

Electro Magnetic Induction

magnetic flux :- No. of magnetic field lines passing throughout area and \perp to it.

Magnetic flux is defined as,

$$\phi = \vec{B} \cdot \vec{ds}$$

$$\phi = B(ds) \cos\theta$$

θ is angle between \vec{B} and \vec{ds}

→ Total magnetic flux through closed loop is

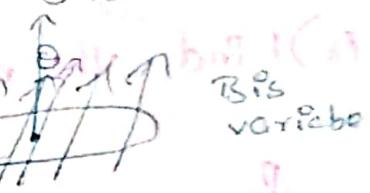
B is constant

$$\phi_{\text{total}} = B(\text{area}) \cos 0^\circ$$



$$\phi_{\text{total}} = B \cdot \pi r^2 \cos 0^\circ$$

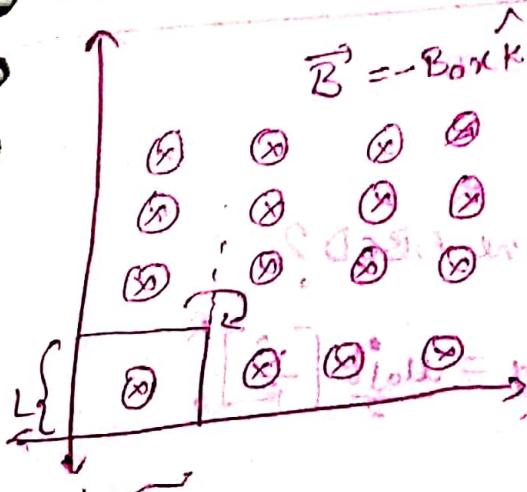
B is variable



$$d\phi = B \cdot d\vec{s} \cos\theta$$

$$\phi_{\text{net}} = \int d\phi = \int B \cdot d\vec{s} \cos\theta$$

Q :- If square loop ABCD is rotated by an angle of 180° about BC side then find magnitude of change in magnetic field.



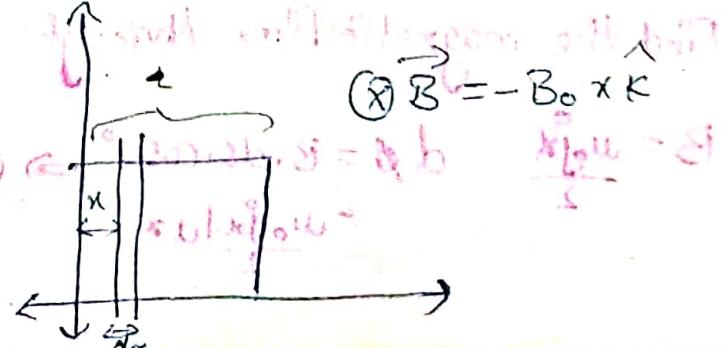
Ans :-

Area vector is inside the page.

$$(\times) \vec{B} = -B_0 \times \vec{K}$$

Area vector is outside the page.

$$(\times) \vec{B} = -B_0 \times \vec{K}$$



$$d\phi = B_0 x (ds) \cos 0^\circ$$

$$= B_0 x l \cdot dx$$

$$d\phi = B_0 L x dx$$

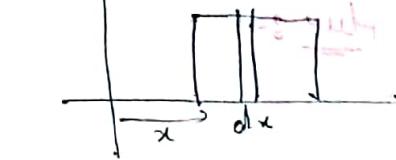
$$\Phi_{\text{total}} = \int d\phi = B_0 L \int_0^L x dx$$

$$\Phi_1 = B_0 L \cdot \frac{\frac{L^2}{2}}{2} = \frac{B_0 L^3}{2}$$

$$\text{change in } \phi = \phi_2 - \phi_1$$

$$= -\frac{B_0 L^3}{2} + \left(-\frac{3B_0 L^3}{2} \right)$$

$$= -2B_0 L^3.$$



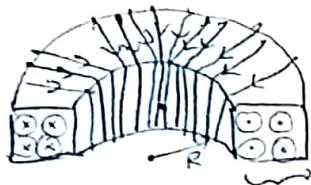
$$d\phi = B_0 x ds \cos 180^\circ$$

$$\int d\phi = -B_0 L \int_0^L x dx$$

$$\Phi_{\text{net}} = -B_0 L \left(\frac{3L^2}{2} \right)$$

$$\phi_2 = -\frac{3B_0 L^3}{2}$$

a) Find the magnetic flux through cross section of toroid.



N - total no. of turns.

$$B = \frac{\mu_0 N i}{2\pi x}$$

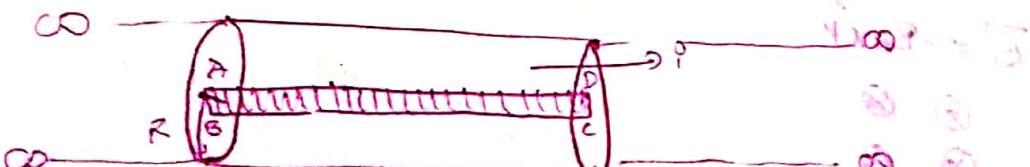
$$d\phi = B \cdot l \cdot dx \cos 0^\circ$$

$$d\phi = \frac{\mu_0 N i l}{2\pi} \frac{dx}{x}$$

$$\phi = \int d\phi = \frac{\mu_0 N i l}{2\pi} \ln \left(\frac{x+1}{R} \right)$$

Toroidal coil for air gap no pole, horizontal $\phi = \frac{\mu_0 N i l}{2\pi} \ln \left(\frac{L+R}{R} \right)$

(a)



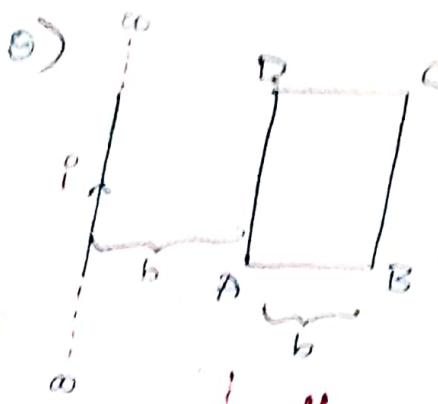
Find the magnetic flux through the plane ABCD?

$$B = \frac{\mu_0 j x}{2} \quad d\phi = B \cdot ds \cdot \cos 90^\circ \Rightarrow \phi = \int d\phi = \frac{\mu_0 j t}{2} \left[\frac{x^2}{R} \right]_0^R$$

$$= \frac{\mu_0 j x l dx}{2}$$

$$\text{Ans} \rightarrow \theta = \omega t$$

$$\phi = \frac{\theta}{2\pi}$$



Find the flux through the loop?

$$d\phi = B dA \cos 90^\circ$$

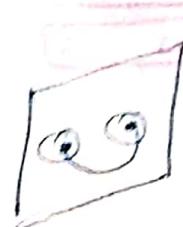
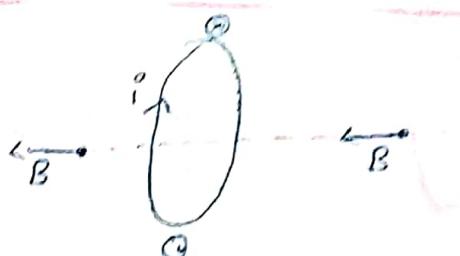
~~area~~

$$d\phi = BdA \cos 90^\circ$$

$$d\phi = \frac{\mu_0 I}{2\pi r} B dA$$

$$\phi = \frac{\mu_0 I}{2\pi} \int_{-b}^{+b} \frac{dy}{r} \Rightarrow \phi = \frac{\mu_0 I l}{2\pi} \ln(x^2_b)$$

$$\phi = \frac{\mu_0 I l}{2\pi} \ln(2)$$



MF line passing through centre.



Semi circular loop out of plane.



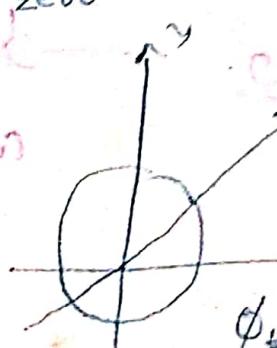
C.S view of circular wire MF lines

* Total flux through XY plane is zero.



$$\phi \text{ through loop} = \pi R^2$$

$$\phi_{\text{total}} = 0$$



$$\phi_{\text{through XY plane}} = -\pi R^2$$

$$\phi_{\text{through XY plane}} = -\pi R^2$$

Note:- $\oint \vec{B} \cdot d\vec{l}$ through the plane in which circular conducting coil is there is zero.

* Refer to NCERT Pg-116 12-Part-I.

Faraday's Law

→ It states that whenever there is a change of Φ_{mag} through closed loop, there exist emf in the loop.

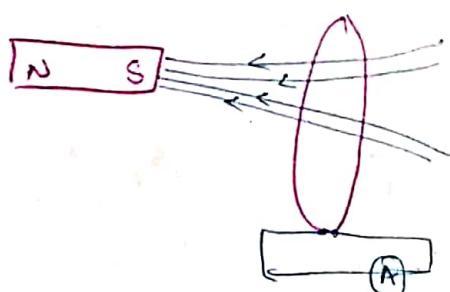
→ Emf developed in the loop is called as induced emf. Current developed is called induced current.

Magnetic flux, $\Phi = B(A \cos \theta)$ can be changed by

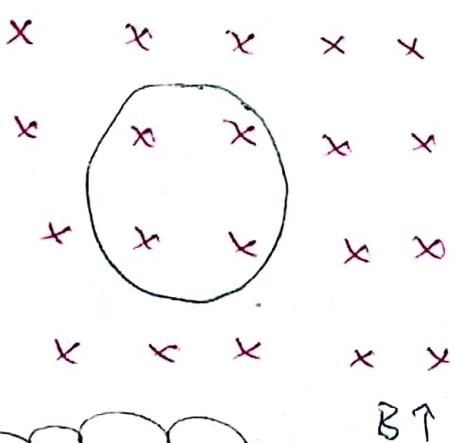
B is variable

Area is variable

θ is variable
(when loop rotates)



→ Whenever there is a relative motion b/w bar magnet and coil, current can be found in the coil.



