

Module 4.1: Feedforward Neural Networks (a.k.a. multilayered network of neurons)

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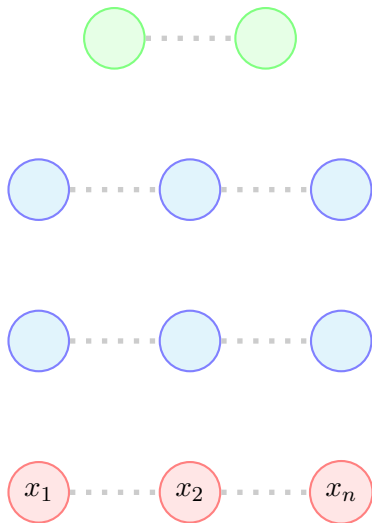


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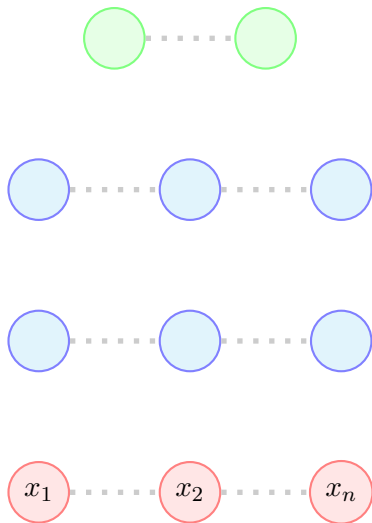


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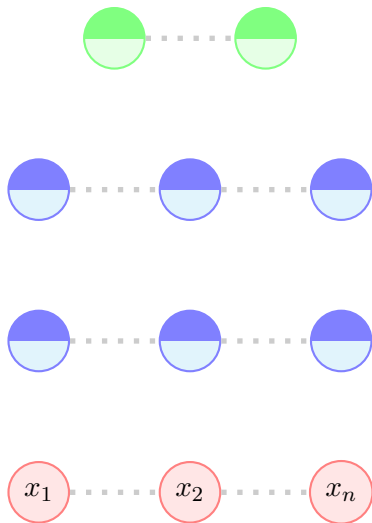




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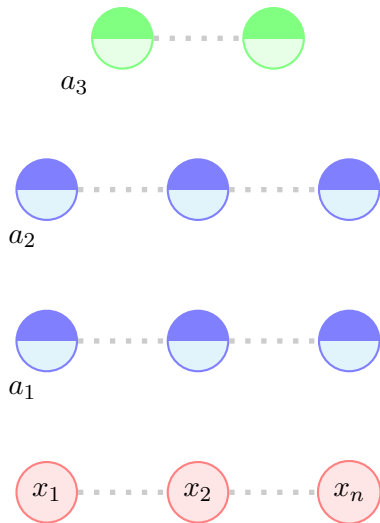


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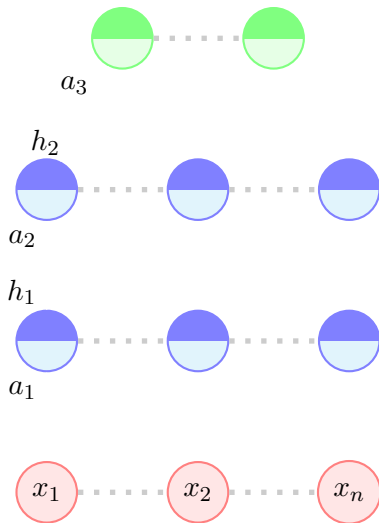


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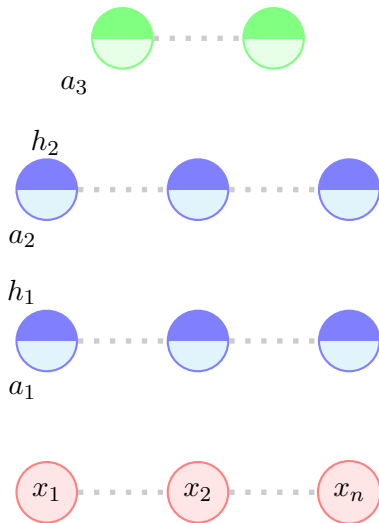


