

## CHAPTER 7

# INTERRUPT AND EXCEPTION HANDLING

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This chapter describes the interrupt and exception-handling mechanism when operating in protected mode on an Intel 64 or IA-32 processor. Most of the information provided here also applies to interrupt and exception mechanisms used in real-address, virtual-8086 mode, and 64-bit mode.

Chapter 22, “8086 Emulation,” describes information specific to interrupt and exception mechanisms in real-address and virtual-8086 mode. Section 7.14, “Exception and Interrupt Handling in 64-bit Mode,” describes information specific to interrupt and exception mechanisms in IA-32e mode and 64-bit sub-mode.

## 7.1 INTERRUPT AND EXCEPTION OVERVIEW

Interrupts and exceptions are events that indicate that a condition exists somewhere in the system, the processor, or within the currently executing program or task that requires the attention of a processor. They typically result in a forced transfer of execution from the currently running program or task to a special software routine or task called an interrupt handler or an exception handler. The action taken by a processor in response to an interrupt or exception is referred to as servicing or handling the interrupt or exception.

Interrupts occur at random times during the execution of a program, in response to signals from hardware. System hardware uses interrupts to handle events external to the processor, such as requests to service peripheral devices. Software can also generate interrupts by executing the `INT n` instruction.

Exceptions occur when the processor detects an error condition while executing an instruction, such as division by zero. The processor detects a variety of error conditions including protection violations, page faults, and internal machine faults. The machine-check architecture of the Pentium 4, Intel Xeon, P6 family, and Pentium processors also permits a machine-check exception to be generated when internal hardware errors and bus errors are detected.

When an interrupt is received or an exception is detected, the currently running procedure or task is suspended while the processor executes an interrupt or exception handler. When execution of the handler is complete, the processor resumes execution of the interrupted procedure or task. The resumption of the interrupted procedure or task happens without loss of program continuity, unless recovery from an exception was not possible or an interrupt caused the currently running program to be terminated.

This chapter describes the processor’s interrupt and exception-handling mechanism, when operating in protected mode. A description of the exceptions and the conditions that cause them to be generated is given at the end of this chapter.

## 7.2 EXCEPTION AND INTERRUPT VECTORS

To aid in handling exceptions and interrupts, each architecturally defined exception and each interrupt condition requiring special handling by the processor is assigned a unique identification number, called a vector number. The processor uses the vector number assigned to an exception or interrupt as an index into the interrupt descriptor table (IDT). The table provides the entry point to an exception or interrupt handler (see Section 7.10, “Interrupt Descriptor Table (IDT)”).

The allowable range for vector numbers is 0 to 255. Vector numbers in the range 0 through 31 are reserved by the Intel 64 and IA-32 architectures for architecture-defined exceptions and interrupts. Not all of the vector numbers in this range have a currently defined function. The unassigned vector numbers in this range are reserved. Do not use the reserved vector numbers.

Vector numbers in the range 32 to 255 are designated as user-defined interrupts and are not reserved by the Intel 64 and IA-32 architecture. These interrupts are generally assigned to external I/O devices to enable those devices to send interrupts to the processor through one of the external hardware interrupt mechanisms (see Section 7.3, “Sources of Interrupts”).

Table 7-1 shows vector number assignments for architecturally defined exceptions and for the NMI interrupt. This table gives the exception type (see Section 7.5, “Exception Classifications”) and indicates whether an error code is saved on the stack for the exception. The source of each predefined exception and the NMI interrupt is also given.

## 7.3 SOURCES OF INTERRUPTS

The processor receives interrupts from two sources:

- External (hardware generated) interrupts.
- Software-generated interrupts.

### 7.3.1 External Interrupts

External interrupts are received through pins on the processor or through the local APIC. The primary interrupt pins on Pentium 4, Intel Xeon, P6 family, and Pentium processors are the LINT[1:0] pins, which are connected to the local APIC (see Chapter 12, “Advanced Programmable Interrupt Controller (APIC)”). When the local APIC is enabled, the LINT[1:0] pins can be programmed through the APIC’s local vector table (LVT) to be associated with any of the processor’s exception or interrupt vectors.

When the local APIC is global/hardware disabled, these pins are configured as INTR and NMI pins, respectively. Asserting the INTR pin signals the processor that an external interrupt has occurred. The processor reads from the system bus the interrupt vector number provided by an external interrupt controller, such as an 8259A (see Section 7.2, “Exception and Interrupt Vectors”). Asserting the NMI pin signals a non-maskable interrupt (NMI), which is assigned to interrupt vector 2.

**Table 7-1. Protected-Mode Exceptions and Interrupts**

Vector	Mnemonic	Description	Type	Error Code	Source
0	#DE	Divide Error	Fault	No	DIV and IDIV instructions.
1	#DB	Debug Exception	Fault/ Trap	No	Instruction, data, and I/O breakpoints; single-step; and others.
2	—	NMI Interrupt	Interrupt	No	Nonmaskable external interrupt.
3	#BP	Breakpoint	Trap	No	INT3 instruction.
4	#OF	Overflow	Trap	No	INTO instruction.
5	#BR	BOUND Range Exceeded	Fault	No	BOUND instruction.
6	#UD	Invalid Opcode (Undefined Opcode)	Fault	No	UD instruction or reserved opcode.
7	#NM	Device Not Available (No Math Coprocessor)	Fault	No	Floating-point or WAIT/FWAIT instruction.
8	#DF	Double Fault	Abort	Yes (zero)	Any instruction that can generate an exception, an NMI, or an INTR.
9		Coprocessor Segment Overrun (reserved)	Fault	No	Floating-point instruction. <sup>1</sup>
10	#TS	Invalid TSS	Fault	Yes	Task switch or TSS access.
11	#NP	Segment Not Present	Fault	Yes	Loading segment registers or accessing system segments.
12	#SS	Stack-Segment Fault	Fault	Yes	Stack operations and SS register loads.
13	#GP	General Protection	Fault	Yes	Any memory reference and other protection checks.
14	#PF	Page Fault	Fault	Yes	Any memory reference.

Table 7-1. Protected-Mode Exceptions and Interrupts (Contd.)

Vector	Mnemonic	Description	Type	Error Code	Source
15	—	(Intel reserved. Do not use.)		No	
16	#MF	x87 FPU Floating-Point Error (Math Fault)	Fault	No	x87 FPU floating-point or WAIT/FWAIT instruction.
17	#AC	Alignment Check	Fault	Yes	Any data reference in memory. <sup>2</sup>
18	#MC	Machine Check	Abort	No	Error codes (if any) and source are model dependent. <sup>3</sup>
19	#XM	SIMD Floating-Point Exception	Fault	No	SSE/SSE2/SSE3 floating-point instructions <sup>4</sup>
20	#VE	Virtualization Exception	Fault	No	EPT violations <sup>5</sup>
21	#CP	Control Protection Exception	Fault	Yes	RET, IRET, RSTORSSP, and SETSSBSY instructions can generate this exception. When CET indirect branch tracking is enabled, this exception can be generated due to a missing ENDBRANCH instruction at target of an indirect call or jump.
22-31	—	Intel reserved. Do not use.			
32-255	—	User Defined (Non-reserved) Interrupts	Interrupt		External interrupt or INT <i>n</i> instruction.

**NOTES:**

- Processors after the Intel386 processor do not generate this exception.
- This exception was introduced in the Intel486 processor.
- This exception was introduced in the Pentium processor and enhanced in the P6 family processors.
- This exception was introduced in the Pentium III processor.
- This exception can occur only on processors that support the 1-setting of the “EPT-violation #VE” VM-execution control.

The processor’s local APIC is normally connected to a system-based I/O APIC. Here, external interrupts received at the I/O APIC’s pins can be directed to the local APIC through the system bus (Pentium 4, Intel Core Duo, Intel Core 2, Intel Atom, and Intel Xeon processors) or the APIC serial bus (P6 family and Pentium processors). The I/O APIC determines the vector number of the interrupt and sends this number to the local APIC. When a system contains multiple processors, processors can also send interrupts to one another by means of the system bus (Pentium 4, Intel Core Duo, Intel Core 2, Intel Atom, and Intel Xeon processors) or the APIC serial bus (P6 family and Pentium processors).

The LINT[1:0] pins are not available on the Intel486 processor and earlier Pentium processors that do not contain an on-chip local APIC. These processors have dedicated NMI and INTR pins. With these processors, external interrupts are typically generated by a system-based interrupt controller (8259A), with the interrupts being signaled through the INTR pin.

Note that several other pins on the processor can cause a processor interrupt to occur. However, these interrupts are not handled by the interrupt and exception mechanism described in this chapter. These pins include the RESET#, FLUSH#, STPCLK#, SMI#, R/S#, and INIT# pins. Whether they are included on a particular processor is implementation dependent. Pin functions are described in the data books for the individual processors. The SMI# pin is described in Chapter 33, “System Management Mode.”

## 7.3.2 Maskable Hardware Interrupts

Any external interrupt that is delivered to the processor by means of the INTR pin or through the local APIC is called a maskable hardware interrupt. Maskable hardware interrupts that can be delivered through the INTR pin include all IA-32 architecture defined interrupt vectors from 0 through 255; those that can be delivered through the local APIC include interrupt vectors 16 through 255.

The IF flag in the EFLAGS register permits all maskable hardware interrupts to be masked as a group (see Section 7.8.1, “Masking Maskable Hardware Interrupts”). Note that when interrupts 0 through 15 are delivered through the local APIC, the APIC indicates the receipt of an illegal vector.

### 7.3.3 Software-Generated Interrupts

The `INT n` instruction permits interrupts to be generated from within software by supplying an interrupt vector number as an operand. For example, the `INT 35` instruction forces an implicit call to the interrupt handler for interrupt 35.

Any of the interrupt vectors from 0 to 255 can be used as a parameter in this instruction. If the processor’s predefined NMI vector is used, however, the response of the processor will not be the same as it would be from an NMI interrupt generated in the normal manner. If vector number 2 (the NMI vector) is used in this instruction, the NMI interrupt handler is called, but the processor’s NMI-handling hardware is not activated.

Interrupts generated in software with the `INT n` instruction cannot be masked by the IF flag in the EFLAGS register.

## 7.4 SOURCES OF EXCEPTIONS

The processor receives exceptions from three sources:

- Processor-detected program-error exceptions.
- Software-generated exceptions.
- Machine-check exceptions.

### 7.4.1 Program-Error Exceptions

The processor generates one or more exceptions when it detects program errors during the execution in an application program or the operating system or executive. Intel 64 and IA-32 architectures define a vector number for each processor-detectable exception. Exceptions are classified as **faults**, **traps**, and **aborts** (see Section 7.5, “Exception Classifications”).

### 7.4.2 Software-Generated Exceptions

The `INTO`, `INT1`, `INT3`, and `BOUND` instructions permit exceptions to be generated in software. These instructions allow checks for exception conditions to be performed at points in the instruction stream. For example, `INT3` causes a breakpoint exception to be generated.

The `INT n` instruction can be used to emulate exceptions in software; but there is a limitation.<sup>1</sup> If `INT n` provides a vector for one of the architecturally-defined exceptions, the processor generates an interrupt to the correct vector (to access the exception handler) but does not push an error code on the stack. This is true even if the associated hardware-generated exception normally produces an error code. The exception handler will still attempt to pop an error code from the stack while handling the exception. Because no error code was pushed, the handler will pop off and discard the EIP instead (in place of the missing error code). This sends the return to the wrong location.

### 7.4.3 Machine-Check Exceptions

The P6 family and Pentium processors provide both internal and external machine-check mechanisms for checking the operation of the internal chip hardware and bus transactions. These mechanisms are implementation dependent. When a machine-check error is detected, the processor signals a machine-check exception (vector 18) and returns an error code.

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1. The `INT n` instruction has opcode `CD` following by an immediate byte encoding the value of *n*. In contrast, `INT1` has opcode `F1` and `INT3` has opcode `CC`.

See Chapter 7, “Interrupt 18—Machine-Check Exception (#MC),” and Chapter 17, “Machine-Check Architecture,” for more information about the machine-check mechanism.

## 7.5 EXCEPTION CLASSIFICATIONS

Exceptions are classified as **faults**, **traps**, or **aborts** depending on the way they are reported and whether the instruction that caused the exception can be restarted without loss of program or task continuity.

- **Faults** — A fault is an exception that can generally be corrected and that, once corrected, allows the program to be restarted with no loss of continuity. When a fault is reported, the processor restores the machine state to the state prior to the beginning of execution of the faulting instruction. The return address (saved contents of the CS and EIP registers) for the fault handler points to the faulting instruction, rather than to the instruction following the faulting instruction.
- **Traps** — A trap is an exception that is reported immediately following the execution of the trapping instruction. Traps allow execution of a program or task to be continued without loss of program continuity. The return address for the trap handler points to the instruction to be executed after the trapping instruction.
- **Aborts** — An abort is an exception that does not always report the precise location of the instruction causing the exception and does not allow a restart of the program or task that caused the exception. Aborts are used to report severe errors, such as hardware errors and inconsistent or illegal values in system tables.

### NOTE

One exception subset normally reported as a fault is not restartable. Such exceptions result in loss of some processor state. For example, executing a POPAD instruction where the stack frame crosses over the end of the stack segment causes a fault to be reported. In this situation, the exception handler sees that the instruction pointer (CS:EIP) has been restored as if the POPAD instruction had not been executed. However, internal processor state (the general-purpose registers) will have been modified. Such cases are considered programming errors. An application causing this class of exceptions should be terminated by the operating system.

## 7.6 PROGRAM OR TASK RESTART

To allow the restarting of program or task following the handling of an exception or an interrupt, all exceptions (except aborts) are guaranteed to report exceptions on an instruction boundary. All interrupts are guaranteed to be taken on an instruction boundary.

