



SUMMER INTERNSHIP EMBEDDED C

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TASK 12

Hands-on Activity-1

- ☐ Write a program to count no. of bits which are set in given binary pattern
- ☐ Write a program to set 5th and 12th bits in a 16-bit unsigned integer
- ☐ Write a program to clear 6th and 19th bits in a 32-bit unsigned integer
- ☐ Write a program to flip even positioned bits in a 16-bit unsigned integer
- ☐ An IP Address will be in the form of "a.b.c.d" format, where a,b,c,d will be in the range of 0-255. Given a,b,c,d values (or string format) pack them into 32-bit unsigned integer.
- ☐ Given an unsigned 32-bit integer holding packed IPv4 address, convert it into "a.b.c.d" format.
- ☐ Convert MAC address into 48-bit binary pattern
- ☐ Convert 48-bit binary pattern as MAC address
- ☐ Arduino examples using Bare metal code (Register level Bit Manipulations)
 - ➔ Blinky
 - ➔ LED controlling using PushButton

Q1

```
#include <stdio.h>
```

```
int countSetBits(int n) {
```

```
    int count = 0;
```

```
    while (n) {
```

```
        count += n & 1;
```

```
        n >>= 1;
```

```
    }
```

```

    return count;
}

int main() {
    int num;

    printf("Enter an integer: ");

    scanf("%d", &num);

    int setBits = countSetBits(num);

    printf("Number of set bits in %d is %d\n", num, setBits);

    return 0;
}

```

Q2

```

#include <stdio.h>

int main()
{
    unsigned short int value = 0;

    unsigned short int mask = (1 << 4) | (1 << 11);

    value |= mask;

    printf("The value after setting the 5th and 12th bits is: %u\n", value);

    return 0;
}

```

Q3

```

#include <stdio.h>

unsigned int clearBits(unsigned int num) {
    unsigned int mask = ~((1 << 5) | (1 << 18));

    return num & mask;
}

```

```

}

int main() {

    unsigned int num;

    printf("Enter a 32-bit unsigned integer: ");

    scanf("%u", &num);

    unsigned int result = clearBits(num);

    printf("Result after clearing the 6th and 19th bits: %u\n", result);

    return 0;

}

```

Q4

```

#include <stdio.h>

unsigned short flipEvenBits(unsigned short num) {

    unsigned short mask = 0x5555;

    return num ^ mask;

}

int main() {

    unsigned short num;

    printf("Enter a 16-bit unsigned integer: ");

    scanf("%hu", &num);

    unsigned short result = flipEvenBits(num);

    printf("Result after flipping the even-positioned bits: %hu\n", result);

    return 0;

}

```

Q5

```
#include <stdio.h>
```

```
unsigned int packIP(unsigned char a, unsigned char b, unsigned char c, unsigned char d) {  
    return (a << 24) | (b << 16) | (c << 8) | d;  
}
```

```
int main() {  
    unsigned char a = 192;  
    unsigned char b = 168;  
    unsigned char c = 1;  
    unsigned char d = 100;  
    unsigned int packedIP = packIP(a, b, c, d);  
    printf("Packed IP address: 0x%X\n", packedIP);  
  
    return 0;  
}
```

Q6

```
#include <stdio.h>
```

```
int main() {  
    unsigned int packed_ip = 0xC0A80164;  
    unsigned char a = (packed_ip >> 24) & 0xFF;  
    unsigned char b = (packed_ip >> 16) & 0xFF;  
    unsigned char c = (packed_ip >> 8) & 0xFF;  
    unsigned char d = packed_ip & 0xFF;  
    printf("The unpacked IP address is: %u.%u.%u.%u\n", a, b, c, d);  
    return 0;  
}
```

```
}
```

Q7

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
unsigned long long convertMACAddress(const char *mac) {
```

```
    unsigned int bytes[6];
```

```
    if (sscanf(mac, "%x:%x:%x:%x:%x:%x", &bytes[0], &bytes[1], &bytes[2], &bytes[3], &bytes[4],  
&bytes[5]) != 6) {
```

