```
In [2]:
from google.colab import drive
drive.mount('/content/drive')
Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client id=947318989803-6bn6
qk8qdgf4n4g3pfee6491hc0brc4i.apps.googleusercontent.com&redirect uri=urn%3aietf%3awg%3aoauth%3a2.0%
b&response type=code&scope=email%20https%3a%2f%2fwww.qooqleapis.com%2fauth%2fdocs.test%20https%3a%2
www.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly
ttps%3a%2f%2fwww.qooqleapis.com%2fauth%2fpeopleapi.readonly
Enter your authorization code:
Mounted at /content/drive
                                                                                                 F
In [ ]:
!unzip '/content/drive/My Drive/Assign - 23 Human Activity Recognition/Copy of
HumanActivityRecognition.zip' -d '/content/drive/My Drive/Assign - 23 Human Activity Recognition/'
Archive: /content/drive/My Drive/Assign - 23 Human Activity Recognition/Copy of
HumanActivityRecognition.zip
   creating: /content/drive/My Drive/Assign - 23 Human Activity Recognition/HAR/
 inflating: /content/drive/My Drive/Assign - 23 Human Activity Recognition/HAR/.DS_Store
   creating: /content/drive/My Drive/Assign - 23 Human Activity Recognition/_
   creating: /content/drive/My Drive/Assign - 23 Human Activity Recognition/
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/._.DS_Store
   creating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/.ipynb checkpoints/
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Recognition/HAR/.ipynb checkpoints/HAR EDA-checkpoint.ipynb
 inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/.ipynb checkpoints/HAR LSTM-checkpoint.ipynb
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/.ipynb checkpoints/HAR LSTM 1-checkpoint.ipynb
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/.ipynb checkpoints/HAR PREDICTION MODELS-checkpoint.ipynb
  inflating: /content/drive/My Drive/Assign - 23 Human Activity Recognition/HAR/HAR_EDA.ipynb
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/._HAR_EDA.ipynb
  inflating: /content/drive/My Drive/Assign - 23 Human Activity Recognition/HAR/HAR LSTM.ipynb
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/ MACOSX/HAR/. HAR LSTM.ipynb
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/HAR_PREDICTION_MODELS.ipynb
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/_
             MACOSX/HAR/. HAR PREDICTION MODELS.ipynb
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sne_perp_20_iter_1000.png
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 inflating: /content/drive/My Drive/Assign - 23 Human Activity Recognition/HAR/t-
sne_perp_50_iter_1000.png
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sne perp 50 iter 1000.png
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sne perp 5 iter 1000.png
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sne_perp_5_iter_1000.png
   creating: /content/drive/My Drive/Assign - 23 Human Activity Recognition/HAR/UCI HAR Dataset/
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/.DS Store
   creating: /content/drive/My Drive/Assign - 23 Human Activity
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  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/ DS Store
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Recognition/HAR/UCI HAR Dataset/activity labels.txt
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Recognition/ MACOSX/HAR/UCI HAR Dataset/. activity labels.txt
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Recognition/HAR/UCI HAR Dataset/csv files/test.csv
   creating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/ MACOSX/HAR/UCI HAR Dataset/csv files/
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
{\tt Recognition/\_MACOSX/HAR/UCI\_HAR\_Dataset/csv\_files/.\_test.csv}
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/csv files/train.csv
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/csv_files/._train.csv
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Recognition/HAR/UCI HAR Dataset/features.txt
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Recognition/HAR/UCI_HAR_Dataset/features_info.txt
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Recognition/__MACOSX/HAR/UCI_HAR_Dataset/._features_info.txt
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   creating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/test/Inertial Signals/
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/test/Inertial Signals/body acc x test.txt
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   creating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/test/Inertial Signals/
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/test/Inertial Signals/._body_acc_x_test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/test/Inertial Signals/body_acc_y_test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
{\tt Recognition/\_MACOSX/HAR/UCI\_HAR\_Dataset/test/Inertial\ Signals/.\_body\_acc\_y\_test.txt}
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/test/Inertial Signals/body_acc_z_test.txt
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Recognition/ MACOSX/HAR/UCI HAR Dataset/test/Inertial Signals/. body acc z test.txt
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Recognition/HAR/UCI HAR Dataset/test/Inertial Signals/body_gyro_x_test.txt
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              _MACOSX/HAR/UCI_HAR_Dataset/test/Inertial Signals/._body_gyro_x_test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/test/Inertial Signals/body_gyro_y_test.txt
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{\tt Recognition/\_MACOSX/HAR/UCI\_HAR\_Dataset/test/Inertial~Signals/.\_body\_gyro\_y\_test.txt}
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Recognition/HAR/UCI HAR Dataset/test/Inertial Signals/body gyro z test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
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Recognition/HAR/UCI HAR Dataset/test/Inertial Signals/total acc x test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
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  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/test/Inertial Signals/total_acc_y_test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/test/Inertial Signals/._total_acc_y_test.txt
inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/test/Inertial Signals/total acc z test.txt
```

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inflating: /content/drive/My Drive/Assign - 23 Human Activity
{\tt Recognition/\_MACOSX/HAR/UCI\_HAR\_Dataset/test/Inertial\ Signals/.\_total\_acc\_z\_test.txt}
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/test/subject test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/test/._subject_test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/test/X test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/test/._X_test.txt inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/test/y test.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/test/._y_test.txt
   creating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/train/
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/train/.DS Store
   creating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/ MACOSX/HAR/UCI HAR Dataset/train/. .DS Store
   creating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/train/Inertial Signals/
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/train/Inertial Signals/body acc x train.txt
   creating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/Inertial Signals/
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
{\tt Recognition/\_MACOSX/HAR/UCI\_HAR\_Dataset/train/Inertial~Signals/.\_body\_acc\_x\_train.txt}
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/train/Inertial Signals/body_acc_y_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/Inertial Signals/._body_acc_y_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
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  inflating: /content/drive/My Drive/Assign - 23 Human Activity
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              _MACOSX/HAR/UCI_HAR_Dataset/train/Inertial Signals/._body_acc_z_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/train/Inertial Signals/body gyro x train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/Inertial Signals/._body_gyro_x_train.txt
inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/train/Inertial Signals/body_gyro_y_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/Inertial Signals/._body_gyro_y_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/train/Inertial Signals/body_gyro_z_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/Inertial Signals/._body_gyro_z_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/train/Inertial Signals/total acc x train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/Inertial Signals
inflating: /content/drive/My Drive/Assign - 23 Human Activity
              MACOSX/HAR/UCI HAR Dataset/train/Inertial Signals/. total acc x train.txt
Recognition/HAR/UCI HAR Dataset/train/Inertial Signals/total acc y train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/Inertial Signals/._total_acc_y_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/train/Inertial Signals/total_acc_z_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/Inertial Signals/._total_acc_z_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/train/subject_train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/ MACOSX/HAR/UCI HAR Dataset/train/. subject train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/train/X train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/._X_train.txt
inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/train/y train.txt
  inflating: /content/drive/My Drive/Assign - 23 Human Activity
Recognition/__MACOSX/HAR/UCI_HAR_Dataset/train/._y_train.txt
```

1.Loading of Data

!+BodyAcc-correlation()-V 7!

```
In [ ]:
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
%matplotlib inline
import seaborn as sns
/usr/local/lib/python3.6/dist-packages/statsmodels/tools/ testing.py:19: FutureWarning:
pandas.util.testing is deprecated. Use the functions in the public API at pandas.testing instead.
  import pandas.util.testing as tm
In [ ]:
#getting the features from features.txt which is engineered by experts
features = list()
with open('/content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI HAR Dataset/features.txt') as f:
    features = [line.split()[1] for line in f.readlines()]
print('No of features = ',len(features))
No of features = 561
In [ ]:
features
Out[]:
['tBodyAcc-mean()-X',
 'tBodyAcc-mean()-Y',
 'tBodyAcc-mean()-Z',
 'tBodyAcc-std()-X',
 'tBodyAcc-std()-Y',
 'tBodyAcc-std()-Z',
 'tBodyAcc-mad()-X',
 'tBodyAcc-mad()-Y',
 'tBodyAcc-mad()-Z',
 'tBodyAcc-max()-X',
 'tBodyAcc-max()-Y',
 'tBodyAcc-max()-Z',
 'tBodyAcc-min()-X',
 'tBodyAcc-min()-Y',
 'tBodyAcc-min()-Z',
 'tBodyAcc-sma()',
 'tBodyAcc-energy()-X',
 'tBodyAcc-energy()-Y',
 'tBodyAcc-energy()-Z',
 'tBodyAcc-igr()-X',
 'tBodyAcc-iqr()-Y',
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 'tBodyAcc-entropy()-Z',
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 'tBodyAcc-arCoeff()-X,2',
 'tBodyAcc-arCoeff()-X,3',
 'tBodyAcc-arCoeff()-X,4',
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 'tBodyAcc-arCoeff()-Y,3',
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 'tBodyAcc-arCoeff()-Z,2',
 'tBodyAcc-arCoeff()-Z,3',
 'tBodyAcc-arCoeff()-Z,4',
 'tBodyAcc-correlation()-X,Y',
 'tBodyAcc-correlation()-X,Z',
```

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'tGravityAcc-mad()-Z',
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'tBodyAccJerk-arCoeff()-Y,4',
'tBodyAccJerk-arCoeff()-Z,1',
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\verb|'tBodyGyro-entropy()-Y'|,
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'tBodyGyro-arCoeff()-Z,3',
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'tBodyGyro-correlation()-Y,Z',
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'tBodyGyroJerk-energy()-Z',
'tBodyGyroJerk-iqr()-X',
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'tBodyGyroJerk-iqr()-Z',
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'tBodyGyroJerk-arCoeff()-Y,2',
'tBodyGyroJerk-arCoeff()-Y,3',
'tBodyGyroJerk-arCoeff()-Y,4',
1 + D - J - O - - - T - - - - - - - - - - - - E - / \ P - 1 |
```

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'angle(Y, gravityMean)',
'angle(Z,gravityMean)']
```

1.1 Training and Test data

```
In []:
# get the data from txt files to pandas dataffame
X_train = pd.read_csv('/content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/train/X_train.txt', delim_whitespace=True, header=None,
names=features)
# add subject column to the dataframe
X_train['subject'] = pd.read_csv('/content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/train/subject_train.txt', header=None, squeeze=True)
v train = pd.read_csv('/content/drive/My Drive/Assign - 23 Human Activity
```

In []:

1.2 Changing features names

```
In [ ]:
```

```
columns = train.columns

# Removing '()' from column names
columns = columns.str.replace('[()]','')
columns = columns.str.replace('[-]', '')
columns = columns.str.replace('[,]','')

train.columns = columns
test.columns = columns
```

In []:

