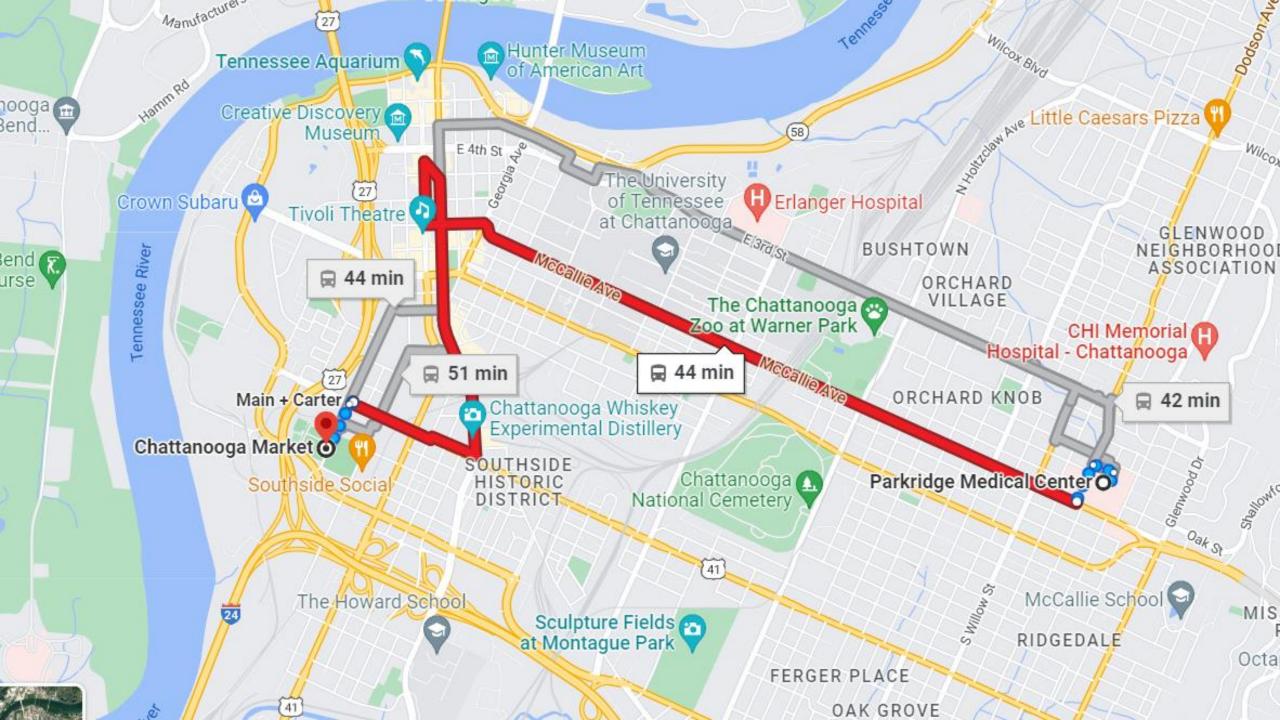
Transit Delay Time prediction using Time Series Transformers

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Problem Statement

- Predict the delay in the Fixed-line Transit System.
- Predictors?
 - Weather (temperature, humidity, precipitation)
 - Day of the week.
 - Time of the day.
 - School breaks / holidays / Concerts or Events.
 - Nature of the route.
 - Downtown vs Suburb.

Challenges

• Nature of Predictors:

Predictor	Cardinality
Temperature	ℝ+
Humidity	\mathbb{R}^+
Precipitation	ℝ+
Travel Time	\mathbb{R}^+
Segment Length	\mathbb{R}^+
School Break	{0, 1}
National Holiday	{0,1}
Day of the Week	$\{Mon, Tue,Sun\}$
Time of the Day (15-min bucket)	{0, 1, 2, 96}
Route Segment	$\{S_1, S_2, \dots S_{50}\}$

^{*}There are more than 3000 route segments in the dataset, we only consider a few for the purpose of simplification

Time Series Transformer

- An extension of the *traditional* transformer that allows you to work with continuous time predictors.
- Check
 https://github.com/PraveshKoirala/Transf
 ormers-Paper
 for an overview on the method.

EXTENSION:

 Change the architecture in such a way that it now works with both Categorical and Continuous predictors.