```
        fprintf(stderr, "Invalid MAC address format.\n");
```

```
        exit(EXIT_FAILURE);
```

```
    }
```

```
    unsigned long long macBinary = 0;
```

```
    for (int i = 0; i < 6; ++i) {
```

```
        macBinary = (macBinary << 8) | (bytes[i] & 0xFF);
```

```
    }
```

```
    return macBinary;
```

```
}
```

```
int main() {
```

```
    char macString[18];
```

```
    printf("Enter MAC address in the format XX:XX:XX:XX:XX:XX: ");
```

```
    if (scanf("%17s", macString) != 1) {
```

```
        fprintf(stderr, "Failed to read MAC address.\n");
```

```
        return EXIT_FAILURE;
```

```
    }
```

```
    unsigned long long macBinary = convertMACAddress(macString);
```

```
    printf("MAC address in 48-bit binary pattern: %012llx\n", macBinary);
```

```

    return 0;
}

Q8

#include <stdio.h>

#include <stdlib.h>

void binaryToMac(const char* binary) {

    unsigned int bytes[6] = {0};

    for (int i = 0; i < 48; ++i) {

        bytes[i / 8] = (bytes[i / 8] << 1) | (binary[i] - '0');

    }

    printf("MAC Address: %02X:%02X:%02X:%02X:%02X:%02X\n",

        bytes[0], bytes[1], bytes[2], bytes[3], bytes[4], bytes[5]);

}

int main() {

    const char* binary_pattern = "101010101011101111001100110111011110111111111111";

    binaryToMac(binary_pattern);

    return 0;

}

```

Task 14

1)bare metal blinky using arduino1

```

#define F_CPU 16000000UL

#include <avr/io.h>

#include <u0 l/delay.h>

int main(void)

{

```

```
// Set pin 7 (PD7) as an output
```

```
DDRD |= (1 << PD7);
```

```
while (1)
```

```
{
```

```
PORTD |= (1 << PD7);
```

```
_delay_ms(1000);
```

```
PORTD &= ~(1 << PD7);
```

```
_delay_ms(1000);
```

```
}
```

```
return 0;
```

```
}
```

2)bare metal push button on1

```
#define F_CPU 16000000UL
```

```
#include <avr/io.h>
```

```
#include <util/delay.h>
```

```
const uint8_t buttonPin = PD2;
```

```
const uint8_t ledPin = PB5;
```

```
uint8_t buttonState = 0;
```

```
void setup() {
```

```
    DDRD &= ~(1 << buttonPin);
```

```
    PORTD |= (1 << buttonPin);
```

```
    DDRB |= (1 << ledPin);
```

```
}
```

```
int main(void) {
```

```
    setup();
```

```
    while (1) {
```

```
        buttonState = PIND & (1 << buttonPin);
```

```
        if (buttonState) {
```

```
PORTB |= (1 << ledPin);

} else {

PORTB &= ~(1 << ledPin);

}

_delay_ms(10);

}

return 0;

}
```

Task 15

Analog Read (Potentiometer)

CODE :

```
const int ledPin = 9;    // Pin where the LED is connected

void setup() {

    // Initialize the LED pin as an output

    pinMode(ledPin, OUTPUT);

