

# Primer on Probability and Statistics

Goal: Quantitative characterization of uncertainty associated with the occurrence of random events. (UQ: uncertainty quantification)

- Frequentist : UQ based on long sample frequencies (statistics)
- Bayesian : UQ based on the rules of probability theory (Thomas Bayes)  
~ 1700

• Discrete random variables : (events that take discrete values)

$p(A)$  denotes the probability that the event  $A$  is true.

By definition  $0 \leq p(A) \leq 1$ , i.e.  $\begin{cases} p(A)=0 \Rightarrow \text{the event will definitely not happen} \\ p(A)=1 \Rightarrow \text{this event will definitely happen.} \end{cases}$

$\bar{A} := \{\text{not } A\}$

$$p(\bar{A}) = 1 - p(A)$$

A discrete random variable  $X$  is an event taking values from a discrete set  $\mathcal{X}$ .

e.g. coin toss :  $X = \{\text{outcome of the coin toss}\}$   $\mathcal{X} = \{\text{heads, tails}\}$

$$p(x) = p(X=\text{heads}) = \frac{1}{2} \text{ if the coin is fair.}$$

We denote the probability of a discrete r.v.  $X=x$  as

$p(X=x)$  or simply as  $p(x)$ .

Properties :  $\begin{cases} 0 \leq p(x) \leq 1 \\ \sum_{x \in \mathcal{X}} p(x) = 1 \\ p(\{\emptyset\}) = 0 \end{cases}$

then  $p(x)$  is called the probability mass function (p.m.f) of the discrete random variable  $X$ .

Fundamental rules of probability :



• Union :  $P(A \cup B) = P(A) + P(B) - P(A \cap B)$   $\geq 0$   
 (A or B)  
 $\Rightarrow$  union  
 $\Rightarrow$  bound  $P(A \cup B) \leq P(A) + P(B)$

• Joint :  $P(A, B) = P(A \cap B) = \underbrace{P(A|B)}_{\text{joint}} \underbrace{P(B)}_{\text{marginal}}$  Product rule  
 (A and B)  
 $= \dots = \text{conditional} \times \text{marginal}$

This directly follows from the definition of conditional probability:

$$P(A|B) := \frac{P(A, B)}{P(B)}, \text{ given that } P(B) > 0$$

Given a joint distribution  $P(A, B)$ , we can define a marginal distribution as :

$$\begin{cases} P(A) = \sum_{b \in \mathcal{B}} P(A, B) = \sum_{b \in \mathcal{B}} P(A|B=b) P(B=b) = \sum_{b \in \mathcal{B}} P(A|B=b) P(B=b) \\ P(B) = \sum_{a \in \mathcal{A}} P(A, B) = \sum_{a \in \mathcal{A}} P(B|A=a) P(A=a) = \sum_{a \in \mathcal{A}} P(B|A=a) P(A=a) \end{cases}$$

This is the sum rule or the rule of total probability.

• Bayes rule : It is a product of combining the definition of conditional probability with the product and sum rules :

$$P(A=a|B=b) = \frac{P(A=a, B=b)}{P(B=b)} = \frac{P(B=b|A=a) P(A=a)}{\sum_{a \in \mathcal{A}} P(B=b|A=a) P(A=a)}$$

Some common discrete distributions :

– Binomial distribution :  $X \sim \text{Bin}(n, \theta)$

$n$  : # of trials

$\theta$  : probability of our desired outcome/event to occur

$X$  : # of successes in  $n$  trials

1. # of heads in n trials

$$P(X=k) = \text{Bin}(k|n, \theta) = \binom{n}{k} \theta^k (1-\theta)^{n-k}, \text{ where}$$

$$\downarrow \text{ pmf} \quad \binom{n}{k} := \frac{n!}{(n-k)!k!}, \quad \text{mean: } E[X] = n\theta$$

$$\text{variance: } \text{Var}[X] = n\theta(1-\theta)$$

⊛ This can be generalized to the so-called multinomial distribution for cases involving non-binary outcome, e.g. toss of die.

— Bernoulli distribution: Suppose we only have one trial.

Then  $X \in \{0, 1\}$  <sup>tails</sup>  $\rightarrow$  <sup>heads</sup> and if  $\theta$  denotes the probability of our desired outcome then the discrete r.v.  $X$  is a Bernoulli random variable:

$$X \sim \text{Ber}(\theta), \quad p(X=1) = \text{Ber}(x|\theta) = \theta^{\mathbb{1}_{\{x=1\}}} (1-\theta)^{\mathbb{1}_{\{x=0\}}}$$

where  $\mathbb{1}$  is the indicator function:  $\mathbb{1}_{\{x=1\}} = \begin{cases} 1, & \text{if } x=1 \\ 0, & \text{if } x=0 \end{cases}$

In other words:  $p(X=1) = \text{Ber}(x|\theta) = \begin{cases} \theta, & \text{if } x=1 \\ 1-\theta, & \text{if } x=0 \end{cases}$

⊛ This is a special case of the Binomial distribution with  $n=1$ .

⊛ Can be generalized to cases with non-binary outcomes.

↳ multi-nailli distribution.

— Poisson distribution: models counts

Event/outcome space  $X \in \{0, 1, 2, 3, \dots\}$

We say that a discrete random variable  $X$  has a Poisson distribution with parameter  $\lambda > 0$ :

$$X \sim \text{Poi}(\lambda), \quad \text{pmf: } p(X=x) = \text{Poi}(x|\lambda) = e^{-\lambda} \frac{\lambda^x}{x!}$$

⊛ This is usually used to model counts of rare events.

Independence:

- Two random variables  $X, Y$  are unconditionally independent if:

$$\underbrace{p(X, Y)}_{\text{joint}} = p(X)p(Y) \quad , \quad X \perp Y$$

= product of the marginals

- Two random variables  $X, Y$  are conditionally independent given  $Z$ :

$$p(X, Y | Z) = p(X | Z) p(Y | Z) \quad , \quad X \perp Y | Z$$

### Moments of discrete random variables:

Goal: Quantify the statistical properties of a random variable or its associated probability distribution.

Mean:  $\mu = E[X] := \sum_{x \in \mathcal{X}} x p(x) \quad , \quad \boxed{p(x) : \text{pmf}}$

(First moment / first-order statistic)

Variance:  $\text{Var}[X] = \sum_{x \in \mathcal{X}} (x - \mu)^2 p(x)$

(Second-moment)  
Second-order statistic

$\vdots$

$n$ -th moment:  $\sum_{x \in \mathcal{X}} (x - \mu)^n p(x)$

$n$ -th-order statistic