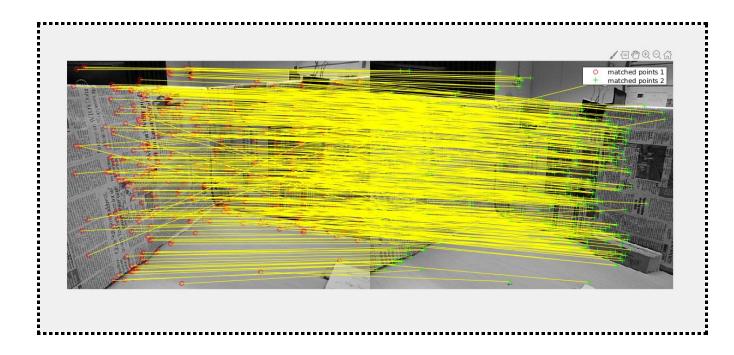
Assignment 3

Pravin Mali 20161099

Extracted Points -



Calibration Matrix -

$$K = \begin{pmatrix} 558.7087 & 0.0000 & 310.3210 \\ 0.0000 & 558.2827 & 240.2395 \\ 0.0000 & 0.0000 & 1.0000 \end{pmatrix}$$

Fundamental Matrix -

Fundamental	Matrix	
0.0000	-0.0000	0.0010
0.0000	0.0000	-0.0082
-0.0024	0.0072	1.0000

Essential Matrix -

Essential Ma	atrix	
0.4287	-4.6969	0.7207
4.5609	0.3819	-0.9020
-1.1176	0.3609	0.1437

Rotational Matrix -

```
Rotational Matrix
0.9535 0.1440 -0.2647
-0.1291 0.9890 0.0728
0.2722 -0.0352 0.9616
```

Translation Matrix -

```
Translation Matrix
-0.0694
-0.1910
-0.9791
```

Scene Reconstruction -