For fault-class exceptions, the return instruction pointer (saved when the processor generates an exception) points to the faulting instruction. So, when a program or task is restarted following the handling of a fault, the faulting instruction is restarted (re-executed). Restarting the faulting instruction is commonly used to handle exceptions that are generated when access to an operand is blocked. The most common example of this type of fault is a page-fault exception (#PF) that occurs when a program or task references an operand located on a page that is not in memory. When a page-fault exception occurs, the exception handler can load the page into memory and resume execution of the program or task by restarting the faulting instruction. To ensure that the restart is handled transparently to the currently executing program or task, the processor saves the necessary registers and stack pointers to allow a restart to the state prior to the execution of the faulting instruction.

For trap-class exceptions, the return instruction pointer points to the instruction following the trapping instruction. If a trap is detected during an instruction which transfers execution, the return instruction pointer reflects the transfer. For example, if a trap is detected while executing a JMP instruction, the return instruction pointer points to the destination of the JMP instruction, not to the next address past the JMP instruction. All trap exceptions allow program or task restart with no loss of continuity. For example, the overflow exception is a trap exception. Here, the return instruction pointer points to the instruction following the INTO instruction that tested EFLAGS.OF (overflow) flag. The trap handler for this exception resolves the overflow condition. Upon return from the trap handler, program or task execution continues at the instruction following the INTO instruction.

The abort-class exceptions do not support reliable restarting of the program or task. Abort handlers are designed to collect diagnostic information about the state of the processor when the abort exception occurred and then shut down the application and system as gracefully as possible.

Interrupts rigorously support restarting of interrupted programs and tasks without loss of continuity. The return instruction pointer saved for an interrupt points to the next instruction to be executed at the instruction boundary where the processor took the interrupt. If the instruction just executed has a repeat prefix, the interrupt is taken at the end of the current iteration with the registers set to execute the next iteration.

The ability of a P6 family processor to speculatively execute instructions does not affect the taking of interrupts by the processor. Interrupts are taken at instruction boundaries located during the retirement phase of instruction execution; so they are always taken in the “in-order” instruction stream. See Chapter 2, “Intel® 64 and IA-32 Architectures,” in the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 1, for more information about the P6 family processors’ microarchitecture and its support for out-of-order instruction execution.

Note that the Pentium processor and earlier IA-32 processors also perform varying amounts of prefetching and preliminary decoding. With these processors as well, exceptions and interrupts are not signaled until actual “in-order” execution of the instructions. For a given code sample, the signaling of exceptions occurs uniformly when the code is executed on any family of IA-32 processors (except where new exceptions or new opcodes have been defined).

## 7.7 NONMASKABLE INTERRUPT (NMI)

The nonmaskable interrupt (NMI) can be generated in either of two ways:

- External hardware asserts the NMI pin.
- The processor receives a message on the system bus (Pentium 4, Intel Core Duo, Intel Core 2, Intel Atom, and Intel Xeon processors) or the APIC serial bus (P6 family and Pentium processors) with a delivery mode NMI.

When the processor receives a NMI from either of these sources, the processor handles it immediately by calling the NMI handler pointed to by interrupt vector number 2. The processor also invokes certain hardware conditions to ensure that no other interrupts, including NMI interrupts, are received until the NMI handler has completed executing (see Section 7.7.1, “Handling Multiple NMIs”).

Also, when an NMI is received from either of the above sources, it cannot be masked by the IF flag in the EFLAGS register.

It is possible to issue a maskable hardware interrupt (through the INTR pin) to vector 2 to invoke the NMI interrupt handler; however, this interrupt will not truly be an NMI interrupt. A true NMI interrupt that activates the processor’s NMI-handling hardware can only be delivered through one of the mechanisms listed above.

### 7.7.1 Handling Multiple NMIs

While an NMI interrupt handler is executing, the processor blocks delivery of subsequent NMIs until the next execution of the IRET instruction. This blocking of NMIs prevents nested execution of the NMI handler. It is recommended that the NMI interrupt handler be accessed through an interrupt gate to disable maskable hardware interrupts (see Section 7.8.1, “Masking Maskable Hardware Interrupts”).

An execution of the IRET instruction unblocks NMIs even if the instruction causes a fault. For example, if the IRET instruction executes with EFLAGS.VM = 1 and IOPL of less than 3, a general-protection exception is generated (see Section 22.2.7, “Sensitive Instructions”). In such a case, NMIs are unmasked before the exception handler is invoked.

## 7.8 ENABLING AND DISABLING INTERRUPTS

The processor inhibits the generation of some interrupts, depending on the state of the processor and of the IF and RF flags in the EFLAGS register, as described in the following sections.

## 7.8.1 Masking Maskable Hardware Interrupts

The IF flag can disable the servicing of maskable hardware interrupts received on the processor's INTR pin or through the local APIC (see Section 7.3.2, "Maskable Hardware Interrupts"). When the IF flag is clear, the processor inhibits interrupts delivered to the INTR pin or through the local APIC from generating an internal interrupt request; when the IF flag is set, interrupts delivered to the INTR or through the local APIC pin are processed as normal external interrupts.

The IF flag does not affect non-maskable interrupts (NMIs) delivered to the NMI pin or delivery mode NMI messages delivered through the local APIC, nor does it affect processor generated exceptions. As with the other flags in the EFLAGS register, the processor clears the IF flag in response to a hardware reset.

The fact that the group of maskable hardware interrupts includes the reserved interrupt and exception vectors 0 through 32 can potentially cause confusion. Architecturally, when the IF flag is set, an interrupt for any of the vectors from 0 through 32 can be delivered to the processor through the INTR pin and any of the vectors from 16 through 32 can be delivered through the local APIC. The processor will then generate an interrupt and call the interrupt or exception handler pointed to by the vector number. So for example, it is possible to invoke the page-fault handler through the INTR pin (by means of vector 14); however, this is not a true page-fault exception. It is an interrupt. As with the INT *n* instruction (see Section 7.4.2, "Software-Generated Exceptions"), when an interrupt is generated through the INTR pin to an exception vector, the processor does not push an error code on the stack, so the exception handler may not operate correctly.

The IF flag can be set or cleared with the STI (set interrupt-enable flag) and CLI (clear interrupt-enable flag) instructions, respectively. These instructions may be executed only if the CPL is equal to or less than the IOPL. A general-protection exception (#GP) is generated if they are executed when the CPL is greater than the IOPL.<sup>1</sup> If IF = 0, maskable hardware interrupts remain inhibited on the instruction boundary following an execution of STI.<sup>2</sup> The inhibition ends after delivery of another event (e.g., exception) or the execution of the next instruction.

The IF flag is also affected by the following operations:

- The PUSHF instruction stores all flags on the stack, where they can be examined and modified. The POPF instruction can be used to load the modified flags back into the EFLAGS register.
- Task switches and the POPF and IRET instructions load the EFLAGS register; therefore, they can be used to modify the setting of the IF flag.
- When an interrupt is handled through an interrupt gate, the IF flag is automatically cleared, which disables maskable hardware interrupts. (If an interrupt is handled through a trap gate, the IF flag is not cleared.)

See the descriptions of the CLI, STI, PUSHF, POPF, and IRET instructions in Chapter 3, "Instruction Set Reference, A-L," in the Intel® 64 and IA-32 Architectures Software Developer's Manual, Volume 2A, and Chapter 4, "Instruction Set Reference, M-U," in the Intel® 64 and IA-32 Architectures Software Developer's Manual, Volume 2B, for a detailed description of the operations these instructions are allowed to perform on the IF flag.

## 7.8.2 Masking Instruction Breakpoints

The RF (resume) flag in the EFLAGS register controls the response of the processor to instruction-breakpoint conditions (see the description of the RF flag in Section 2.3, "System Flags and Fields in the EFLAGS Register").

When set, it prevents an instruction breakpoint from generating a debug exception (#DB); when clear, instruction breakpoints will generate debug exceptions. The primary function of the RF flag is to prevent the processor from going into a debug exception loop on an instruction-breakpoint. See Section 19.3.1.1, "Instruction-Breakpoint Exception Condition," for more information on the use of this flag.

As noted in Section 7.8.3, execution of the MOV or POP instruction to load the SS register suppresses any instruction breakpoint on the next instruction (just as if EFLAGS.RF were 1).

1. The effect of the IOPL on these instructions is modified slightly when the virtual mode extension is enabled by setting the VME flag in control register CR4: see Section 22.3, "Interrupt and Exception Handling in Virtual-8086 Mode." Behavior is also impacted by the PVI flag: see Section 22.4, "Protected-Mode Virtual Interrupts."

2. Nonmaskable interrupts and system-management interrupts may also be inhibited on the instruction boundary following such an execution of STI.



### 7.8.3 Masking Exceptions and Interrupts When Switching Stacks

To switch to a different stack segment, software often uses a pair of instructions, for example:

```
MOV SS, AX
MOV ESP, StackTop
```

(Software might also use the POP instruction to load SS and ESP.)

If an interrupt or exception occurs after the new SS segment descriptor has been loaded but before the ESP register has been loaded, these two parts of the logical address into the stack space are inconsistent for the duration of the interrupt or exception handler (assuming that delivery of the interrupt or exception does not itself load a new stack pointer).

To account for this situation, the processor prevents certain events from being delivered after execution of a MOV to SS instruction or a POP to SS instruction. The following items provide details:

- Any instruction breakpoint on the next instruction is suppressed (as if EFLAGS.RF were 1).
- Any data breakpoint on the MOV to SS instruction or POP to SS instruction is inhibited until the instruction boundary following the next instruction.
- Any single-step trap that would be delivered following the MOV to SS instruction or POP to SS instruction (because EFLAGS.TF is 1) is suppressed.
- The suppression and inhibition ends after delivery of an exception or the execution of the next instruction.
- If a sequence of consecutive instructions each loads the SS register (using MOV or POP), only the first is guaranteed to inhibit or suppress events in this way.

Intel recommends that software use the LSS instruction to load the SS register and ESP together. The problem identified earlier does not apply to LSS, and the LSS instruction does not inhibit events as detailed above.

## 7.9 PRIORITIZATION OF CONCURRENT EVENTS

If more than one event is pending at an instruction boundary (between execution of instructions), the processor services them in a predictable order. Table 7-2 shows the priority among classes of event sources.

**Table 7-2. Priority Among Concurrent Events**

Priority	Description
1 (Highest)	Hardware Reset and Machine Checks - RESET - Machine Check (#MC)
2	Trap on Task Switch - T flag in TSS is set (#DB)
3	External Hardware Interventions - FLUSH - STOPCLK - SMI - INIT
4	Traps on the Previous Instruction - Trap-class Debug Exceptions (#DB due to TF flag set or data/I-O breakpoint)
5	Nonmaskable Interrupts (NMI) <sup>1</sup>
6	Maskable Hardware Interrupts <sup>1</sup>
7	Fault-class Debug Exceptions (#DB due to instruction breakpoint)



**Table 7-2. Priority Among Concurrent Events (Contd.)**

Priority	Description
8	Faults from Fetching Next Instruction - Code-Segment Limit Violation (#GP) - Code Page Fault (#PF)
9 (Lowest)	Faults from Decoding the Next Instruction - Control protection exception due to missing ENDBRANCH at target of an indirect call or jump (#CP) - Instruction length > 15 bytes (#GP) - Invalid Opcode (#UD) - Coprocessor Not Available (#NM)

**NOTE**

1. The Intel® 486 processor and earlier processors group nonmaskable and maskable interrupts in the same priority class.

The processor first services a pending event from the class which has the highest priority, transferring execution to the first instruction of the handler. Lower priority exceptions are discarded; lower priority interrupts are held pending. Discarded exceptions may be re-generated when the event handler returns execution to the point in the program or task where the original event occurred. While the priority among the classes listed in Table 7-2 is consistent across processor implementations, the priority of events within a class is implementation-dependent and may vary from processor to processor.

Table 7-2 specifies the prioritization of events that may be pending at an instruction boundary. It does not specify the prioritization of faults that arise during instruction execution or event delivery (these include #BR, #TS, #NP, #SS, #GP, #PF, #AC, #MF, #XM, #VE, or #CP). It also does not apply to the events generated by the “Call to Interrupt Procedure” instructions (INT n, INTO, INT3, and INT1), as these events are integral to the execution of those instructions and do not occur between instructions.

## 7.10 INTERRUPT DESCRIPTOR TABLE (IDT)

The interrupt descriptor table (IDT) associates each exception or interrupt vector with a gate descriptor for the procedure or task used to service the associated exception or interrupt. Like the GDT and LDTs, the IDT is an array of 8-byte descriptors (in protected mode). Unlike the GDT, the first entry of the IDT may contain a descriptor. To form an index into the IDT, the processor scales the exception or interrupt vector by eight (the number of bytes in a gate descriptor). Because there are only 256 interrupt or exception vectors, the IDT need not contain more than 256 descriptors. It can contain fewer than 256 descriptors, because descriptors are required only for the interrupt and exception vectors that may occur. All empty descriptor slots in the IDT should have the present flag for the descriptor set to 0.

The base addresses of the IDT should be aligned on an 8-byte boundary to maximize performance of cache line fills. The limit value is expressed in bytes and is added to the base address to get the address of the last valid byte. A limit value of 0 results in exactly 1 valid byte. Because IDT entries are always eight bytes long, the limit should always be one less than an integral multiple of eight (that is,  $8N - 1$ ).

The IDT may reside anywhere in the linear address space. As shown in Figure 7-1, the processor locates the IDT using the IDTR register. This register holds both a 32-bit base address and 16-bit limit for the IDT.

The LIDT (load IDT register) and SIDT (store IDT register) instructions load and store the contents of the IDTR register, respectively. The LIDT instruction loads the IDTR register with the base address and limit held in a memory operand. This instruction can be executed only when the CPL is 0. It normally is used by the initialization code of an operating system when creating an IDT. An operating system also may use it to change from one IDT to another. The SIDT instruction copies the base and limit value stored in IDTR to memory. This instruction can be executed at any privilege level.

If a vector references a descriptor beyond the limit of the IDT, a general-protection exception (#GP) is generated.

