



8051(micro-controller) using LCD Display

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AVVA PRAVEEN BABU

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Learning Objective:

- Learning how to use the 8051 microcontroller to display text on an LCD.

Inputs and Outputs:

- ☐ **Inputs:** Commands for the LCD display.
- ☐ **Output:** Displayed text on the LCD.

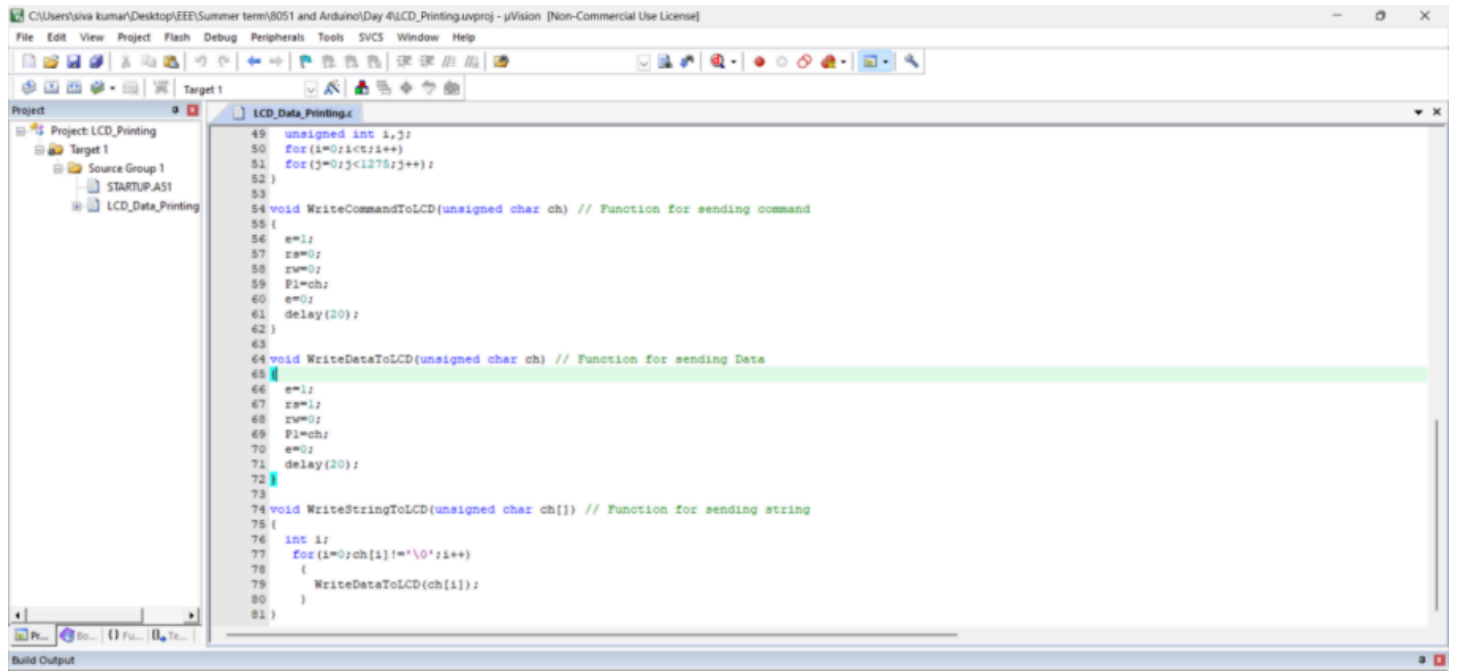
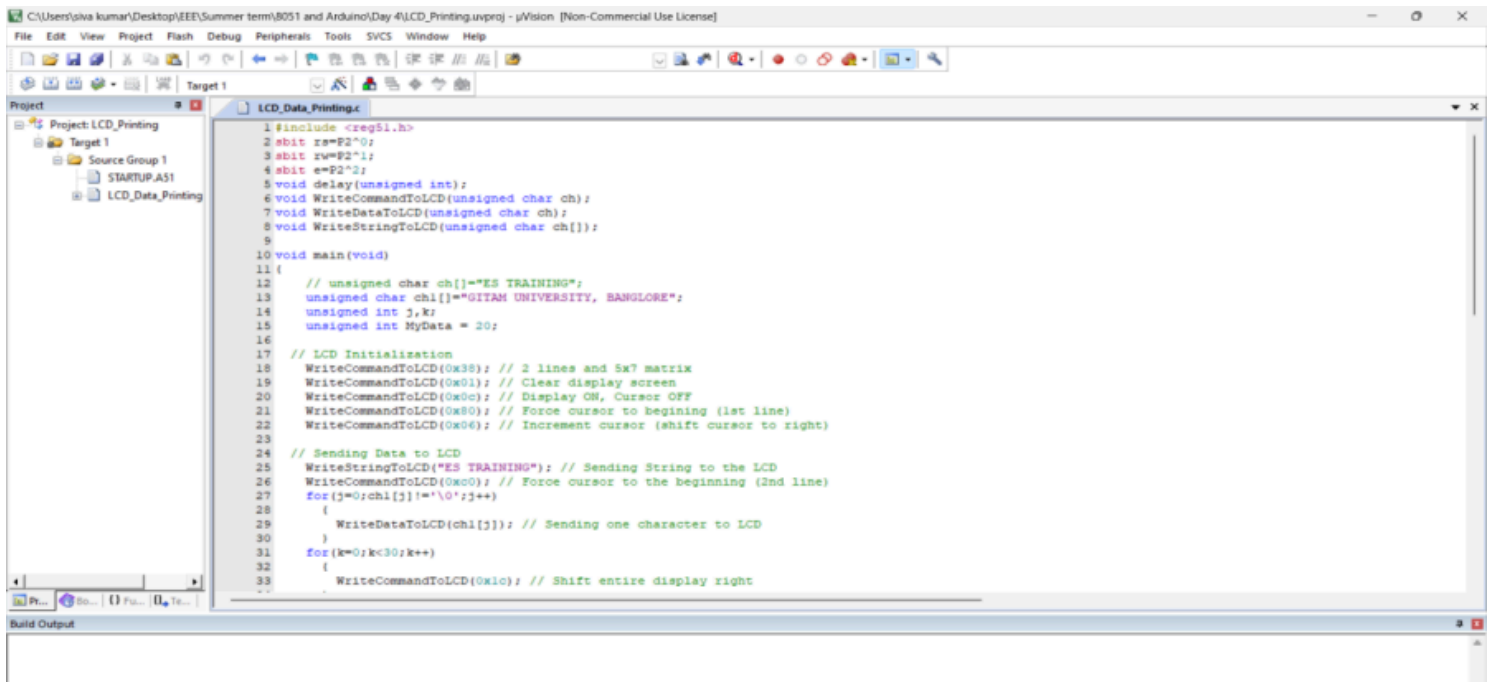
Logic:

- Functions must be implemented to send commands and data to the LCD.
- Some LCD commands are, for example, clear display and cursor positioning. ☐
- Before displaying numerical data as symbols, they should first be converted to ASCII.
- Establish basic connections with the power supply and ground and enable pins.

Common Mistakes:

- **Command mismatch:** Be sure the correct commands are being sent to the LCD.
- **Command positioning:** Proper display requires placing commands properly.
- **Clear display and new line commands:** Use the right commands that would either clear the display or take you to a new line for of these commands

Results:-



```
C:\Users\siva kumar\Desktop\EEE\Summer term\B051 and Arduino\Day 4\LCD_Printing.uvproj - uVision [Non-Commercial Use License]
File Edit View Project Flash Debug Peripherals Tools SVCS Window Help

Project: LCD_Printing
Target 1
Source Group 1
STARTUP.AS1
LCD_Data_Printing.c

31 for(k=0;k<30;k++)
32 {
33     WriteCommandToLCD(0x10); // Shift entire display right
34 }
35 while(1)
36 {
37     WriteCommandToLCD(0x01); // Clear display screen
38     WriteCommandToLCD(0x80); // Force cursor to the beginning (1st line)
39     WriteStringToLCD("CLASS STRENGTH"); // Sending string to LCD
40     WriteCommandToLCD(0x00); // Force cursor to the beginning (2nd line)
41     WriteDataToLCD(MyData / 10) + 48; // Separating the first digit of Mydata
42     WriteDataToLCD(MyData % 10) + 48; // Separating the second digit of Mydata
43     WriteStringToLCD(" STUDENTS");
44 }
45 }
46
47 void delay(unsigned int t) // Function for setting lms delay
48 {
49     unsigned int i,j;
50     for(i=0;i<t;i++)
51     for(j=0;j<1275;j++);
52 }
53
54 void WriteCommandToLCD(unsigned char ch) // Function for sending command
55 {
56     e=1;
57     rs=0;
58     rw=0;
59     P1=ch;
60     e=0;
61     delay(20);
62 }
63 }
```