Induced emf in the loop is given by rate of change of magnetic flux

$$\text{Induced emf} = \left| \frac{d\Phi}{dt} \right|$$

Lenz's Law

→ Left hand thumb rule

Thumbs → magnetic field
Curl fingers → Direction of induced current

→ Always induced current produced in the loop such that, it opposes the cause of its creation.

$\times \times \times$ ~~increasing~~ \rightarrow $\phi = B \cdot dS$ \rightarrow B is increasing



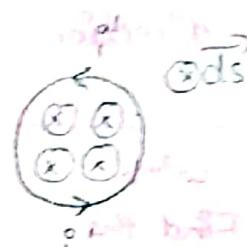
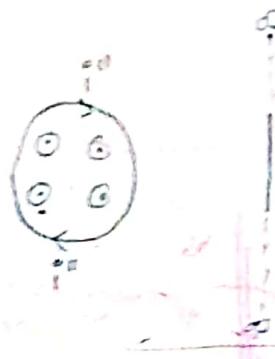
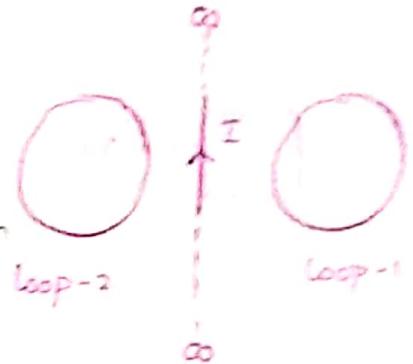
$\phi = B \cdot dS$

$B \uparrow \Rightarrow \phi \uparrow$

\rightarrow Induced current is in **ACW** direction.

Q) Find the direction of current in loop 1 and loop 2 if 'B' is increasing?

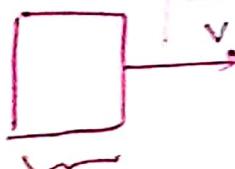
\Rightarrow If 'B' is increasing the direction of induced current in loop-1 **ACW** loop-2 **CW**



$\phi = B \cdot dS$

$B \uparrow \phi \uparrow$

Example



$x \times \times \times$
 $x \times \times \times$
 $x \times \times \times$
 $x \times \times \times$

B is uniform
 v is constant.

Resistance of loop is R

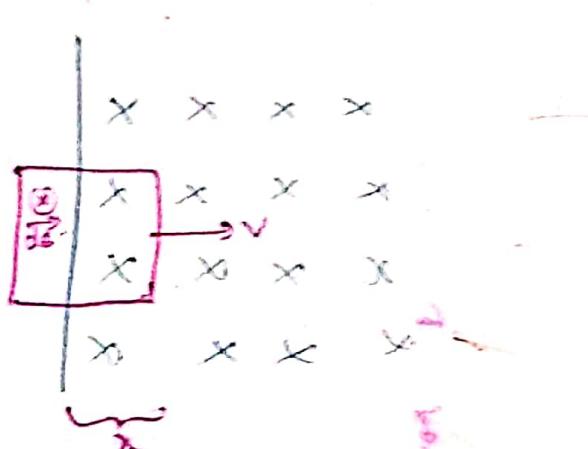
While entering loop :-

$$\phi = B \cdot dS \text{ also}$$

$$\phi = B \cdot I \cdot R$$

$$\text{Induced emf} = \left| \frac{d\phi}{dt} \right| = B I \frac{dx}{dt}$$

$$E = B L v$$



\rightarrow If R is the resistance of loop, Induced current $\frac{d\phi}{dt} = \frac{BL^2}{R}$

$$I = \frac{BL^2}{R}$$

\rightarrow Induced current direction is now while loop entering B

While loop is moving inside the B :



While loop leaving the B

Current is $\frac{BL}{R}$ in cw direction.

a) If semi circular wire rotates with constant angular velocity ω . Find the induced emf as function of time and draw a graph b/w emf and time?

Ans:

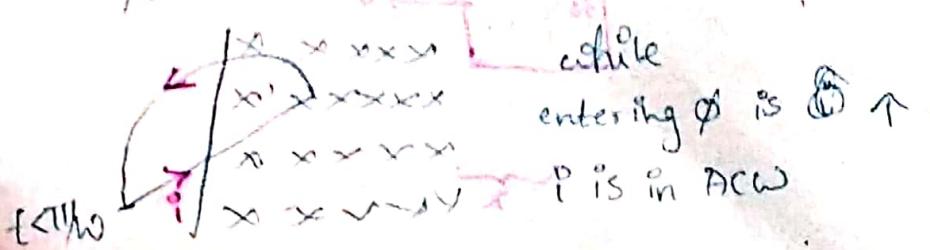
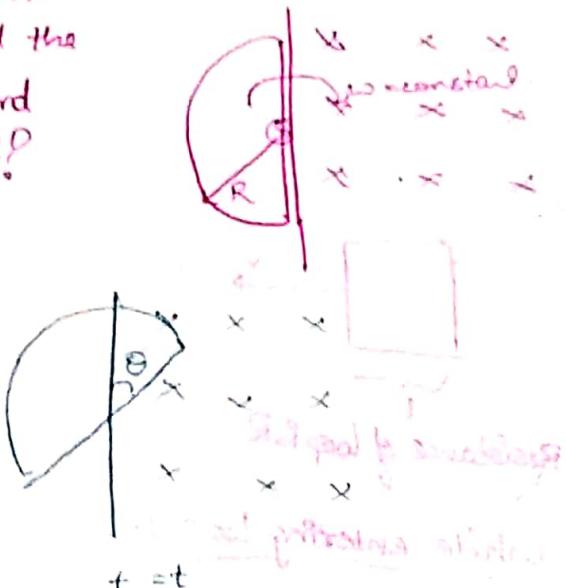
$$\omega = \frac{d\theta}{dt}$$

$$\text{Area} = \frac{\theta}{2\pi} \pi R^2 = \frac{1}{2} \theta R^2$$

$$\phi = B(\text{Area}) = B \cdot \frac{1}{2} \theta R^2$$

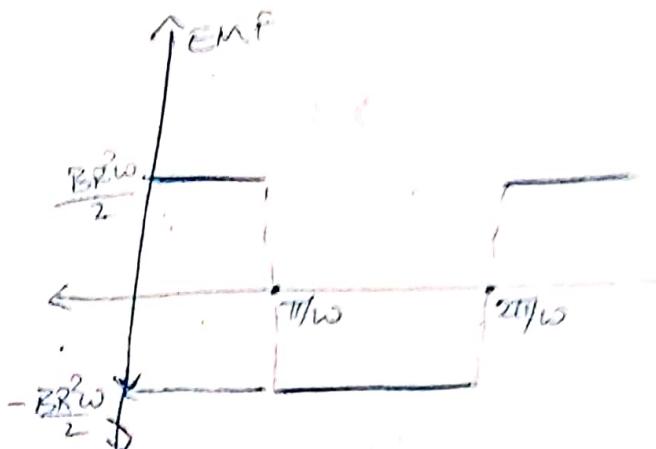
$$\phi = \frac{1}{2} BR^2 \theta$$

$$\int \frac{d\phi}{dt} = \frac{1}{2} BR^2 \cdot \frac{d\theta}{dt} \Rightarrow \text{emf} = \frac{1}{2} BR^2 \omega = \text{constant}$$





$$\theta > \pi/\omega$$



Q3- If loop is rotating with constant angular acceleration then find induced emf and draw graph b/w emf and time.

Ans

$$\text{Area} = \frac{1}{2} \theta R^2$$

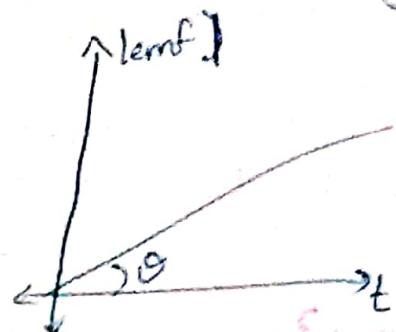
$$\phi = B \times \frac{1}{2} \theta R^2 \cos \theta$$

$$\frac{d\phi}{dt} = B \times \frac{1}{2} \theta R^2 \cos \theta$$

$$\frac{d\phi}{dt} = \frac{BR^2}{2} \frac{d\theta}{dt}$$

$$\text{emf} = \frac{BR^2}{2} \frac{d\theta}{dt} \quad \left[\text{emf} = \frac{BR^2}{2} \omega t \right] \quad \omega = \frac{d\theta}{dt} = \frac{\theta}{t}$$

$$\text{Induced emf magnetic field} = \left(\frac{BR^2}{2} \right) \frac{1}{t} \theta^2 = \frac{B}{2} \theta^2$$



$$\tan \theta = \frac{BR^2 \omega}{2}$$

$$(\theta - (\pi/2)) + (\theta - \pi/2) \cdot \theta =$$

$$\left(\frac{(\theta - \pi/2) + (\theta - \pi/2) \cdot \theta}{2} \right) \omega =$$

