Generative Adversatial Networks

$$P_g(\pi) = \int p(\pi, z) dz = \int \underbrace{p(\pi|z)}_{\mathcal{N}(0, \mathbf{I})} p(z) dz$$

$$\mathcal{N}(\pi|y_g(z)|\xi_g(a)) \stackrel{\mathcal{N}(0, \mathbf{I})}{\longrightarrow} p(z|\pi) \approx Q_g(z)$$

$$L(\theta, \phi) = -\log p_{\theta}(x) \leq |K|L \left[q_{\phi}(z|x) || p(z) \right] - |E| \left[\log p_{\theta}(x|z) \right]$$

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$$\theta^*, \varphi^* = \underset{\theta, \varphi}{\operatorname{arguin}} ||\mathsf{K}|| [q(x) || p_{\theta}(x)] = ||\mathsf{E}|| [\log \frac{q(x)}{p_{\theta}(x)}]|$$

Density-ratio estimation:

$$p(x|y) = \frac{p(y|x)p(x)}{p(y)}$$

$$\Gamma(x) = \frac{\rho(x)}{\rho(x)} - \frac{\rho(x|y=+1)}{\rho(x|y=-1)} = \frac{\rho(y=+1|x)}{\rho(y=+1|x)} \approx \frac{P(y=+1|x)}{P(y=+1|x)} \approx \frac{\sum_{y=-1}^{6} (x-y)}{1-\rho(y=+1|x)} \approx \frac{\sum_{y=-1}^{6} (x-y)}{1-\rho(y=+1|x)}$$

GANS:

Goal is to construct a model for po(x).

$$G_{\mathfrak{g}}(z) = \chi$$
, $Z \sim P(z)$, $Z \in \mathbb{R}^{q}$, $\chi \in \mathbb{R}^{d}$
 $G_{\mathfrak{g}}: \mathbb{R}^{q} \longrightarrow \mathbb{R}^{d}$, $\chi \sim P_{\mathfrak{g}}(\chi)$

(We want to train this generative mapping such that the distribution of the close as possible to q(x) (compirical dist. of the observed date

Unlike MLE approaches, here we introduce a discriminator $D_{\varphi}:\mathbb{R}^d \to [0,L] \quad , \quad D_{\varphi}(\pi)$

Training:

$$\theta^*, \varphi^* = \min_{\theta \in \mathcal{A}} \max_{\theta \in \mathcal{A}} \mathbb{E} \left[\log D_{\varphi}(x) \right] + \mathbb{E} \left[1 - \log D_{\varphi}(G_{\theta}(z)) \right]$$
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Algorithm :

, P A >

~ for the tree

Souple
$$Z_1, ..., Z_m \sim P(Z)$$

Souple $X_1, ..., X_m \sim Q(X)$

$$\varphi_{n+1} = \varphi_n + \eta \nabla_{\varphi} \left\{ \frac{1}{m} \sum_{i=1}^m \log(D_{\varphi}(x_i)) + \log[1 - D_{\varphi}(G_{\varphi}(X_i))] + \log[1 - D_{\varphi}(G_{\varphi}(X_i))] \right\}$$

while ϑ is tept fixed. binary cross-shrops

For
$$\widehat{\mathcal{T}}$$
 Steps do:

$$\frac{\int_{\mathcal{S}^{m}} \int_{\mathcal{T}^{m}} \int$$

while q is kept fixed.

Remarks:

1.) For Go(2) fixed, the optimal discriminator is:

$$\int_{\rho}^{*} (x) = \frac{q(x)}{q(x) + p_{\theta}(x)}$$

$$J(\theta) = \max_{\theta} L(\theta, \theta) = \mathbb{E} \left[\log \frac{q(x)}{q(x) + p(x)} \right] + \mathbb{E} \left[\log \frac{p(x)}{q(x)} \right]$$

The global minimum of
$$J(\theta)$$
 can be achieved iff $p_{\theta}(x) = \int J(\theta^{+}) = -\log 4$

[Goodfellow et al 20]

J(8) can be re-written as:

2.) If $G_{\theta}(z)$ and $D_{\theta}(x)$ have enough capacity, and at each step of the training algorithm $D_{\theta}(x)$ is allowed to reach its optimum, and $P_{\theta}(x)$ is updated to improve the following criterion:

then poors - q(x).