

8 Puzzle problem using DFS

Algorithm:

Step 1 start:

Step 2. Assign initial state and goal states:

$$i.s = \begin{bmatrix} [1, 2, 3], \\ [4, 0, 5], \\ [7, 8, 6] \end{bmatrix},$$

$$g.s = \begin{bmatrix} [1, 2, 3], \\ [4, 5, 6], \\ [7, 8, 0] \end{bmatrix}.$$

Step 3: Calc - manhattan distance

initial-pos = x_1, y_1 ,

goal-pos = x_2, y_2

for i in range(3):

for j in range(3):

tile = self.state[i][j]

if tile \neq 0:

total-dist = $(x_2 - x_1) + (y_2 - y_1)$

step 4: get possible moves.

swap up, down, left, right

first find the position of empty space
and return the position.

for dx, dy in directions:

$new_x, new_y = empty_x + dx, empty_y + dy$
if $0 \leq new_x < 3$ and $0 \leq new_y < 3$:

return moves.

Steps: dfs - with - manhattan function.

Implement DFS approach using a stack.

while stack:

node = stack.pop()

if node.state == goal - state:

return construct - solution (node)

visited.add (tuple (map (tuple, node.state)))

return None

step 6

Repeat the find-empty-space function until the goal state is reached.

step 7

Construct solution function.

Backtrack from the goal node to the start node

~~Proceed~~

Code:

class Node :

```
def __init__(self, state, parent = None,
              move = None, depth = 0):
```

```
    self.state = state
```

```
    self.parent = parent
```

```
    self.move = move
```

```
    self.depth = depth
```

```
    self.manhattan-distance = self.calculate-
    m-dist()
```

```
def cal-man-dist(self):
    total-dist = 0
```

```
    go_pos = { 1: (0,0), 2: (0,1), 3: (0,2),
               5: (1,0), 8: (1,1), 6: (1,2),
               0: (2,0), 7: (2,1), 4: (2,2)
            }
```



```

for i in range(3):
    for j in range(3):
        dist = self.s[i][j]
        if dist != 0:
            x2, y2 = g[t]
            t_dist += abs(x2 - i) + abs(y2 - j)
    return t_dist

```

```

def is sol dfs_with_man(initial_st, g_st):

```

```

    stack = [N(in_st)]
    visited = set()

```

```

    while stack:
        node = stack.pop()

```

```

        if node.state == goal_state:
            return const_sol(node)

```

```

        visited.add(tuple(map(tuple, node.state)))

```

```

        for new_s, move in g_p_m(node.state):
            if tuple(map(tuple, new_s)) not in visited:

```

```

                new_node = Node(n_st, parent = n, move = move)

```

```

                if new_node.manhattan <= node.manhattan:
                    stack.append(new_node)
            return None

```

```
def find - empty space(s)
```

```
    for i in range(3):
        for j in range(3):
            if s[i][j] == 0:
                return i, j
```

```
    return None
```

```
def construct - sol" (n):
```

```
    path = []
```

```
    while node.parent is not None:
```

```
        path.append(n)
```

```
        node = node.parent
```

```
    path.reverse()
```

```
    for step in path:
```

```
        print - puzzle (step.state)
```

```
        print()
```

output:

solution found!!

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