

## Module 4.8: Backpropagation: Pseudo code

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$$\nabla_{W_k} \mathcal{L}(\theta), \nabla_{\mathbf{b}_k} \mathcal{L}(\theta) \quad (\text{gradient w.r.t. weights and biases, } 1 \leq k \leq L)$$

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We can now write the full learning algorithm

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**Algorithm:** `gradient_descent()`

---

$t \leftarrow 0$ ;

$max\_iterations \leftarrow 1000$ ;

*Initialize*  $\theta_0 = [W_1^0, \dots, W_L^0, b_1^0, \dots, b_L^0]$ ;

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**end**

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**while**  $t++ < max\_iterations$  **do**

$h_1, h_2, \dots, h_{L-1}, a_1, a_2, \dots, a_L, \hat{y} = forward\_propagation(\theta_t)$ ;

**end**

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$h_1, h_2, \dots, h_{L-1}, a_1, a_2, \dots, a_L, \hat{y} = forward\_propagation(\theta_t)$ ;

$\nabla\theta_t = backward\_propagation(h_1, h_2, \dots, h_{L-1}, a_1, a_2, \dots, a_L, y, \hat{y})$ ;

**end**

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 $t \leftarrow 0;$  $max\_iterations \leftarrow 1000;$  $Initialize \quad \theta_0 = [W_1^0, \dots, W_L^0, b_1^0, \dots, b_L^0];$ **while**  $t++ < max\_iterations$  **do** $h_1, h_2, \dots, h_{L-1}, a_1, a_2, \dots, a_L, \hat{y} = forward\_propagation(\theta_t);$  $\nabla \theta_t = backward\_propagation(h_1, h_2, \dots, h_{L-1}, a_1, a_2, \dots, a_L, y, \hat{y});$  $\theta_{t+1} \leftarrow \theta_t - \eta \nabla \theta_t;$ **end**

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**Algorithm:** forward\_propagation( $\theta$ )

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**for**  $k = 1$  *to*  $L - 1$  **do**

|

**end**

---

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**for**  $k = 1$  *to*  $L - 1$  **do**

$a_k = b_k + W_k h_{k-1};$

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**for**  $k = 1$  *to*  $L - 1$  **do**

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     $h_k = g(a_k);$

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**end**

$a_L = b_L + W_L h_{L-1};$

$\hat{y} = O(a_L);$

---

Just do a forward propagation and compute all  $h_i$ 's,  $a_i$ 's,  $y$  and  $\hat{y}$

---

**Algorithm:** back\_propagation( $h_1, h_2, \dots, h_{L-1}, a_1, a_2, \dots, a_L, \hat{y}$ )

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//Compute output gradient ;

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//Compute output gradient ;

$$\nabla_{a_L} \mathcal{L}(\theta) = -(e(y) - \hat{y}) ;$$

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**end**

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    // Compute gradients w.r.t. layer below ;

$$\nabla_{h_{k-1}} \mathcal{L}(\theta) = W_k^T (\nabla_{a_k} \mathcal{L}(\theta)) ;$$

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$$\nabla_{a_{k-1}} \mathcal{L}(\theta) = \nabla_{h_{k-1}} \mathcal{L}(\theta) \odot [\dots, g'(a_{k-1,j}), \dots] ;$$

**end**

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