

Approximation of functions (from data)

1.) Local approximation via Taylor series:

Taylor polynomial of degree n , $f: \mathbb{R} \rightarrow \mathbb{R}$:

$$\begin{aligned} T_n(x) &= \sum_{k=0}^n \frac{f^{(k)}(x_0)}{k!} (x-x_0)^k \\ &= \underline{f(x_0)} + \frac{\overset{\downarrow}{f'(x_0)}}{1!} (x-x_0) + \frac{\overset{\downarrow}{f''(x_0)}}{2!} (x-x_0)^2 + \frac{\overset{\downarrow}{f'''(x_0)}}{3!} (x-x_0)^3 + \dots \end{aligned}$$

- $T_n(x)$ is a polynomial, but the function f that it approximates need not be one.

If f is indeed a polynomial, then $T_n(x)$ is an exact representation of f , if the degree of f is $k \leq n$.

But, this assumes that we can evaluate $f(x_0)$, and all its n derivatives at x_0 .

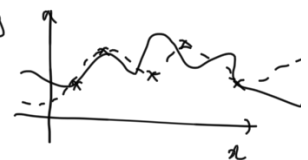
In practice, usually all we have is a set scattered observations:

$$\mathcal{D} := \{x_i, y_i\}, \quad i=1, \dots, N, \quad x_i \in \mathbb{R}^d, \quad y_i \in \mathbb{R}^m$$

we want to "learn" the function $f: \mathbb{R}^d \rightarrow \mathbb{R}^m$ that generated the observed data, i.e. $y_i = \underline{f(x_i)}$
 \hookrightarrow unknown.

In classical scientific computing it is common to seek "parametric" approximations of the form:

$$\frac{f}{\theta}(x) = \sum_{k=1}^n w_k \phi_k(x)$$



where $\theta := \{w_1, \dots, w_n\}$, and $\phi_k(x)$ are known
G unknown weights / parameters features / basis functions
... encodes only

Key questions:

with desirable properties (prior info ω may have)

- 1.) How do we choose $\phi_k(x)$?
- 2.) How do we determine δ ?
- 3.) How to assess the quality of our prediction?

2.) Lagrange interpolation:

Assume: $f(x) = \sum_{k=1}^n W_k \phi_k(x)$

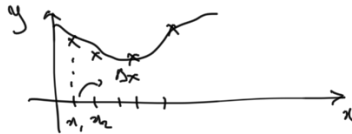
• $W_k := y_k \rightarrow$ k -th observed output (corr. to input)

• $\phi_k(x) = \prod_{\substack{0 \leq k \leq n \\ k \neq j}} \frac{x - x_j}{x_k - x_j}$

One can theoretically prove that the maximum approximation error

$$\max_x |E_n f(x)| \leq \frac{\max_x |f^{(n+1)}(x)|}{4(n+1)} h^{n+1}, \quad h := \Delta x = x_i - x_{i-1}$$

⊕ Here we have assumed that the ^{input} data x_i live on a regular grid



⊕ Runge's phenomenon can be avoided (mitigated) if a suitable distribution on input points (nodes) is used!

In a generic interval $[a, b]$:

• $x_i = \frac{a+b}{2} + \frac{b-a}{2} \hat{x}_i, \quad \hat{x}_i = -\cos\left(\frac{\pi i}{n}\right), \quad i=0, \dots, n$

↳ Chebyshev - Gauss - Lobatto nodes

• $x_i = \frac{a+b}{2} - \frac{b-a}{2} \cos\left(\frac{(2i+1)\pi}{2(n+1)}\right), \quad i=0, \dots, n$

↳ Chebyshev - Gauss nodes

3.) Interpolation with trigonometric polynomials (Fourier features):

[for approximating periodic functions $f: [0, 2\pi] \rightarrow \mathbb{R}$] . FFT

on a regular grid

Assume: $f(x) = \sum_{k=-m}^m w_k \phi_k(x)$, $\left\{ \begin{array}{l} \cdot w_k = \frac{1}{n+1} \sum_{j=0}^n f(x_j) e^{-ikx_j} \\ \cdot \phi_k(x) = e^{ikx} \end{array} \right.$

+ Exponential convergence for smooth periodic ↪ Fourier feature

General comments:

In all case the model parameters / weights can be identified via optimization by minimizing the mean-square prediction error:

$$\theta^* = \underset{\theta}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n [y_i - f_{\theta}(x_i)]^2 \quad \left\{ \begin{array}{l} \text{this is known as the} \\ \text{"least-squares" method.} \end{array} \right.$$

- Pros: + rigorous theory, well-understood behavior, error/convergence estimates.
- Cons: - rigid prior assumptions, scalability to high-dimensions, data corrupted by noise, outliers, etc.