```
train = pd.read_csv('/content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/csv_files/train.csv')
train.head()
```

Out[]:

	tBodyAccmeanX	tBodyAccmeanY	tBodyAccmeanZ	tBodyAccstdX	tBodyAccstdY	tBodyAccstdZ	tBodyAccmadX	tBodyAccmadY	t
0	0.288585	-0.020294	-0.132905	-0.995279	-0.983111	-0.913526	-0.995112	-0.983185	
1	0.278419	-0.016411	-0.123520	-0.998245	-0.975300	-0.960322	-0.998807	-0.974914	
2	0.279653	-0.019467	-0.113462	-0.995380	-0.967187	-0.978944	-0.996520	-0.963668	
3	0.279174	-0.026201	-0.123283	-0.996091	-0.983403	-0.990675	-0.997099	-0.982750	
4	0.276629	-0.016570	-0.115362	-0.998139	-0.980817	-0.990482	-0.998321	-0.979672	

5 rows × 564 columns

In []:

```
test = pd.read_csv('/content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/csv_files/train.csv')
test.head()
```

	tBodyAccmeanX	tBodyAccmeanY	tBodyAccmeanZ	tBodyAccstdX	tBodyAccstdY	tBodyAccstdZ	tBodyAccmadX	tBodyAccmadY	t
0	0.288585	-0.020294	-0.132905	-0.995279	-0.983111	-0.913526	-0.995112	-0.983185	
1	0.278419	-0.016411	-0.123520	-0.998245	-0.975300	-0.960322	-0.998807	-0.974914	
2	0.279653	-0.019467	-0.113462	-0.995380	-0.967187	-0.978944	-0.996520	-0.963668	
3	0.279174	-0.026201	-0.123283	-0.996091	-0.983403	-0.990675	-0.997099	-0.982750	
4	0.276629	-0.016570	-0.115362	-0.998139	-0.980817	-0.990482	-0.998321	-0.979672	

5 rows × 564 columns

o rows - co-a columno						
4	<u> •</u>					

1.3 Checking for duplicates

In []:

```
print('The number of duplicates in training data:', sum(train.duplicated()))
print('The number of duplicates in testing data:', sum(test.duplicated()))
```

The number of duplicates in training data: 0 The number of duplicates in testing data: 0

1.4 Checking for null values

In []:

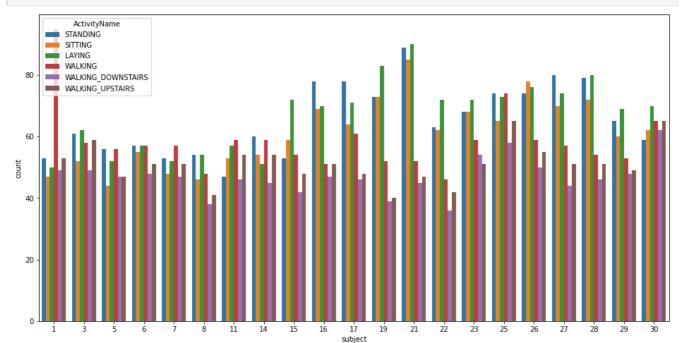
```
print(train.isna().values.sum())
print(test.isna().values.sum())

0
0
```

1.5 Checking for data imbalance

In []:

```
plt.figure(figsize=(16,8))
sns.countplot(x = 'subject', hue='ActivityName', data=train)
plt.show()
```

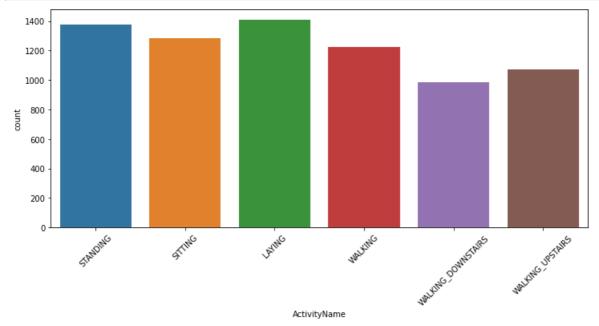


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1.6 Checking the distribution of classes

In []:

```
plt.figure(figsize=(12,5))
sns.countplot(x='ActivityName', data=train)
plt.xticks(rotation=45)
plt.show()
```



2.Univariate Analysis

In []:

```
#plt.figure(figsize=(12,5))
facetGrid = sns.FacetGrid(train, hue='ActivityName', size=6, aspect=2)
facetGrid.map(sns.distplot, 'tBodyAccMagmean', hist=False).add_legend()

plt.annotate("Stationary Activities", xy=(-0.956,17), xytext=(-0.9, 23), size=20, arrowprops= dict(arrowstyle="simple",connectionstyle="arc3,rad=0.1"))
plt.annotate("Moving Activities", xy=(0,3), xytext=(0.2, 9), size=20, arrowprops= dict(arrowstyle="simple",connectionstyle="arc3,rad=0.1"))
plt.show()

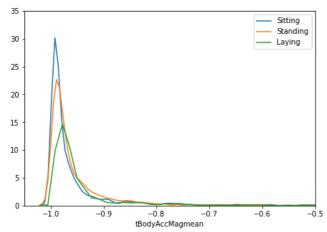
/usr/local/lib/python3.6/dist-packages/seaborn/axisgrid.py:243: UserWarning: The `size` parameter has been renamed to `height`; please update your code.
    warnings.warn(msg, UserWarning)
```

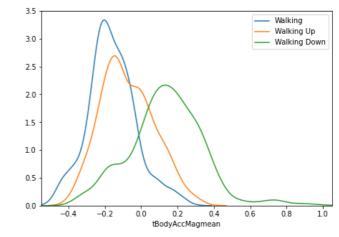


```
0 1 0 0.5 0.0 0.5 1.0 tBodyAccMagmean
```

```
In [ ]:
```

```
df1 = train[train['Activity']==1]
df2 = train[train['Activity']==2]
df3 = train[train['Activity']==3]
df4 = train[train['Activity']==4]
df5 = train[train['Activity']==5]
df6 = train[train['Activity']==6]
plt.figure(figsize=(16,5))
plt.subplot(1,2,1)
sns.distplot(df4['tBodyAccMagmean'], hist=False, label='Sitting')
\verb|sns.distplot(df5['tBodyAccMagmean']|, | \verb|hist=False|, | label='Standing'|)|
sns.distplot(df6['tBodyAccMagmean'], hist=False, label='Laying')
plt.axis([-1.05, -0.5, 0, 35])
plt.legend()
plt.subplot(1,2,2)
sns.distplot(df1['tBodyAccMagmean'], hist=False, label='Walking')
sns.distplot(df2['tBodyAccMagmean'], hist=False, label='Walking Up')
sns.distplot(df3['tBodyAccMagmean'], hist=False, label='Walking Down')
plt.axis([-0.55, 1.05, 0, 3.5])
plt.legend()
plt.show()
```

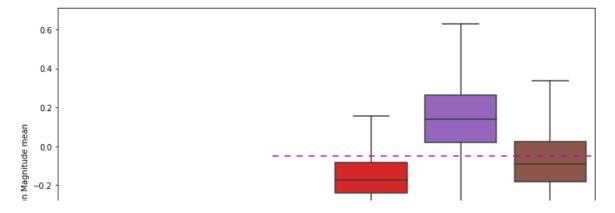


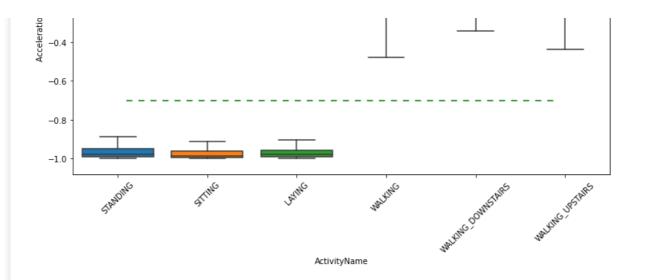


2.1 Mangnitude of an acceleration

In []:

```
plt.figure(figsize=(12,8))
sns.boxplot(x='ActivityName', y='tBodyAccMagmean', data=train, showfliers=False, saturation=1)
plt.ylabel('Acceleration Magnitude mean')
plt.axhline(y=-0.7, xmin=0.1, xmax=0.9, dashes=(5,5), c='g')
plt.axhline(y=-0.05, xmin=0.4, dashes=(5,5), c='m')
plt.xticks(rotation=45)
plt.show()
```

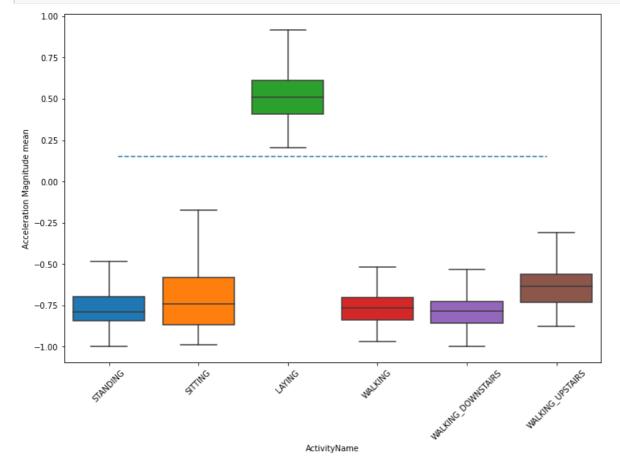




2.2 Position of gravity

In []:

```
plt.figure(figsize=(12,8))
sns.boxplot(x='ActivityName', y='angleXgravityMean', data=train, showfliers=False, saturation=1)
plt.ylabel('Acceleration Magnitude mean')
plt.axhline(y=0.15, xmin=0.1, xmax=0.9, linestyle='--')
plt.xticks(rotation=45)
plt.show()
```



3.Applying t-SNE

In []:

 $\textbf{from sklearn}. \textbf{manifold import} \ \texttt{TSNE}$

```
In [ ]:
```

In []:

```
X_pre_tsne = train.drop(['subject', 'Activity','ActivityName'], axis=1)
y pre tsne = train['ActivityName']
perform_tsne(X_data = X_pre_tsne,y_data=y_pre_tsne, perplexities =[2,5,10,20,50])
[t-SNE] Computing 7 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.470s...
[t-SNE] Computed neighbors for 7352 samples in 39.318s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 0.635854
[t-SNE] Computed conditional probabilities in 0.039s
[t-SNE] Iteration 50: error = 124.7889252, gradient norm = 0.0259888 (50 iterations in 6.079s)
[t-SNE] Iteration 100: error = 107.2060394, gradient norm = 0.0268191 (50 iterations in 3.206s)
[t-SNE] Iteration 150: error = 100.9500732, gradient norm = 0.0196198 (50 iterations in 2.336s)
[t-SNE] Iteration 200: error = 97.5597992, gradient norm = 0.0134663 (50 iterations in 2.208s)
[t-SNE] Iteration 250: error = 95.2138290, gradient norm = 0.0137577 (50 iterations in 2.208s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 95.213829
[t-SNE] Iteration 300: error = 4.1161933, gradient norm = 0.0015603 (50 iterations in 1.952s)
[t-SNE] Iteration 350: error = 3.2078633, gradient norm = 0.0010180 (50 iterations in 1.815s)
[t-SNE] Iteration 400: error = 2.7788248, gradient norm = 0.0007109 (50 iterations in 1.870s)
[t-SNE] Iteration 450: error = 2.5152574, gradient norm = 0.0005720 (50 iterations in 1.874s)
[t-SNE] Iteration 500: error = 2.3322468, gradient norm = 0.0004793 (50 iterations in 1.865s)
[t-SNE] Iteration 550: error = 2.1944561, gradient norm = 0.0004137 (50 iterations in 1.935s)
[t-SNE] Iteration 600: error = 2.0852098, gradient norm = 0.0003691 (50 iterations in 1.930s)
[t-SNE] Iteration 650: error = 1.9956943, gradient norm = 0.0003266 (50 iterations in 1.952s)
[t-SNE] Iteration 700: error = 1.9199437, gradient norm = 0.0003021 (50 iterations in 1.940s)
[t-SNE] Iteration 750: error = 1.8549099, gradient norm = 0.0002766 (50 iterations in 1.949s)
[t-SNE] Iteration 800: error = 1.7983253, gradient norm = 0.0002560 (50 iterations in 1.983s)
[t-SNE] Iteration 850: error = 1.7482818, gradient norm = 0.0002413 (50 iterations in 1.928s)
[t-SNE] Iteration 900: error = 1.7036929, gradient norm = 0.0002254 (50 iterations in 1.937s)
[t-SNE] Iteration 950: error = 1.6635983, gradient norm = 0.0002115 (50 iterations in 1.943s)
[t-SNE] Iteration 1000: error = 1.6274554, gradient norm = 0.0002008 (50 iterations in 1.937s)
[t-SNE] KL divergence after 1000 iterations: 1.627455
```

/usr/local/lib/python3.6/dist-packages/seaborn/regression.py:573: UserWarning: The `size` parameter has been renamed to `height`; please update your code. warnings.warn(msg, UserWarning)

saving this plot as image in present working directory...

perplexity : 2 and max_iter : 1000

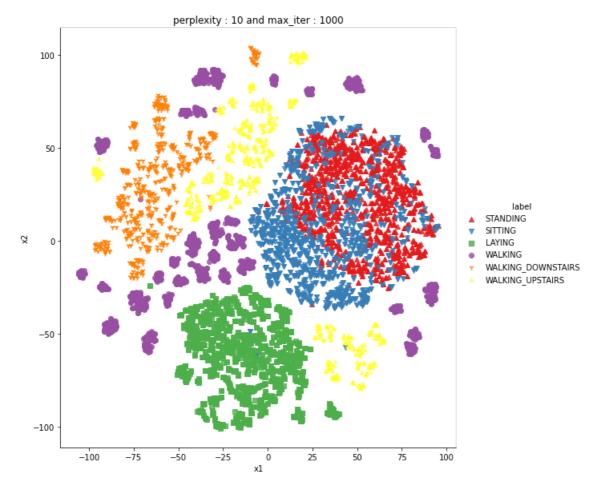
```
50
                                                                                                     STANDING
      0
                                                                                                      SITTING
Ø
                                                                                                      LAYING
                                                                                                      WALKING
                                                                                                      WALKING DOWNSTAIRS
                                                                                                      WALKING_UPSTAIRS
    -50
   -100
             -100
                                -50
                                                                     50
                                                                                       100
                                                   0
```

```
[t-SNE] Computing 16 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.627s...
[t-SNE] Computed neighbors for 7352 samples in 39.817s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 0.961265
[t-SNE] Computed conditional probabilities in 0.067s
[t-SNE] Iteration 50: error = 114.0185089, gradient norm = 0.0218635 (50 iterations in 5.959s)
[t-SNE] Iteration 100: error = 97.7227173, gradient norm = 0.0154143 (50 iterations in 2.253s)
[t-SNE] Iteration 150: error = 93.2074738, gradient norm = 0.0098429 (50 iterations in 1.956s)
[t-SNE] Iteration 200: error = 91.1990356, gradient norm = 0.0067135 (50 iterations in 1.922s)
[t-SNE] Iteration 250: error = 90.0177536, gradient norm = 0.0046048 (50 iterations in 1.926s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 90.017754
[t-SNE] Iteration 300: error = 3.5725126, gradient norm = 0.0014673 (50 iterations in 1.910s)
[t-SNE] Iteration 350: error = 2.8130083, gradient norm = 0.0007548 (50 iterations in 1.861s)
[t-SNE] Iteration 400: error = 2.4323199, gradient norm = 0.0005205 (50 iterations in 1.888s)
[t-SNE] Iteration 450: error = 2.2149634, gradient norm = 0.0004009 (50 iterations in 1.934s)
[t-SNE] Iteration 500: error = 2.0706520, gradient norm = 0.0003326 (50 iterations in 1.922s) [t-SNE] Iteration 550: error = 1.9654067, gradient norm = 0.0002826 (50 iterations in 1.931s)
[t-SNE] Iteration 600: error = 1.8840668, gradient norm = 0.0002470 (50 iterations in 1.892s)
[t-SNE] Iteration 650: error = 1.8190072, gradient norm = 0.0002179 (50 iterations in 1.888s)
[t-SNE] Iteration 700: error = 1.7654541, gradient norm = 0.0001979 (50 iterations in 1.885s)
[t-SNE] Iteration 750: error = 1.7199605, gradient norm = 0.0001814 (50 iterations in 1.881s)
[t-SNE] Iteration 800: error = 1.6810946, gradient norm = 0.0001655 (50 iterations in 1.868s)
[t-SNE] Iteration 850: error = 1.6473318, gradient norm = 0.0001528 (50 iterations in 1.907s)
[t-SNE] Iteration 900: error = 1.6175196, gradient norm = 0.0001414 (50 iterations in 1.879s)
[t-SNE] Iteration 950: error = 1.5911634, gradient norm = 0.0001349 (50 iterations in 1.883s)
[t-SNE] Iteration 1000: error = 1.5674787, gradient norm = 0.0001273 (50 iterations in 1.901s)
[t-SNE] KL divergence after 1000 iterations: 1.567479
```

/usr/local/lib/python3.6/dist-packages/seaborn/regression.py:573: UserWarning: The `size` parameter has been renamed to `height`; please update your code.
warnings.warn(msg, UserWarning)

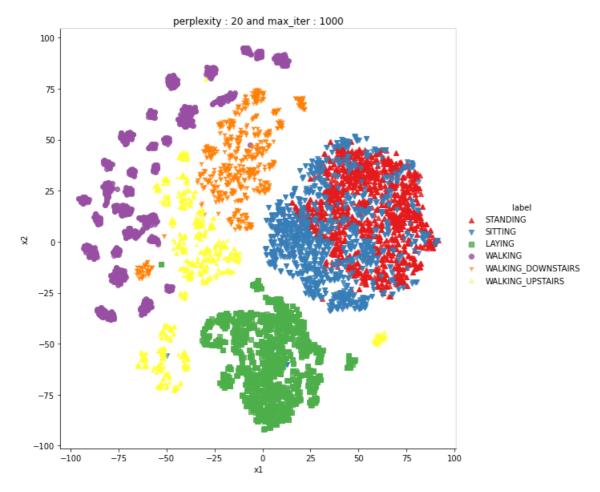
saving this plot as image in present working directory...

```
Done
[t-SNE] Computing 31 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.630s...
[t-SNE] Computed neighbors for 7352 samples in 40.574s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.133828
[t-SNE] Computed conditional probabilities in 0.125s
[t-SNE] Iteration 50: error = 105.7421417, gradient norm = 0.0184827 (50 iterations in 4.469s)
[t-SNE] Iteration 100: error = 90.4412537, gradient norm = 0.0102276 (50 iterations in 2.565s)
[t-SNE] Iteration 150: error = 87.3087616, gradient norm = 0.0059609 (50 iterations in 2.104s)
[t-SNE] Iteration 200: error = 86.0333710, gradient norm = 0.0056068 (50 iterations in 2.051s)
[t-SNE] Iteration 250: error = 85.3234100, gradient norm = 0.0028100 (50 iterations in 2.036s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 85.323410
[t-SNE] Iteration 300: error = 3.1339159, gradient norm = 0.0013938 (50 iterations in 2.004s)
[t-SNE] Iteration 350: error = 2.4887671, gradient norm = 0.0006497 (50 iterations in 1.992s)
[t-SNE] Iteration 400: error = 2.1686134, gradient norm = 0.0004229 (50 iterations in 2.025s)
[t-SNE] Iteration 450: error = 1.9840684, gradient norm = 0.0003129 (50 iterations in 2.037s)
[t-SNE] Iteration 500: error = 1.8657923, gradient norm = 0.0002500 (50 iterations in 2.042s)
[t-SNE] Iteration 550: error = 1.7825463, gradient norm = 0.0002096 (50 iterations in 2.051s)
[t-SNE] Iteration 600: error = 1.7201005, gradient norm = 0.0001818 (50 iterations in 2.030s)
[t-SNE] Iteration 650: error = 1.6710354, gradient norm = 0.0001617 (50 iterations in 2.041s)
[t-SNE] Iteration 700: error = 1.6316726, gradient norm = 0.0001442 (50 iterations in 2.034s)
[t-SNE] Iteration 750: error = 1.5990770, gradient norm = 0.0001281 (50 iterations in 2.036s)
[t-SNE] Iteration 800: error = 1.5716115, gradient norm = 0.0001198 (50 iterations in 2.073s) [t-SNE] Iteration 850: error = 1.5487018, gradient norm = 0.0001108 (50 iterations in 2.049s)
[t-SNE] Iteration 900: error = 1.5292275, gradient norm = 0.0001041 (50 iterations in 2.055s)
[t-SNE] Iteration 950: error = 1.5123469, gradient norm = 0.0000976 (50 iterations in 2.067s)
[t-SNE] Iteration 1000: error = 1.4976254, gradient norm = 0.0000919 (50 iterations in 2.061s)
[t-SNE] KL divergence after 1000 iterations: 1.497625
```