Algorithm for Time Series Forecasting

```
Input: \mathbf{z}, \mathbf{x} \in \mathbb{R}^*, two sequences of IL-Ratio inputs (+ve reals).
         Output: P = \mathbb{R}^{length(X)} where p_t \in (0,1) is the t-th IL-Ratio.
         Hyperparameters: l_{max} = 10, L_{enc} = 4, L_{dec} = 4, H, d_e = d_{model}, d_{mln} \in \mathbb{N}
         Parameters: \theta includes all of the following parameters:
                 W_e \in \mathbb{R}^{d_e \times 1}, W_p \in \mathbb{R}^{d_e \times l_{max}}, the token and positional embedding matrices.
                 For l \in [L_{enc}]:
                          \boldsymbol{W}_{l}^{enc}, multi-head encoder attention parameters for layer l
                        | \mathbf{\gamma}_{l}^{1}, \mathbf{\beta}_{l}^{1}, \mathbf{\gamma}_{l}^{2}, \mathbf{\beta}_{l}^{2} \in \mathbb{R}^{d_{\theta}}, two sets of layer-norm parameters,
                         \boldsymbol{W}_{mlp}^{l} \in \mathbb{R}^{d_{mlp} \times d_e}, \boldsymbol{b}_{mlp}^{l} \in \mathbb{R}^{d_{mlp}}, \boldsymbol{W}_{mlp2}^{l} \in \mathbb{R}^{d_e \times d_{mlp}}, \boldsymbol{b}_{mlp2}^{l} \in \mathbb{R}^{d_e}, \text{ MLP parameters.}
               For l \in [L_{dec}]
                          \boldsymbol{W}_{l}^{dec}, multi-head decoder attention parameters for layer l
                         W_l^{e/d}, multi-head cross-attention parameters for layer l.
                        | \gamma_I^3, \beta_I^3, \gamma_I^4, \beta_I^4 \in \mathbb{R}^{d_\theta}, two sets of layer-norm parameters,
                        |\boldsymbol{W}_{mlp_e}^l \in \mathbb{R}^{d_{mlp} \times d_e}, \boldsymbol{b}_{mlp}^l \in \mathbb{R}^{d_{mlp}}, \boldsymbol{W}_{mlp_4}^l \in \mathbb{R}^{d_e \times d_{mlp}}, \boldsymbol{b}_{mlp_4}^l \in \mathbb{R}^{d_e}, \text{ MLP parameters.}
                 W_u \in \mathbb{R}^{length(X) \times d_\theta}, the unembedding matrix.
/* Encoder portion */
        l_x \leftarrow lenath(z)
         for t \in [l_z]: e_t \leftarrow W_e[:, z[t]] + W_p[:, t]
         Z \leftarrow [e_1, e_2, \dots e_{l_2}]
         for l = 1, 2, ..., L_{enc} do
                   \mathbf{Z} \leftarrow \mathbf{Z} + MHAttention(\mathbf{Z} | \mathbf{W}_{i}^{enc}, Mask \equiv 1)
                   for t \in [l_z]: \mathbf{Z}[:,t] \leftarrow layer\_norm(\mathbf{Z}[:,t]| \boldsymbol{\gamma}_l^1, \boldsymbol{\beta}_l^1)
                   Z \leftarrow Z + W_{mlp2}^{l} ReLU(W_{mlp1}^{l} Z + b_{mlp1}^{l} \mathbf{1}^{T}) + b_{mlp2}^{l} \mathbf{1}^{T}
                   for t \in [l_z] : \mathbf{Z}[:,t] \leftarrow layer\_norm(\mathbf{Z}[:,t]|\boldsymbol{\gamma}_l^2,\boldsymbol{\beta}_l^2)
        end
/* Decoder portion */
10 l_x \leftarrow length(x)
11 for t \in [l_X]: e_t \leftarrow W_e[:, x[t]] + W_p[:, t]
12 X \leftarrow [e_1, e_2, \dots e_{l_X}]
                   X \leftarrow X + MHAttention(X|W_l^{dec}, Mask[t, t'] \equiv [[t \leq t']])
                   for t \in [l_X]: X[:,t] \leftarrow layer\_norm(X[:,t]|\gamma_l^3, \beta_l^3)
                  X \leftarrow X + MHAttention(X, Z|W_1^{e/d}, Mask \equiv 1)
                   for t \in [l_z] : X[:,t] \leftarrow layer\_norm(X[:,t]|\gamma_1^4,\beta_1^4)
                  X \leftarrow X + W_{mlv4}^l ReLU(W_{mlv3}^l Z + b_{mlv3}^l \mathbf{1}^T) + b_{mlv4}^l \mathbf{1}^T
                   for t \in [l_x] : X[:,t] \leftarrow layer\_norm(X[:,t]|\gamma_1^5, \beta_1^5)
20
21 return P = W_u X
```

