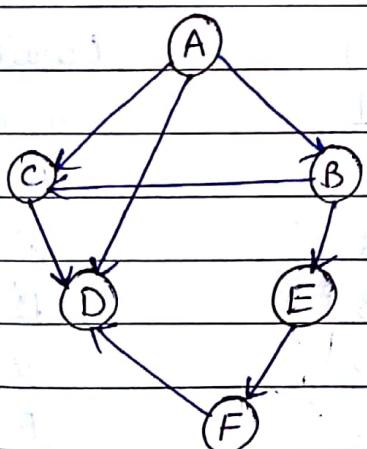
- (i) BFS (Breadth first search)
- (ii) DFS (Depth first search).

i) BFS:-

BFS algorithm traverse a graph in a breadthward motion and uses a queue to remember to get the next vertex to start a search.

Algorithm :-

1. Initialise all nodes to the ready status (status=1).
2. Put the starting node A in queue and change its status (status=2).
3. Repeat step 4 and 5 until queue is empty.
4. Remove the front node N. of queue process N and change the status (status=3).
5. Add to the rear of queue all the neighbour (status=1) and change their status to the waiting status (status=2)
6. Exit.



(ready)	(Waiting)
Status 1	Status 2
A X 2 3	AB
B A X 2 3	C
C 1 2 3	D
D 1 2 3	E
F 1 2 3	F
F 1 2 3	

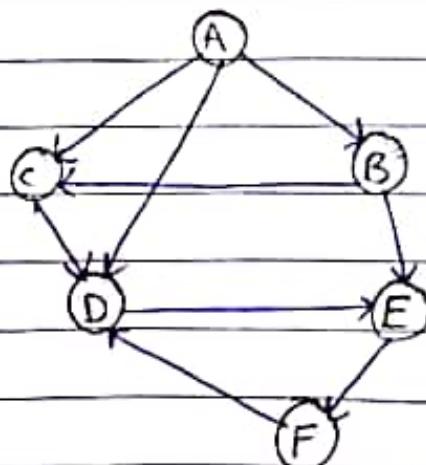
(process)	status 3	A	B	C	D	E	F	
-----------	----------	---	---	---	---	---	---	--

ii) DFS:-

DFS algorithm traverses a graph in a depthward motion and uses a stack to remember to get the next vertex to start a search.

Algorithm:-

1. Initialize all the nodes to the ready status (status_i=0).
2. Put the starting node in STACK and change its status (status=2).
3. Repeat step 4 to 5 until stack is empty.
4. Remove the top node of STACK process and change the status (status=3).
5. Add to the top of STACK all the neighbours of that are in the ready state (status=1) and change their status to the waiting states (status=2).
6. Exit.



(ready)	(waiting)
status 1	status 2
A X Z 3	A
B X Z 3	C
C X Z 3	D
D Y Z 3	B
E X Z 3	E
F Y Z 3	F

status 3 [A | C | D | B | E | F]

Stack is
empty.

Warshall's algorithm:-

The Warshall's algorithm is an algorithm for finding shortest path in a weighted graph with the or -ve edge weight. It finds the length of the

shortest between all pairs of vertices.

Algorithm:-

for $i := 1$ to n do

 for $j := 1$ to n do

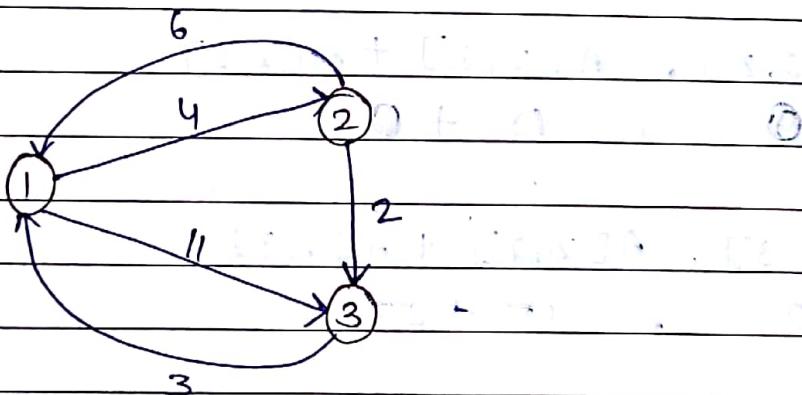
$A[i, j] := \text{cost}[i, j];$

for $k := 1$ to n do

 for $i := 1$ to n do

 for $j := 1$ to n do

$A[i, j] := \min(A[i, j], A[i, k] + A[k, j]);$



A	i/j	1	2	3
1	0	4	11	
2	6	0	2	
3	3	∞	0	

A'	i/j	1	2	3	A^2	i/j	1	2	3	A^3	i/j	1	2	3
1	0	4	11		1	0	4	6		1	0	4	6	
2	6	0	2		2	6	0	2		2	5	0	2	
3	3	7	0		3	3	7	0		3	3	7	0	

$A[1,2]$, $A[1,1] + A[2,2]$
 4, 0 + 0

$A[2,1]$, $A[2,2] + A[2,1]$
 6 0 + 6

$A[1,3]$, $A[1,1] + A[1,3]$
 11, 0 + 11

$A[2,1]$, $A[2,2] + A[2,1]$

$A[2,2]$, $A[2,2] + A[2,2]$
 0, 0 + 0

$A[2,3]$, $A[2,2] + A[2,3]$
 2, 0 + 2

Ans:-

i\j	1	2	3
1	0	4	6
2	5	0	2
3	3	7	0

Sorting:- In data structure sorting is a process by which we arrange the data in a logical order. This logical orders can be either ascending (smaller to larger) or descending order (larger to smaller).

