```
# import numpy as np
         # from numpy import asarray
         # from keras.models import Sequential
         # from keras.layers import Conv2D
         \# data = [[0, 0, 0, 1, 1, 0, 0, 0],
         # [0, 0, 0, 1, 1, 0, 0, 0],
         # [0, 0, 0, 1, 1, 0, 0, 0],
         # [0, 0, 0, 1, 1, 0, 0, 0],
         # [0, 0, 0, 1, 1, 0, 0, 0],
         # [0, 0, 0, 1, 1, 0, 0, 0],
         # [0, 0, 0, 1, 1, 0, 0, 0],
         # [0, 0, 0, 1, 1, 0, 0, 0]]
         # data = asarray(data)
         \# data = data.reshape(1, 8, 8, 1)
In [82]:
         import numpy as np
         from keras.models import Sequential
         from keras.layers import Conv2D, Activation, AveragePooling2D, MaxPooling2D, GlobalAvera
         # Define input data
         data = np.array([[0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0]])
         data = data.reshape(1, 8, 8, 1)
         # Create model
         model = Sequential()
         # Add first convolutional layer
         model.add(Conv2D(32, (3, 3), padding='same', input_shape=(8, 8, 1)))
         model.add(Activation('relu'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
         # Add second convolutional layer
         model.add(Conv2D(64, (3, 3), padding='same'))
         model.add(Activation('relu'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
         # Flatten the feature maps
         model.add(Flatten())
         model.add(Dense(128))
         model.add(Activation('relu'))
         model.add(Dense(1))
         model.add(Activation('relu'))
         model.compile(loss='binary_crossentropy', optimizer='adam', metrics=['accuracy'])
         model.summary()
```

In [69]: # # define input data

```
loss, accuracy = model.evaluate(data, np.array([1]), verbose=0)
        print("Accuracy:", accuracy)
       Model: "sequential_55"
        Layer (type)
                                  Output Shape
                                                           Param #
        ______
        conv2d_85 (Conv2D)
                                  (None, 8, 8, 32)
                                                           320
        activation_32 (Activation) (None, 8, 8, 32)
        max_pooling2d_49 (MaxPoolin (None, 4, 4, 32)
        g2D)
        conv2d_86 (Conv2D)
                                  (None, 4, 4, 64)
                                                           18496
        activation_33 (Activation) (None, 4, 4, 64)
        max_pooling2d_50 (MaxPoolin (None, 2, 2, 64)
        g2D)
                                                           0
        flatten_9 (Flatten)
                                  (None, 256)
        dense_2 (Dense)
                                  (None, 128)
                                                           32896
        activation_34 (Activation) (None, 128)
        dense_3 (Dense)
                                   (None, 1)
                                                           129
        activation_35 (Activation) (None, 1)
        ______
       Total params: 51,841
       Trainable params: 51,841
       Non-trainable params: 0
       Accuracy: 0.0
In [ ]: # define a vertical line detector
        detector = [[[[0]],[[1]],[[0]]],
                   [[[0]],[[1]],[[0]]],
                   [[[0]],[[1]],[[0]]]]
        weights = [asarray(detector), asarray([0.0])]
        # store the weights in the model
        model.set_weights(weights)
        # confirm they were stored
        print(model.get_weights())
In [ ]: # apply filter to input data
        yhat = model.predict(data)
In [ ]: for r in range(yhat.shape[1]):
        # print each column in the row
         print([yhat[0,r,c,0] for c in range(yhat.shape[2])])
In [ ]: # example of calculation 2d convolutions
        from numpy import asarray
        from keras.models import Sequential
        from keras.layers import Conv2D
        # define input data
        data = [[0, 0, 0, 1, 1, 0, 0, 0],
                          [0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0],
                           [0, 0, 0, 1, 1, 0, 0, 0],
```

```
[0, 0, 0, 1, 1, 0, 0, 0],
                             [0, 0, 0, 1, 1, 0, 0, 0],
                             [0, 0, 0, 1, 1, 0, 0, 0]]
        data = asarray(data)
        data = data.reshape(1, 8, 8, 1)
        # create model
        model = Sequential()
        model.add(Conv2D(1, (3,3), input\_shape=(8, 8, 1)))
        # define a vertical line detector
        detector = [[[[0]],[[1]],[[0]]],
                     [[[0]],[[1]],[[0]]],
                     [[[0]],[[1]],[[0]]]]
        weights = [asarray(detector), asarray([0.0])]
        # store the weights in the model
        model.set_weights(weights)
        # confirm they were stored
        print(model.get_weights())
        # apply filter to input data
        yhat = model.predict(data)
        for r in range(yhat.shape[1]):
                # print each column in the row
                print([yhat[0,r,c,0] for c in range(yhat.shape[2])])
In [ ]: from numpy import asarray
        print(asarray([1, 1, 1]).dot(asarray([1, 1, 1])))
In [ ]: | from numpy import asarray
        from numpy import tensordot
        m1 = asarray([[0, 1, 0],
            [0, 1, 0],
            [0, 1, 0]])
        m2 = asarray([[0, 1, 1],
           [0, 1, 1],
            [0, 1, 1]])
        print(tensordot(m1, m2))
```