}

void loop() {

    // Fade in from 0 to 100^6

    for (int brightness = 0; brightness <= 100^6; brightness++) {

        analogWrite(ledPin, brightness); // Set the brightness

        delay(10); // Wait for 10 milliseconds

    }
```



```
// Fade out from 100^6 to 0
```

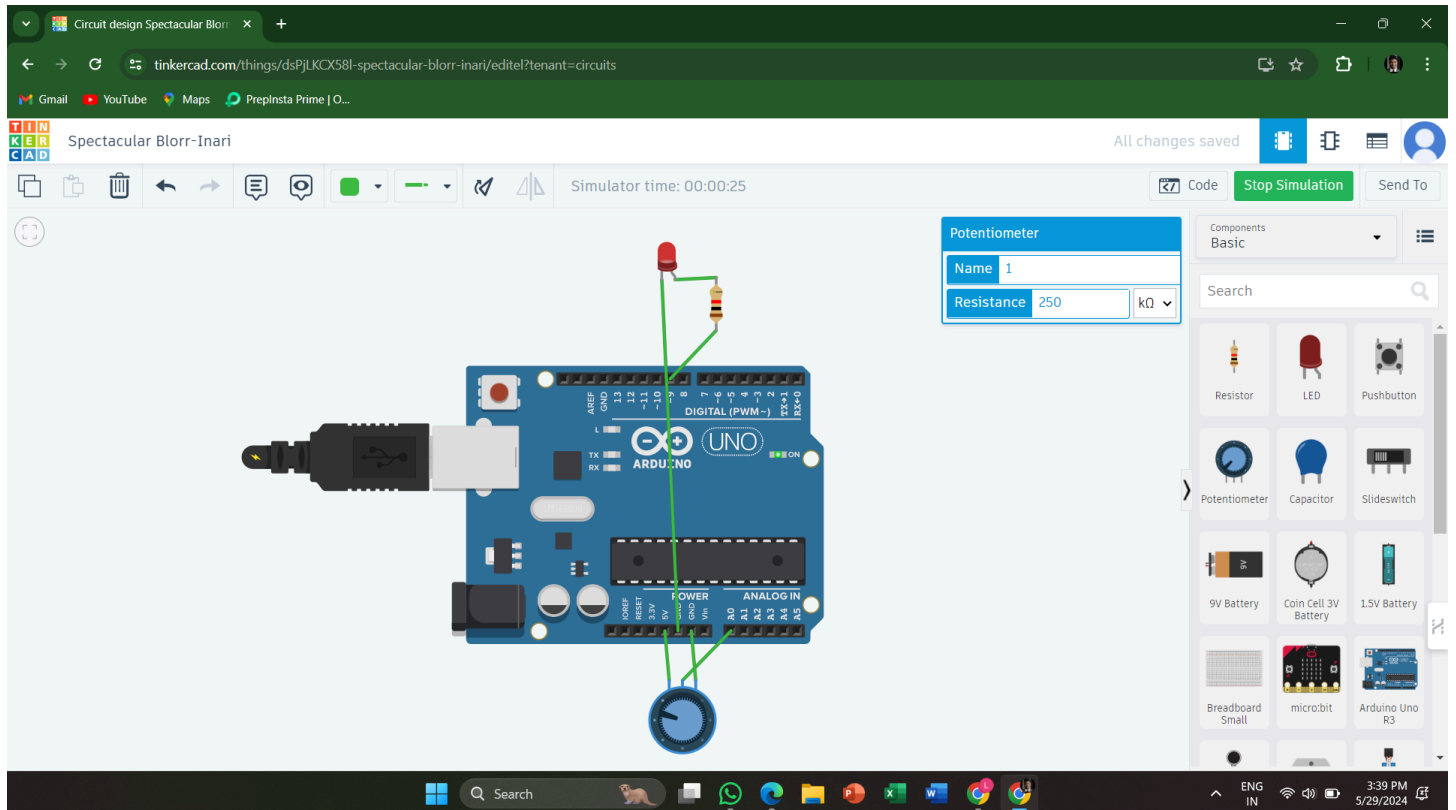
```
for (int brightness = 100^6; brightness >= 0; brightness--) {
```

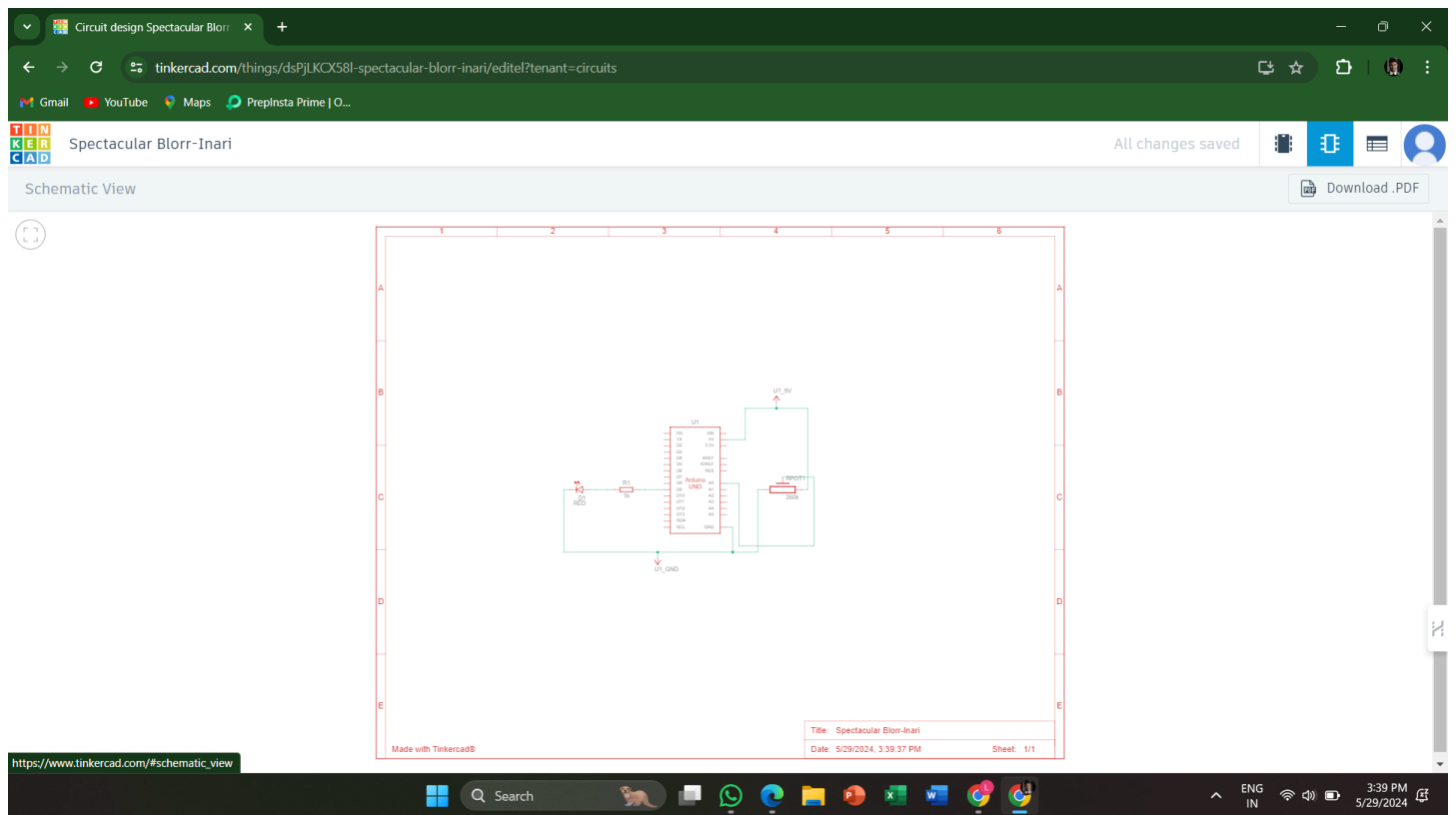
```
    analogWrite(ledPin, brightness); // Set the brightness
```