1. What is the standard unit of length?

2. What is the standard unit of mass?

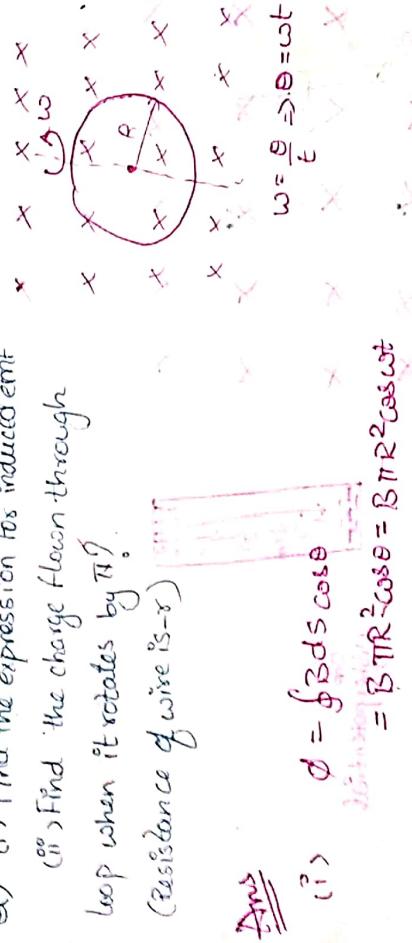


$$\begin{aligned} \mathcal{E} &= B_0 \left(l^2 + \frac{l^2 + 2lx'}{2} \right) \\ \mathcal{B} &= B_0 \left(\frac{3l^2}{2} + lx' \right) \\ \text{Emf} &= \left| \frac{d\psi}{dt} \right| = \frac{d}{dt} \left(B_0 \left(\frac{3l^2}{2} + lx' \right) \right) \\ &= B_0 \frac{dx'}{dt} \end{aligned}$$

Emf = $B_0 l v$

Induced current is in accl

- (i) Find the expression for induced emf
 (ii) Find the charge flown through loop when it rotates by $\pi/2$.
 (Resistance of wire is r)



Ans

$$\begin{aligned} (i) \quad \mathcal{E} &= \int B ds \cos \theta \\ &= B \pi R^2 \cos \theta = B \pi R^2 \cos \omega t \end{aligned}$$

$$\begin{aligned} \mathcal{E}_{AC} &= \left| \frac{d\phi}{dt} \right| = \left| B \pi R^2 \frac{d(\cos \omega t)}{dt} \right| \\ &= \underline{\underline{B \pi R^2 \omega}} \end{aligned}$$

$$\begin{aligned} \mathcal{E}_{AC} &= \left| B \pi R^2 (-\sin \omega t) \cdot \omega \right| \\ \text{Emf} &= B \pi R^2 \omega \sin \omega t \rightarrow \text{AC emf} \end{aligned}$$

$$(ii) \quad \text{Charge flown} = \left| -B \pi \frac{R^2 - B \pi R^2}{\omega} \right|$$

$$\text{charge flown} = \frac{2 B \pi R^2}{\omega}$$

Higher potential
palm and

Keep you
in tree if
has high
potential

Scant

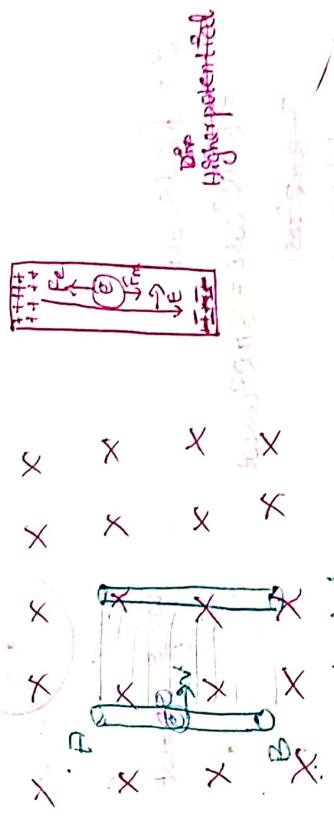
Note: (1) $\text{EMF} = \frac{d\phi}{dt} \Rightarrow \text{Induced current } I = \frac{\text{emf}}{R}$

$$\frac{dq}{dt} = \frac{d\phi}{R \cdot dt}$$

$$dq = \frac{d\phi}{R}$$

- (2) Charge flow is independent of time
- charge flow = $\frac{\phi_{final} - \phi_{initial}}{\text{Resistance}}$

Motional EMF



At steady state $E = B(l \cdot v)$ and $I = \frac{E}{R}$, no more accumulation of charge.

$$-E(\vec{v} \times \vec{B}) = (E \vec{E}) \cdot (\vec{v} \times \vec{B}) \quad \vec{E} = \vec{v} \times \vec{B}$$

Induced by motion

$$\Delta V = +E \cdot dL \quad \vec{E} = B(vt) \vec{l}$$

$$|\Delta V| = \Phi(\vec{v} \times \vec{B}) \cdot dL \quad \Phi = B(vt)L$$

$$|\Delta V| = \sqrt{BL^2}$$

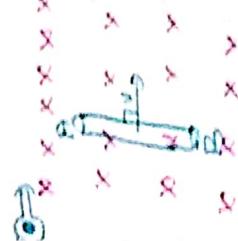
Higher potential and lower potential is decided by right hand palm rule.

Right hand Thumb Rule
Keep your thumb in the ~~extending~~ direction of velocity and all other fingers in the direction of magnetic field then the above surface of hand has higher potential and the lower side of hand has lower potential.

Semile

$$\text{Change in potential } \Delta V = (\vec{v} \times \vec{B}) \cdot d\vec{l}$$

$$= 0$$



$$\Delta V = V_B - V_A = BL$$



$$\Delta V = V_B - V_A = BL (\cos\theta)$$

$$\Delta V = (\vec{v} \cdot \vec{B}) d\vec{l}$$
$$= VB \sin\theta \cos(\theta - \phi)$$
$$\Delta V = VB \sin\theta$$

~~X~~ to work out ~~V_B~~ but ~~shape~~ of the conductor is not known. Difficult to calculate.

~~X X X X X~~ $\Delta V_1 = (\vec{v} \times \vec{B}) \cdot \vec{dl}_1$
~~X X X X X~~ $\Delta V_2 = (\vec{v} \times \vec{B}) \cdot \vec{dl}_2$
~~X X X X X~~ $\Delta V_n = (\vec{v} \times \vec{B}) \cdot \vec{dl}_n$

(Q)

$$V_{AB} = \Delta V_1 + \Delta V_2 + \dots + \Delta V_n$$

$$V_{AB} = (\vec{v} \times \vec{B}) (\vec{dl}_1 + \vec{dl}_2 + \dots + \vec{dl}_n)$$

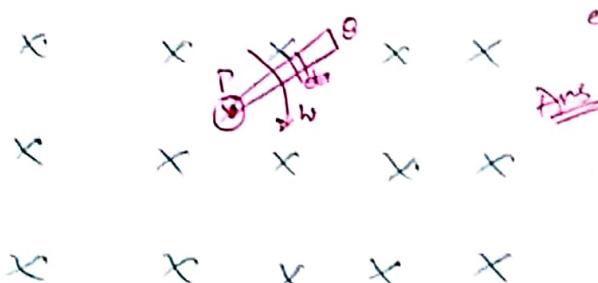
$$V_{AB} = (\vec{v} \times \vec{B}) \cdot \vec{AB}$$

does not depend on shape
depends only on initial and final post of conductor.

Ans

a)  Find the P.d. across the ends of rod.

21



$$dB = B dx$$

$$dv = B dx \times \omega$$

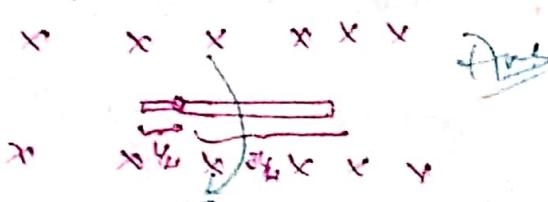
$$V_{net} = \int dv = B \omega \int x dx$$

$$V_{net} = \frac{B \omega l^2}{2}$$

S is higher potential
P is lower potential

(Q)

b) 



$$\frac{\pi R^2}{2} \frac{Bt^2 - l^2}{16} \frac{l^2}{16 - 2}$$

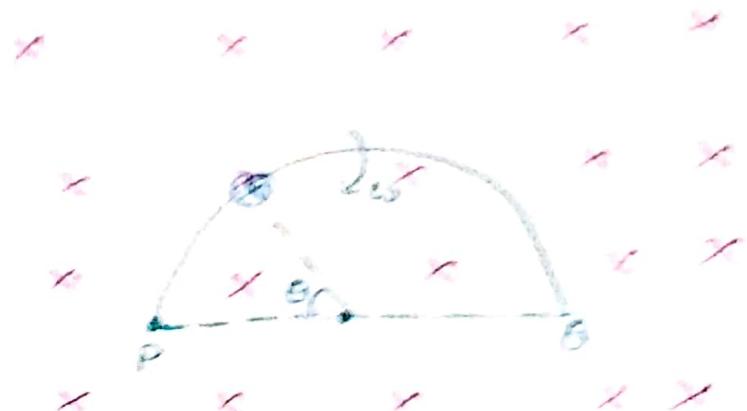
Post marks

$$V_A - V_B = \frac{B \omega}{2} \left(\frac{3l}{4} \right)^2 = \frac{9 \pi \omega l^2}{32}$$

$$V_P - V_B = \frac{B \omega}{2} \left(\frac{l}{4} \right)^2 = \frac{8 \omega l^2}{32}$$

$$V_B - V_P = \frac{6B\omega R^2}{4\pi\epsilon_0} \cdot \frac{\pi R^2}{4}$$

Q)