## NOTE

Because interrupts are delivered to the processor core only once, an incorrectly configured IDT could result in incomplete interrupt handling and/or the blocking of interrupt delivery.

IA-32 architecture rules need to be followed for setting up IDTR base/limit/access fields and each field in the gate descriptors. The same apply for the Intel 64 architecture. This includes implicit referencing of the destination code segment through the GDT or LDT and accessing the stack.

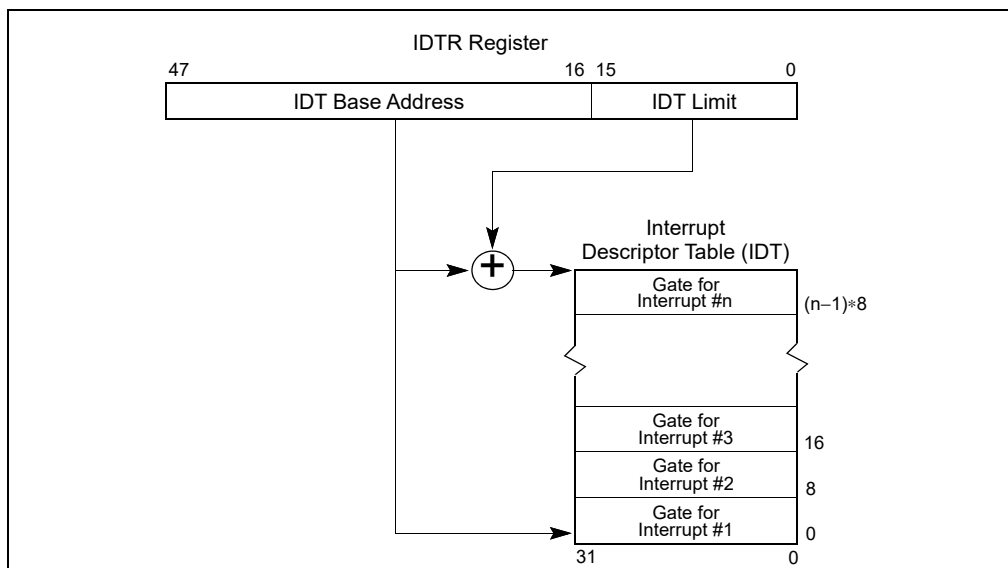


Figure 7-1. Relationship of the IDTR and IDT

## 7.11 IDT DESCRIPTORS

The IDT may contain any of three kinds of gate descriptors:

- Task-gate descriptor
- Interrupt-gate descriptor
- Trap-gate descriptor

Figure 7-2 shows the formats for the task-gate, interrupt-gate, and trap-gate descriptors. The format of a task gate used in an IDT is the same as that of a task gate used in the GDT or an LDT (see Section 9.2.5, "Task-Gate Descriptor"). The task gate contains the segment selector for a TSS for an exception and/or interrupt handler task.

Interrupt and trap gates are very similar to call gates (see Section 6.8.3, "Call Gates"). They contain a far pointer (segment selector and offset) that the processor uses to transfer program execution to a handler procedure in an exception- or interrupt-handler code segment. These gates differ in the way the processor handles the IF flag in the EFLAGS register (see Section 7.12.1.3, "Flag Usage By Exception- or Interrupt-Handler Procedure").

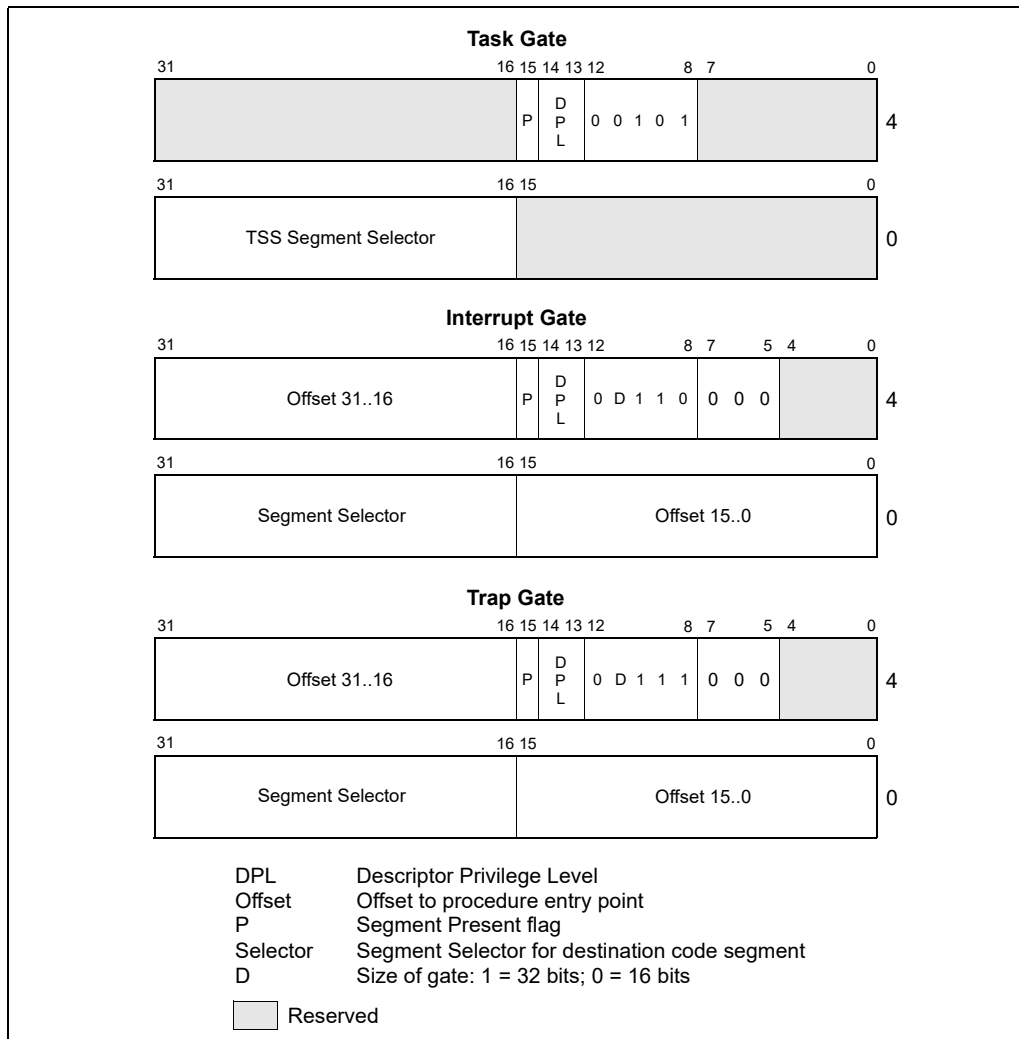


Figure 7-2. IDT Gate Descriptors

## 7.12 EXCEPTION AND INTERRUPT HANDLING

The processor handles calls to exception- and interrupt-handlers similar to the way it handles calls with a CALL instruction to a procedure or a task. When responding to an exception or interrupt, the processor uses the exception or interrupt vector as an index to a descriptor in the IDT. If the index points to an interrupt gate or trap gate, the processor calls the exception or interrupt handler in a manner similar to a CALL to a call gate (see Section 6.8.2, “Gate Descriptors,” through Section 6.8.6, “Returning from a Called Procedure”). If index points to a task gate, the processor executes a task switch to the exception- or interrupt-handler task in a manner similar to a CALL to a task gate (see Section 9.3, “Task Switching”).

### 7.12.1 Exception- or Interrupt-Handler Procedures

An interrupt gate or trap gate references an exception- or interrupt-handler procedure that runs in the context of the currently executing task (see Figure 7-3). The segment selector for the gate points to a segment descriptor for an executable code segment in either the GDT or the current LDT. The offset field of the gate descriptor points to the beginning of the exception- or interrupt-handling procedure.

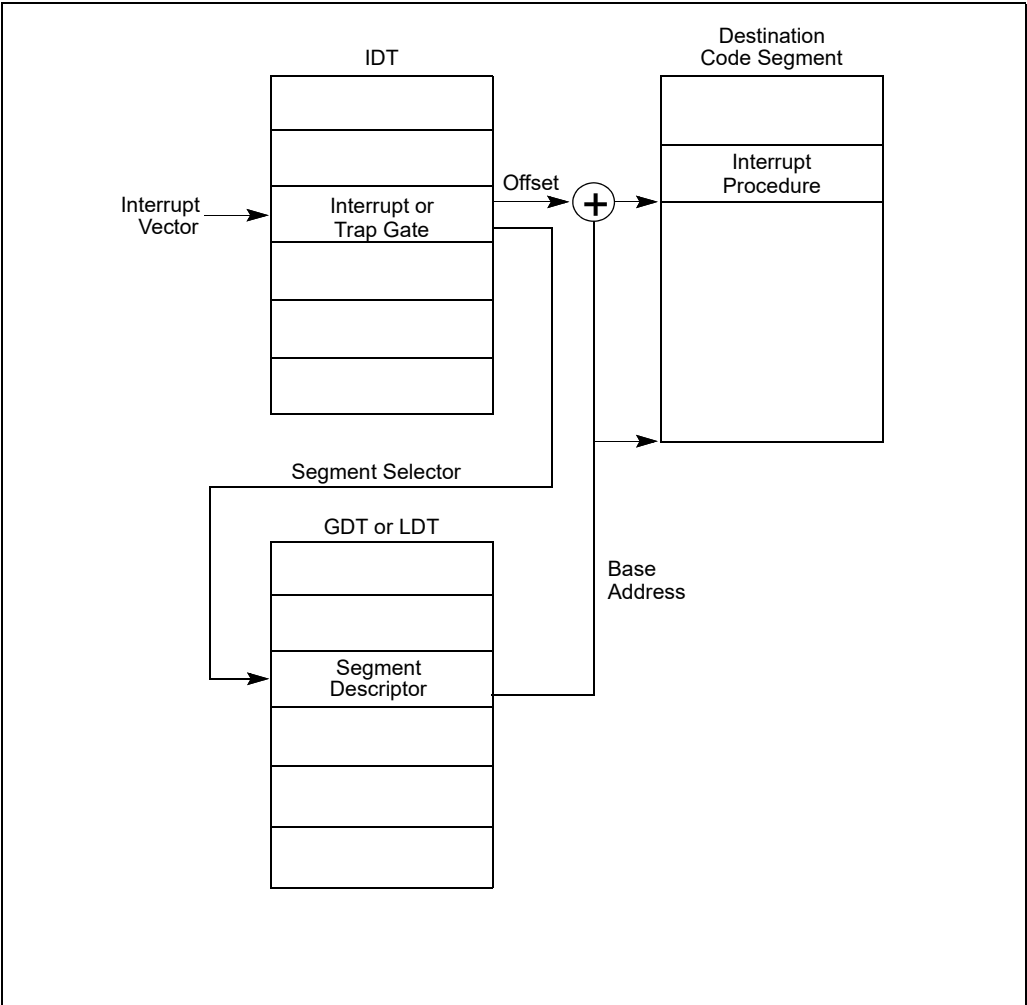
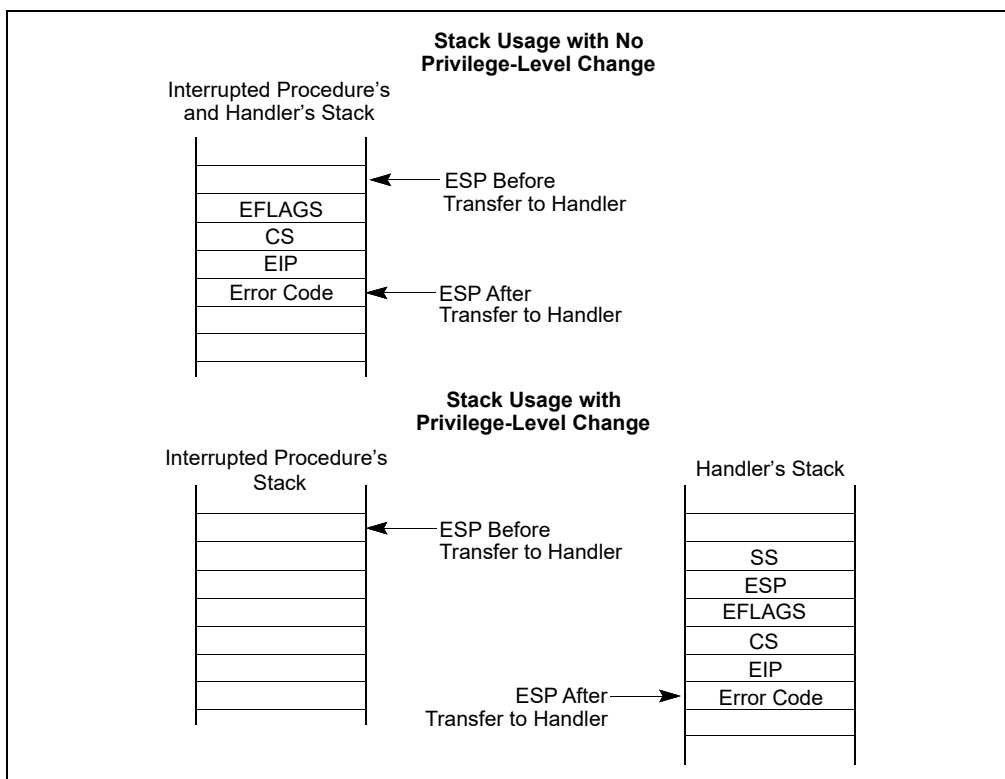


Figure 7-3. Interrupt Procedure Call

When the processor performs a call to the exception- or interrupt-handler procedure:

- If the handler procedure is going to be executed at a numerically lower privilege level, a stack switch occurs. When the stack switch occurs:
  - a. The segment selector and stack pointer for the stack to be used by the handler are obtained from the TSS for the currently executing task. On this new stack, the processor pushes the stack segment selector and stack pointer of the interrupted procedure.
  - b. The processor then saves the current state of the EFLAGS, CS, and EIP registers on the new stack (see Figure 7-4).
  - c. If an exception causes an error code to be saved, it is pushed on the new stack after the EIP value.
- If the handler procedure is going to be executed at the same privilege level as the interrupted procedure:
  - a. The processor saves the current state of the EFLAGS, CS, and EIP registers on the current stack (see Figure 7-4).
  - b. If an exception causes an error code to be saved, it is pushed on the current stack after the EIP value.



