

# Pravender kumar

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## EDUCATION

**National Institute of Technology, Durgapur**  
*M.Tech in Operations Research*

**2024**

*CGPA – 8.21*

**Guru Gobind Singh Indraprastha University, Delhi**  
*B. tech in Mechanical Engineering*

**2020**

*CGPA-7.88*

## PROFESSIONAL EXPERIENCE / INTERNSHIP

**Senior Engineer – Tata Elxsi**

*Dec 2023– Present*

**Real-Time Person Re-Identification and Unauthorized Access Detection System**

- Designed and implemented a real-time surveillance system to identify and track individuals across multiple camera views.
- Used **YOLOv9** for person detection and **Dlib + face\_recognition** for facial recognition.
- Extracted facial and body embeddings using **ResNet50**, enabling vector-based matching and Implemented **cosine similarity** for feature matching and unique identity assignment.
- Developed a **proximity-based alert mechanism** for unauthorized vehicle access prevention.
- Technologies: Python, OpenCV, YOLOv9, ResNet50, Scipy, JSON, real-time video streaming.

**Internship– Tata Elxsi**

*June 2023 – April 2024*

**Fusion of Camera & LiDAR Sensors for Depth Estimation (Associate with TATA ELXSI)**

- Created a fusion algorithm combining LiDAR point cloud (via **Open3D**) with camera detections.
- Applied **YOLO** for object detection to support depth estimation in real-time scenarios.

## ACADEMIC PROJECTS

**A Meta-Heuristic Solution for Finding an Optimal Mix of a Truck and Multi Drones for Last-Mile Delivery.**

*(MTech project supervised by Dr. Subhadip Sarkar, Department of Management Studies, NIT Durgapur)*

This dissertation introduces a new prototype that makes use of cutting-edge computational algorithms to integrate drones into the traditional Vehicle Routing Problem (VRP). The study first visits every city using the nearest neighbor technique, and then it uses the two-opt heuristic to fine-tune its routes. Combining Metaheuristics with a Mixed Integer Linear Programming (**MILP**) technique allows for the resolution of additional complications.

1. Formulation a last-mile delivery vehicle and drone mathematical model to maximize work distribution and routing.
2. Utilizing an industrial **GUROBI** optimization solver, code and solve the mathematical model.
3. Verify and validate the **Meta-Heuristic** solution for finding an optimal mix of a truck and multi drones for Last-Mile Delivery (LMD).

**POWER GENERATION USING MANUAL TRADMILL (B. tech Project)**

## SKILL

**TECHNICAL PROFICIENCY:** Machine Learning, Computer Vision, Optimization Techniques, Deep Learning, Gen AI

**PROGRAMMING LANGUAGE:** Python, C++, CPLEX, Gurobi, Google OR-Tools

**DEVELOPER TOOLS:** Visual Studio, Google Colab, Jupyter Notebook, PyCharm

**TECHNOLOGY/FRAMEWORK:** Pandas, NumPy, Scikit-Learn, Matplotlib, Langchain, Git, RAG

## AWARDS

Secured an AIR rank of **1726** in **GATE-2022**.

Publication of paper entitled "**A REVIEW PAPER ON UTILITY OF TREADMILL FOR POWER GENERATION**" published in IJTRE(International Journal for Technological Research in Engineering), Volume 7, Issue 3, November-2019