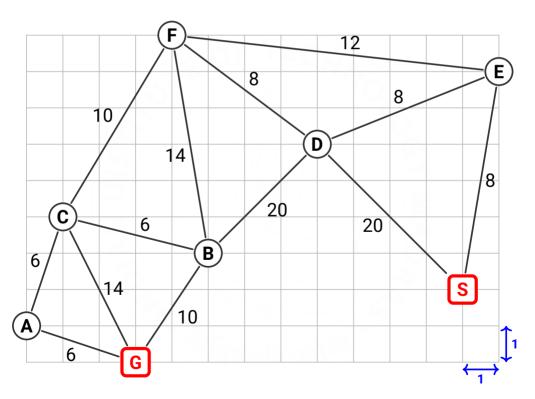
## Practice Assignment: City Map Example 2 wA\* (w=3) Search

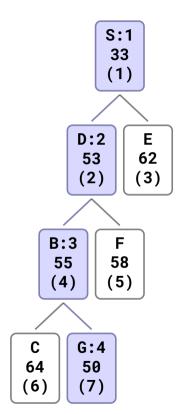
Prepared by S. Baskaran

## **State Space**

MoveGen returns nodes in ALPHABETICAL ORDER.



## **Search Tree**



## Solution

```
f = g + w * h, where w = 3.
OPEN and CLOSED carry tuples: (NODE, PARENT, f, g, h)
OPEN
             (S, null, 33, 0, 11):[]
CLOSED
             []
1.
NODE
             S
             (S, null, 33, 0, 11)
close
             D:E:[]
moveGen
             (D,S,53,20,11)
new-open
             (E, S, 62, 8, 18)
new-open
             (D,S,53,20,11):(E,S,62,8,18):[]
OPEN
CLOSED
             (S, null, 33, 0, 11):[]
2.
NODE
             D
close
             (D, S, 53, 20, 11)
moveGen
             B:E:F:S:[]
             (B, D, 55, 40, 5)
new-open
             (F, D, 58, 28, 10)
new-open
OPEN
             (B, D, 55, 40, 5): (F, D, 58, 28, 10):
             (E,S,62,8,18):[]
             (D,S,53,20,11):(S,null,33,0,11):[]
CLOSED
3.
NODE
             R
             (B, D, 55, 40, 5)
close
             C:D:F:G:[]
moveGen
             (C, B, 64, 46, 6)
new-open
             (G, B, 50, 50, 0)
new-open
OPEN
             (G, B, 50, 50, 0): (F, D, 58, 28, 10):
             (E,S,62,8,18):(C,B,64,46,6):[]
CLOSED
             (B, D, 55, 40, 5): (D, S, 53, 20, 11):
             (S, null, 33, 0, 11):[]
4.
NODE
             G
close
             (G, B, 50, 50, 0)
GOAL
             G
OPEN
             (F,D,58,28,10):(E,S,62,8,18):
             (C,B,64,46,6):[]
             (G,B,50,50,0):(B,D,55,40,5):
CLOSED
             (D,S,53,20,11):(S,null,33,0,11):[]
PATH
             S:D:B:G:[]
PATH COST
             50
```