**Figure 7-4. Stack Usage on Transfers to Interrupt and Exception-Handling Routines**

To return from an exception- or interrupt-handler procedure, the handler must use the IRET (or IRETD) instruction. The IRET instruction is similar to the RET instruction except that it restores the saved flags into the EFLAGS register. The IOPL field of the EFLAGS register is restored only if the CPL is 0. The IF flag is changed only if the CPL is less than or equal to the IOPL. See Chapter 3, "Instruction Set Reference, A-L," of the Intel® 64 and IA-32 Architectures Software Developer's Manual, Volume 2A, for a description of the complete operation performed by the IRET instruction.

If a stack switch occurred when calling the handler procedure, the IRET instruction switches back to the interrupted procedure's stack on the return.

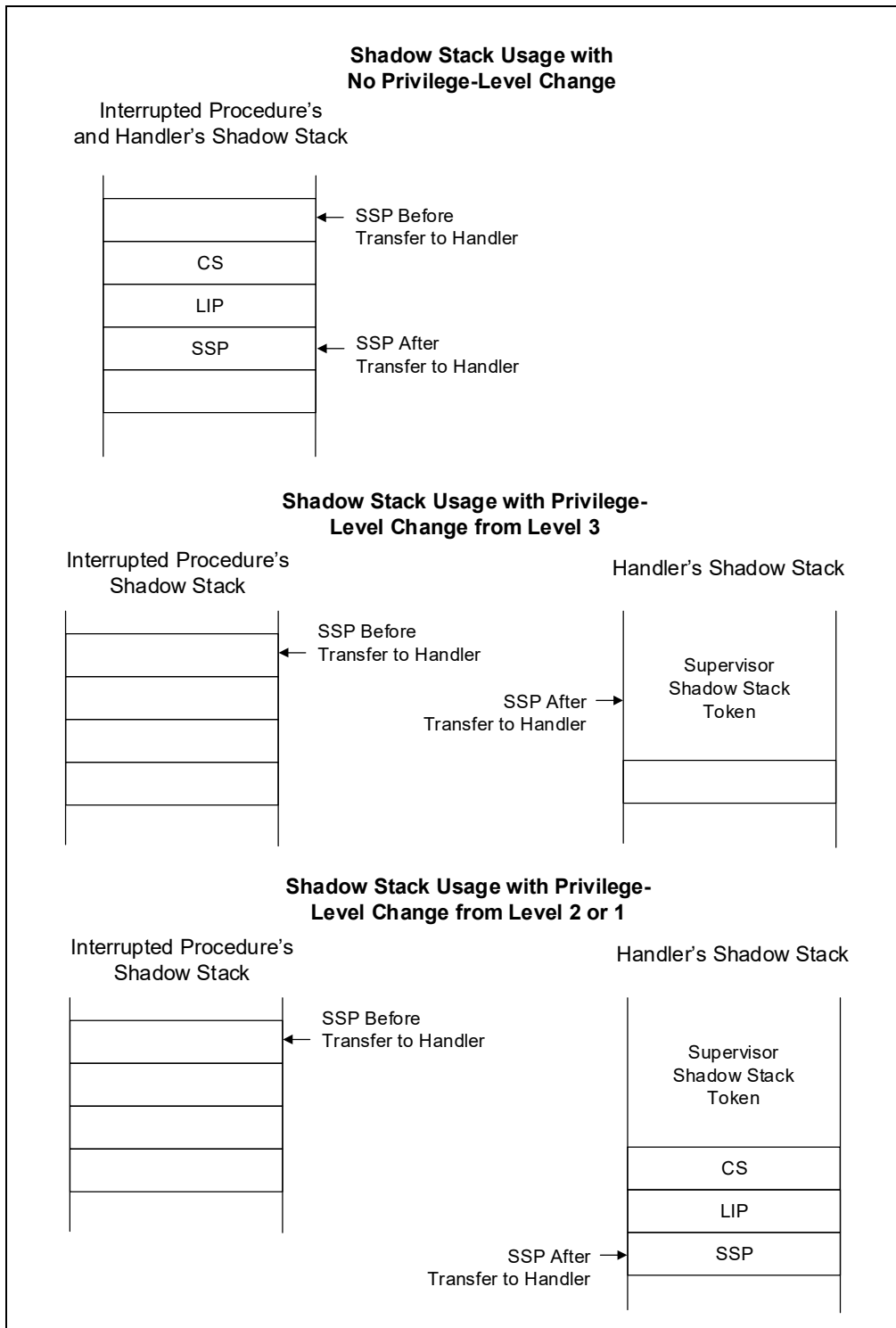
### 7.12.1.1 Shadow Stack Usage on Transfers to Interrupt and Exception Handling Routines

When the processor performs a call to the exception- or interrupt-handler procedure:

- If the handler procedure is going to be executed at a numerically lower privilege level, a shadow stack switch occurs. When the shadow stack switch occurs:
  - a. On a transfer from privilege level 3, if shadow stacks are enabled at privilege level 3 then the SSP is saved to the IA32\_PL3\_SSP MSR.
  - b. If shadow stacks are enabled at the privilege level where the handler will execute then the shadow stack for the handler is obtained from one of the following MSRs based on the privilege level at which the handler executes.
    - IA32\_PL2\_SSP if handler executes at privilege level 2.
    - IA32\_PL1\_SSP if handler executes at privilege level 1.
    - IA32\_PL0\_SSP if handler executes at privilege level 0.
  - c. The SSP obtained is then verified to ensure it points to a valid supervisory shadow stack that is not currently active by verifying a supervisor shadow stack token at the address pointed to by the SSP. The operations performed to verify and acquire the supervisor shadow stack token by making it busy are as described in Section 18.2.3 of the Intel® 64 and IA-32 Architectures Software Developer's Manual, Volume 1.
  - d. On this new shadow stack, the processor pushes the CS, LIP (CS.base + EIP), and SSP of the interrupted procedure if the interrupted procedure was executing at privilege level less than 3; see Figure 7-5.<sup>1</sup>
- If the handler procedure is going to be executed at the same privilege level as the interrupted procedure and shadow stacks are enabled at current privilege level:
  - a. The processor saves the current state of the CS, LIP (CS.base + EIP), and SSP registers on the current shadow stack; see Figure 7-5.

---

1. If any of these pushes leads to an exception or a VM exit, the supervisor shadow-stack token remains busy.



**Figure 7-5. Shadow Stack Usage on Transfers to Interrupt and Exception-Handling Routines**

To return from an exception- or interrupt-handler procedure, the handler must use the IRET (or IRETD) instruction. When executing a return from an interrupt or exception handler from the same privilege level as the interrupted procedure, the processor performs these actions to enforce return address protection:

- Restores the CS and EIP registers to their values prior to the interrupt or exception.



If shadow stack is enabled:

- Compares the values on shadow stack at address SSP+8 (the LIP) and SSP+16 (the CS) to the CS and (CS.base + EIP) popped from the stack and causes a control protection exception (#CP(FAR-RET/IRET)) if they do not match.
- Pops the top-of-stack value (the SSP prior to the interrupt or exception) from shadow stack into SSP register.

When executing a return from an interrupt or exception handler from a different privilege level than the interrupted procedure, the processor performs the actions below.

- If shadow stack is enabled at current privilege level:
  - If SSP is not aligned to 8 bytes then causes a control protection exception (#CP(FAR-RET/IRET)).
  - If privilege level of the procedure being returned to is less than 3 (returning to supervisor mode):
    - Compares the values on shadow stack at address SSP+8 (the LIP) and SSP+16 (the CS) to the CS and (CS.base + EIP) popped from the stack and causes a control protection exception (#CP(FAR-RET/IRET)) if they do not match.
    - Temporarily saves the top-of-stack value (the SSP of the procedure being returned to) internally.
  - If a busy supervisor shadow stack token is present at address SSP+24, then marks the token free using operations described in section Section 18.2.3 of the Intel® 64 and IA-32 Architectures Software Developer's Manual, Volume 1.
  - If the privilege level of the procedure being returned to is less than 3 (returning to supervisor mode), restores the SSP register from the internally saved value.
  - If the privilege level of the procedure being returned to is 3 (returning to user mode) and shadow stack is enabled at privilege level 3, then restores the SSP register with value of IA32\_PL3\_SSP MSR.

### 7.12.1.2 Protection of Exception- and Interrupt-Handler Procedures

The privilege-level protection for exception- and interrupt-handler procedures is similar to that used for ordinary procedure calls when called through a call gate (see Section 6.8.4, "Accessing a Code Segment Through a Call Gate"). The processor does not permit transfer of execution to an exception- or interrupt-handler procedure in a less privileged code segment (numerically greater privilege level) than the CPL.

An attempt to violate this rule results in a general-protection exception (#GP). The protection mechanism for exception- and interrupt-handler procedures is different in the following ways:

- Because interrupt and exception vectors have no RPL, the RPL is not checked on implicit calls to exception and interrupt handlers.
- The processor checks the DPL of the interrupt or trap gate only if an exception or interrupt is generated with an INT *n*, INT3, or INTO instruction.<sup>1</sup> Here, the CPL must be less than or equal to the DPL of the gate. This restriction prevents application programs or procedures running at privilege level 3 from using a software interrupt to access critical exception handlers, such as the page-fault handler, providing that those handlers are placed in more privileged code segments (numerically lower privilege level). For hardware-generated interrupts and processor-detected exceptions, the processor ignores the DPL of interrupt and trap gates.

Because exceptions and interrupts generally do not occur at predictable times, these privilege rules effectively impose restrictions on the privilege levels at which exception and interrupt- handling procedures can run. Either of the following techniques can be used to avoid privilege-level violations.

- The exception or interrupt handler can be placed in a conforming code segment. This technique can be used for handlers that only need to access data available on the stack (for example, divide error exceptions). If the handler needs data from a data segment, the data segment needs to be accessible from privilege level 3, which would make it unprotected.
- The handler can be placed in a nonconforming code segment with privilege level 0. This handler would always run, regardless of the CPL that the interrupted program or task is running at.

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1. This check is not performed by execution of the INT1 instruction (opcode F1); it would be performed by execution of INT 1 (opcode CD 01).

### 7.12.1.3 Flag Usage By Exception- or Interrupt-Handler Procedure

When accessing an exception or interrupt handler through either an interrupt gate or a trap gate, the processor clears the TF flag in the EFLAGS register after it saves the contents of the EFLAGS register on the stack. (On calls to exception and interrupt handlers, the processor also clears the VM, RF, and NT flags in the EFLAGS register, after they are saved on the stack.) Clearing the TF flag prevents instruction tracing from affecting interrupt response and ensures that no single-step exception will be delivered after delivery to the handler. A subsequent IRET instruction restores the TF (and VM, RF, and NT) flags to the values in the saved contents of the EFLAGS register on the stack.

The only difference between an interrupt gate and a trap gate is the way the processor handles the IF flag in the EFLAGS register. When accessing an exception- or interrupt-handling procedure through an interrupt gate, the processor clears the IF flag to prevent other interrupts from interfering with the current interrupt handler. A subsequent IRET instruction restores the IF flag to its value in the saved contents of the EFLAGS register on the stack. Accessing a handler procedure through a trap gate does not affect the IF flag.

## 7.12.2 Interrupt Tasks

When an exception or interrupt handler is accessed through a task gate in the IDT, a task switch results. Handling an exception or interrupt with a separate task offers several advantages:

- The entire context of the interrupted program or task is saved automatically.
- A new TSS permits the handler to use a new privilege level 0 stack when handling the exception or interrupt. If an exception or interrupt occurs when the current privilege level 0 stack is corrupted, accessing the handler through a task gate can prevent a system crash by providing the handler with a new privilege level 0 stack.
- The handler can be further isolated from other tasks by giving it a separate address space. This is done by giving it a separate LDT.

The disadvantage of handling an interrupt with a separate task is that the amount of machine state that must be saved on a task switch makes it slower than using an interrupt gate, resulting in increased interrupt latency.

A task gate in the IDT references a TSS descriptor in the GDT (see Figure 7-6). A switch to the handler task is handled in the same manner as an ordinary task switch (see Section 9.3, “Task Switching”). The link back to the interrupted task is stored in the previous task link field of the handler task’s TSS. If an exception caused an error code to be generated, this error code is copied to the stack of the new task.

When exception- or interrupt-handler tasks are used in an operating system, there are actually two mechanisms that can be used to dispatch tasks: the software scheduler (part of the operating system) and the hardware scheduler (part of the processor's interrupt mechanism). The software scheduler needs to accommodate interrupt tasks that may be dispatched when interrupts are enabled.

## NOTE

Because IA-32 architecture tasks are not re-entrant, an interrupt-handler task must disable interrupts between the time it completes handling the interrupt and the time it executes the IRET instruction. This action prevents another interrupt from occurring while the interrupt task's TSS is still marked busy, which would cause a general-protection (#GP) exception.

