

## Continuous random variables

- Events that take continuous values.

Define the events :  $A := \{X \leq a\}$ ,  $B = \{X \leq b\}$ ,  $W = \{a < X \leq b\}$

By construction, observe :  $B = A \cup W$ ,  $A \cap W = \{\emptyset\}$

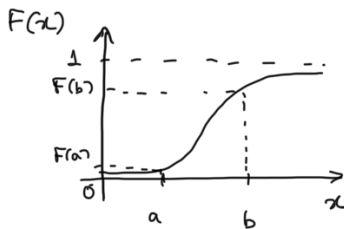
$$p(B) = p(A) + p(W) - \overset{0}{p(A \cap W)} \Rightarrow \boxed{p(W) = p(B) - p(A)} \quad (1)$$

Now let us define the function  $F(x) := p(X \leq x)$

↳ cumulative distribution function of  
the continuous random variable  $X$ .  
(cdf)

By definition,

$F$  is a monotonically non-decreasing function :



- $0 \leq F(x) \leq 1$

- $\lim_{x \rightarrow -\infty} F(x) = 0$

- $\lim_{x \rightarrow +\infty} F(x) = 1$

- If  $x \leq y \Rightarrow F(x) \leq F(y)$   
(monotonically non-decreasing)

$$(1) \Rightarrow p(W) = p(a < X \leq b) = F(b) - F(a)$$

If the cdf  $F(x)$  is also differentiable (not always the case!), then

define  $f(x) := \frac{d}{dx} F(x)$

↳ probability density function of the continuous random variable  $X$ . (pdf)

By definition,  $p(a < X \leq b) = \int_a^b f(x) dx$

Notice that  $f(x) > 0$ , but it is possible that  $f(x) > 1$ , for any given continuous random variable  $X$ , as long as the density integrates to 1, i.e.:

Properties of a p.d.f :

$$\begin{cases} \int_{-\infty}^{+\infty} f(x) dx = 1 \\ f(x) \geq 0 \\ \int_{x \in X} f(x) dx = p(x \in X) \end{cases}$$

Recap :

1. A random variable  $X$  is an event that can take possible different values  $x \in X$   
 $\hookrightarrow X$ : event space, i.e. the collection of all possible outcomes.
2. A discrete/continuous random variable can be characterized by its probability mass/density function.
3. Often we will encounter two scenarios:

i.) Given some realization  $x$ , what  $p(x)$ ?

ii.) Given some  $p(x)$ , generate events  $x$  that are distributed according to  $p(x)$ ? [Sampling problem]

from now on  
 $\circledast$   $p(x)$  denotes a pdf.

• Let  $X$  be a continuous random variable with a pdf  $p(x)$

- Mean / Expected value of  $X$ :  $\mathbb{E}[X] = \int_{x \sim p(x)} x p(x) dx = \mu$   
 (First order moment/statistic of  $X$ )

-  $\text{Var}[X] := \mathbb{E}[(X - \mu)^2] = \int_{x \sim p(x)} (x - \mu)^2 p(x) dx$   
 $\vdots$   
 2<sup>nd</sup>-order moment

-  $n$ -th order moment/statistic:  $\mathbb{E}[(X - \mu)^n] = \int_{x \sim p(x)} (x - \mu)^n p(x) dx$

Basic rules of probability

	Discrete r.v.s	Continuous r.v.s
$p(x)$	pmf	pdf

sum rule	$p(x) = \sum_{y \in Y} p(x, y)$	$p(x) = \int_{y \in Y} p(x, y) dy$
product rule	$p(x, y) = p(x y) p(y)$	$p(x, y) = p(x y) p(y)$
Bayes	$p(x y) = \frac{p(y x) p(x)}{\underbrace{\sum_{x \in X} p(y x) p(x)}_{p(y)}}$	$p(x y) = \frac{p(y x) p(x)}{\underbrace{\int_{x \in X} p(y x) p(x) dx}_{p(y)}}$

• Properties of the expectation of a random variable :

1.  $E[a] = a$ , for any constant  $a$ .
2.  $E[a f(x)] = a E[f(x)]$ ,  $\int_{x \in X} a f(x) p(x) dx = a \int_{x \in X} f(x) p(x) dx$
3.  $E[a f(x) + b g(x)] = a E[f(x)] + b E[g(x)]$ , Linear.

• Properties of variance :

$$\sigma^2 := \text{Var}[X] = E[(X - \mu)^2] = \int_{x \in X} (x - \mu)^2 p(x) dx \geq 0$$

$\text{Var}[X] = E[X^2] - E[X]^2$ , this identity holds since:

$$\underbrace{\int_{x \in X} (x - \mu)^2 p(x) dx}_{\text{Var}[X]} = \underbrace{\int_{x \in X} x^2 p(x) dx}_{E[X^2]} + \underbrace{\mu^2 \int_{x \in X} p(x) dx}_{\mu^2} - \underbrace{2\mu \int_{x \in X} x p(x) dx}_{2\mu^2} \quad \begin{matrix} \nearrow 1 \\ \text{E}[X] := \mu \end{matrix}$$

$$\Rightarrow \text{Var}[X] = E[X^2] - E[X]^2$$

• Standard deviation :  $\sigma := \text{Std}[X] = \sqrt{\text{Var}[X]} = \sqrt{\sigma^2}$

\* Statistical independence :

Two random variables  $x, y$  are statistically independent if :

$$p(x, y) = p(x)p(y)$$

Then:

- $p(y|x) = p(y)$
- $p(x|y) = p(x)$
- $\text{Var}[X+Y] = \text{Var}[X] + \text{Var}[Y]$  (this is not true if  $X, Y$  are not independent)

In fact, if  $X, Y$  are not independent:

$$\text{Var}[X+Y] = \text{Var}[X] + \text{Var}[Y] + \text{Cov}[X, Y] + \text{Cov}[Y, X]$$

... next time we continue to define the concepts of covariance / correla