$$h_L = \hat{y} = f(x)$$



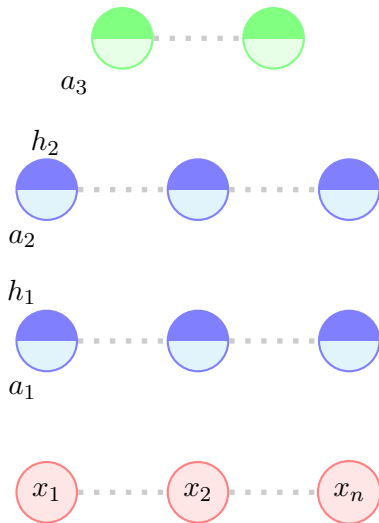
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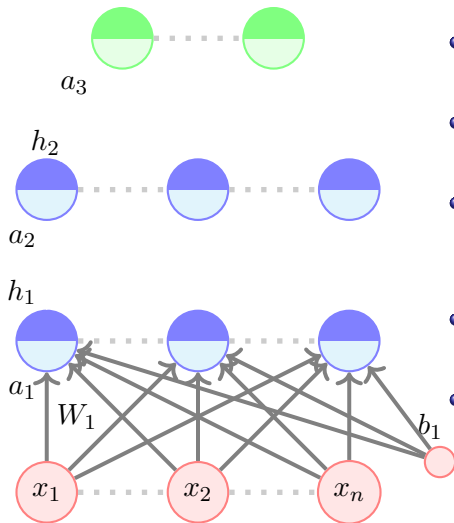
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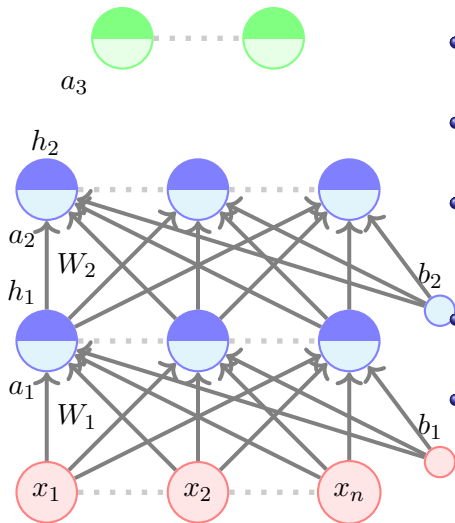
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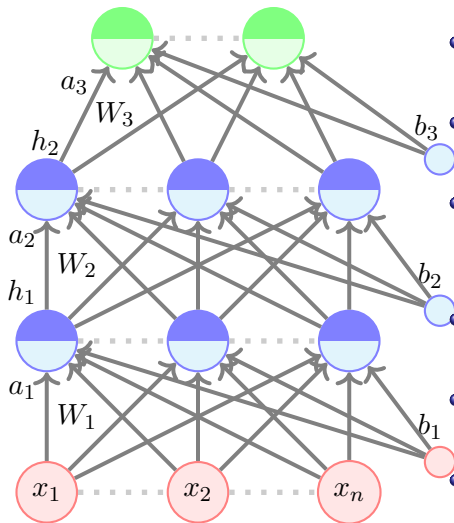
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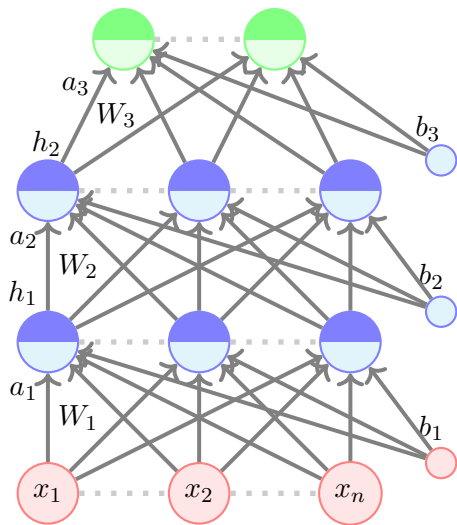


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- $W_L \in \mathbb{R}^{n \times k}$ and $b_L \in \mathbb{R}^k$ are the weight and bias between the last hidden layer and the output layer ($L = 3$ in this case)

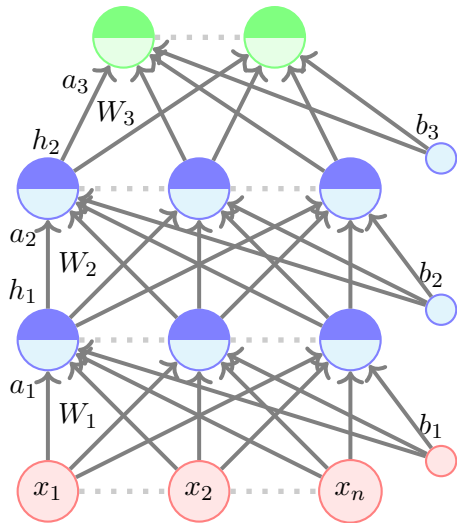
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$$a_i(x) = b_i + W_i h_{i-1}(x)$$