Ans

$$\text{using } V_B - V_Q = \frac{2\pi R^2 \rho_s \omega}{2} \text{ and } V_Q - V_P = \frac{2\pi R^2 \rho_s \omega}{2} \text{ we get}$$

$$V_B - V_P = 2\pi R^2 \rho_s \omega \left(\frac{1}{2} \right)$$

$$V_B - V_P = 2\pi R^2 \rho_s \omega \left(\frac{1}{2} \right)^2$$

$$V_B - V_P = 2\pi R^2 \rho_s \omega^2 \left(\frac{1}{2} \right)$$

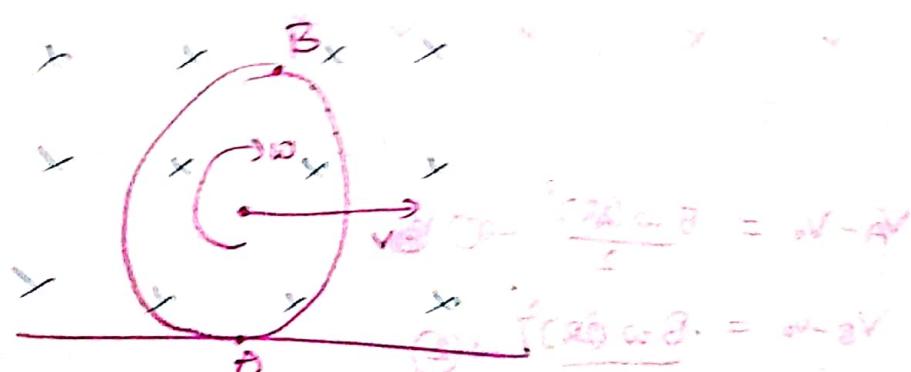
$$V_B - V_A = 2\pi R^2 \rho_s \omega^2 \left(\sin^2 \theta/2 - \cos^2 \theta/2 \right)$$

$$V_B - V_A = -2\pi R^2 \rho_s \omega^2 \cos \theta$$

$$V_A - V_P = 2\pi R^2 \rho_s \omega^2 \cos \theta$$

Q)

X X X X



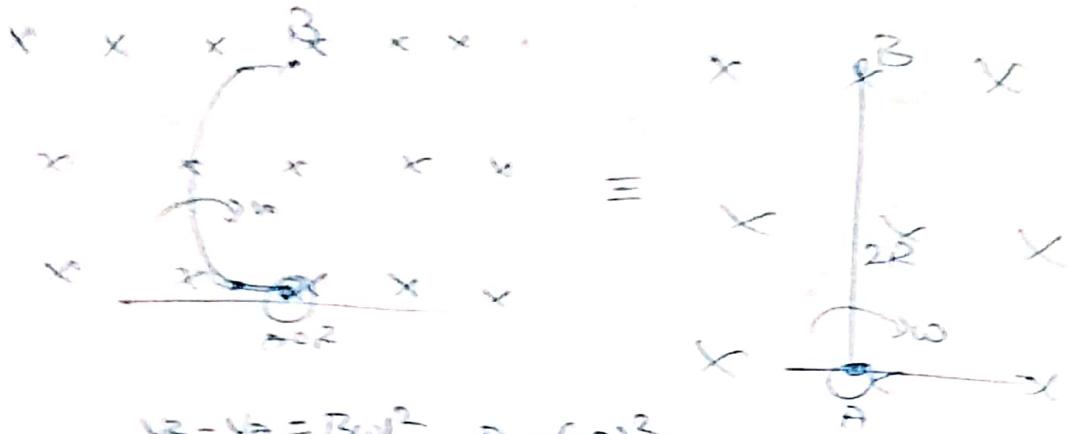
Find the potential difference across A and B?

$$B \cos \theta = \phi B - \phi A$$

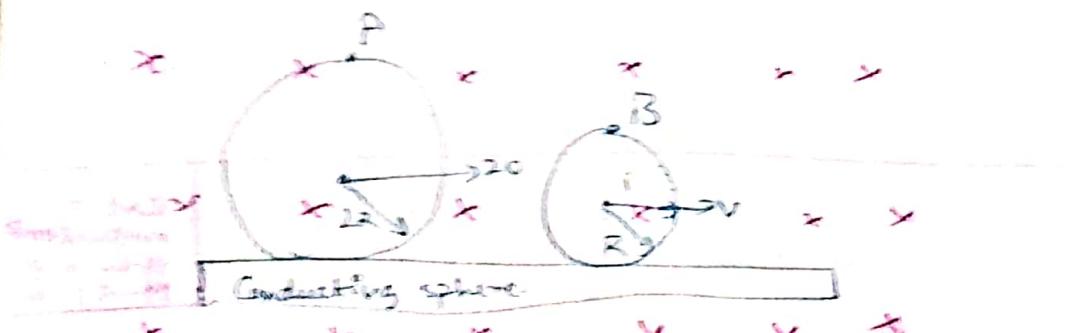
Expt - 2
National Engg
20-04 3-10
20-04 3-14

Work and Inertia is zero.

$\omega = \omega$
pure rotation



a) $v_A - v_B = \omega A R - \omega B (2R)$



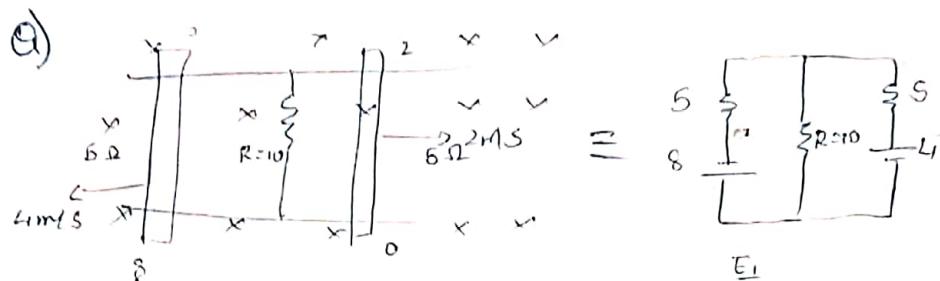
Find the pd b/w A and B?

$$V_A - V_B = \frac{B\omega (2R)^2}{2} \rightarrow ①$$

$$V_B - V_A = \frac{B\omega (R)^2}{2} \rightarrow ②$$

① - ② (Same sense with rotating with respect to center)

$$V_A - V_B = 6B\omega R^2$$

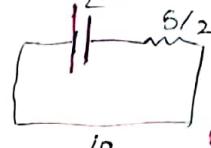


$$BLv = 8$$

$$2 \times 2 \times 1 = 4$$

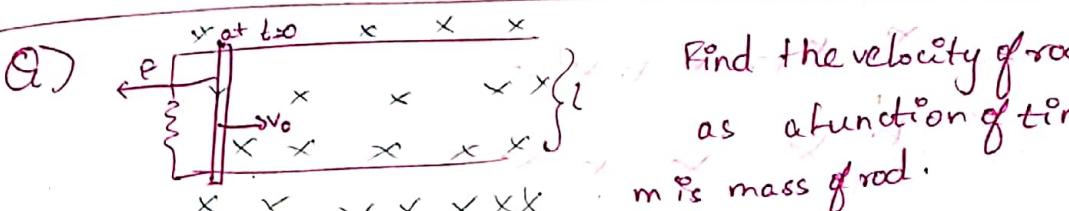
$$4 \times 2 \times 1 = 8$$

$$E_{\text{net}} = \frac{\frac{E_1}{5} - \frac{8}{5}}{\frac{2}{5}} = -\frac{4}{5}$$



$$P_{\text{net}} = 10 + 8/2 = 14$$

$$P = \frac{2 \times 2}{25} = \frac{4}{25}$$



Find the velocity of rod
as a function of time

m is mass of rod.

$$\theta R = B V_0 l$$

$$m \frac{dv}{dt} = -\frac{B V_0 l}{R} \cdot B l$$

$$m \frac{dv}{v} = -\frac{B^2 l^2}{R} dt$$

$$m \ln\left(\frac{v}{v_0}\right) = -\frac{B^2 l^2 t}{R}$$

$$\ln\left(\frac{v}{v_0}\right) = -\frac{B^2 l^2 t}{m R}$$

$$v = v_0 e^{-\frac{B^2 l^2 t}{m R}}$$

(B)

Find the total heat lost through resistor

$H = \frac{1}{2} I^2 R t$

$$I = \frac{BL}{R} v_0 e^{-\frac{B^2 l^2 t}{m R}}$$

$$H = \int \frac{BL^2}{R^2} v_0^2 e^{-\frac{B^2 l^2 t}{m R}} \cdot R' dt = \int \frac{B^2 l^2 v_0^2}{R} e^{-\frac{B^2 l^2 t}{m R}} dt$$

Induced
→ Force

Force of motion

Force of motion

(Q)



Free fall motion
initial velocity = 0
initial position = 0
final position = S

If rod is released from rest find acceleration of rod.



$$m a = mg - BvL \cdot B L \quad \therefore a = g - B v^2$$

$$m a = mg - \frac{1}{2} B L^2$$

$$m a = mg - c B L$$

$$a(m + c B^2 L^2) = g m$$

$$a = g - B v^2$$

$$a = c B v^2$$

$$\frac{dv}{dt} = g - c B L \frac{dv}{dt}$$

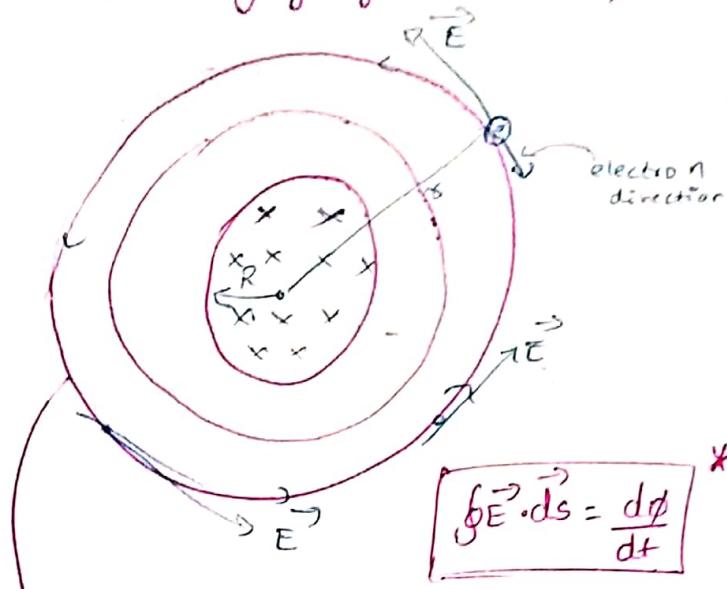
$$v = c B L a$$

$$a = \frac{mg}{m + c B^2 L^2}$$

(E)