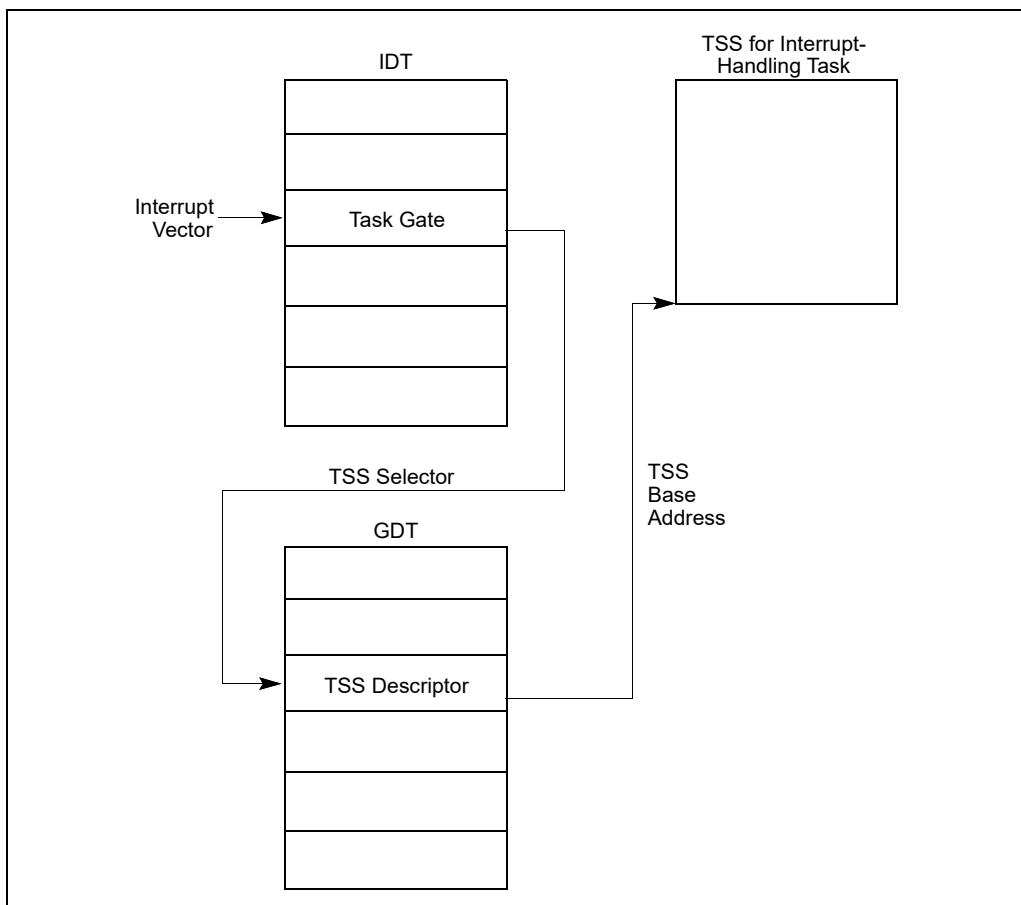


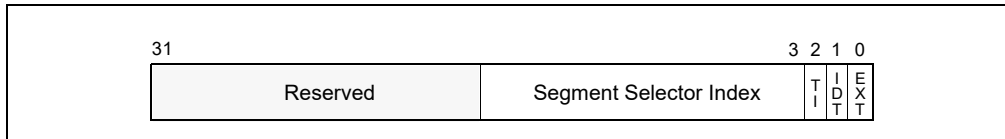
Figure 7-6. Interrupt Task Switch

## 7.13 ERROR CODE

When an exception condition is related to a specific segment selector or IDT vector, the processor pushes an error code onto the stack of the exception handler (whether it is a procedure or task). The error code has the format shown in Figure 7-7. The error code resembles a segment selector; however, instead of a TI flag and RPL field, the error code contains 3 flags:

- EXT**      **External event (bit 0)** — When set, indicates that the exception occurred during delivery of an event external to the program, such as an interrupt or an earlier exception.<sup>1</sup> The bit is cleared if the exception occurred during delivery of a software interrupt (INT *n*, INT3, or INTO).
- IDT**      **Descriptor location (bit 1)** — When set, indicates that the index portion of the error code refers to a gate descriptor in the IDT; when clear, indicates that the index refers to a descriptor in the GDT or the current LDT.
- TI**        **GDT/LDT (bit 2)** — Only used when the IDT flag is clear. When set, the TI flag indicates that the index portion of the error code refers to a segment or gate descriptor in the LDT; when clear, it indicates that the index refers to a descriptor in the current GDT.

1. The bit is also set if the exception occurred during delivery of INT1.



**Figure 7-7. Error Code**

The segment selector index field provides an index into the IDT, GDT, or current LDT to the segment or gate selector being referenced by the error code. In some cases the error code is null (all bits are clear except possibly EXT). A null error code indicates that the error was not caused by a reference to a specific segment or that a null segment selector was referenced in an operation.

The format of the error code is different for page-fault exceptions (#PF). See the “Interrupt 14—Page-Fault Exception (#PF)” section in this chapter.

The format of the error code is different for control protection exceptions (#CP). See the “Interrupt 21—Control Protection Exception (#CP)” section in this chapter.

The error code is pushed on the stack as a doubleword or word (depending on the default interrupt, trap, or task gate size). To keep the stack aligned for doubleword pushes, the upper half of the error code is reserved. Note that the error code is not popped when the IRET instruction is executed to return from an exception handler, so the handler must remove the error code before executing a return.

Error codes are not pushed on the stack for exceptions that are generated externally (with the INTR or LINT[1:0] pins) or the INT *n* instruction, even if an error code is normally produced for those exceptions.

## 7.14 EXCEPTION AND INTERRUPT HANDLING IN 64-BIT MODE

In 64-bit mode, interrupt and exception handling is similar to what has been described for non-64-bit modes. The following are the exceptions:

- All interrupt handlers pointed by the IDT are in 64-bit code (this does not apply to the SMI handler).
- The size of interrupt-stack pushes is fixed at 64 bits; and the processor uses 8-byte, zero extended stores.
- The stack pointer (SS:RSP) is pushed unconditionally on interrupts. In legacy modes, this push is conditional and based on a change in current privilege level (CPL).
- The new SS is set to NULL if there is a change in CPL.
- IRET behavior changes.
- There is a new interrupt stack-switch mechanism and a new interrupt shadow stack-switch mechanism.
- The alignment of interrupt stack frame is different.

### 7.14.1 64-Bit Mode IDT

Interrupt and trap gates are 16 bytes in length to provide a 64-bit offset for the instruction pointer (RIP). The 64-bit RIP referenced by interrupt-gate descriptors allows an interrupt service routine to be located anywhere in the linear-address space. See Figure 7-8.

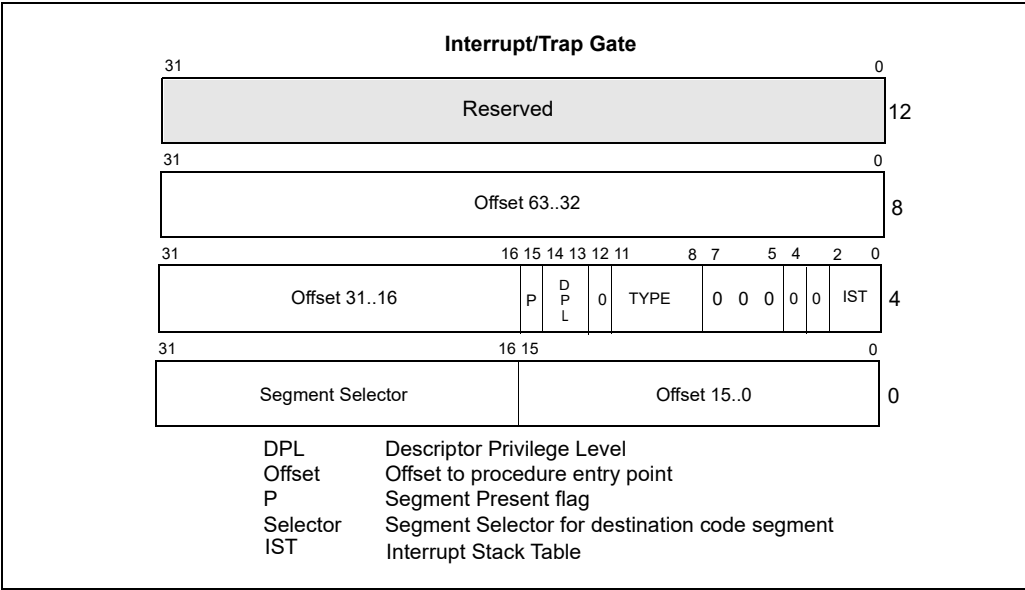


Figure 7-8. 64-Bit IDT Gate Descriptors

In 64-bit mode, the IDT index is formed by scaling the interrupt vector by 16. The first eight bytes (bytes 7:0) of a 64-bit mode interrupt gate are similar but not identical to legacy 32-bit interrupt gates. The type field (bits 11:8 in bytes 7:4) is described in Table 3-2. The Interrupt Stack Table (IST) field (bits 4:0 in bytes 7:4) is used by the stack switching mechanisms described in Section 7.14.5, “Interrupt Stack Table.” Bytes 11:8 hold the upper 32 bits of the target RIP (interrupt segment offset) in canonical form. A general-protection exception (#GP) is generated if software attempts to reference an interrupt gate with a target RIP that is not in canonical form.

The target code segment referenced by the interrupt gate must be a 64-bit code segment (CS.L = 1, CS.D = 0). If the target is not a 64-bit code segment, a general-protection exception (#GP) is generated with the IDT vector number reported as the error code.

Only 64-bit interrupt and trap gates can be referenced in IA-32e mode (64-bit mode and compatibility mode). Legacy 32-bit interrupt or trap gate types (0EH or 0FH) are redefined in IA-32e mode as 64-bit interrupt and trap gate types. No 32-bit interrupt or trap gate type exists in IA-32e mode. If a reference is made to a 16-bit interrupt or trap gate (06H or 07H), a general-protection exception (#GP(0)) is generated.

7.14.2 64-Bit Mode Stack Frame

In legacy mode, the size of an IDT entry (16 bits or 32 bits) determines the size of interrupt-stack-frame pushes. SS:ESP is pushed only on a CPL change. In 64-bit mode, the size of interrupt stack-frame pushes is fixed at eight bytes. This is because only 64-bit mode gates can be referenced. 64-bit mode also pushes SS:RSP unconditionally, rather than only on a CPL change.

When shadow stacks are enabled at the interrupt handler’s privilege level and the interrupted procedure was not executing at a privilege level 3, then the processor pushes the CS:LIP:SSP of the interrupted procedure on the shadow stack of the interrupt handler (where LIP is the linear address of the return address).

Aside from error codes, pushing SS:RSP unconditionally presents operating systems with a consistent interrupt-stackframe size across all interrupts. Interrupt service-routine entry points that handle interrupts generated by the INTn instruction or external INTR# signal can push an additional error code place-holder to maintain consistency.

In legacy mode, the stack pointer may be at any alignment when an interrupt or exception causes a stack frame to be pushed. This causes the stack frame and succeeding pushes done by an interrupt handler to be at arbitrary alignments. In IA-32e mode, the RSP is aligned to a 16-byte boundary before pushing the stack frame. The stack frame itself is aligned on a 16-byte boundary when the interrupt handler is called. The processor can arbitrarily realign the new RSP on interrupts because the previous (possibly unaligned) RSP is unconditionally saved on the newly aligned stack. The previous RSP will be automatically restored by a subsequent IRET.

Aligning the stack permits exception and interrupt frames to be aligned on a 16-byte boundary before interrupts are re-enabled. This allows the stack to be formatted for optimal storage of 16-byte XMM registers, which enables the interrupt handler to use faster 16-byte aligned loads and stores (MOVAPS rather than MOVUPS) to save and restore XMM registers.

Although the RSP alignment is always performed when LMA = 1, it is only of consequence for the kernel-mode case where there is no stack switch or IST used. For a stack switch or IST, the OS would have presumably put suitably aligned RSP values in the TSS.

### 7.14.3 IRET in IA-32e Mode

In IA-32e mode, IRET executes with an 8-byte operand size. There is nothing that forces this requirement. The stack is formatted in such a way that for actions where IRET is required, the 8-byte IRET operand size works correctly.

Because interrupt stack-frame pushes are always eight bytes in IA-32e mode, an IRET must pop eight byte items off the stack. This is accomplished by preceding the IRET with a 64-bit operand-size prefix. The size of the pop is determined by the address size of the instruction. The SS/ESP/RSP size adjustment is determined by the stack size.

IRET pops SS:RSP unconditionally off the interrupt stack frame only when it is executed in 64-bit mode. In compatibility mode, IRET pops SS:RSP off the stack only if there is a CPL change. This allows legacy applications to execute properly in compatibility mode when using the IRET instruction. 64-bit interrupt service routines that exit with an IRET unconditionally pop SS:RSP off of the interrupt stack frame, even if the target code segment is running in 64-bit mode or at CPL = 0. This is because the original interrupt always pushes SS:RSP.

When shadow stacks are enabled and the target privilege level is not 3, the CS:LIP from the shadow stack frame is compared to the return linear address formed by CS:EIP from the stack. If they do not match then the processor caused a control protection exception (#CP(FAR-RET/IRET)), else the processor pops the SSP of the interrupted procedure from the shadow stack. If the target privilege level is 3 and shadow stacks are enabled at privilege level 3, then the SSP for the interrupted procedure is restored from the IA32\_PL3\_SSP MSR.

In IA-32e mode, IRET is allowed to load a NULL SS under certain conditions. If the target mode is 64-bit mode and the target CPL  $\geq$  3, IRET allows SS to be loaded with a NULL selector. As part of the stack switch mechanism, an interrupt or exception sets the new SS to NULL, instead of fetching a new SS selector from the TSS and loading the corresponding descriptor from the GDT or LDT. The new SS selector is set to NULL in order to properly handle returns from subsequent nested far transfers. If the called procedure itself is interrupted, the NULL SS is pushed on the stack frame. On the subsequent IRET, the NULL SS on the stack acts as a flag to tell the processor not to load a new SS descriptor.

### 7.14.4 Stack Switching in IA-32e Mode

The IA-32 architecture provides a mechanism to automatically switch stack frames in response to an interrupt. The 64-bit extensions of Intel 64 architecture implement a modified version of the legacy stack-switching mechanism and an alternative stack-switching mechanism called the interrupt stack table (IST).