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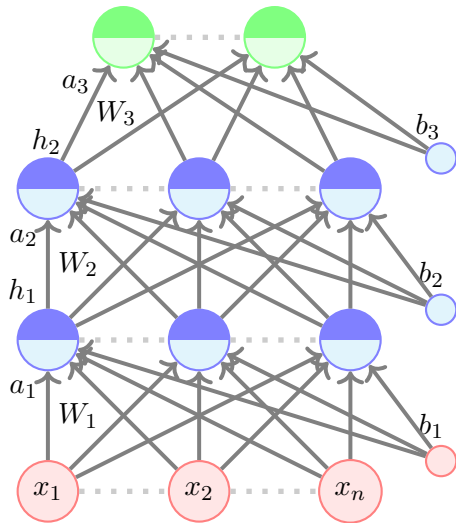
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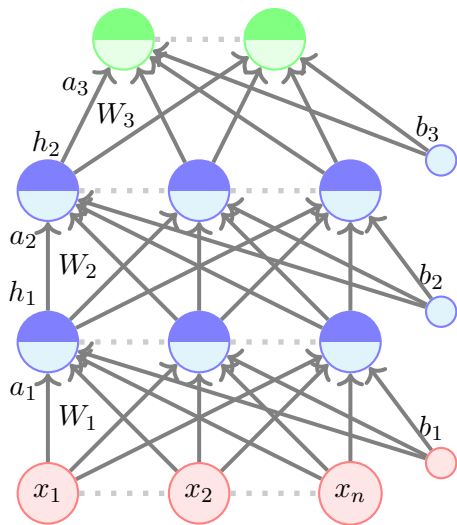
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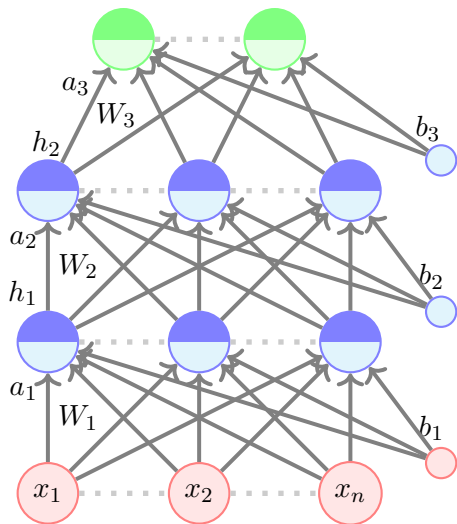
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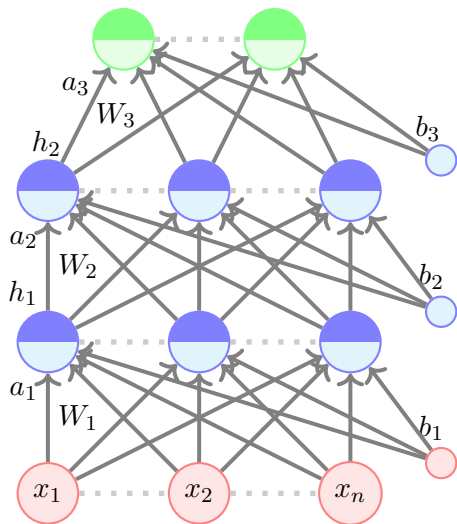
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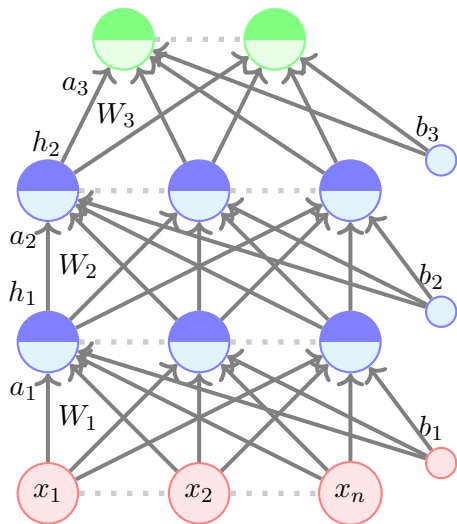
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- To simplify notation we will refer to $a_i(x)$ as a_i and $h_i(x)$ as h_i