```
Done
[t-SNE] Computing 61 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.581s...
[t-SNE] Computed neighbors for 7352 samples in 41.287s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.274335
[t-SNE] Computed conditional probabilities in 0.250s
[t-SNE] Iteration 50: error = 97.9168091, gradient norm = 0.0180808 (50 iterations in 3.376s)
[t-SNE] Iteration 100: error = 84.0771027, gradient norm = 0.0077034 (50 iterations in 2.517s)
[t-SNE] Iteration 150: error = 81.9161835, gradient norm = 0.0036698 (50 iterations in 2.256s)
[t-SNE] Iteration 200: error = 81.1607971, gradient norm = 0.0024739 (50 iterations in 2.240s)
[t-SNE] Iteration 250: error = 80.7808075, gradient norm = 0.0019368 (50 iterations in 2.241s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 80.780807
[t-SNE] Iteration 300: error = 2.7023807, gradient norm = 0.0013082 (50 iterations in 2.266s)
[t-SNE] Iteration 350: error = 2.1672068, gradient norm = 0.0005762 (50 iterations in 2.175s)
[t-SNE] Iteration 400: error = 1.9168081, gradient norm = 0.0003474 (50 iterations in 2.158s)
[t-SNE] Iteration 450: error = 1.7704682, gradient norm = 0.0002482 (50 iterations in 2.194s)
[t-SNE] Iteration 500: error = 1.6761820, gradient norm = 0.0001938 (50 iterations in 2.201s)
[t-SNE] Iteration 550: error = 1.6116860, gradient norm = 0.0001583 (50 iterations in 6.233s)
[t-SNE] Iteration 600: error = 1.5650036, gradient norm = 0.0001345 (50 iterations in 2.708s)
[t-SNE] Iteration 650: error = 1.5296665, gradient norm = 0.0001166 (50 iterations in 2.204s)
[t-SNE] Iteration 700: error = 1.5022783, gradient norm = 0.0001058 (50 iterations in 2.203s)
[t-SNE] Iteration 750: error = 1.4808836, gradient norm = 0.0000953 (50 iterations in 2.190s)
[t-SNE] Iteration 800: error = 1.4634231, gradient norm = 0.0000878 (50 iterations in 2.201s)
[t-SNE] Iteration 850: error = 1.4492576, gradient norm = 0.0000851 (50 iterations in 2.248s)
[t-SNE] Iteration 900: error = 1.4377539, gradient norm = 0.0000799 (50 iterations in 2.202s)
[t-SNE] Iteration 950: error = 1.4278898, gradient norm = 0.0000753 (50 iterations in 2.178s)
[t-SNE] Iteration 1000: error = 1.4196749, gradient norm = 0.0000706 (50 iterations in 2.205s)
[t-SNE] KL divergence after 1000 iterations: 1.419675
```

saving this plot as image in present working directory...

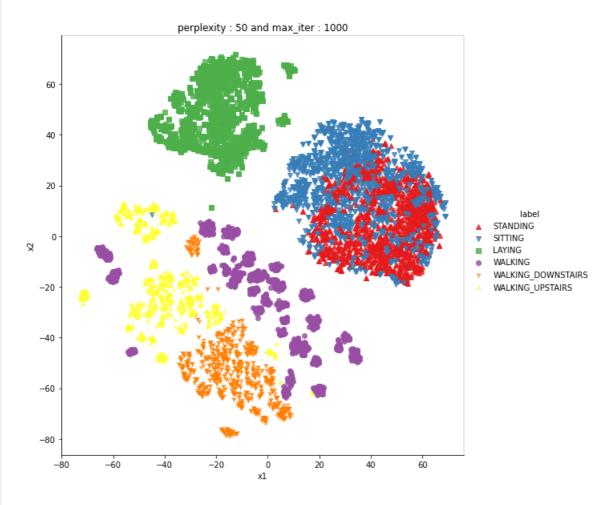


```
Done
[t-SNE] Computing 151 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.587s...
[t-SNE] Computed neighbors for 7352 samples in 42.468s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.437672
[t-SNE] Computed conditional probabilities in 0.597s
[t-SNE] Iteration 50: error = 86.1462936, gradient norm = 0.0224882 (50 iterations in 5.255s)
       Iteration 100: error = 75.6794968, gradient norm = 0.0052310 (50 iterations in 4.064s)
[t-SNE] Iteration 150: error = 74.7102890, gradient norm = 0.0022697 (50 iterations in 3.326s)
[t-SNE] Iteration 200: error = 74.3220215, gradient norm = 0.0014518 (50 iterations in 3.310s)
[t-SNE] Iteration 250: error = 74.1314392, gradient norm = 0.0013451 (50 iterations in 3.282s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 74.131439
[t-SNE] Iteration 300: error = 2.1503248, gradient norm = 0.0011810 (50 iterations in 3.045s)
[t-SNE] Iteration 350: error = 1.7540185, gradient norm = 0.0004869 (50 iterations in 2.864s)
[t-SNE] Iteration 400: error = 1.5858097, gradient norm = 0.0002783 (50 iterations in 2.811s)
[t-SNE] Iteration 450: error = 1.4925530, gradient norm = 0.0001883 (50 iterations in 2.836s)
[t-SNE] Iteration 500: error = 1.4330434, gradient norm = 0.0001395 (50 iterations in 2.810s)
[t-SNE] Iteration 550: error = 1.3922095, gradient norm = 0.0001103 (50 iterations in 2.899s)
[t-SNE] Iteration 600: error = 1.3631427, gradient norm = 0.0000933 (50 iterations in 2.842s)
[t-SNE] Iteration 650: error = 1.3421729, gradient norm = 0.0000837 (50 iterations in 2.854s)
[t-SNE] Iteration 700: error = 1.3270123, gradient norm = 0.0000748 (50 iterations in 2.885s)
[t-SNE] Iteration 750: error = 1.3154559, gradient norm = 0.0000716 (50 iterations in 2.847s)
[t-SNE] Iteration 800: error = 1.3065617, gradient norm = 0.0000638 (50 iterations in 2.919s)
       Iteration 850: error = 1.2991855, gradient norm = 0.0000604 (50 iterations in 2.896s)
[t-SNE] Iteration 900: error = 1.2934437, gradient norm = 0.0000589 (50 iterations in 2.939s)
It-SNEl Iteration 950: error = 1.2887629. gradient norm = 0.0000542 (50 iterations in 2.941s)
```

```
[t-SNE] Iteration 1000: error = 1.2845986, gradient norm = 0.0000527 (50 iterations in 2.927s) [t-SNE] KL divergence after 1000 iterations: 1.284599
```

/usr/local/lib/python3.6/dist-packages/seaborn/regression.py:573: UserWarning: The `size` parameter has been renamed to `height`; please update your code. warnings.warn(msg, UserWarning)

saving this plot as image in present working directory...



Done

4. Classical ML models

In []:

```
train = pd.read_csv('/content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/csv_files/train.csv')
test = pd.read_csv('/content/drive/My Drive/Assign - 23 Human Activity
Recognition/HAR/UCI_HAR_Dataset/csv_files/test.csv')
print(train.shape, test.shape)
```

(7352, 564) (2947, 564)

In []:

```
train.head()
```

Out[]:

	tBodyAccmeanX	tBodyAccmeanY	tBodyAccmeanZ	tBodyAccstdX	tBodyAccstdY	tBodyAccstdZ	tBodyAccmadX	tBodyAccmadY	t
0	0.288585	-0.020294	-0.132905	-0.995279	-0.983111	-0.913526	-0.995112	-0.983185	
1	0.278419	-0.016411	-0.123520	-0.998245	-0.975300	-0.960322	-0.998807	-0.974914	

```
2 tBodyAcc27e66X tBodyAcc11e46Y tBodyAcc11e46X tBodyAcc314X tBodyAcc314X tBodyAcc314X tBodyAcc314X tBodyAcc314X tBodyAcc314X
 3
         0.279174
                        -0.026201
                                      -0.123283
                                                   -0.996091
                                                               -0.983403
                                                                            -0.990675
                                                                                         -0.997099
                                                                                                       -0.982750
         0.276629
                        -0.016570
                                      -0.115362
                                                   -0.998139
                                                               -0.980817
                                                                            -0.990482
                                                                                         -0.998321
                                                                                                       -0.979672
5 rows × 564 columns
4
In [ ]:
X train = train.drop(['subject', 'Activity', 'ActivityName'], axis=1)
X test = test.drop(['subject', 'Activity', 'ActivityName'], axis=1)
In [ ]:
y train = train.ActivityName
y_test = test.ActivityName
print('X_train and y_train : ({},{})'.format(X_train.shape, y_train.shape))
print('X_test and y_test : ({},{})'.format(X_test.shape, y_test.shape))
X train and y train : ((7352, 561), (7352,))
X_{test} and y_{test}: ((2947, 561),(2947,))
```

4.1 General function to perform any model

Function to plot the confusion matrix

```
In []:
import itertools
import numpy as np
```

```
import matplotlib.pyplot as plt
from sklearn.metrics import confusion matrix
plt.rcParams["font.family"] = 'DejaVu Sans'
def plot confusion matrix(cm, classes,
                          normalize=False,
                          title='Confusion matrix',
                          cmap=plt.cm.Blues):
   if normalize:
       cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]
   plt.imshow(cm, interpolation='nearest', cmap=cmap)
   plt.title(title)
   plt.colorbar()
   tick_marks = np.arange(len(classes))
   plt.xticks(tick marks, classes, rotation=90)
   plt.yticks(tick marks, classes)
   fmt = '.2f' if normalize else 'd'
   thresh = cm.max() / 2.
   for i, j in itertools.product(range(cm.shape[0]), range(cm.shape[1])):
       plt.text(j, i, format(cm[i, j], fmt),
                horizontalalignment="center",
                 color="white" if cm[i, j] > thresh else "black")
   plt.tight_layout()
   plt.ylabel('True label')
   plt.xlabel('Predicted label')
```

Generic function to run any model specified

```
In [ ]:
```

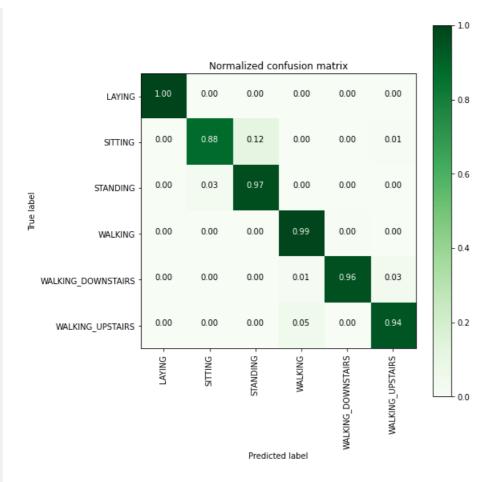
```
def perform model(model, X train, y train, X test, y test, class labels, cm normalize=True, \
                print_cm=True, cm_cmap=plt.cm.Greens):
   # to store results at various phases
   results = dict()
   train_start_time = datetime.now()
   model.fit(X train, y train)
   train end time = datetime.now()
   results['training time'] = train end time - train start time
   print('training time: {}'.format(results['training time']))
   # predict test data
   print('Predicting test data')
   test start time = datetime.now()
   y_pred = model.predict(X_test)
   test end time = datetime.now()
   results['testing time'] = test end time - test start time
   print('testing time{}'.format(results['testing_time']))
   results['predicted'] = y pred
   # calculate overall accuracty of the model
   accuracy = metrics.accuracy score(y true=y test, y pred=y pred)
    # store accuracy in results
   results['accuracy'] = accuracy
   print('----')
   print('| Accuracy |')
   print('----')
   print('\n {}\n\n'.format(accuracy))
   # confusion matrix
   cm = metrics.confusion matrix(y_test, y_pred)
   results['confusion matrix'] = cm
   if print cm:
      print('----')
      print('| Confusion Matrix |')
      print('----')
       print('\n {}'.format(cm))
   # plot confusin matrix
   plt.figure(figsize=(8,8))
   plt.grid(b=False)
   plot confusion matrix(cm, classes=class labels, normalize=True, title='Normalized confusion
matrix', cmap = cm cmap)
   plt.show()
   # get classification report
   print('----')
   print('| Classifiction Report |')
   print('----')
   classification report = metrics.classification_report(y_test, y_pred)
   # store report in results
   results['classification report'] = classification report
   print(classification_report)
   # add the trained model to the results
   results['model'] = model
   return results
```

Method to print the gridsearch Attributes