Induced Electric field

⇒ If the varying magnetic field will produce electric field.



$$B = f(t) \quad \Rightarrow \quad \frac{d\Phi}{dt}$$

$$\text{Induced emf} = -\frac{d\Phi}{dt}$$

$$-\oint \vec{E} \cdot d\vec{s} = -\frac{d\Phi}{dt}$$

$$\oint \vec{E} \cdot d\vec{s} \propto \frac{d}{dt} (B \pi R^2)$$

$$E \oint ds = \pi R^2 \frac{dB}{dt}$$

$$E \cdot 2\pi R = \pi R^2 \frac{dB}{dt}$$

$$E = \frac{R^2}{2\pi} \left(\frac{dB}{dt} \right)$$

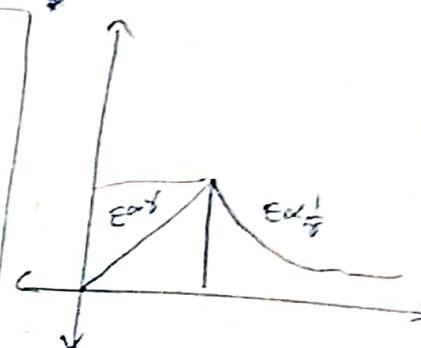
These are induced electric field lines
 Note:- Induced electric field lines are closed loops
 concentric circles (they are closed loops)
 * Induced electric field are non-conservative.
 Work done ≠ 0 in closed loop.

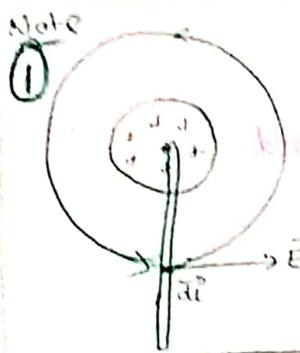


$$E_C = \frac{R^2}{2d} \left(\frac{dB}{dt} \right)$$

$$E_A = \frac{R}{2} \left(\frac{dB}{dt} \right)$$

$$E_B = \frac{R}{2} \left(\frac{dB}{dt} \right)$$



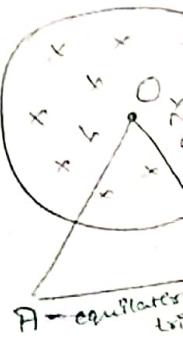


Note ① As rod is kept along the radial direction

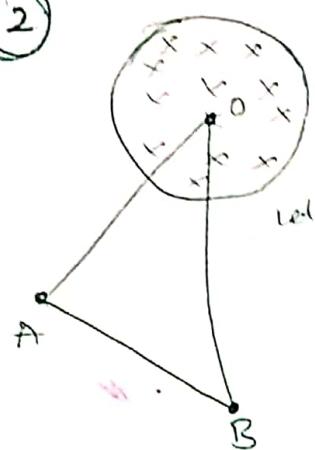
$$\Delta v = -\int \vec{E} \cdot d\vec{l}$$

~~total change in velocity~~ $\Delta v = 0$

∴ If a rod is kept along radial directions
P.d across the rod is ZERO



2



$$B = f(L) \uparrow$$

OA & OB are imaginary rods

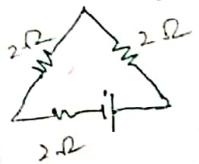
Total induced emf in the loop $= \frac{d\phi}{dt}$

$$\text{Let OA and OB be imaginary rods. } = \frac{d}{dt} (B \cdot \frac{1}{2} R^2 \alpha)$$

$$E_{OA} + E_{AB} + E_{BO} = \frac{1}{2} R^2 \alpha \frac{dB}{dt}$$

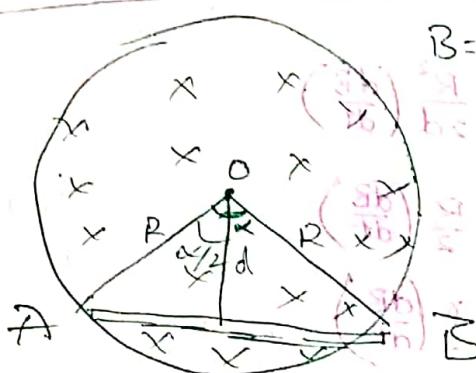
$$E_{AB} = \frac{1}{2} R^2 \alpha \frac{dB}{dt}$$

$$\therefore V_B - V_A = \frac{1}{2} R^2 \alpha \frac{dB}{dt}$$



α -angle made by rod
at centre

3



$$B = f(L) \uparrow$$

$$V_B - V_A = \frac{1}{2} d \times 2\sqrt{R^2 - d^2} \cdot \frac{dB}{dt}$$

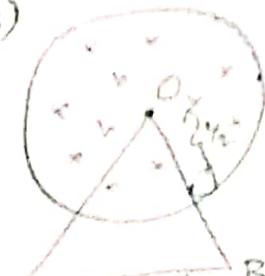
$$V_B - V_A = d\sqrt{R^2 - d^2} \cdot \frac{dB}{dt}$$

$$d = R \cos \alpha / 2$$

$$d = R \cos \alpha / 2 \quad V_B - V_A = R \cos \alpha / 2 \cdot R \sin \alpha / 2 \cdot \frac{dB}{dt}$$

$$\therefore V_B - V_A = \frac{1}{2} R^2 \sin \alpha \frac{dB}{dt}$$

a)



A - concentric
vertical
loop having resistance
each side 2Ω

$$Emf = \frac{1}{2} R^2 \frac{\pi}{3} \frac{dB}{dt}$$

$$Emf = \frac{1}{2} \times \frac{1}{2} \times \frac{\pi R^2}{3} \times \frac{dB}{dt}$$

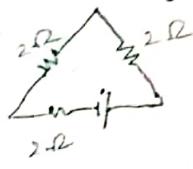
$$Emf = \frac{\pi}{12} R^2 \frac{dB}{dt}$$

$$\frac{\pi}{12} = \frac{\pi R^2}{18}$$

$$\pi \left(\frac{1}{4} + \frac{1}{12} \right)$$

$$\pi \frac{16}{12} = \frac{4\pi}{3}$$

OAB equilateral triangle loop
having resistance of each side 2Ω
Find the P.d across AIB if rate of
change of field is $2T/\text{sec}$.



$$V_{AIB} = \frac{\pi}{12} - \frac{\pi}{36} = \frac{\pi}{18}$$

$$V_B - V_A = \frac{\pi}{18} V$$

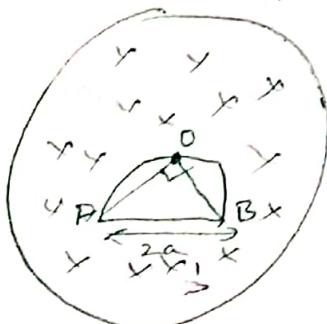
$$R_{\text{net}} = 6 - 2$$

$$R = \frac{\pi}{12 \times 6}$$

$$I \times 2 = \frac{\pi}{18} \times 2 = \frac{\pi}{36}$$

V across 2Ω resistor.

b)



$$B = B_0 + \alpha t$$

$$\frac{dB}{dt} = \alpha$$

$\int E \cdot dl$ along BOP
but not PB

$$Emf = \frac{1}{2} R^2 \frac{\pi}{2} \frac{dB}{dt}$$

$$\frac{\pi R^2}{4} \frac{dB}{dt}$$

$$Emf = \frac{\pi R^2}{4} \frac{d\alpha}{dt}$$

$$\frac{\pi R^2}{4} \frac{d\alpha}{dt}$$

$$Emf = \frac{1}{2} R^2 \frac{d(B + \alpha t)}{dt}$$

$$= \frac{1}{2} R^2 [\alpha]$$

$$Emf = \frac{1}{2} a \cdot 2a \frac{d\alpha}{dt}$$

$$Emf = a^2 \alpha$$

$$Emf \text{ of semicircular loop} = \frac{\pi R^2 a^2 \alpha}{2} \frac{d\alpha}{dt}$$

$$= \frac{\pi a^2}{2} \alpha$$

$$Emf \text{ without } AB = a^2 \alpha \left(\frac{\pi}{2} - 1 \right)$$

Self Inductance



No external field

$$B = \frac{\mu_0 i}{2R}$$

$$\phi = B(\pi R^2) = \frac{\mu_0 i}{2R} (\pi R^2)$$

$$\phi_{self} = \frac{\mu_0 i \pi R^2}{2}$$

$i \uparrow, B \uparrow, \phi \uparrow$

{ every loop opposes changes in currents by itself }

↓
self induction

$$\phi \propto i$$

$$\phi = L_i$$

$$L = \frac{\phi}{i}$$

↓
Self inductance

$$= \frac{\text{Tesla m}^2}{\text{amp}} = \text{Henry.}$$

$$L_{ring} = \frac{\phi}{i} = \frac{\mu_0 i \pi R}{2} = \frac{\mu_0 \pi R}{2}$$

$$B = \mu_0 n i$$

$$\phi = \mu_0 n i \pi R^2 \rightarrow \text{Flux through each turn}$$

$$L = \mu_0 n i \pi R^2 \rightarrow \text{inductance through each turn}$$

$$\phi_{total} = (nL)(\mu_0 n i \pi R^2)$$

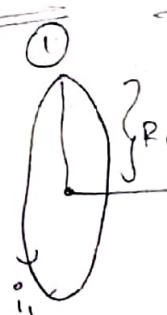
$$\phi_{total} = n^2 \mu_0 L \pi R^2 i$$

$$L_{total} = n^2 \mu_0 L \pi R^2$$

$$L_{\text{solenoid}} = \mu_0 n^2 \pi R^2 L$$

$$\begin{aligned} L &\propto L \\ &\propto R^2 \\ &\propto n^2 \end{aligned}$$

Mutual Inductance



flux th

Find the inductance of solenoid?