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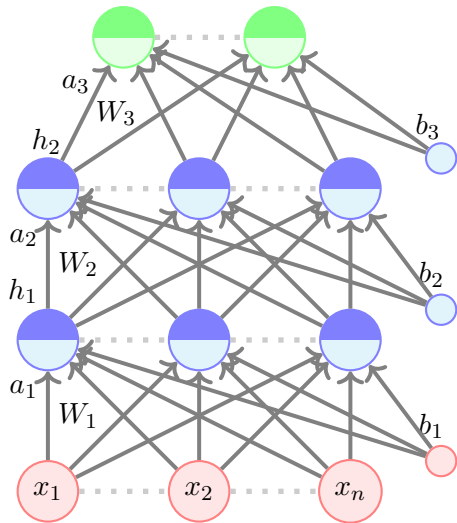
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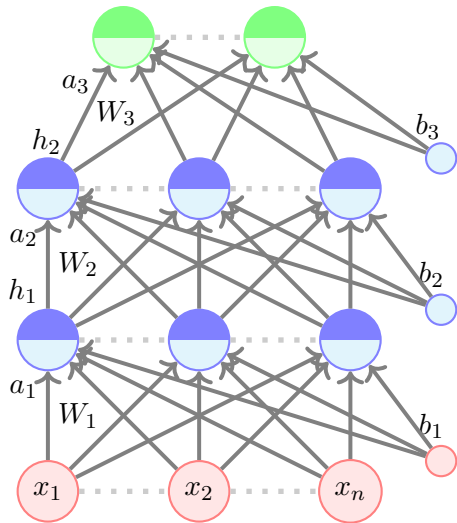
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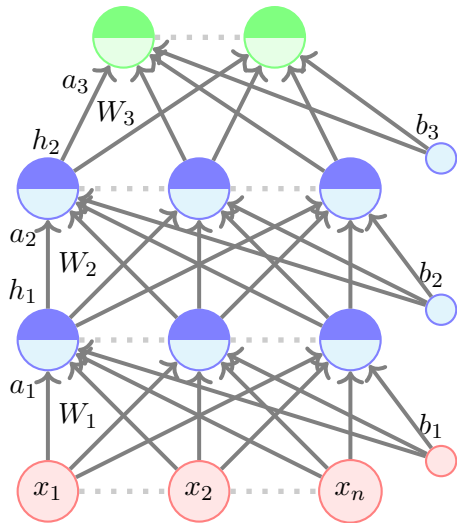


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• **Model:**

$$\hat{y}_i = f(x_i) = O(W^3 g(W^2 g(W^1 x + b_1) + b_2) + b_3)$$

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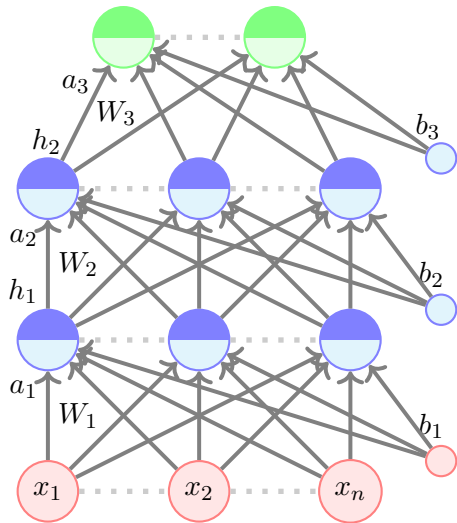
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- **Parameters:**

$$\theta = W_1, \dots, W_L, b_1, b_2, \dots, b_L (L = 3)$$

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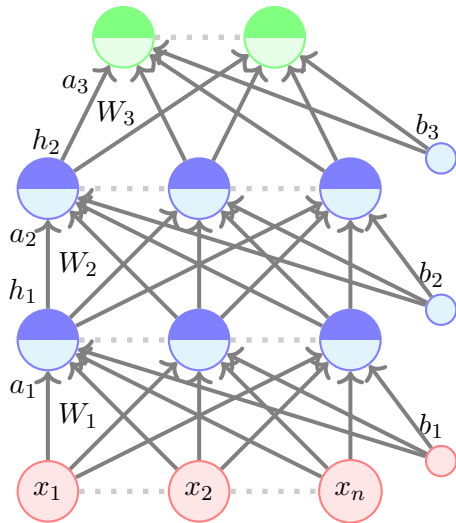
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- **Objective/Loss/Error function:** Say,

$$\min \frac{1}{N} \sum_{i=1}^N (\hat{y}_i - y_i)^2$$

$$\text{In general, } \min \mathcal{L}(\theta)$$

where $\mathcal{L}(\theta)$ is some function of the parameters