```
In [ ]:
```

```
print('----')
   print('\n\t{}\n'.format(model.best_estimator_))
   # parameters that gave best results while performing grid search
   print('----')
   print('| Best parameters |')
   print('----')
   print('\tParameters of best estimator : \n\n\t{}\n'.format(model.best params ))
   # number of cross validation splits
   print('----')
   print('| No of CrossValidation sets |')
   print('----')
   print('\n\tTotal numbre of cross validation sets: {}\n'.format(model.n splits ))
   # Average cross validated score of the best estimator, from the Grid Search
   print('----')
   print('| Best Score |')
  print('----')
  \verb|print('\n\t| Average Cross Validate scores of best estimator:
\n\n\t{}\n'.format(model.best_score_))
```

```
4.2 Logistic Regression with Grid Search
In [ ]:
from sklearn import linear model
from sklearn import metrics
from sklearn.model selection import GridSearchCV
In [ ]:
# start Grid search
parameters = {'C':[0.01, 0.1, 1, 10, 20, 30], 'penalty':['12','11']}
log reg = linear model.LogisticRegression()
log_reg_grid = GridSearchCV(log_reg, param_grid=parameters, cv=3, verbose=1, n jobs=-1)
log_reg_grid_results = perform_model(log_reg_grid, X_train, y_train, X_test, y_test, class_labels=
labels)
Fitting 3 folds for each of 12 candidates, totalling 36 fits
[Parallel(n_jobs=-1)]: Using backend LokyBackend with 2 concurrent workers.
[Parallel(n jobs=-1)]: Done 36 out of 36 | elapsed: 25.5s finished
training_time: 0:00:28.591985
Predicting test data
testing time0:00:00.009525
| Accuracy |
   0.9586019681031558
| Confusion Matrix |
 [[537 0 0 0 0
                      0]
 [ 0 431 57 0 0
                      3]
   0 15 517 0 0
                      01
 [ 0 0 0 493 2 1]
 [ 0 0 0 4 402 14]
 [ 0 0 0 25 1 445]]
```



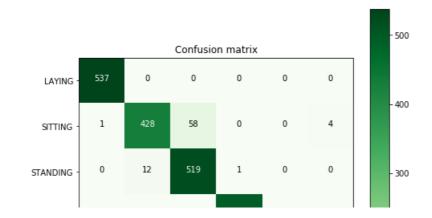
| Classifiction Report |

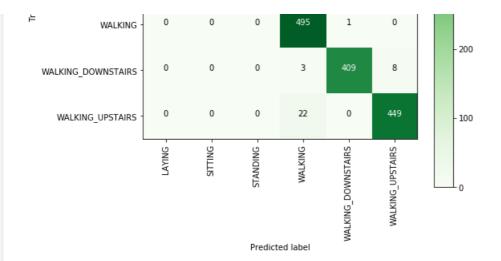
	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	537
SITTING	0.97	0.88	0.92	491
STANDING	0.90	0.97	0.93	532
WALKING	0.94	0.99	0.97	496
WALKING_DOWNSTAIRS	0.99	0.96	0.97	420
WALKING_UPSTAIRS	0.96	0.94	0.95	471
accuracy			0.96	2947
macro avg	0.96	0.96	0.96	2947
weighted avg	0.96	0.96	0.96	2947

In []:

ue label

```
plt.figure(figsize=(8,8))
plt.grid(b=False)
plot_confusion_matrix(log_reg_grid_results['confusion_matrix'], classes=labels, cmap=plt.cm.Greens
, )
plt.show()
```





In []:

```
# observe the attributes of the model
print_grid_search_attributes(log_reg_grid_results['model'])
    Best Estimator |
_____
LogisticRegression(C=30, class weight=None, dual=False, fit intercept=True,
        intercept_scaling=1, max_iter=100, multi_class='ovr', n_jobs=1,
        penalty='12', random_state=None, solver='liblinear', tol=0.0001,
        verbose=0, warm start=False)
| Best parameters |
Parameters of best estimator :
{'C': 30, 'penalty': '12'}
_____
| No of CrossValidation sets |
_____
Total numbre of cross validation sets: 3
 Best Score |
______
Average Cross Validate scores of best estimator :
0.9461371055495104
```

4.3Linear SVC with GridSearch

```
In []:

parameters = {'C':[0.125, 0.5, 1, 2, 8, 16]}
lr_svc = LinearSVC(tol=0.00005)
lr_svc_grid = GridSearchCV(lr_svc, param_grid=parameters, n_jobs=-1, verbose=1)
lr_svc_grid_results = perform_model(lr_svc_grid, X_train, y_train, X_test, y_test, class_labels=labels)
```

training the model.. Fitting 3 folds for each of 6 candidates, totalling 18 fits

```
[Parallel(n_jobs=-1)]: Done 18 out of 18 | elapsed: 24.9s finished
```

Predicting test data

Done

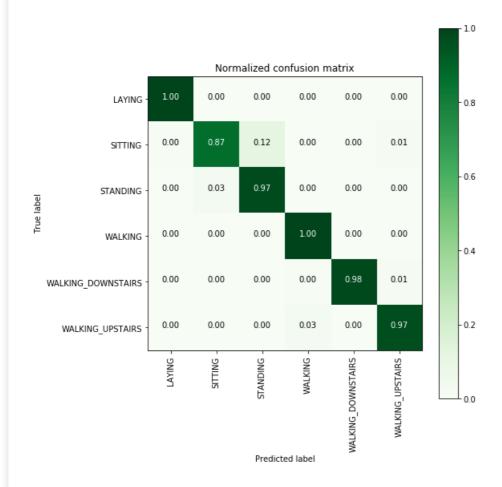
testing time(HH:MM:SS:ms) - 0:00:00.012182

Accuracy |

0.9660671869697998

| Confusion Matrix |

[[537	′ () () () (0]
[2	426	58	0	0	5]
[0	14	518	0	0	0]
[0	0	0	495	0	1]
[0	0	0	2	413	5]
[0	0	0	12	1	458]]



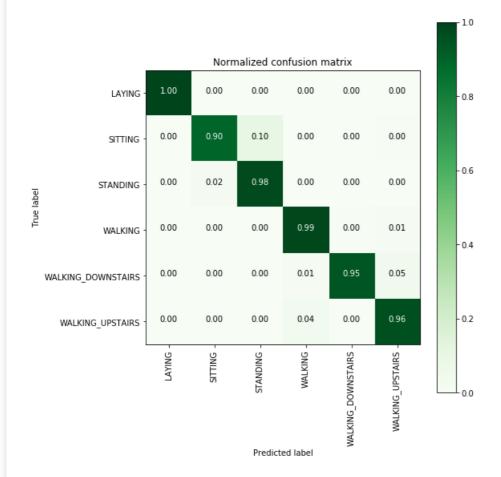
| Classifiction Report |

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	537
SITTING	0.97	0.87	0.92	491
STANDING	0.90	0.97	0.94	532
WALKING	0.97	1.00	0.99	496
WALKING DOWNSTAIRS	1.00	0.98	0.99	420
WALKING UPSTAIRS	0.98	0.97	0.97	471

avg / total 0.97 0.97 0.97 2947

```
In [ ]:
print grid search attributes(lr svc grid results['model'])
    Best Estimator |
LinearSVC(C=8, class weight=None, dual=True, fit intercept=True,
    intercept_scaling=1, loss='squared_hinge', max_iter=1000,
    multi class='ovr', penalty='12', random state=None, tol=5e-05,
    verbose=0)
| Best parameters |
_____
Parameters of best estimator :
{'C': 8}
| No of CrossValidation sets |
Total numbre of cross validation sets: 3
_____
| Best Score |
_____
Average Cross Validate scores of best estimator :
0.9465451577801959
```

4.4Kernel SVM with GridSearch



| Classifiction Report |

	precision	recall	fl-score	support				
LAYING	1.00	1.00	1.00	537				
SITTING	0.97	0.90	0.93	491				
STANDING	0.92	0.98	0.95	532				
WALKING	0.96	0.99	0.97	496				
WALKING DOWNSTAIRS	0.99	0.95	0.97	420				
WALKING_UPSTAIRS	0.95	0.96	0.95	471				
avg / total	0.96	0.96	0.96	2947				

In []:

```
print_grid_search_attributes(rbf_svm_grid_results['model'])

Best Estimator

SVC(C=16, cache_size=200, class_weight=None, coef0=0.0, decision_function_shape='ovr', degree=3, gamma=0.0078125, kernel='rbf', max_iter=-1, probability=False, random_state=None, shrinking=True, tol=0.001, verbose=False)

Best parameters
```

```
Parameters of best estimator :
{'C': 16, 'gamma': 0.0078125}
_____
| No of CrossValidation sets |
Total numbre of cross validation sets: 3
Best Score
-----
Average Cross Validate scores of best estimator :
 0.9440968443960827
4.5Decision Trees with GridSearchCV
In [ ]:
from sklearn.tree import DecisionTreeClassifier
parameters = {'max depth':np.arange(3,10,2)}
dt = DecisionTreeClassifier()
dt_grid = GridSearchCV(dt,param_grid=parameters, n_jobs=-1)
dt_grid_results = perform_model(dt_grid, X_train, y_train, X_test, y_test, class_labels=labels)
print_grid_search_attributes(dt_grid_results['model'])
training the model..
Done
training_time(HH:MM:SS.ms) - 0:00:19.476858
Predicting test data
Done
testing time(HH:MM:SS:ms) - 0:00:00.012858
_____
| Accuracy |
   0.8642687478791992
| Confusion Matrix |
[[537 0 0 0 0 0]
 [ 0 386 105 0 0 0]
[ 0 93 439 0 0 0]
[ 0 0 0 472 16 8]
[ 0 0 0 15 344 61]
                     0]
 [ 0 0 0 73 29 369]]
                                                            - 1.0
                         Normalized confusion matrix
```

1.00

0.00

LAYING

SITTING

0.00

0.00

0.21

0.00

0.00

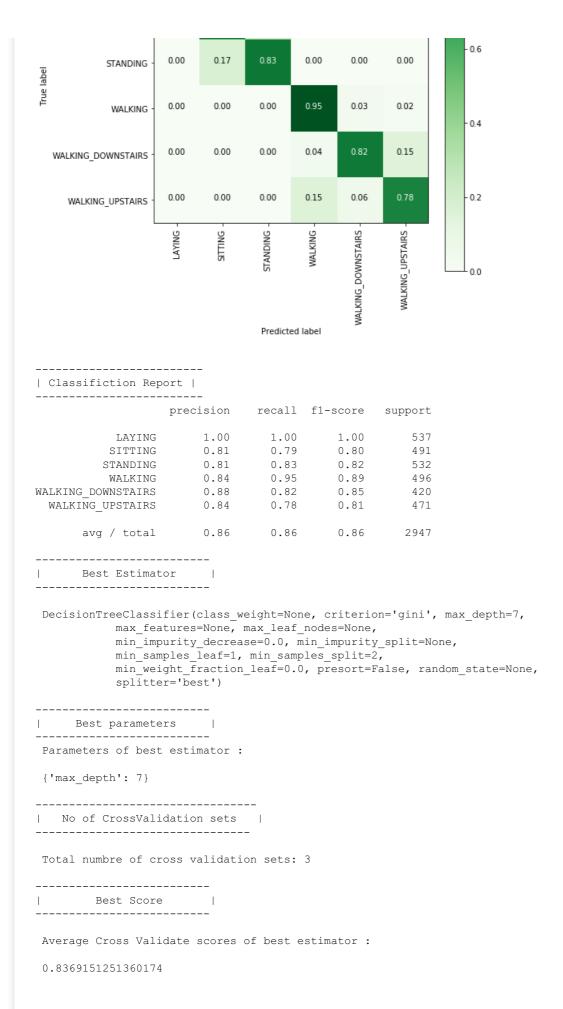
0.00

0.00

0.00

0.00

0.8



4.6Random Forest Classifier with GridSearch