ii

mut

(a)

External field

$$= \frac{\mu_0 i}{2R} (\pi R^2)$$

πR

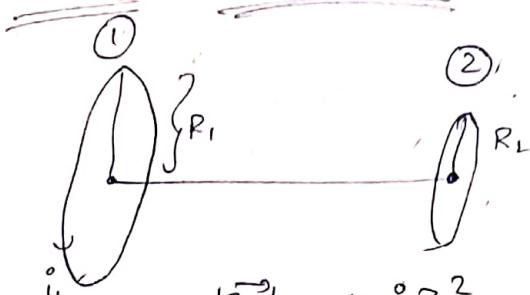
Currents by itself

of solenoid?

form

in turn

Mutual Inductance



$$|\vec{B}_2| = \frac{\mu_0 i_1 R_1^2}{2(R_1^2 + d^2)^{3/2}}$$

$$\text{Flux through second coil } \phi_2 = B_2 (\pi R_2^2) \cos 0^\circ$$

$$\phi_2 = \frac{\mu_0 i_1 R_1^2}{2(R_1^2 + d^2)^{3/2}} (\pi R_2^2)$$

$$\boxed{\phi_2 = \frac{\mu_0 \pi R_1^2 R_2^2 i_1}{2(R_1^2 + d^2)^{3/2}}}$$

$$M_{21} = M_{12} = \frac{\mu_0 \pi R_1^2 R_2^2}{2(R_1^2 + d^2)^{3/2}}$$

$$i_1 \uparrow \quad \phi \uparrow \quad i_2 \neq 0$$

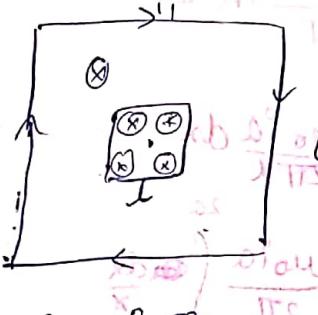
mutual Conductance

$$\phi_2 \propto i_1 \quad (\propto) \quad \phi_1 \propto i_2$$

$$\phi_2 = M_{21} i_1 \quad \phi_1 = M_{12} i_2$$

$$M_{12} = M_{21} = \frac{\phi_2}{\phi_1} \quad (\propto) \quad \frac{\phi_1}{\phi_2}$$

(Q)



$L \ll L$

Find the M between two coil.

$$B = 2 \frac{\sqrt{2} \mu_0 i_1}{\pi L} \cdot \frac{L}{2}$$

$$M = \frac{2 \sqrt{2} \mu_0}{\pi} \frac{d^2}{L}$$

$$\boxed{\phi_2 = \frac{2 \sqrt{2} \mu_0 L^2 i_1}{\pi L} \cdot \frac{d}{2}}$$

Note :- Self Inductance (\propto)
mutual Inductance
depends only on physical
dimensions not on the current

Induced EMF or

Symbol of Inductor

Consider a Inductor



Flux through

Induced emf

$$e = -\frac{d\phi}{dt}$$



Induced emf due to



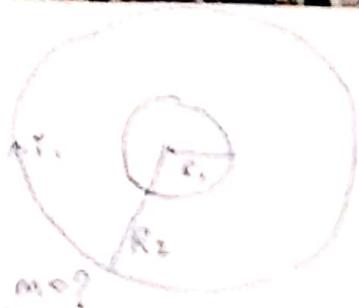
Change in flux

$$\text{d}Φ = \text{d}B A$$

at constant

$$A = A_0 \sin(\omega t)$$

a)



Rings are concentric conductors

$$m = \frac{\mu_0 B \pi R_2^2}{2 R_1}$$

$$m = \frac{\mu_0 \pi}{2} \frac{R_2^2}{R_1}$$

b)



Rings are overlapping but not coplanar
They are kept at 45°

$$\vec{B} \cdot d\vec{s}$$

$$\oint \vec{B} \cdot d\vec{s}$$

$$m = 0$$

c)



$$\oint \vec{B} \cdot d\vec{s} = \frac{\mu_0 A}{2\pi} \ln 2$$

$$\frac{d\Phi}{dt} = \frac{\mu_0 A}{2\pi} \frac{d\theta}{dt}$$

$$\frac{d\Phi}{dt} = \frac{\mu_0 A}{2\pi} \left(\frac{d\theta}{dt} \right)^2$$

$$\Phi = \frac{\mu_0 A}{2\pi} \ln(2)$$

$$m = \frac{\mu_0 A}{2\pi} \ln(2)$$

R_2^2

$\frac{R_2^2}{R_1}$

Induced EMF across Inductor

→ will show Inductance.

Symbol of Inductor →

Consider a Inductor with Inductance L:



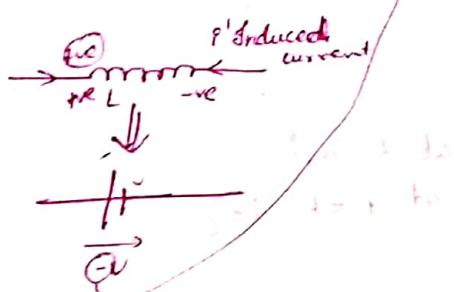
$$\text{Flux through Inductor} = \phi = Li$$

$$\text{Induced emf} e = -\frac{d\phi}{dt}$$

$$e = -\frac{d(Li)}{dt} = -L \frac{di}{dt}$$

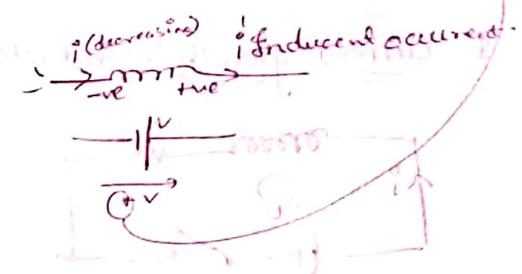
$$\frac{di}{dt} > 0$$

$$\text{Induced emf } e = -L \frac{di}{dt} \text{ is -ve}$$



$$\frac{di}{dt} < 0$$

$$\text{Induced emf } e = -L \frac{di}{dt} \text{ is +ve}$$



Energy stored in Inductor

if from o to i.

at an instant -

$$\text{P.d across inductor} = L \frac{di}{dt}$$

Power delivered by external agent at that instant $P_{ext} = Vi$

$$P_{ext} = \frac{Vi}{i}$$

instantaneous power

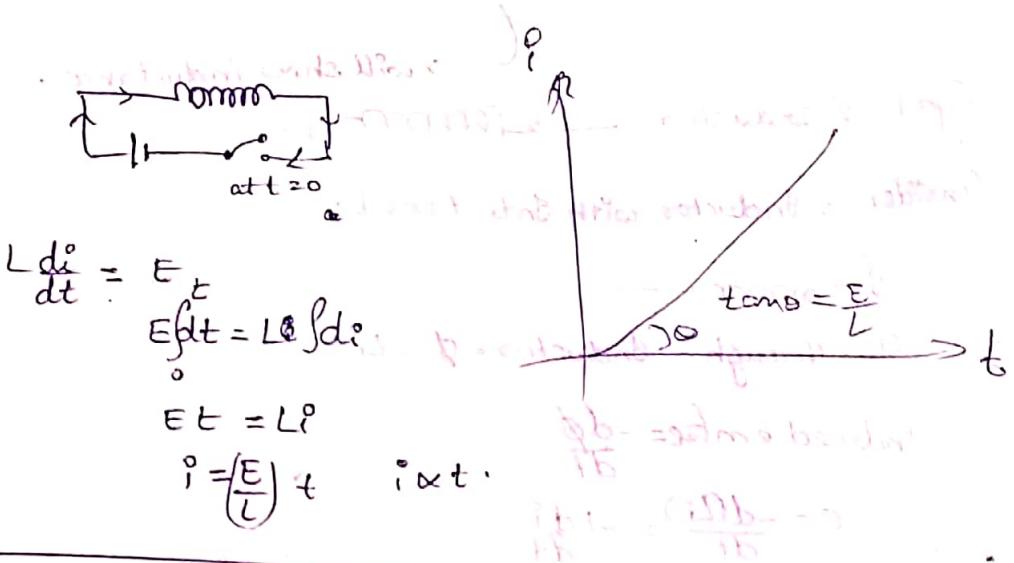
$$P_{ext} = \frac{Vi}{i} = \frac{V}{L} \frac{i}{\frac{di}{dt}} = \frac{V}{L} i \frac{1}{\frac{di}{dt}}$$

$$P_{ext} = \frac{V}{L} i \frac{1}{\frac{di}{dt}}$$

$$W_{ext} = L \left[\frac{i^2}{2} \right]$$

$$W_{ext} = L \frac{i^2}{2} = \frac{1}{2} L i^2$$

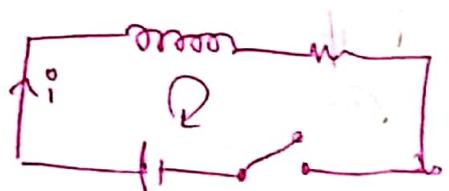
Note:- If inductor alone is connected to battery.



$$L \frac{di}{dt} = E$$
$$E dt = L i d\theta$$
$$E t = L i$$
$$i = \left(\frac{E}{L}\right) t + i_{\infty}$$