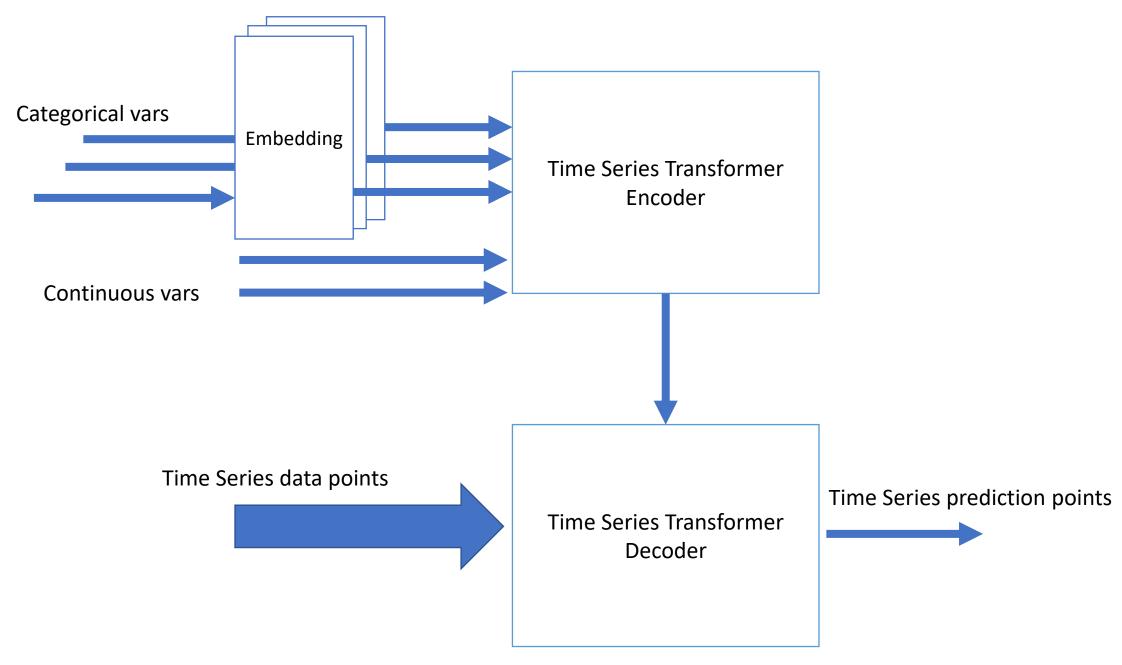


Fig: Architecture of Mixed Time Series Transformer

Critical Analysis

- Why not go with pure decoder architecture since it's just a next item prediction task?
 - Answer: Sticked with tried and tested model. Could potentially look into using a decoder only architecture.
- Bigger question on the inherent assumption i.e. "Delay of a segment is dependent upon past environment and past delays of the segment."
 - But realistically, delay also largely depends upon the past traffic conditions of ALL the other connected route segments. How do you encode that?