```
from sklearn.ensemble import RandomForestClassifier
params = {'n_estimators': np.arange(10,201,20), 'max_depth':np.arange(3,15,2)}
rfc = RandomForestClassifier()
rfc_grid = GridSearchCV(rfc, param_grid=params, n_jobs=-1)
rfc_grid_results = perform_model(rfc_grid, X_train, y_train, X_test, y_test, class_labels=labels)
print_grid_search_attributes(rfc_grid_results['model'])
```

training the model.. Done

training time(HH:MM:SS.ms) - 0:06:22.775270

Predicting test data Done

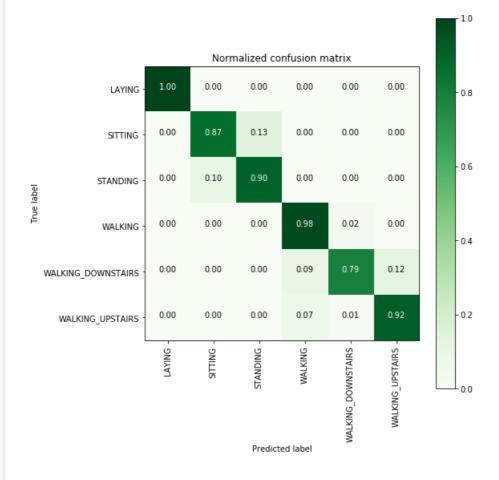
testing time(HH:MM:SS:ms) - 0:00:00.025937

| Accuracy |

0.9131319986426875

| Confusion Matrix |

[[537 0 0 0 0 0 0] [0 427 64 0 0 0] [0 52 480 0 0 0] [0 0 0 484 10 2] [0 0 0 38 332 50] [0 0 0 34 6 431]]



| Classifiction Report |

```
precision recall f1-score support
LAYING 1.00 1.00 1.00 SITTING 0.89 0.87 0.88 STANDING 0.88 0.90 0.89 WALKING 0.87 0.98 0.92 WALKING_DOWNSTAIRS 0.95 0.79 0.86 WALKING_UPSTAIRS 0.89 0.92 0.90
                                                                                                                                                                                           537
                                                                                                                                                                                                 491
                                                                                                                                                                                            532
                                                                                                                                                                                           496
                                                                                                                                                                                              471
                                                                                  0.92
                                                                                                                     0.91
                                                                                                                                                     0.91
                        avg / total
                                                                                                                                                                                          2947
 | Best Estimator |
    {\tt RandomForestClassifier\,(bootstrap=True,\ class\_weight=None,\ criterion='gini',\ class\_weight=None,\ class\_weight=None,\ class\_weight=None,\ class\_weight=None,\ class\_weight=None,\ class\_weight=None,\ class\_we
                                         max depth=7, max features='auto', max leaf nodes=None,
                                         min impurity decrease=0.0, min impurity split=None,
                                         min_samples_leaf=1, min_samples_split=2,
                                         min weight fraction leaf=0.0, n estimators=70, n jobs=1,
                                          oob_score=False, random_state=None, verbose=0,
                                          warm_start=False)
  _____
                Best parameters
    -----
    Parameters of best estimator :
    {'max depth': 7, 'n estimators': 70}
  | No of CrossValidation sets
   Total numbre of cross validation sets: 3
 | Best Score |
    Average Cross Validate scores of best estimator :
    0.9141730141458106
```

4.7Gradient Boosted Decision Trees With GridSearch

In []:

| Accuracy |

```
gbdt_grid_results = perform_model(gbdt_grid, X_train, y_train, X_print_grid_search_attributes(gbdt_grid_results['model'])

training the model..
Done

training_time(HH:MM:SS.ms) - 0:28:03.653432

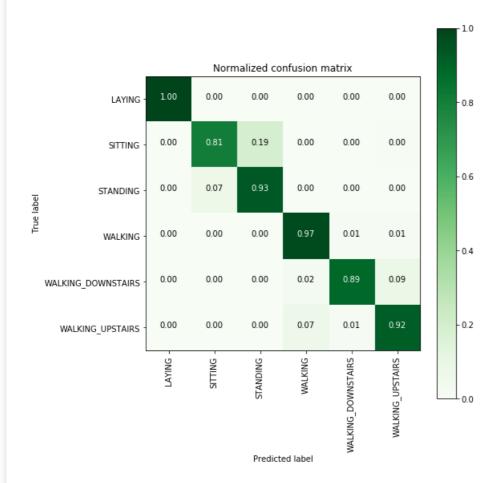
Predicting test data
Done

testing time(HH:MM:SS:ms) - 0:00:00.058843
```

0.9222938581608415

| Confusion Matrix |

[[537	' () () () (0]
[0	396	93	0	0	2]
[0	37	495	0	0	0]
[0	0	0	483	7	6]
[0	0	0	10	374	36]
[0	1	0	31	6	433]]



| Classifiction Report |

	precision	recall	f1-score	support				
LAYING SITTING	1.00 0.91	1.00	1.00	537 491				
STANDING	0.84	0.93	0.88	532				
WALKING WALKING_DOWNSTAIRS	0.92 0.97	0.97 0.89	0.95 0.93	496 420				
WALKING_UPSTAIRS	0.91	0.92	0.91	471				
avg / total	0.92	0.92	0.92	2947				

| Best Estimator |

GradientBoostingClassifier(criterion='friedman mse', init=None, learning_rate=0.1, loss='deviance', max_depth=5, max_features=None, max_leaf_nodes=None, min_impurity_decrease=0.0, min_impurity_split=None, min_samples_leaf=1, min_samples_split=2, min_weight_fraction_leaf=0.0, n_estimators=140, presort='auto', random state=None, subsample=1.0, verbose=0, warm start=False)

4.8Comparing all models

In []:

```
Accuracy Error')
print('\n
print('
                        _____
                                    ----')
                                    {:.04}%'.format(log_reg_grid_results['accuracy'] * 100,\
print('Logistic Regression : {:.04}%
                                            100-(log_reg_grid_results['accuracy'] * 100)))
print('Linear SVC : {:.04}% '.format(lr_svc_grid_results['accuracy'] * 100,\
                                                 100-(lr svc grid results['accuracy'] * 100)
print('rbf SVM classifier : {:.04}%
                                    {:.04}% '.format(rbf_svm_grid_results['accuracy'] * 100,\
                                                 100-(rbf svm grid results['accuracy'] * 1
))))
print('DecisionTree : {:.04}%
                                    {:.04}% '.format(dt grid results['accuracy'] * 100,\
                                                 100-(dt grid results['accuracy'] * 100)))
print('Random Forest : {:.04}% '.format(rfc grid results['accuracy'] * 100,\
                                                    100-(rfc_grid_results['accuracy'] * 100)
print('GradientBoosting DT : {:.04}% '.format(rfc grid results['accuracy'] * 100,\
                                                 100-(rfc grid results['accuracy'] * 100)))
```

```
Logistic Regression: 96.27% 3.733% Linear SVC : 96.61% 3.393% rbf SVM classifier: 96.27% 3.733% DecisionTree: 86.43% 13.57% Random Forest: 91.31% 8.687% GradientBoosting DT: 91.31% 8.687%
```

Accuracy

Error

5.Deep Learning model

In [1]:

```
# Activities are the class labels
# It is a 6 class classification
ACTIVITIES = {
    0: 'WALKING',
    1: 'WALKING_UPSTAIRS',
    2: 'WALKING_DOWNSTAIRS',
    3: 'SITTING',
    4: 'STANDING',
    5: 'LAYING',
}
```

```
In [2]:

def confusion_matrix(y_true, y_pred):
    y_true = pd.Series(ACTIVITIES[y] for y in np.argmax(y_true, axis=1))
    y_pred = pd.Series(ACTIVITIES[y] for y in np.argmax(y_pred, axis=1))

return pd.crosstab(Y_true, Y_pred, rownames=['True'], colnames=['Pred'])
```

5.1 Loading the data:

• raw signals is in inertial Signals folder of train and test

```
In [3]:
```

```
import os
import pandas as pd
import numpy as np
```

In [4]:

```
# Raw data signals
SIGNALS = [
    "body_acc_x",
    "body_acc_y",
    "body_acc_z",
    "body_gyro_x",
    "body_gyro_z",
    "body_gyro_z",
    "total_acc_x",
    "total_acc_y",
    "total_acc_z"
]
```

In [9]:

```
# Utility function to read the data from csv file
def _read_csv(filename):
    return pd.read_csv(filename, delim_whitespace=True, header=None)

# Utility function to load the load
def load_signals(subset):
    signals_data = []
    for signal in SIGNALS:
        filename = f'{subset}/Inertial Signals/{signal}_{subset}.txt'
    signals_data.append(np.array(_read_csv(filename)))
    # Transpose is used to change the dimensionality of the output,
    # aggregating the signals by combination of sample/timestep.
    # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
    return np.transpose(signals_data, (1, 2, 0))
```

In [10]:

```
def load_y(subset):
    filename = f'{subset}/y_{subset}.txt'
    print(filename)
    y = _read_csv(filename)[0]
    return np.array(pd.get_dummies(y))
```

In [11]:

```
def load_data():
    X_train, X_test = load_signals('train'), load_signals('test')
    y_train, y_test = load_y('train'), load_y('test')
    return X_train, X_test, y_train, y_test
```

In [12]:

```
|X train, X test, y train, y test = load data()
print(X_train.shape)
print(y_train.shape)
print(X test.shape)
print(y_test.shape)
train/y train.txt
test/y_test.txt
(7352, 128, 1)
(7352, 6)
(2947, 128, 1)
(2947, 6)
In [ ]:
len(set([tuple(category) for category in y_train]))
Out[]:
In [13]:
timesteps = len(X train[0])
input_dim = len(X_train[0][0])
num_class = len(set([tuple(category) for category in y_train]))
print(timesteps)
print(input_dim)
print(num_class)
128
1
6
In [ ]:
# Initializing parameters
epochs = 30
batch_size = 16
n hidden = 32
In [ ]:
model = Sequential()
model.add(LSTM(n_hidden, input_shape=(timesteps, input_dim)))
model.add(Dropout(0.5))
model.add(Dense(num_class, activation='sigmoid'))
model.summary()
Model: "sequential_3"
Layer (type)
                              Output Shape
                                                         Param #
1stm 2 (LSTM)
                                                         5376
                              (None, 32)
dropout_2 (Dropout)
                              (None, 32)
                                                         0
                                                         198
dense (Dense)
                              (None, 6)
Total params: 5,574
Trainable params: 5,574
Non-trainable params: 0
In [ ]:
# Compiling the model
model.compile(loss='categorical_crossentropy',
```

optimizer='rmsprop',
metrics=['accuracy'])