LR circuits

I Current growth in inductor



$$\text{at } t=0, i=0$$

$$\text{at } t=t, i=?$$

$$\text{Given } -L \frac{di}{dt} - iR + E = 0$$

try to bring linear $\bullet L \frac{di}{dt} + iR dt = Edt$

$$L di = dt (E - iR)$$

$$\frac{L di}{E - iR} = dt$$

$$L \left[\ln(E - iR) \right] = [t]_0^t$$

$$-\frac{1}{R} L \ln \left(\frac{E - iR}{E - iR_0} \right) = t$$

$$\left[\frac{(E - iR)}{E} \right] = e^{-\frac{t}{LR}}$$

$$\left[\frac{i}{R} \right] = \left[\frac{E}{E} \right] - \left[\frac{E}{E} \right] e^{-\frac{t}{LR}}$$

$$i = \frac{E}{R} (1 - e^{-\frac{Rt}{L}})$$

at $t = 0$

$$i = \frac{E}{R} (1 - 1) = 0$$

\downarrow
acts as insulator

at $t = \infty$

$$i = \frac{E}{R} (1 - 0)$$

$$i_{\max} = \frac{E}{R}$$

acts as conducting wire

Time constant

time taken to increase the current by 63% of maximum value

$$\text{at } t = \frac{L}{R}$$

$$i = \frac{E}{R} (1 - e^{-\frac{Rt}{L}})$$

$$i = i_{\max} (1 - e^{-1})$$

$$= i_{\max} \left(1 - \frac{1}{e}\right)$$

$$= 0.63 i_{\max}$$

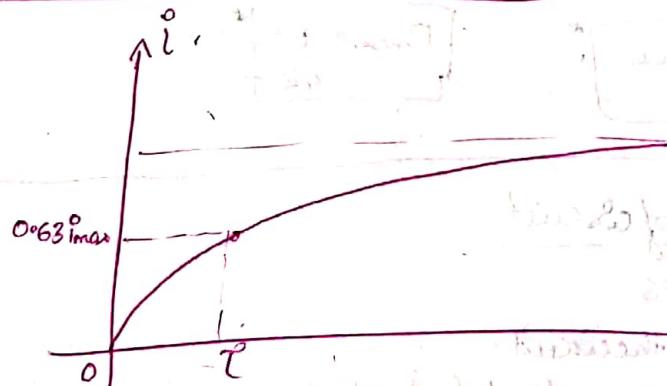
$$t = \frac{L}{R} = \tau$$

'time constant' = τ

$$i = 63\% \text{ of max current}$$

$$\text{finally } i = i_{\max} (1 - e^{-\frac{t}{\tau}})$$

$$\tau = \frac{L}{R}$$

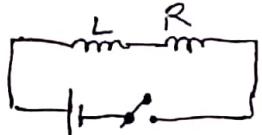


time taken to increase current by 63%

adjusted w.r.t. the resistance

influence of inductance & resistance

1 = τ time constant



Final energy stored in the inductor

$$U_f = \frac{1}{2} L I^2$$

$$U_f = \frac{1}{2} L \left(\frac{E}{R}\right)^2$$

$$U_f = \frac{LE^2}{2R^2}$$

Rate of energy stored in the inductor

$$E = \frac{1}{2} L I^2$$

$$= \frac{1}{2} L \left[\frac{E}{R} \left(1 - e^{-\frac{tR}{L}} \right) \right]^2$$

$$E = \frac{LE^2}{2R^2} \left[1 - e^{-\frac{tR}{L}} \right]^2$$

$$U = \frac{dE}{dt} = \frac{LE^2}{2R} \cdot 2 \left(1 - e^{-\frac{tR}{L}} \right) \cdot e^{-\frac{tR}{L}}$$

$$U = \frac{E^2}{R} \left(1 - e^{-\frac{R}{L}t} \right) \left(e^{-\frac{tR}{L}} \right)$$

at $e^{-\frac{R}{L}t} = \frac{1}{2}$, U is maximum

$$e^{-\frac{R}{L}t} = \frac{1}{2}$$

$$\frac{R}{L}t = \ln 2$$

$$t = \frac{L \ln 2}{R} = T \ln 2$$

$$f(x) = (1-x)x$$

$f(x) \text{ is max at } x = \frac{1}{2}$

$$U_{\max} = \frac{E^2}{R} \left(1 - \frac{1}{2} \right) \left(\frac{1}{2} \right)$$

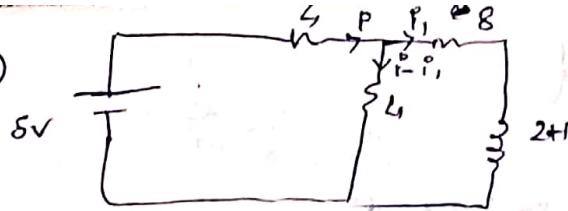
$$U_{\max} = \frac{E^2}{4R}$$

Find the time constant of circuit

- ① Short circuit the batteries
- ② Open the inductor in the circuit.
- ③ Find the net resistance b/w ends of inductor
- ④ Time constant $\tau = \frac{L}{R_{\text{net}}}$

vector

o)



Find the current through
inductor and battery as
a function of time.

$$5 - 4i - 4i + 4i_1 = 0 \quad -8i_1 - 2\frac{di}{dt} + 4i - 4i_1 = 0$$

$$\frac{5+4i_1}{8} = i$$

$$T = \frac{L}{R_{\text{net}}} = \frac{L}{5}$$

$$i_1 = i_{\max}^0 (1 - e^{-\frac{t}{T}})$$

$$-8i_1 - 2\frac{di}{dt} + \frac{5}{2} + i_1 - 4i_1 = 0$$

$$2\frac{di}{dt} = -11i_1 + \frac{5}{2}$$

$$\frac{di}{-22i_1 + 5} = \frac{1}{4T}$$

$$\ln(-22i_1 + 5) = \frac{t}{4T}$$

at $t = \infty$



$$R_{\text{net}} = 4 + \frac{8 \times 4}{8+4}$$

$$R_{\text{net}} = 4 + \frac{8}{3} = \frac{20}{3} \Omega$$

$$i_1 = \frac{5}{20/3} = \frac{3}{4} \text{ amp}$$

$$i_1 = \left(\frac{4}{4+5}\right)i_1 = \frac{4}{12} \left(\frac{3}{4}\right) = \frac{1}{4} \text{ amp}$$

$$i_1 = \frac{1}{4} (1 - e^{-\frac{t}{4T}})$$

Current through inductor.

$$i = \frac{5}{8} + \frac{1}{8} (1 - e^{-\frac{t}{4T}})$$

$$i = \frac{1}{8} \left[6 - e^{-\frac{t}{4T}} \right] \quad \text{current from battery.}$$

Decay of Current

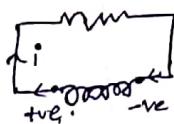
at $t=0, i=i_0$ $-iR - L \frac{di}{dt} = 0$ decreasing current $\frac{di}{dt} < 0$



$$-L \frac{di}{dt} = iR$$

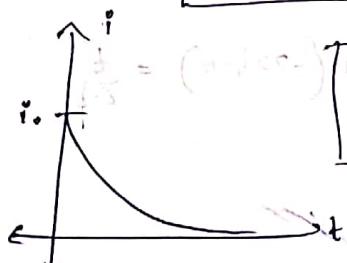
$$\int \frac{di}{i} = -\frac{R dt}{L}$$

at $t=t$



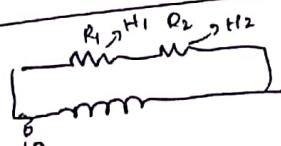
$$\ln\left(\frac{i}{i_0}\right) = -\frac{Rt}{L}$$

$$i = i_0 \times e^{-Rt/L}$$



Total Heat produced in the reston $= \frac{1}{2} L i_0^2$

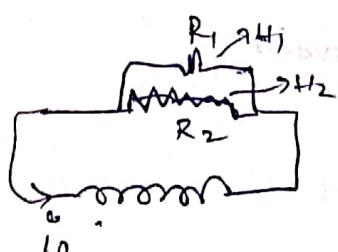
Notes



$$H_1 + H_2 = \frac{1}{2} L i_0^2$$

$$H_1 = \left(\frac{R_1}{R_1 + R_2} \right) \left(\frac{1}{2} L i_0^2 \right)$$

$$H_2 = \left(\frac{R_2}{R_1 + R_2} \right) \left(\frac{1}{2} L i_0^2 \right)$$



$$H_1 + H_2 = \frac{1}{2} L i_0^2$$

$$H_1 = \left(\frac{R_1}{R_1 + R_2} \right) \left(\frac{1}{2} L i_0^2 \right)$$

$$H_2 = \left(\frac{R_2}{R_1 + R_2} \right) \left(\frac{1}{2} L i_0^2 \right)$$



$$\frac{dQ}{dt} = -\left(\frac{1}{LC}\right) Q \Rightarrow \boxed{\frac{dQ}{dt} + \omega^2 Q = 0}$$

$$\omega = \sqrt{\frac{1}{LC}}$$

$$q = Q_0 \sin(\omega t + \phi)$$

$$\text{at } t=0, q=Q_0$$

$$Q_0 = Q_0 \sin(\phi)$$

$$\boxed{Q_0 = A}$$

$$\left. \begin{array}{l} \text{at } t=0, \dot{q}=0 \\ \dot{q} = \frac{dq}{dt} = -Q_0 \omega \cos(\omega t + \phi) \\ \phi = \pi/2 \end{array} \right\}$$

$$\cos \phi = 0$$

$$\boxed{\phi = \pi/2}$$

$$q = Q_0 \sin(\omega t + \pi/2)$$

$$\boxed{q = Q_0 \cos(\omega t)}$$

In the current $i = \frac{dq}{dt}$

$$i = Q_0 \omega \sin \omega t$$

$$i_{\max} = Q_0 \omega \Rightarrow \boxed{i_{\max} = A \omega}$$

Max

$$\frac{(Q_0 \sin \omega t)^2}{2C} = \frac{Q_0^2}{2C} \sin^2 \omega t$$

Max B:

$$\frac{1}{2} U^2 = \frac{1}{2} \cdot Q_0^2 \omega^2 \sin^2 \omega t$$

$$= \frac{1}{2} Q_0^2 \left(\frac{1}{C} \right) \sin^2 \omega t$$

$$= \frac{Q_0^2}{2C} \sin^2 \omega t$$

$$V_{\text{max}} = U_0 \cdot \frac{Q_0^2}{2C}$$

By C.O.Energy.

$$\frac{Q_0^2}{2C} = \frac{(Q_0/3)^2}{2C} + \frac{(2Q_0)^2}{2(2C)} + \frac{1}{2} L i_{max}^2$$

$$\frac{Q_0^2}{2C} - \frac{Q_0^2}{18C} - \frac{4Q_0^2}{36C} = \frac{1}{2} L i_{max}^2$$

$$\frac{10}{36} \frac{Q_0^2}{C} = \frac{1}{2} L i_{max}^2$$

$$\frac{2Q_0^2}{C3L} = i_{max}^2$$

$$i_{max} = Q_0 \sqrt{\frac{2}{3LC}}$$

a) find the charge as a function of time on 2C capacitor.