Sorting is related to searching, sorting arranges data in sequence which makes searching better or easier.

Types of Sorting :-

1. Internal sorting
2. External sorting

1. Internal sorting:- In this technique all the sorted data present in main memory.

following types of internal sorting :-

- i) Bubble sort
- ii) Insertion sort
- iii) Quick sort
- iv) Heap sort
- v) Selection sort

2. External sorting:- In this technique sorted data is present in secondary memory Because the size of data is large it cannot fit in the main memory
There is only one type of external sorting is merge sort.

A. Insertion sort:-

Algo

1. Repeat step 2 to 4 for $K = 2, 3, \dots, N$.
2. Set $\text{temp} := A[K]$ and $\text{Ptr} := K-1$.
3. Repeat while $\text{temp} < A[\text{Ptr}]$ and $\text{Ptr} \geq 1$.
 - a) Set $A[\text{Ptr}+1] := A[\text{Ptr}]$
 - b) Set $\text{Ptr} := \text{Ptr} - 1$
4. Set $A[\text{Ptr}+1] := \text{temp}$
5. Exit.

B. Quick sort :- (Fastest)

Algo → Quick sort ($K[]$, LB, UB)

1. Initialize Flag := True.

2. If $LB < UB$ then

a) Set $I := LB$, $J := UB + 1$, $KEY := K[I]$

b) Repeat Step (i) to (v) while (Flag = True)

(i) set $I := I + 1$

(ii) Repeat while ($K[I] < KEY$) do

SET $T := I + 1$

(iii) set $T := T - 1$

(iv) Repeat while ($K[T] > KEY$) do

set $T := T - 1$

(v) If ($I \leq T$) then

Swap $K[I]$ and $K[T]$

else

Flag := False

c) Swap $K[LB]$ and $K[T]$

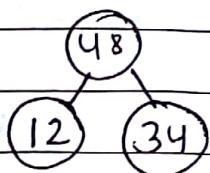
d) call Quicksort ($K[], LB, T - 1$)

e) call Quicksort ($K[], T + 1, UB$).

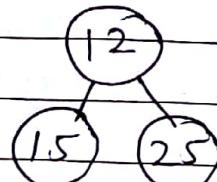
3 Exit.

C. Heap Sort :-

- ① It is a binary tree. complete binary tree
- ② Value of node should be greater than its children called MAXHEAP.
- ③ Value of node should be smaller than its children called MINHEAP.



MAXHEAP



MINHEAP

Algo

Heapsort (A, N)

1. Repeat for ($J=1$ to $N-1$) do
call INSHEAP (A, J, A[J+1])
2. Repeat while ($N > 1$) do
 - (a) call DELHEAP (A, N, ITEM)
 - (b) Set $A[N+1] := ITEM$
3. Exit.

INSHEAP (TREE, N, ITEM)

1. Set $N := N+1$ and $PTR := N$
2. Repeat steps 3 to 6 while $PTR > 1$
3. Set $PAR := \lfloor PTR/2 \rfloor$
4. If $ITEM \leq TREE[PAR]$, then
Set $TREE[PTR] := ITEM$ & Return
5. Set $TREE[PTR] := TREE[PAR]$
6. Set $PTR := PAR$.
7. Set $TREE[1] := PAR$
8. Return

DELHEAP (TREE, N, ITEM)

1. Set $ITEM := TREE[1]$
2. Set $LAST := TREE[N]$ & $N := N-1$
3. Set $PTR := 1$, $LEFT := 2$ & $RIGHT := 3$.
4. Repeat steps 5 to 7 while $RIGHT \leq N$
5. If $(LAST \geq TREE[LEFT])$ and $LAST \geq TREE[RIGHT]$ then
Set $TREE[PTR] := LAST$ & Return
6. If $(TREE[RIGHT] \leq TREE[LEFT])$ then
 - (a) Set $TREE[PTR] := TREE[LEFT]$
 - (b) $PTR := LEFT$.

else

(a) set TREE [PTR] := TREE [RIGHT]

(b) PTR := RIGHT.

7. Set LEFT := L * PTR & RIGHT := LEFT + 1

8. If (LEFT = N) and LAST < TREE [LEFT] then
 TREE [PTR] := TREE [LEFT]
 PTR := LEFT.

9. Set TREE [PTR] := LAST

10. Return.

D. Selection sort:-

Algo.

1. Repeat step 2, 3, 4 for K=1, 2, ..., n-1. Set min:=k

2. Repeat for i:= K+1, K+2, ..., n

If A[i] < A[min] then

Set min:=i.

3. If (min ≠ K) then

temp := A[K]

A[K] := A[min];

A[min] := temp;

4. Exit.

E. Merge sort:-

Algo

Mergesort (low, high)

{

if (low < high) then

{

mid := ⌊(low + high)/2⌋;

Mergesort (low, mid);

Mergesort (mid+1, high);

Merge (low, mid, high);

{

}

Merge (low, mid, high)

{

h := low

i := low

j := mid + 1

while (h < mid) and (j < high) do

{

if (a[h] < a[j]) then

{

b[i] := a[h];

h := h + 1;

}

else

{

b[i] := a[j];

j := j + 1;

}

i := i + 1

}

if (h > mid) then

for k := j to high do

{

b[i] := a[k]

i := i + 1;

}

else

for $k := h$ to mid do

{

$b[i] := a[k]$

$i := i + 1$

}

for $k := \text{low}$ to high do

$a[k] := b[k];$

}

3

QUESTION

ANSWER

ANSWER

ANSWER

ANSWER

ANSWER

ANSWER

ANSWER