```
    delay(10); // Wait for 10 milliseconds
```

```
}
```

```
}
```





Component List

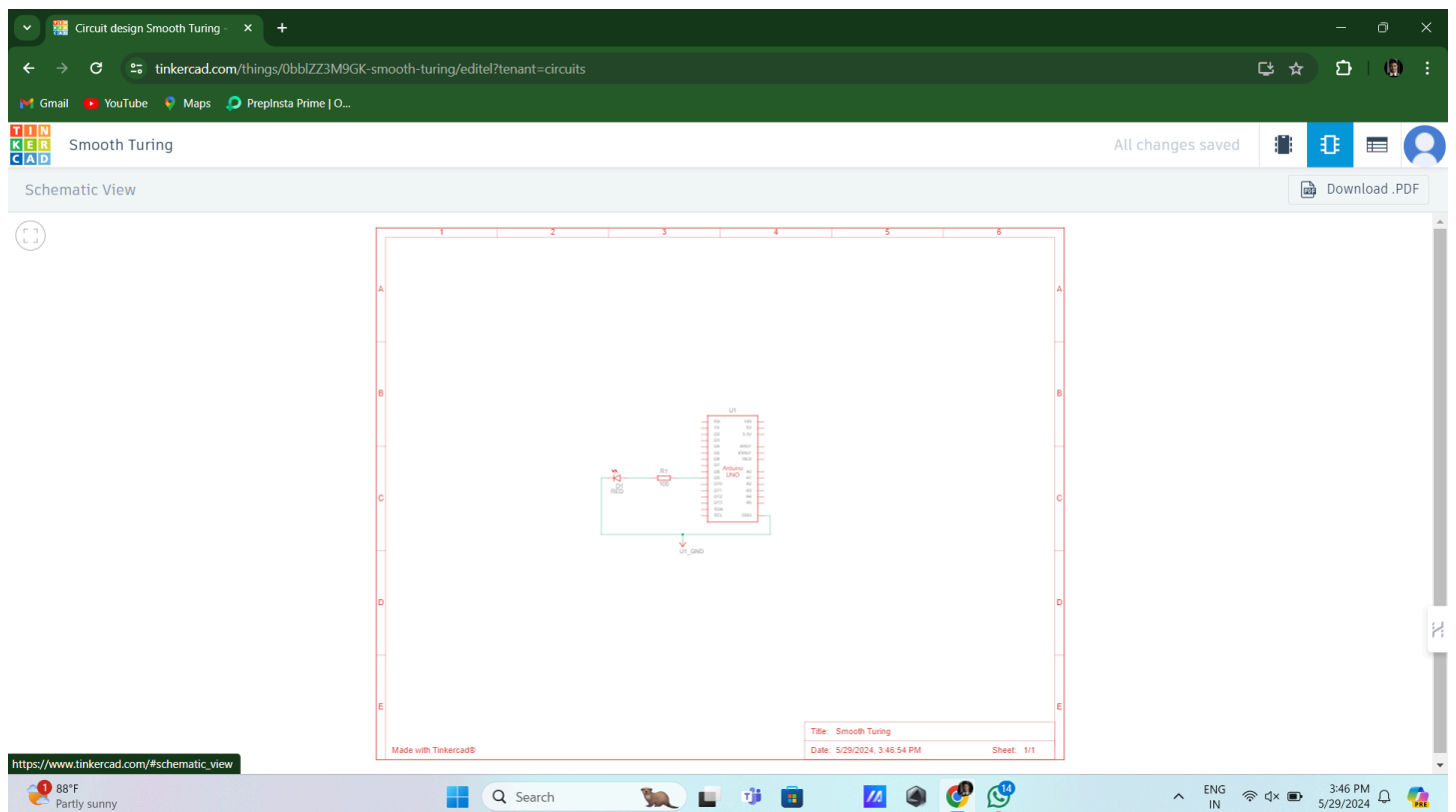
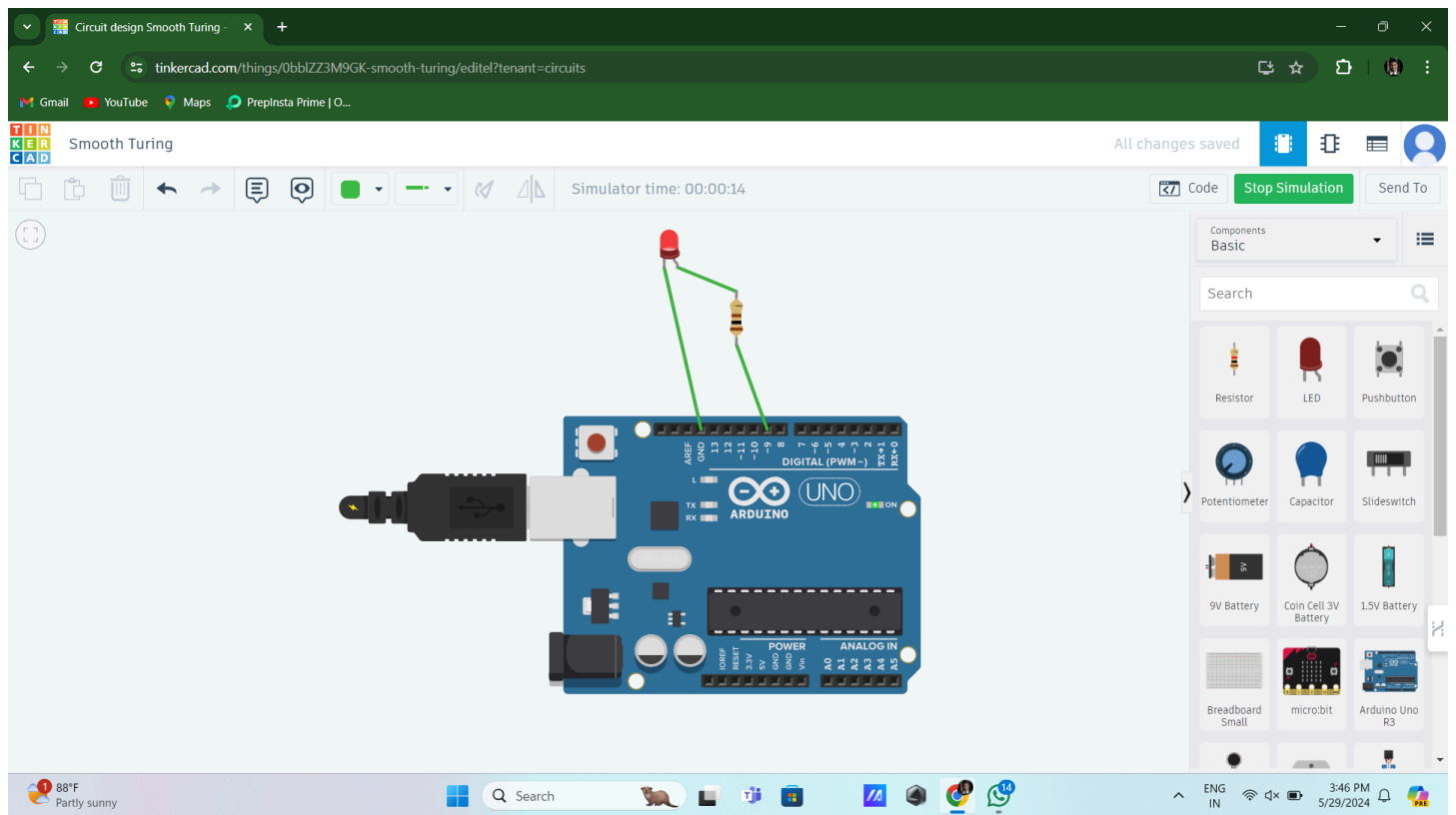
Name	Quantity	Component
Rpot1	1	250 kΩ Potentiometer
R1	1	1 kΩ Resistor
U1	1	Arduino Uno R3
D1	1	Red LED

Analout Output(fading)

CODE :