In IA-32 modes, the legacy IA-32 stack-switch mechanism is unchanged. In IA-32e mode, the legacy stack-switch mechanism is modified. When stacks are switched as part of a 64-bit mode privilege-level change (resulting from an interrupt), a new SS descriptor is not loaded. IA-32e mode loads only an inner-level RSP from the TSS. The new SS selector is forced to NULL and the SS selector's RPL field is set to the new CPL. The new SS is set to NULL in order to handle nested far transfers (far CALL, INT, interrupts, and exceptions). The old SS and RSP are saved on the new stack (Figure 7-9). On the subsequent IRET, the old SS is popped from the stack and loaded into the SS register.

In summary, a stack switch in IA-32e mode works like the legacy stack switch, except that a new SS selector is not loaded from the TSS. Instead, the new SS is forced to NULL.

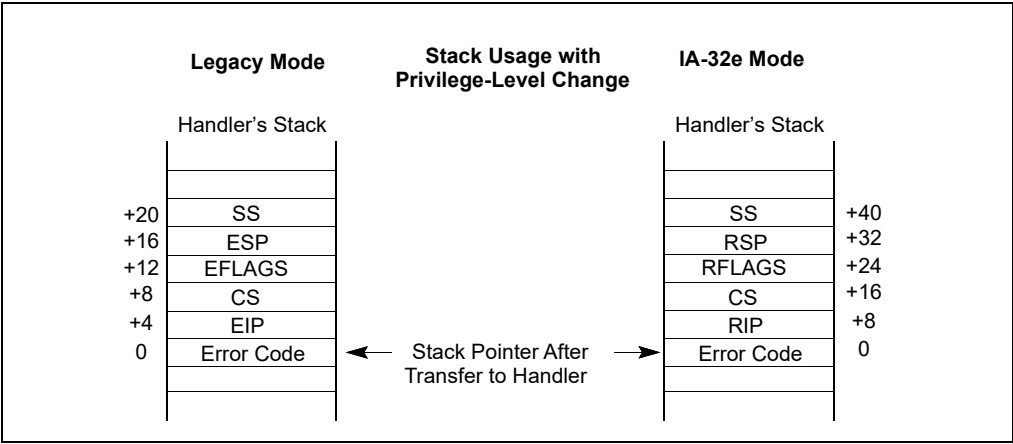


Figure 7-9. IA-32e Mode Stack Usage After Privilege Level Change

7.14.5 Interrupt Stack Table

In IA-32e mode, a new interrupt stack table (IST) mechanism is available as an alternative to the modified legacy stack-switching mechanism described above. This mechanism unconditionally switches stacks when it is enabled. It can be enabled on an individual interrupt-vector basis using a field in the IDT entry. This means that some interrupt vectors can use the modified legacy mechanism and others can use the IST mechanism.

The IST mechanism is only available in IA-32e mode. It is part of the 64-bit mode TSS. The motivation for the IST mechanism is to provide a method for specific interrupts (such as NMI, double-fault, and machine-check) to always execute on a known good stack. In legacy mode, interrupts can use the task-switch mechanism to set up a known-good stack by accessing the interrupt service routine through a task gate located in the IDT. However, the legacy task-switch mechanism is not supported in IA-32e mode.

The IST mechanism provides up to seven IST pointers in the TSS. The pointers are referenced by an interrupt-gate descriptor in the interrupt-descriptor table (IDT); see Figure 7-8. The gate descriptor contains a 3-bit IST index field that provides an offset into the IST section of the TSS. Using the IST mechanism, the processor loads the value pointed by an IST pointer into the RSP.

When an interrupt occurs, the new SS selector is forced to NULL and the SS selector’s RPL field is set to the new CPL. The old SS, RSP, RFLAGS, CS, and RIP are pushed onto the new stack. Interrupt processing then proceeds as normal. If the IST index is zero, the modified legacy stack-switching mechanism described above is used.

To support this stack-switching mechanism with shadow stacks enabled, the processor provides an MSR, IA32\_INTERRUPT\_SSP\_TABLE, to program the linear address of a table of seven shadow stack pointers that are selected using the IST index from the gate descriptor. To switch to a shadow stack selected from the interrupt shadow stack table pointed to by the IA32\_INTERRUPT\_SSP\_TABLE, the processor requires that the shadow stack addresses programmed into this table point to a supervisor shadow stack token; see Figure 7-10.



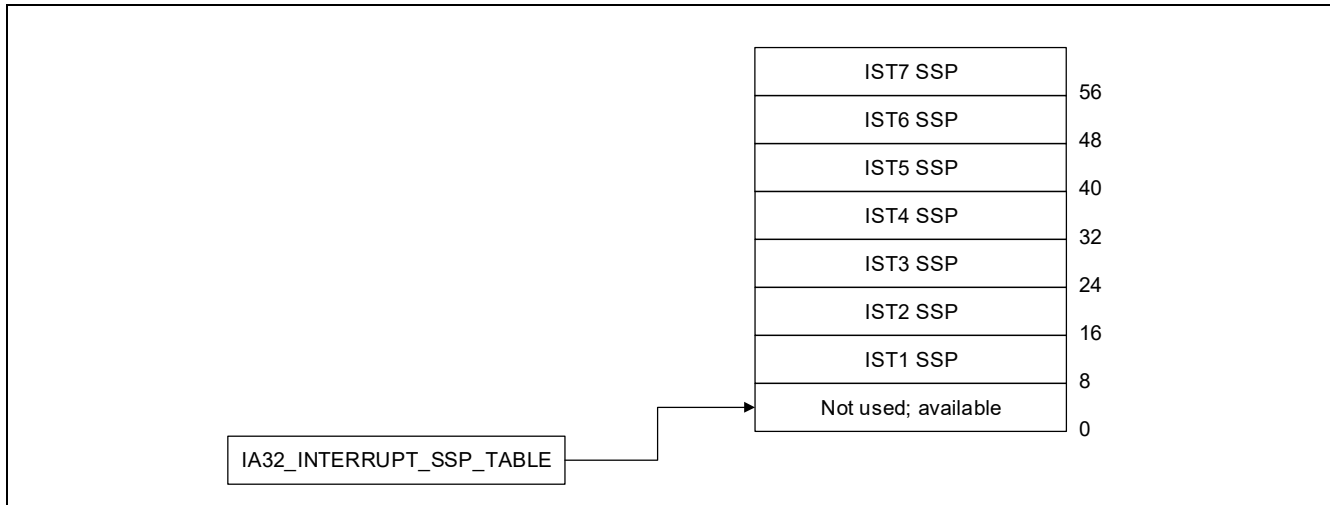


Figure 7-10. Interrupt Shadow Stack Table

## 7.15 EXCEPTION AND INTERRUPT REFERENCE

The following sections describe conditions which generate exceptions and interrupts. They are arranged in the order of vector numbers. The information contained in these sections are as follows:

- **Exception Class** — Indicates whether the exception class is a fault, trap, or abort type. Some exceptions can be either a fault or trap type, depending on when the error condition is detected. (This section is not applicable to interrupts.)
- **Description** — Gives a general description of the purpose of the exception or interrupt type. It also describes how the processor handles the exception or interrupt.
- **Exception Error Code** — Indicates whether an error code is saved for the exception. If one is saved, the contents of the error code are described. (This section is not applicable to interrupts.)
- **Saved Instruction Pointer** — Describes which instruction the saved (or return) instruction pointer points to. It also indicates whether the pointer can be used to restart a faulting instruction.
- **Program State Change** — Describes the effects of the exception or interrupt on the state of the currently running program or task and the possibilities of restarting the program or task without loss of continuity.

## Interrupt 0—Divide Error Exception (#DE)

**Exception Class**      **Fault.**

### Description

Indicates the divisor operand for a DIV or IDIV instruction is 0 or that the result cannot be represented in the number of bits specified for the destination operand.

### Exception Error Code

None.

### Saved Instruction Pointer

Saved contents of CS and EIP registers point to the instruction that generated the exception.

### Program State Change

A program-state change does not accompany the divide error, because the exception occurs before the faulting instruction is executed.

## Interrupt 1—Debug Exception (#DB)

**Exception Class**      **Trap or Fault.** The exception handler can distinguish between traps or faults by examining the contents of DR6 and the other debug registers.

### Description

Indicates that one or more of several debug-exception conditions has been detected. Whether the exception is a fault or a trap depends on the condition (see Table 7-3). See Chapter 19, “Debug, Branch Profile, TSC, and Intel® Resource Director Technology (Intel® RDT) Features,” for detailed information about the debug exceptions.

**Table 7-3. Debug Exception Conditions and Corresponding Exception Classes**

Exception Condition	Exception Class
Instruction fetch breakpoint	Fault
Data read or write breakpoint	Trap
I/O read or write breakpoint	Trap
General detect condition (in conjunction with in-circuit emulation)	Fault
Single-step	Trap
Task-switch	Trap
Execution of INT1 <sup>1</sup>	Trap

### NOTES:

1. Hardware vendors may use the INT1 instruction for hardware debug. For that reason, Intel recommends software vendors instead use the INT3 instruction for software breakpoints.

### Exception Error Code

None. An exception handler can examine the debug registers to determine which condition caused the exception.

### Saved Instruction Pointer

Fault — Saved contents of CS and EIP registers point to the instruction that generated the exception.

Trap — Saved contents of CS and EIP registers point to the instruction following the instruction that generated the exception.

### Program State Change

Fault — A program-state change does not accompany the debug exception, because the exception occurs before the faulting instruction is executed. The program can resume normal execution upon returning from the debug exception handler.

Trap — A program-state change does accompany the debug exception, because the instruction or task switch being executed is allowed to complete before the exception is generated. However, the new state of the program is not corrupted and execution of the program can continue reliably.

The following items detail the treatment of debug exceptions on the instruction boundary following execution of the MOV or the POP instruction that loads the SS register:

- If EFLAGS.TF is 1, no single-step trap is generated.
- If the instruction encounters a data breakpoint, the resulting debug exception is delivered after completion of the instruction after the MOV or POP. This occurs even if the next instruction is INT *n*, INT3, or INTO.
- Any instruction breakpoint on the instruction after the MOV or POP is suppressed (as if EFLAGS.RF were 1).

Any debug exception inside an RTM region causes a transactional abort and, by default, redirects control flow to the fallback instruction address. If advanced debugging of RTM transactional regions has been enabled, any transactional abort due to a debug exception instead causes execution to roll back to just before the XBEGIN instruction

and then delivers a #DB. See Section 17.3.7, “RTM-Enabled Debugger Support,” of Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 1.

## Interrupt 2—NMI Interrupt

**Exception Class**      **Not applicable.**

### Description

The nonmaskable interrupt (NMI) is generated externally by asserting the processor's NMI pin or through an NMI request set by the I/O APIC to the local APIC. This interrupt causes the NMI interrupt handler to be called.

### Exception Error Code

Not applicable.

### Saved Instruction Pointer

The processor always takes an NMI interrupt on an instruction boundary. The saved contents of CS and EIP registers point to the next instruction to be executed at the point the interrupt is taken. See Section 7.5, "Exception Classifications," for more information about when the processor takes NMI interrupts.

### Program State Change

The instruction executing when an NMI interrupt is received is completed before the NMI is generated. A program or task can thus be restarted upon returning from an interrupt handler without loss of continuity, provided the interrupt handler saves the state of the processor before handling the interrupt and restores the processor's state prior to a return.

## Interrupt 3—Breakpoint Exception (#BP)

**Exception Class**      **Trap.**

### Description

Indicates that a breakpoint instruction (INT3, opcode CC) was executed, causing a breakpoint trap to be generated. Typically, a debugger sets a breakpoint by replacing the first opcode byte of an instruction with the opcode for the INT3 instruction. (The INT3 instruction is one byte long, which makes it easy to replace an opcode in a code segment in RAM with the breakpoint opcode.) The operating system or a debugging tool can use a data segment mapped to the same physical address space as the code segment to place an INT3 instruction in places where it is desired to call the debugger.

With the P6 family, Pentium, Intel486, and Intel386 processors, it is more convenient to set breakpoints with the debug registers. (See Section 19.3.2, “Breakpoint Exception (#BP)—Interrupt Vector 3,” for information about the breakpoint exception.) If more breakpoints are needed beyond what the debug registers allow, the INT3 instruction can be used.

Any breakpoint exception inside an RTM region causes a transactional abort and, by default, redirects control flow to the fallback instruction address. If advanced debugging of RTM transactional regions has been enabled, any transactional abort due to a break exception instead causes execution to roll back to just before the XBEGIN instruction and then delivers a **debug exception (#DB)** — **not** a breakpoint exception. See Section 17.3.7, “RTM-Enabled Debugger Support,” of Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 1.

A breakpoint exception can also be generated by executing the INT *n* instruction with an operand of 3. The action of this instruction (INT 3) is slightly different than that of the INT3 instruction (see “INT *n*/INT0/INT3/INT1—Call to Interrupt Procedure” in Chapter 3 of the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 2A).

### Exception Error Code

None.

### Saved Instruction Pointer

Saved contents of CS and EIP registers point to the instruction following the INT3 instruction.

### Program State Change

Even though the EIP points to the instruction following the breakpoint instruction, the state of the program is essentially unchanged because the INT3 instruction does not affect any register or memory locations. The debugger can thus resume the suspended program by replacing the INT3 instruction that caused the breakpoint with the original opcode and decrementing the saved contents of the EIP register. Upon returning from the debugger, program execution resumes with the replaced instruction.

## Interrupt 4—Overflow Exception (#OF)

**Exception Class**      **Trap.**

### Description

Indicates that an overflow trap occurred when an INTO instruction was executed. The INTO instruction checks the state of the OF flag in the EFLAGS register. If the OF flag is set, an overflow trap is generated.