Ans:

$$Q_0 - \frac{q}{2} - \frac{L \frac{dq}{dt}}{2C} - \frac{q}{2C} = 0$$

$$\frac{Q_0}{C} - \frac{q}{C} - \frac{3}{2} = \frac{L \frac{dq}{dt}}{2C}$$

$$\textcircled{2} \quad \frac{3}{2C} \left(\frac{2Q_0}{3} - q \right) = L \cdot \frac{d^2q}{dt^2}$$

$$\frac{d^2q}{dt^2} = \frac{3}{2CL} \left(\frac{2Q_0}{3} - q \right)$$

$$\frac{2Q_0}{3} - q = x \Rightarrow -\frac{dq}{dt} = \frac{dx}{dt}$$

$$-\frac{dq}{dt} = \frac{dx}{dt^2}$$

$$-\frac{d^2x}{dt^2} = \frac{3}{2LC}(x)$$

$$\frac{d^2x}{dt^2} = \frac{3}{2LC}(-x)$$

$$\omega = \sqrt{\frac{3}{2LC}}$$

$$x = A \sin(\omega t \pm \phi)$$

$$\text{at } t=0, x = \frac{2\theta_0}{3}$$

$$\frac{2\theta_0}{3} = A \sin(\phi)$$

$$\text{at } t=0 \quad i = \frac{dq}{dt} = 0$$

$$\frac{dx}{dt} = Aw \cos(\omega t \pm \phi) = 0$$

$$\omega t + \phi = \pi/2$$

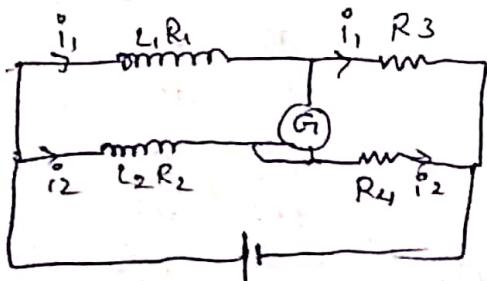
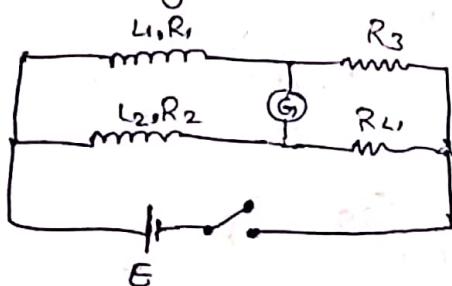
$$0 + \phi = \pi/2 \rightarrow \phi = \pi/2$$

$$x = \frac{2\theta_0}{3} (\cos \omega t)$$

$$q = \frac{2\theta_0}{3} - \frac{2\theta_0}{3} \cos \omega t$$

$$q = \frac{2\theta_0}{3} (1 - \cos \omega t)$$

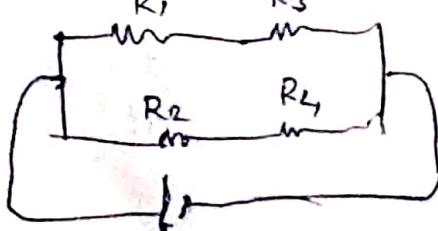
Q8: If switch is closed, find the condn for the reading of galvanometer is always zero?



At $t=\infty$, current in galvanometer is zero.

$$\Rightarrow \frac{R_1}{R_2} = \frac{R_3}{R_4}$$

\Rightarrow



$$+ L_1 \frac{di_1}{dt} + \dots$$

$$L_1 \frac{di_1}{dt} +$$

$$L_1 \frac{di_1}{dt}$$

$$\frac{di_1}{dt} (L_1)$$

at $t=0$

$$\frac{di_1}{dt}$$

a)

$$+ L_1 \frac{d\overset{\circ}{i}_1}{dt} + \overset{\circ}{i}_1 R_1 = + L_2 \frac{d\overset{\circ}{i}_2}{dt} + \overset{\circ}{i}_2 R_2$$

$$L_1 \frac{d\overset{\circ}{i}_1}{dt} + \overset{\circ}{i}_1 R_1 = L_2 \frac{d\overset{\circ}{i}_2}{dt} + \overset{\circ}{i}_2 R_2 \rightarrow ①$$

$$\Leftrightarrow L_1 \frac{d\overset{\circ}{i}_1}{dt} + \overset{\circ}{i}_1 R_1 = L_2 \frac{R_3}{R_4} \frac{d\overset{\circ}{i}_1}{dt} + \overset{\circ}{i}_1 \frac{R_2 R_3}{R_4}$$

$$\overset{\circ}{i}_1 R_3 = \overset{\circ}{i}_2 R_4$$

$$\frac{d\overset{\circ}{i}_1}{dt} R_3 = \frac{d\overset{\circ}{i}_2}{dt} R_4$$

$$\boxed{\frac{d\overset{\circ}{i}_1}{dt} \left(L_1 - L_2 \frac{R_3}{R_4} \right) = \overset{\circ}{i}_1 \left(\frac{R_2 R_3}{R_4} - R_1 \right)}$$

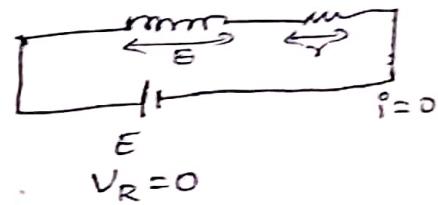
$$\text{at } t=0 \Rightarrow \overset{\circ}{i}_1 = 0$$

$$\frac{d\overset{\circ}{i}_1}{dt} \left(L_1 - L_2 \frac{R_3}{R_4} \right) = 0$$

↓
0

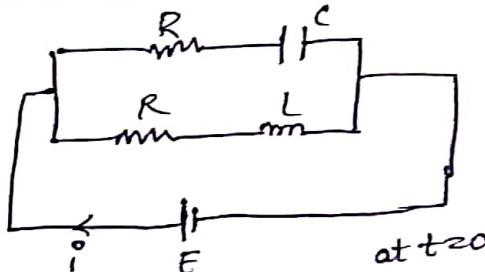
$$L_1 - L_2 \frac{R_3}{R_4} = 0$$

$$\boxed{\frac{L_1}{L_2} = \frac{R_3}{R_4}}$$



$$\begin{aligned} L \frac{di}{dt} &= E \\ \frac{di}{dt} &= \frac{E}{L} \neq 0 \end{aligned}$$

a)



Find the current from battery as a function of time.

$$\text{take } R = \sqrt{LC}$$

$$q = CE \left(1 - e^{-\frac{t}{RC}} \right)$$

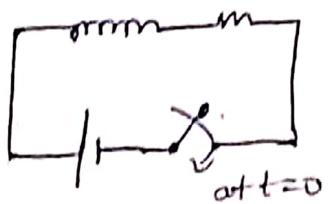
$$\overset{\circ}{i}_1 = \frac{dq}{dt} = CE e^{-\frac{t}{RC}} \cdot \frac{1}{RC} \Rightarrow \overset{\circ}{i}_1 = \frac{E}{R} e^{-\frac{t}{RC}}$$

$$\overset{\circ}{i}_2 = \frac{E}{R} \left(1 - e^{-\frac{Rt}{L}} \right)$$

$$\overset{\circ}{i} = \overset{\circ}{i}_1 + \overset{\circ}{i}_2 = \frac{E}{R} \left(1 - e^{-\frac{t}{RC}} \right) + \frac{E}{R} \left(1 - e^{\frac{Rt}{L}} \right)$$

$$\overset{\circ}{i} = \frac{E}{R}$$

Q) Find the heat released in the circuit in one time constant



$$H = \int i^2 R dt$$

$$H = \int \left(\frac{E}{R} \left(1 - e^{-\frac{Rt}{L}} \right) \right)^2 \cdot R dt$$

$$H = \frac{E^2}{R} \int \left(1 - e^{-\frac{Rt}{L}} \right)^2 dt$$

$$H = \frac{E^2}{R} \int \left[1 + e^{-\frac{2Rt}{L}} - 2e^{-\frac{Rt}{L}} \right] dt$$

$$H = \frac{E^2}{R} \left[t + \frac{e^{-\frac{2Rt}{L}}}{-\frac{2R}{L}} - \frac{2e^{-\frac{Rt}{L}}}{-\frac{R}{L}} \right]_0^\tau$$

$$H = \frac{E^2}{R} \left[\tau - \frac{L}{2R} (e^{-2} - 1) + \frac{2L}{R} (e^{-1} - 1) \right]$$