```
In [ ]:
```

```
# Training the model
model.fit(X train,
      y_train,
     batch size=batch size,
     validation data=(X_test, y_test),
      epochs=epochs)
Epoch 1/30
oss: 1.1176 - val accuracy: 0.4676
Epoch 2/30
oss: 0.9394 - val accuracy: 0.5779
Epoch 3/30
460/460 [============ ] - 21s 46ms/step - loss: 0.8613 - accuracy: 0.6175 - val 1
oss: 0.8312 - val_accuracy: 0.6257
Epoch 4/30
oss: 0.8149 - val accuracy: 0.6220
Epoch 5/30
460/460 [=========== ] - 21s 46ms/step - loss: 0.7102 - accuracy: 0.6674 - val 1
oss: 0.7966 - val accuracy: 0.6200
Epoch 6/30
oss: 0.8417 - val accuracy: 0.6586
Epoch 7/30
oss: 0.6999 - val accuracy: 0.7333
Epoch 8/30
460/460 [============= ] - 21s 46ms/step - loss: 0.5186 - accuracy: 0.8164 - val 1
oss: 0.5982 - val accuracy: 0.7957
Epoch 9/30
oss: 0.6864 - val accuracy: 0.7374
Epoch 10/30
460/460 [=========== ] - 21s 46ms/step - loss: 0.3793 - accuracy: 0.8841 - val 1
oss: 0.3570 - val accuracy: 0.8836
Epoch 11/30
460/460 [============ ] - 21s 46ms/step - loss: 0.3210 - accuracy: 0.9045 - val 1
oss: 0.5727 - val accuracy: 0.8266
Epoch 12/30
460/460 [============= ] - 21s 46ms/step - loss: 0.3013 - accuracy: 0.9135 - val 1
oss: 0.4094 - val accuracy: 0.8785
Epoch 13/30
oss: 0.3376 - val accuracy: 0.8948
Epoch 14/30
460/460 [============== ] - 23s 50ms/step - loss: 0.2646 - accuracy: 0.9193 - val 1
oss: 0.3875 - val_accuracy: 0.8738
Epoch 15/30
oss: 0.3625 - val accuracy: 0.8806
Epoch 16/30
oss: 0.3929 - val accuracy: 0.8867
Epoch 17/30
oss: 0.4756 - val accuracy: 0.8707
Epoch 18/30
oss: 0.3333 - val accuracy: 0.8992
Epoch 19/30
oss: 0.2877 - val_accuracy: 0.9131
Epoch 20/30
460/460 [============= ] - 24s 52ms/step - loss: 0.1788 - accuracy: 0.9408 - val 1
oss: 0.3716 - val accuracy: 0.9077
Epoch 21/30
460/460 [============ ] - 24s 52ms/step - loss: 0.1872 - accuracy: 0.9403 - val 1
oss: 0.4027 - val_accuracy: 0.9006
Epoch 22/30
```

460/460 [============] - 24s 52ms/step - loss: 0.1932 - accuracy: 0.9406 - val 1

```
oss: U.2458 - val accuracy: U.9158
Epoch 23/30
oss: 0.2768 - val accuracy: 0.9148
Epoch 24/30
460/460 [============= ] - 24s 52ms/step - loss: 0.1825 - accuracy: 0.9421 - val 1
oss: 0.3055 - val accuracy: 0.9074
Epoch 25/30
oss: 0.3111 - val_accuracy: 0.9111
Epoch 26/30
oss: 0.3808 - val accuracy: 0.9023
Epoch 27/30
oss: 0.3045 - val accuracy: 0.9199
Epoch 28/30
460/460 [============= ] - 24s 51ms/step - loss: 0.1713 - accuracy: 0.9460 - val 1
oss: 0.2625 - val accuracy: 0.9189
Epoch 29/30
oss: 0.3111 - val_accuracy: 0.9111
Epoch 30/30
oss: 0.4735 - val accuracy: 0.9063
Out[]:
<tensorflow.python.keras.callbacks.History at 0x7f22725cb898>
```

Task:

- Hyperparameter tuning done using keras tuner --> https://www.youtube.com/watch?v=vvC15I4CY1Q&t=1428s
- Different dropout rate (higher dropout rate upto 0.7)
- Two layer lstm

```
In [15]:
```

```
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense, LSTM, Dropout
```

In [16]:

```
from kerastuner.tuners import RandomSearch
from kerastuner.engine.hyperparameters import HyperParameters
```

In [20]:

```
# Initializing parameters
epochs = 50
batch_size = 64
```

In [30]:

```
#https://neurospace.io/blog/2019/04/using-talos-for-feature-hyperparameter-optimization/
def build_model(hp):
    model = Sequential()

    #layer 1
    model.add(LSTM(hp.Int('lstm_layer_1', min_value=32, max_value=512, step=16), input_shape=(times teps, input_dim), return_sequences=True))
    model.add(Dropout(hp.Choice('dropout_1', values=[0.3, 0.4, 0.5])))

#layer 2
    model.add(LSTM(hp.Int('lstm_layer_2', min_value=32, max_value=512, step=16)))
    model.add(Dropout(hp.Choice('dropout_2', values=[0.3, 0.4, 0.5])))

#output
    model.add(Dense(num_class, activation='sigmoid'))
```

In [20]:

```
tuner= RandomSearch(build_model, objective='val_accuracy', max_trials=3, executions_per_trial=1, di
rectory='output', project_name='Human Activity Detection')
tuner.search(X_train, y_train, epochs=epochs, batch_size=batch_size, validation_data=(X_test, y_test))
```

```
Epoch 1/50
230/230 [============ ] - 13s 57ms/step - loss: 1.3081 - accuracy: 0.4950 - val 1
oss: 0.9772 - val accuracy: 0.5779
Epoch 2/50
230/230 [============== ] - 12s 53ms/step - loss: 0.9099 - accuracy: 0.5773 - val 1
oss: 0.8541 - val accuracy: 0.5972
Epoch 3/50
230/230 [============ ] - 12s 54ms/step - loss: 0.7999 - accuracy: 0.6153 - val 1
oss: 0.8225 - val accuracy: 0.6176
Epoch 4/50
oss: 0.9007 - val_accuracy: 0.5422
Epoch 5/50
230/230 [============ ] - 12s 54ms/step - loss: 0.8383 - accuracy: 0.5703 - val_1
oss: 0.8283 - val accuracy: 0.6013
Epoch 6/50
230/230 [============ ] - 12s 54ms/step - loss: 0.7633 - accuracy: 0.6183 - val 1
oss: 0.8030 - val accuracy: 0.6037
Epoch 7/50
oss: 0.7668 - val accuracy: 0.6383
Epoch 8/50
oss: 0.7705 - val accuracy: 0.6200
Epoch 9/50
oss: 0.7579 - val accuracy: 0.6230
Epoch 10/50
230/230 [============= ] - 12s 54ms/step - loss: 0.7088 - accuracy: 0.6415 - val 1
oss: 0.8226 - val accuracy: 0.6233
Epoch 11/50
230/230 [============ ] - 12s 53ms/step - loss: 0.7661 - accuracy: 0.6143 - val 1
oss: 0.7549 - val accuracy: 0.6074
Epoch 12/50
230/230 [============ ] - 12s 53ms/step - loss: 0.8967 - accuracy: 0.6088 - val 1
oss: 0.8533 - val accuracy: 0.5925
Epoch 13/50
230/230 [============= ] - 12s 53ms/step - loss: 0.7232 - accuracy: 0.6468 - val 1
oss: 0.8306 - val accuracy: 0.6030
Epoch 14/50
230/230 [============= ] - 12s 54ms/step - loss: 0.6766 - accuracy: 0.6574 - val 1
oss: 0.8190 - val_accuracy: 0.5989
Epoch 15/50
230/230 [=================== ] - 12s 54ms/step - loss: 0.7740 - accuracy: 0.5894 - val 1
oss: 0.8858 - val_accuracy: 0.5670
Epoch 16/50
230/230 [============= ] - 12s 53ms/step - loss: 0.7139 - accuracy: 0.6181 - val 1
oss: 0.7471 - val accuracy: 0.6101
Epoch 17/50
230/230 [============ ] - 12s 53ms/step - loss: 0.6634 - accuracy: 0.6572 - val 1
oss: 0.7189 - val accuracy: 0.6159
Epoch 18/50
230/230 [============ ] - 12s 53ms/step - loss: 0.6191 - accuracy: 0.6657 - val 1
oss: 0.7080 - val accuracy: 0.6132
Epoch 19/50
230/230 [============= ] - 12s 53ms/step - loss: 0.5959 - accuracy: 0.6746 - val 1
oss: 0.9856 - val_accuracy: 0.5860
Epoch 20/50
230/230 [============ ] - 12s 53ms/step - loss: 0.6627 - accuracy: 0.6638 - val 1
oss: 0.9546 - val accuracy: 0.5670
Epoch 21/50
```