```
const int ledPin = 9;    // Pin where the LED is connected
```

```
void setup() {  
  
    // Initialize the LED pin as an output  
  
    pinMode(ledPin, OUTPUT);  
  
}  
  
void loop() {  
  
    // Fade in from 0 to 100^6  
  
    for (int brightness = 0; brightness <= 100^6; brightness++) {  
  
        analogWrite(ledPin, brightness); // Set the brightness  
  
        delay(10); // Wait for 10 milliseconds  
  
    }  
  
    // Fade out from 100^6 to 0  
  
    for (int brightness = 100^6; brightness >= 0; brightness--) {  
  
        analogWrite(ledPin, brightness); // Set the brightness  
  
        delay(10); // Wait for 10 milliseconds  
  
    }  
  
}
```



Smooth Turing

All changes saved

Component List

Download CSV

Name	Quantity	Component
U1	1	Arduino Uno R3
R1	1	100 Ω Resistor
D1	1	Red LED

88°F Partly sunny

Search

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Digital Input using Interrupt

CODE :

```
const int buttonPin = 2; // Pin where the push button is connected
```

```
volatile bool buttonPressed = false; // Flag to indicate button press
```

```
void setup() {
```

```
    pinMode(buttonPin, INPUT); // Set the button pin as input
```

```
    attachInterrupt(digitalPinToInterrupt(buttonPin), buttonPressISR, RISING); // Attach interrupt on rising edge
```

```
    Serial.begin(9600); // Initialize serial communication
```

```
}
```

```
void loop() {
```

```
    if (buttonPressed) {
```

```
        Serial.println("Button Pressed!"); // Print message when button is pressed
```

```

buttonPressed = false;      // Reset the flag

}

}

void buttonPressISR() {

    buttonPressed = true; // Set the flag to indicate button press

}

```