Some arithmetic instructions (such as the ADD and SUB) perform both signed and unsigned arithmetic. These instructions set the OF and CF flags in the EFLAGS register to indicate signed overflow and unsigned overflow, respectively. When performing arithmetic on signed operands, the OF flag can be tested directly or the INTO instruction can be used. The benefit of using the INTO instruction is that if the overflow exception is detected, an exception handler can be called automatically to handle the overflow condition.

### Exception Error Code

None.

### Saved Instruction Pointer

The saved contents of CS and EIP registers point to the instruction following the INTO instruction.

### Program State Change

Even though the EIP points to the instruction following the INTO instruction, the state of the program is essentially unchanged because the INTO instruction does not affect any register or memory locations. The program can thus resume normal execution upon returning from the overflow exception handler.



## Interrupt 5—BOUND Range Exceeded Exception (#BR)

**Exception Class**      **Fault.**

### Description

Indicates that a BOUND-range-exceeded fault occurred when a BOUND instruction was executed. The BOUND instruction checks that a signed array index is within the upper and lower bounds of an array located in memory. If the array index is not within the bounds of the array, a BOUND-range-exceeded fault is generated.

### Exception Error Code

None.

### Saved Instruction Pointer

The saved contents of CS and EIP registers point to the BOUND instruction that generated the exception.

### Program State Change

A program-state change does not accompany the bounds-check fault, because the operands for the BOUND instruction are not modified. Returning from the BOUND-range-exceeded exception handler causes the BOUND instruction to be restarted.

## Interrupt 6—Invalid Opcode Exception (#UD)

**Exception Class**      **Fault.**

### Description

Indicates that the processor did one of the following things:

- Attempted to execute an invalid or reserved opcode.
- Attempted to execute an instruction with an operand type that is invalid for its accompanying opcode; for example, the source operand for a LES instruction is not a memory location.
- Attempted to execute an MMX or SSE/SSE2/SSE3 instruction on an Intel 64 or IA-32 processor that does not support the MMX technology or SSE/SSE2/SSE3/SSSE3 extensions, respectively. CPUID feature flags MMX (bit 23), SSE (bit 25), SSE2 (bit 26), SSE3 (ECX, bit 0), SSSE3 (ECX, bit 9) indicate support for these extensions.
- Attempted to execute an MMX instruction or SSE/SSE2/SSE3/SSSE3 SIMD instruction (with the exception of the MOVNTI, PAUSE, PREFETCHh, SFENCE, LFENCE, MFENCE, CLFLUSH, MONITOR, and MWAIT instructions) when the EM flag in control register CR0 is set (1).
- Attempted to execute an SSE/SSE2/SSE3/SSSE3 instruction when the OSFXSR bit in control register CR4 is clear (0). Note this does not include the following SSE/SSE2/SSE3 instructions: MASKMOVQ, MOVNTQ, MOVNTI, PREFETCHh, SFENCE, LFENCE, MFENCE, and CLFLUSH; or the 64-bit versions of the PAVGB, PAVGW, PEXTRW, PINSRW, PMAXSW, PMAXUB, PMINSW, PMINUB, PMOVMSKB, PMULHUW, PSADB, PSHUFW, PADDQ, PSUBQ, PALIGNR, PABSB, PABSD, PABSW, PHADDD, PHADDSW, PHADDW, PHSUBD, PHSUBSW, PHSUBW, PMADDUSB, PMULHRW, PSHUFB, PSIGNB, PSIGND, and PSIGNW.
- Attempted to execute an SSE/SSE2/SSE3/SSSE3 instruction on an Intel 64 or IA-32 processor that caused a SIMD floating-point exception when the OSXMMEXCPT bit in control register CR4 is clear (0).
- Executed a UD0, UD1 or UD2 instruction. Note that even though it is the execution of the UD0, UD1 or UD2 instruction that causes the invalid opcode exception, the saved instruction pointer will still points at the UD0, UD1 or UD2 instruction.
- Detected a LOCK prefix that precedes an instruction that may not be locked or one that may be locked but the destination operand is not a memory location.
- Attempted to execute an LLDT, SLDT, LTR, STR, LSL, LAR, VERR, VERW, or ARPL instruction while in real-address or virtual-8086 mode.
- Attempted to execute the RSM instruction when not in SMM mode.

In Intel 64 and IA-32 processors that implement out-of-order execution microarchitectures, this exception is not generated until an attempt is made to retire the result of executing an invalid instruction; that is, decoding and speculatively attempting to execute an invalid opcode does not generate this exception. Likewise, in the Pentium processor and earlier IA-32 processors, this exception is not generated as the result of prefetching and preliminary decoding of an invalid instruction. (See Section 7.5, “Exception Classifications,” for general rules for taking of interrupts and exceptions.)

The opcodes D6 and F1 are undefined opcodes reserved by the Intel 64 and IA-32 architectures. These opcodes, even though undefined, do not generate an invalid opcode exception.

### Exception Error Code

None.

### Saved Instruction Pointer

The saved contents of CS and EIP registers point to the instruction that generated the exception.

### Program State Change

A program-state change does not accompany an invalid-opcode fault, because the invalid instruction is not executed.

## Interrupt 7—Device Not Available Exception (#NM)

**Exception Class**     **Fault.**

### Description

Indicates one of the following things:

The device-not-available exception is generated by either of three conditions:

- The processor executed an x87 FPU floating-point instruction while the EM flag in control register CR0 was set (1). See the paragraph below for the special case of the WAIT/FWAIT instruction.
- The processor executed a WAIT/FWAIT instruction while the MP and TS flags of register CR0 were set, regardless of the setting of the EM flag.
- The processor executed an x87 FPU, MMX, or SSE/SSE2/SSE3 instruction (with the exception of MOVNTI, PAUSE, PREFETCHh, SFENCE, LFENCE, MFENCE, and CLFLUSH) while the TS flag in control register CR0 was set and the EM flag is clear.

The EM flag is set when the processor does not have an internal x87 FPU floating-point unit. A device-not-available exception is then generated each time an x87 FPU floating-point instruction is encountered, allowing an exception handler to call floating-point instruction emulation routines.

The TS flag indicates that a context switch (task switch) has occurred since the last time an x87 floating-point, MMX, or SSE/SSE2/SSE3 instruction was executed; but that the context of the x87 FPU, XMM, and MXCSR registers were not saved. When the TS flag is set and the EM flag is clear, the processor generates a device-not-available exception each time an x87 floating-point, MMX, or SSE/SSE2/SSE3 instruction is encountered (with the exception of the instructions listed above). The exception handler can then save the context of the x87 FPU, XMM, and MXCSR registers before it executes the instruction. See Section 2.5, "Control Registers," for more information about the TS flag.

The MP flag in control register CR0 is used along with the TS flag to determine if WAIT or FWAIT instructions should generate a device-not-available exception. It extends the function of the TS flag to the WAIT and FWAIT instructions, giving the exception handler an opportunity to save the context of the x87 FPU before the WAIT or FWAIT instruction is executed. The MP flag is provided primarily for use with the Intel 286 and Intel386 DX processors. For programs running on the Pentium 4, Intel Xeon, P6 family, Pentium, or Intel486 DX processors, or the Intel 487 SX coprocessors, the MP flag should always be set; for programs running on the Intel486 SX processor, the MP flag should be clear.

### Exception Error Code

None.

### Saved Instruction Pointer

The saved contents of CS and EIP registers point to the floating-point instruction or the WAIT/FWAIT instruction that generated the exception.

### Program State Change

A program-state change does not accompany a device-not-available fault, because the instruction that generated the exception is not executed.

If the EM flag is set, the exception handler can then read the floating-point instruction pointed to by the EIP and call the appropriate emulation routine.

If the MP and TS flags are set or the TS flag alone is set, the exception handler can save the context of the x87 FPU, clear the TS flag, and continue execution at the interrupted floating-point or WAIT/FWAIT instruction.

## Interrupt 8—Double Fault Exception (#DF)

**Exception Class**     **Abort.**

### Description

Indicates that the processor detected a second exception while calling an exception handler for a prior exception. Normally, when the processor detects another exception while trying to call an exception handler, the two exceptions can be handled serially. If, however, the processor cannot handle them serially, it signals the double-fault exception. To determine when two faults need to be signalled as a double fault, the processor divides the exceptions into three classes: benign exceptions, contributory exceptions, and page faults (see Table 7-4).

**Table 7-4. Interrupt and Exception Classes**

Class	Vector Number	Description
Benign Exceptions and Interrupts	1	Debug
	2	NMI Interrupt
	3	Breakpoint
	4	Overflow
	5	BOUND Range Exceeded
	6	Invalid Opcode
	7	Device Not Available
	9	Coprocessor Segment Overrun
	16	Floating-Point Error
	17	Alignment Check
	18	Machine Check
	19	SIMD floating-point
	All	INT <i>n</i>
	All	INTR
Contributory Exceptions	0	Divide Error
	10	Invalid TSS
	11	Segment Not Present
	12	Stack Fault
	13	General Protection
Page Faults	21	Control Protection
	14	Page Fault
	20	Virtualization Exception

Table 7-5 shows the various combinations of exception classes that cause a double fault to be generated. A double-fault exception falls in the abort class of exceptions. The program or task cannot be restarted or resumed. The double-fault handler can be used to collect diagnostic information about the state of the machine and/or, when possible, to shut the application and/or system down gracefully or restart the system.

A segment or page fault may be encountered while prefetching instructions; however, this behavior is outside the domain of Table 7-5. Any further faults generated while the processor is attempting to transfer control to the appropriate fault handler could still lead to a double-fault sequence.

Table 7-5. Conditions for Generating a Double Fault

First Exception	Second Exception		
	Benign	Contributory	Page Fault
Benign	Handle Exceptions Serially	Handle Exceptions Serially	Handle Exceptions Serially
Contributory	Handle Exceptions Serially	Generate a Double Fault	Handle Exceptions Serially
Page Fault	Handle Exceptions Serially	Generate a Double Fault	Generate a Double Fault
Double Fault	Handle Exceptions Serially	Enter Shutdown Mode	Enter Shutdown Mode

If another contributory or page fault exception occurs while attempting to call the double-fault handler, the processor enters shutdown mode. This mode is similar to the state following execution of an HLT instruction. In this mode, the processor stops executing instructions until an NMI interrupt, SMI interrupt, hardware reset, or INIT# is received. The processor generates a special bus cycle to indicate that it has entered shutdown mode. Software designers may need to be aware of the response of hardware when it goes into shutdown mode. For example, hardware may turn on an indicator light on the front panel, generate an NMI interrupt to record diagnostic information, invoke reset initialization, generate an INIT initialization, or generate an SMI. If any events are pending during shutdown, they will be handled after an wake event from shutdown is processed (for example, A20M# interrupts).

If a shutdown occurs while the processor is executing an NMI interrupt handler, then only a hardware reset can restart the processor. Likewise, if the shutdown occurs while executing in SMM, a hardware reset must be used to restart the processor.

### Exception Error Code

Zero. The processor always pushes an error code of 0 onto the stack of the double-fault handler.

### Saved Instruction Pointer

The saved contents of CS and EIP registers are undefined.

### Program State Change

A program-state following a double-fault exception is undefined. The program or task cannot be resumed or restarted. The only available action of the double-fault exception handler is to collect all possible context information for use in diagnostics and then close the application and/or shut down or reset the processor.

If the double fault occurs when any portion of the exception handling machine state is corrupted, the handler cannot be invoked and the processor must be reset.

## Interrupt 9—Coprocessor Segment Overrun

**Exception Class**      **Abort. (Intel reserved; do not use. Recent IA-32 processors do not generate this exception.)**

### Description

Indicates that an Intel386 CPU-based systems with an Intel 387 math coprocessor detected a page or segment violation while transferring the middle portion of an Intel 387 math coprocessor operand. The P6 family, Pentium, and Intel486 processors do not generate this exception; instead, this condition is detected with a general protection exception (#GP), interrupt 13.

### Exception Error Code

None.

### Saved Instruction Pointer

The saved contents of CS and EIP registers point to the instruction that generated the exception.

### Program State Change

A program-state following a coprocessor segment-overrun exception is undefined. The program or task cannot be resumed or restarted. The only available action of the exception handler is to save the instruction pointer and reinitialize the x87 FPU using the FNINIT instruction.

## Interrupt 10—Invalid TSS Exception (#TS)

**Exception Class**      **Fault.**

### Description

Indicates that there was an error related to a TSS. Such an error might be detected during a task switch or during the execution of instructions that use information from a TSS. Table 7-6 shows the conditions that cause an invalid TSS exception to be generated.

**Table 7-6. Invalid TSS Conditions**

Error Code Index	Invalid Condition
TSS segment selector index	The TSS segment limit is less than 67H for 32-bit TSS or less than 2CH for 16-bit TSS.
TSS segment selector index	During an IRET task switch, the TI flag in the TSS segment selector indicates the LDT.
TSS segment selector index	During an IRET task switch, the TSS segment selector exceeds descriptor table limit.
TSS segment selector index	During an IRET task switch, the busy flag in the TSS descriptor indicates an inactive task.
TSS segment selector index	During a task switch, an attempt to access data in a TSS results in a limit violation or canonical fault.
TSS segment selector index	During an IRET task switch, the backlink is a NULL selector.
TSS segment selector index	During an IRET task switch, the backlink points to a descriptor which is not a busy TSS.
TSS segment selector index	The new TSS descriptor is beyond the GDT limit.
TSS segment selector index	The new TSS selector is null on an attempt to lock the new TSS.
TSS segment selector index	The new TSS selector has the TI bit set on an attempt to lock the new TSS.
TSS segment selector index	The new TSS descriptor is not an available TSS descriptor on an attempt to lock the new TSS.
LDT segment selector index	LDT not valid or not present.
Stack segment selector index	The stack segment selector exceeds descriptor table limit.
Stack segment selector index	The stack segment selector is NULL.
Stack segment selector index	The stack segment descriptor is a non-data segment.
Stack segment selector index	The stack segment is not writable.
Stack segment selector index	The stack segment DPL ? CPL.
Stack segment selector index	The stack segment selector RPL ? CPL.
Code segment selector index	The code segment selector exceeds descriptor table limit.
Code segment selector index	The code segment selector is NULL.
Code segment selector index	The code segment descriptor is not a code segment type.
Code segment selector index	The nonconforming code segment DPL ? CPL.
Code segment selector index	The conforming code segment DPL is greater than CPL.
Data segment selector index	The data segment selector exceeds the descriptor table limit.
Data segment selector index	The data segment descriptor is not a readable code or data type.
Data segment selector index	The data segment descriptor is a nonconforming code type and RPL > DPL.
Data segment selector index	The data segment descriptor is a nonconforming code type and CPL > DPL.
TSS segment selector index	The TSS segment descriptor/upper descriptor is beyond the GDT segment limit.
TSS segment selector index	The TSS segment descriptor is not an available TSS type.
TSS segment selector index	The TSS segment descriptor is an available 286 TSS type in IA-32e mode.