```
230/230 [============ ] - 12s 53ms/step - loss: 0.6087 - accuracy: 0.6929 - val 1
oss: 1.0976 - val accuracy: 0.5843
Epoch 22/50
230/230 [============ ] - 12s 53ms/step - loss: 0.6273 - accuracy: 0.6861 - val 1
oss: 0.8144 - val accuracy: 0.6607
Epoch 23/50
230/230 [============ ] - 12s 53ms/step - loss: 0.5633 - accuracy: 0.7221 - val 1
oss: 0.7328 - val accuracy: 0.7027
Epoch 24/50
oss: 0.6887 - val accuracy: 0.7190
Epoch 25/50
oss: 0.6755 - val_accuracy: 0.7272
Epoch 26/50
230/230 [============ ] - 12s 53ms/step - loss: 0.4879 - accuracy: 0.7913 - val 1
oss: 0.6414 - val_accuracy: 0.7397
Epoch 27/50
230/230 [============ ] - 12s 53ms/step - loss: 0.4602 - accuracy: 0.7899 - val 1
oss: 0.6861 - val_accuracy: 0.7316
Epoch 28/50
230/230 [============ ] - 12s 53ms/step - loss: 0.4125 - accuracy: 0.7994 - val 1
oss: 0.6284 - val_accuracy: 0.7808
Epoch 29/50
230/230 [============ ] - 12s 53ms/step - loss: 0.4186 - accuracy: 0.8003 - val_1
oss: 0.6035 - val accuracy: 0.7893
Epoch 30/50
230/230 [============= ] - 12s 53ms/step - loss: 0.5598 - accuracy: 0.7542 - val 1
oss: 0.6139 - val accuracy: 0.7489
Epoch 31/50
230/230 [============ ] - 12s 53ms/step - loss: 0.4244 - accuracy: 0.7998 - val 1
oss: 0.5173 - val accuracy: 0.7845
Epoch 32/50
230/230 [============ ] - 12s 53ms/step - loss: 0.3758 - accuracy: 0.8162 - val 1
oss: 0.5978 - val accuracy: 0.7754
Epoch 33/50
230/230 [============ ] - 12s 53ms/step - loss: 0.3638 - accuracy: 0.8161 - val 1
oss: 0.7298 - val accuracy: 0.7445
Epoch 34/50
230/230 [============= ] - 12s 53ms/step - loss: 0.3501 - accuracy: 0.8214 - val 1
oss: 0.5711 - val accuracy: 0.8005
Epoch 35/50
230/230 [============ ] - 12s 53ms/step - loss: 0.3659 - accuracy: 0.8179 - val 1
oss: 0.5366 - val accuracy: 0.8195
Epoch 36/50
230/230 [============ ] - 12s 53ms/step - loss: 0.3308 - accuracy: 0.8626 - val 1
oss: 0.5754 - val_accuracy: 0.7822
Epoch 37/50
230/230 [========================== ] - 12s 53ms/step - loss: 0.3714 - accuracy: 0.8327 - val 1
oss: 0.4618 - val_accuracy: 0.8646
Epoch 38/50
230/230 [============= ] - 12s 53ms/step - loss: 0.2851 - accuracy: 0.8859 - val 1
oss: 0.4085 - val_accuracy: 0.8873
Epoch 39/50
230/230 [============ ] - 12s 53ms/step - loss: 0.3204 - accuracy: 0.8871 - val 1
oss: 0.4200 - val accuracy: 0.8812
Epoch 40/50
230/230 [============ ] - 12s 53ms/step - loss: 0.2776 - accuracy: 0.9072 - val 1
oss: 0.4033 - val accuracy: 0.8839
Epoch 41/50
230/230 [============ ] - 12s 53ms/step - loss: 0.2204 - accuracy: 0.9302 - val 1
oss: 0.4260 - val_accuracy: 0.8768
Epoch 42/50
oss: 0.4872 - val accuracy: 0.8653
Epoch 43/50
230/230 [============= ] - 12s 53ms/step - loss: 0.1964 - accuracy: 0.9388 - val 1
oss: 0.3835 - val accuracy: 0.8884
Epoch 44/50
230/230 [============ ] - 12s 53ms/step - loss: 0.1640 - accuracy: 0.9403 - val 1
oss: 0.3417 - val accuracy: 0.9023
Epoch 45/50
oss: 0.7611 - val accuracy: 0.8280
Epoch 46/50
230/230 [============ ] - 12s 53ms/step - loss: 0.1627 - accuracy: 0.9495 - val 1
```

oss. 0 4056 - val accuracy. 0 8985

Trial complete

Trial summary

|-Trial ID: f0a70ad8e7363c1a476406c77faff3c0

|-Score: 0.9022734761238098

|-Best step: 0

Hyperparameters:

|-dropout_1: 0.7

|-dropout_2: 0.5

|-lstm_layer_1: 32

|-lstm layer 2: 32

```
Epoch 1/50
oss: 1.0084 - val accuracy: 0.6179
Epoch 2/50
230/230 [============ ] - 14s 61ms/step - loss: 0.8583 - accuracy: 0.6227 - val 1
oss: 0.8091 - val accuracy: 0.6407
Epoch 3/50
230/230 [============ ] - 14s 61ms/step - loss: 0.7285 - accuracy: 0.6594 - val 1
oss: 0.6891 - val accuracy: 0.6325
Epoch 4/50
230/230 [============ ] - 14s 61ms/step - loss: 0.7240 - accuracy: 0.6733 - val 1
oss: 0.6906 - val accuracy: 0.7173
Epoch 5/50
230/230 [============= ] - 14s 61ms/step - loss: 0.5296 - accuracy: 0.7692 - val 1
oss: 0.5057 - val accuracy: 0.7570
Epoch 6/50
230/230 [============ ] - 14s 61ms/step - loss: 0.4543 - accuracy: 0.7715 - val 1
oss: 0.4493 - val accuracy: 0.7560
Epoch 7/50
230/230 [============= ] - 14s 61ms/step - loss: 0.3433 - accuracy: 0.8013 - val 1
oss: 0.3766 - val_accuracy: 0.7665
Epoch 8/50
230/230 [============= ] - 14s 61ms/step - loss: 0.3124 - accuracy: 0.8143 - val 1
oss: 0.5161 - val_accuracy: 0.7628
Epoch 9/50
230/230 [============ ] - 14s 61ms/step - loss: 0.2890 - accuracy: 0.8268 - val 1
oss: 0.3958 - val_accuracy: 0.7689
Epoch 10/50
230/230 [============ ] - 14s 61ms/step - loss: 0.2756 - accuracy: 0.8418 - val 1
oss: 0.4547 - val accuracy: 0.7530
Epoch 11/50
oss: 0.3819 - val accuracy: 0.9043
Epoch 12/50
```

```
IID UIMD, DOOD TODD. U.ZOIU GCCGIGCY. U.JEUU VAI I
oss: 0.3579 - val accuracy: 0.9002
Epoch 13/50
230/230 [============= ] - 14s 60ms/step - loss: 0.1883 - accuracy: 0.9449 - val 1
oss: 0.2688 - val accuracy: 0.9074
Epoch 14/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1619 - accuracy: 0.9460 - val 1
oss: 0.2500 - val accuracy: 0.9091
Epoch 15/50
oss: 0.2851 - val accuracy: 0.9084
Epoch 16/50
230/230 [=============== ] - 14s 61ms/step - loss: 0.1764 - accuracy: 0.9418 - val 1
oss: 0.2305 - val accuracy: 0.9145
Epoch 17/50
oss: 0.2280 - val accuracy: 0.9158
Epoch 18/50
oss: 0.9861 - val_accuracy: 0.7665
Epoch 19/50
230/230 [============== ] - 14s 61ms/step - loss: 0.1743 - accuracy: 0.9415 - val 1
oss: 0.1807 - val accuracy: 0.9308
Epoch 20/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1286 - accuracy: 0.9523 - val 1
oss: 0.2010 - val accuracy: 0.9253
Epoch 21/50
230/230 [============== ] - 14s 61ms/step - loss: 0.1375 - accuracy: 0.9518 - val 1
oss: 0.2790 - val_accuracy: 0.9036
Epoch 22/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1316 - accuracy: 0.9483 - val 1
oss: 0.4169 - val_accuracy: 0.8856
Epoch 23/50
oss: 0.2771 - val_accuracy: 0.9114
Epoch 24/50
230/230 [============== ] - 14s 61ms/step - loss: 0.1427 - accuracy: 0.9486 - val 1
oss: 0.2313 - val accuracy: 0.9179
Epoch 25/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1206 - accuracy: 0.9523 - val 1
oss: 0.2301 - val accuracy: 0.9189
Epoch 26/50
230/230 [============ ] - 14s 61ms/step - loss: 0.1751 - accuracy: 0.9404 - val 1
oss: 0.3006 - val accuracy: 0.9080
Epoch 27/50
oss: 0.2986 - val accuracy: 0.9145
Epoch 28/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1774 - accuracy: 0.9418 - val 1
oss: 0.2787 - val accuracy: 0.9128
Epoch 29/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1529 - accuracy: 0.9430 - val 1
oss: 0.2200 - val accuracy: 0.9186
Epoch 30/50
oss: 0.1911 - val accuracy: 0.9287
Epoch 31/50
oss: 0.2763 - val accuracy: 0.9162
Epoch 32/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1500 - accuracy: 0.9476 - val 1
oss: 0.2310 - val_accuracy: 0.9250
Epoch 33/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1508 - accuracy: 0.9465 - val 1
oss: 0.2585 - val_accuracy: 0.9141
Epoch 34/50
oss: 0.2451 - val_accuracy: 0.9135
Epoch 35/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1383 - accuracy: 0.9471 - val 1
oss: 0.2398 - val accuracy: 0.9196
Epoch 36/50
oss: 0.2289 - val accuracy: 0.9114
Epoch 37/50
oss: 0.2340 - val accuracy: 0.9226
```

Enoch 38/50

```
Thorit 20/20
230/230 [============ ] - 14s 61ms/step - loss: 0.1270 - accuracy: 0.9521 - val_1
oss: 0.2868 - val accuracy: 0.9155
Epoch 39/50
oss: 0.2366 - val accuracy: 0.9247
Epoch 40/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1360 - accuracy: 0.9498 - val 1
oss: 0.2306 - val accuracy: 0.9199
Epoch 41/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1132 - accuracy: 0.9558 - val 1
oss: 0.2246 - val accuracy: 0.9233
Epoch 42/50
230/230 [============= ] - 14s 60ms/step - loss: 0.1286 - accuracy: 0.9517 - val 1
oss: 0.4619 - val accuracy: 0.8911
Epoch 43/50
oss: 0.3329 - val accuracy: 0.9196
Epoch 44/50
230/230 [============ ] - 14s 61ms/step - loss: 0.1037 - accuracy: 0.9565 - val 1
oss: 0.3532 - val accuracy: 0.9135
Epoch 45/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1131 - accuracy: 0.9584 - val 1
oss: 0.2360 - val_accuracy: 0.9213
Epoch 46/50
oss: 0.3185 - val accuracy: 0.9135
Epoch 47/50
230/230 [============== ] - 14s 60ms/step - loss: 0.1060 - accuracy: 0.9582 - val 1
oss: 0.2109 - val_accuracy: 0.9186
Epoch 48/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1081 - accuracy: 0.9553 - val 1
oss: 0.2840 - val_accuracy: 0.9128
Epoch 49/50
230/230 [============= ] - 14s 61ms/step - loss: 0.1097 - accuracy: 0.9548 - val 1
oss: 0.3230 - val accuracy: 0.9087
Epoch 50/50
230/230 [============ ] - 14s 61ms/step - loss: 0.1105 - accuracy: 0.9551 - val 1
oss: 0.3373 - val accuracy: 0.9070
```

Trial complete

Trial summary

|-Trial ID: 9310da732da59560df13dd738cdd4932

|-Score: 0.9307770729064941

|-Best step: 0

Hyperparameters:

|-dropout_1: 0.3

|-dropout_2: 0.3

|-lstm layer 1:96

|-lstm_layer_2: 32

6. Best Model

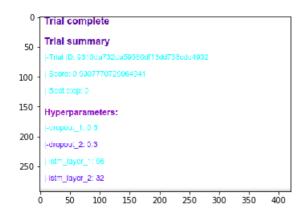
```
In [2]:
```

```
import cv2
import matplotlib.pyplot as plt
%matplotlib inline

img = cv2.imread('/home/prem-kumar/Documents/Screenshot from 2020-06-17 12-51-58.png')
plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))
```

Out[2]:

<matplotlib.image.AxesImage at 0x7fe40ad0d190>



Note:

• I took a screenshot where i got over 93.07% accuracy.

In [36]:

```
best_model = tuner.get_best_models(num_models=1)[0]
```

Model: "sequential 4"

Layer (type)	Output Shape	Param #
lstm_4 (LSTM)	(None, 128, 96)	37632
dropout_4 (Dropout)	(None, 128, 96)	0
lstm_5 (LSTM)	(None, 32)	16512
dropout_5 (Dropout)	(None, 32)	0
dense_2 (Dense)	(None, 6)	198
Total params: 54,342 Trainable params: 54,342 Non-trainable params: 0		

Summary:

In [3]:

```
from prettytable import PrettyTable
x = PrettyTable()
x.field_names = ['Model', 'layer', 'No of LSTM units', 'Dropout Rate', 'Final Accuracy']
x.add_row(['LSTM', 'layer-1', '96', '0.3', '-'])
```