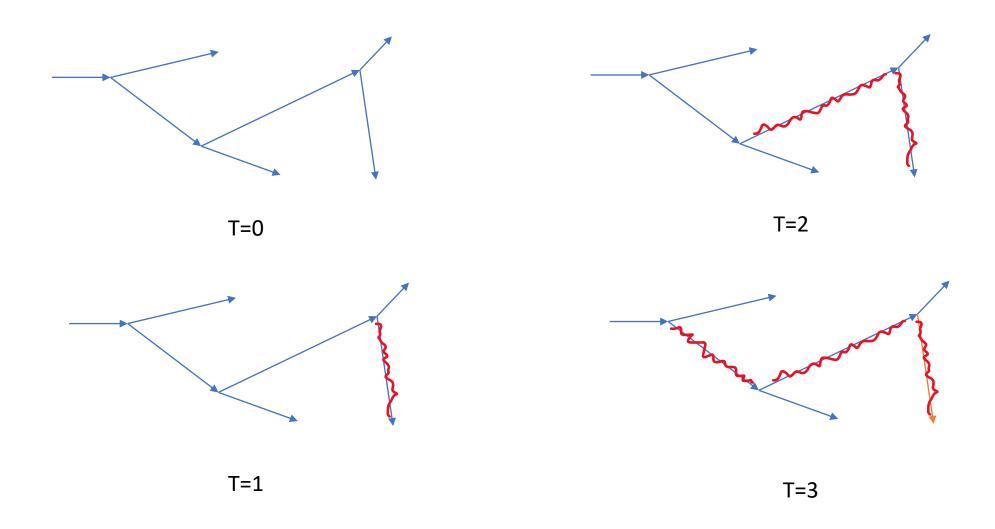


Fig: Delay propagation in Traffic Networks

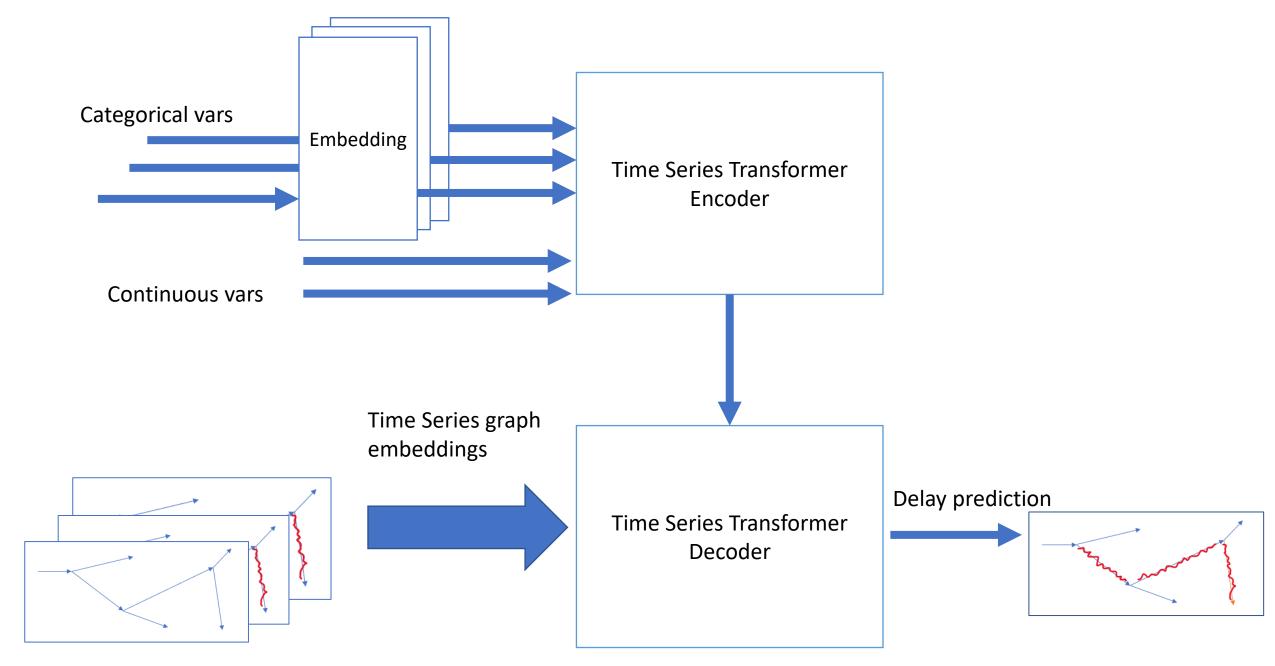


Fig: Architecture of Mixed Time Series Transformer

How do you incorporate the information of the global structure in Transformers?

- Generate Embedding using Graph Neural Networks?
- Predict \mathbb{R}^n in decoder instead of a single \mathbb{R} ?
 - Hoping that decoder self-attention will figure out a way to associate segment delays across time?