**Table 7-6. Invalid TSS Conditions (Contd.)**

Error Code Index	Invalid Condition
TSS segment selector index	The TSS segment upper descriptor is not the correct type.
TSS segment selector index	The TSS segment descriptor contains a non-canonical base.

This exception can be generated either in the context of the original task or in the context of the new task (see Section 9.3, “Task Switching”). Until the processor has completely verified the presence of the new TSS, the exception is generated in the context of the original task. Once the existence of the new TSS is verified, the task switch is considered complete. Any invalid-TSS conditions detected after this point are handled in the context of the new task. (A task switch is considered complete when the task register is loaded with the segment selector for the new TSS and, if the switch is due to a procedure call or interrupt, the previous task link field of the new TSS references the old TSS.)

The invalid-TSS handler must be a task called using a task gate. Handling this exception inside the faulting TSS context is not recommended because the processor state may not be consistent.

### Exception Error Code

An error code containing the segment selector index for the segment descriptor that caused the violation is pushed onto the stack of the exception handler. If the EXT flag is set, it indicates that the exception was caused by an event external to the currently running program (for example, if an external interrupt handler using a task gate attempted a task switch to an invalid TSS).

### Saved Instruction Pointer

If the exception condition was detected before the task switch was carried out, the saved contents of CS and EIP registers point to the instruction that invoked the task switch. If the exception condition was detected after the task switch was carried out, the saved contents of CS and EIP registers point to the first instruction of the new task.

### Program State Change

The ability of the invalid-TSS handler to recover from the fault depends on the error condition that causes the fault. See Section 9.3, “Task Switching,” for more information on the task switch process and the possible recovery actions that can be taken.

If an invalid TSS exception occurs during a task switch, it can occur before or after the commit-to-new-task point. If it occurs before the commit point, no program state change occurs. If it occurs after the commit point (when the segment descriptor information for the new segment selectors have been loaded in the segment registers), the processor will load all the state information from the new TSS before it generates the exception. During a task switch, the processor first loads all the segment registers with segment selectors from the TSS, then checks their contents for validity. If an invalid TSS exception is discovered, the remaining segment registers are loaded but not checked for validity and therefore may not be usable for referencing memory. The invalid TSS handler should not rely on being able to use the segment selectors found in the CS, SS, DS, ES, FS, and GS registers without causing another exception. The exception handler should load all segment registers before trying to resume the new task; otherwise, general-protection exceptions (#GP) may result later under conditions that make diagnosis more difficult. The Intel recommended way of dealing with this situation is to use a task for the invalid TSS exception handler. The task switch back to the interrupted task from the invalid-TSS exception-handler task will then cause the processor to check the registers as it loads them from the TSS.



## Interrupt 11—Segment Not Present (#NP)

**Exception Class**      **Fault.**

### Description

Indicates that the present flag of a segment or gate descriptor is clear. The processor can generate this exception during any of the following operations:

- While attempting to load CS, DS, ES, FS, or GS registers. [Detection of a not-present segment while loading the SS register causes a stack fault exception (#SS) to be generated.] This situation can occur while performing a task switch.
- While attempting to load the LDTR using an LLDT instruction. Detection of a not-present LDT while loading the LDTR during a task switch operation causes an invalid-TSS exception (#TS) to be generated.
- When executing the LTR instruction and the TSS is marked not present.
- While attempting to use a gate descriptor or TSS that is marked segment-not-present, but is otherwise valid.

An operating system typically uses the segment-not-present exception to implement virtual memory at the segment level. If the exception handler loads the segment and returns, the interrupted program or task resumes execution.

A not-present indication in a gate descriptor, however, does not indicate that a segment is not present (because gates do not correspond to segments). The operating system may use the present flag for gate descriptors to trigger exceptions of special significance to the operating system.

A contributory exception or page fault that subsequently referenced a not-present segment would cause a double fault (#DF) to be generated instead of #NP.

### Exception Error Code

An error code containing the segment selector index for the segment descriptor that caused the violation is pushed onto the stack of the exception handler. If the EXT flag is set, it indicates that the exception resulted from either:

- an external event (NMI or INTR) that caused an interrupt, which subsequently referenced a not-present segment
- a benign exception that subsequently referenced a not-present segment

The IDT flag is set if the error code refers to an IDT entry. This occurs when the IDT entry for an interrupt being serviced references a not-present gate. Such an event could be generated by an INT instruction or a hardware interrupt.

### Saved Instruction Pointer

The saved contents of CS and EIP registers normally point to the instruction that generated the exception. If the exception occurred while loading segment descriptors for the segment selectors in a new TSS, the CS and EIP registers point to the first instruction in the new task. If the exception occurred while accessing a gate descriptor, the CS and EIP registers point to the instruction that invoked the access (for example a CALL instruction that references a call gate).

### Program State Change

If the segment-not-present exception occurs as the result of loading a register (CS, DS, SS, ES, FS, GS, or LDTR), a program-state change does accompany the exception because the register is not loaded. Recovery from this exception is possible by simply loading the missing segment into memory and setting the present flag in the segment descriptor.

If the segment-not-present exception occurs while accessing a gate descriptor, a program-state change does not accompany the exception. Recovery from this exception is possible merely by setting the present flag in the gate descriptor.

If a segment-not-present exception occurs during a task switch, it can occur before or after the commit-to-new-task point (see Section 9.3, “Task Switching”). If it occurs before the commit point, no program state change

occurs. If it occurs after the commit point, the processor will load all the state information from the new TSS (without performing any additional limit, present, or type checks) before it generates the exception. The segment-not-present exception handler should not rely on being able to use the segment selectors found in the CS, SS, DS, ES, FS, and GS registers without causing another exception. (See the Program State Change description for “Interrupt 10—Invalid TSS Exception (#TS)” in this chapter for additional information on how to handle this situation.)

## Interrupt 12—Stack Fault Exception (#SS)

**Exception Class**      **Fault.**

### Description

Indicates that one of the following stack related conditions was detected:

- A limit violation is detected during an operation that refers to the SS register. Operations that can cause a limit violation include stack-oriented instructions such as POP, PUSH, CALL, RET, IRET, ENTER, and LEAVE, as well as other memory references which implicitly or explicitly use the SS register (for example, MOV AX, [BP+6] or MOV AX, SS:[EAX+6]). The ENTER instruction generates this exception when there is not enough stack space for allocating local variables.
- A not-present stack segment is detected when attempting to load the SS register. This violation can occur during the execution of a task switch, a CALL instruction to a different privilege level, a return to a different privilege level, an LSS instruction, or a MOV or POP instruction to the SS register.
- A canonical violation is detected in 64-bit mode during an operation that reference memory using the stack pointer register containing a non-canonical memory address.

Recovery from this fault is possible by either extending the limit of the stack segment (in the case of a limit violation) or loading the missing stack segment into memory (in the case of a not-present violation).

In the case of a canonical violation that was caused intentionally by software, recovery is possible by loading the correct canonical value into RSP. Otherwise, a canonical violation of the address in RSP likely reflects some register corruption in the software.

### Exception Error Code

If the exception is caused by a not-present stack segment or by overflow of the new stack during an inter-privilege-level call, the error code contains a segment selector for the segment that caused the exception. Here, the exception handler can test the present flag in the segment descriptor pointed to by the segment selector to determine the cause of the exception. For a normal limit violation (on a stack segment already in use) the error code is set to 0.

### Saved Instruction Pointer

The saved contents of CS and EIP registers generally point to the instruction that generated the exception. However, when the exception results from attempting to load a not-present stack segment during a task switch, the CS and EIP registers point to the first instruction of the new task.

### Program State Change

A program-state change does not generally accompany a stack-fault exception, because the instruction that generated the fault is not executed. Here, the instruction can be restarted after the exception handler has corrected the stack fault condition.

If a stack fault occurs during a task switch, it occurs after the commit-to-new-task point (see Section 9.3, “Task Switching”). Here, the processor loads all the state information from the new TSS (without performing any additional limit, present, or type checks) before it generates the exception. The stack fault handler should thus not rely on being able to use the segment selectors found in the CS, SS, DS, ES, FS, and GS registers without causing another exception. The exception handler should check all segment registers before trying to resume the new task; otherwise, general protection faults may result later under conditions that are more difficult to diagnose. (See the Program State Change description for “Interrupt 10—Invalid TSS Exception (#TS)” in this chapter for additional information on how to handle this situation.)

## Interrupt 13—General Protection Exception (#GP)

**Exception Class**     **Fault.**

### Description

Indicates that the processor detected one of a class of protection violations called “general-protection violations.” The conditions that cause this exception to be generated comprise all the protection violations that do not cause other exceptions to be generated (such as, invalid-TSS, segment-not-present, stack-fault, or page-fault exceptions). The following conditions cause general-protection exceptions to be generated:

- Exceeding the segment limit when accessing the CS, DS, ES, FS, or GS segments.
- Exceeding the segment limit when referencing a descriptor table (except during a task switch or a stack switch).
- Transferring execution to a segment that is not executable.
- Writing to a code segment or a read-only data segment.
- Reading from an execute-only code segment.
- Loading the SS register with a segment selector for a read-only segment (unless the selector comes from a TSS during a task switch, in which case an invalid-TSS exception occurs).
- Loading the SS, DS, ES, FS, or GS register with a segment selector for a system segment.
- Loading the DS, ES, FS, or GS register with a segment selector for an execute-only code segment.
- Loading the SS register with the segment selector of an executable segment or a null segment selector.
- Loading the CS register with a segment selector for a data segment or a null segment selector.
- Accessing memory using the DS, ES, FS, or GS register when it contains a null segment selector.
- Switching to a busy task during a call or jump to a TSS.
- Using a segment selector on a non-IRET task switch that points to a TSS descriptor in the current LDT. TSS descriptors can only reside in the GDT. This condition causes a #TS exception during an IRET task switch.
- Violating any of the privilege rules described in Chapter 6, “Protection.”
- Exceeding the instruction length limit of 15 bytes (this only can occur when redundant prefixes are placed before an instruction).
- Loading the CR0 register with a set PG flag (paging enabled) and a clear PE flag (protection disabled).
- Loading the CR0 register with a set NW flag and a clear CD flag.
- Referencing an entry in the IDT (following an interrupt or exception) that is not an interrupt, trap, or task gate.
- Attempting to access an interrupt or exception handler through an interrupt or trap gate from virtual-8086 mode when the handler’s code segment DPL is greater than 0.
- Attempting to write a 1 into a reserved bit of CR4.
- Attempting to execute a privileged instruction when the CPL is not equal to 0 (see Section 6.9, “Privileged Instructions,” for a list of privileged instructions).
- Attempting to execute SGDT, SIDT, SLDT, SMSW, or STR when CR4.UMIP = 1 and the CPL is not equal to 0.
- Writing to a reserved bit in an MSR.
- Accessing a gate that contains a null segment selector.
- Executing the INT *n* instruction when the CPL is greater than the DPL of the referenced interrupt, trap, or task gate.
- The segment selector in a call, interrupt, or trap gate does not point to a code segment.
- The segment selector operand in the LLDT instruction is a local type (TI flag is set) or does not point to a segment descriptor of the LDT type.
- The segment selector operand in the LTR instruction is local or points to a TSS that is not available.
- The target code-segment selector for a call, jump, or return is null.

- If the PAE and/or PSE flag in control register CR4 is set and the processor detects any reserved bits in a page-directory-pointer-table entry set to 1. These bits are checked during a write to control registers CR0, CR3, or CR4 that causes a reloading of the page-directory-pointer-table entry.
- Attempting to write a non-zero value into the reserved bits of the MXCSR register.
- Executing an SSE/SSE2/SSE3 instruction that attempts to access a 128-bit memory location that is not aligned on a 16-byte boundary when the instruction requires 16-byte alignment. This condition also applies to the stack segment.

A program or task can be restarted following any general-protection exception. If the exception occurs while attempting to call an interrupt handler, the interrupted program can be restartable, but the interrupt may be lost.

### Exception Error Code

The processor pushes an error code onto the exception handler's stack. If the fault condition was detected while loading a segment descriptor, the error code contains a segment selector to or IDT vector number for the descriptor; otherwise, the error code is 0. The source of the selector in an error code may be any of the following:

- An operand of the instruction.
- A selector from a gate which is the operand of the instruction.
- A selector from a TSS involved in a task switch.
- IDT vector number.

### Saved Instruction Pointer

The saved contents of CS and EIP registers point to the instruction that generated the exception.

### Program State Change

In general, a program-state change does not accompany a general-protection exception, because the invalid instruction or operation is not executed. An exception handler can be designed to correct all of the conditions that cause general-protection exceptions and restart the program or task without any loss of program continuity.

If a general-protection exception occurs during a task switch, it can occur before or after the commit-to-new-task point (see Section 9.3, "Task Switching"). If it occurs before the commit point, no program state change occurs. If it occurs after the commit point, the processor will load all the state information from the new TSS (without performing any additional limit, present, or type checks) before it generates the exception. The general-protection exception handler should thus not rely on being able to use the segment selectors found in the CS, SS, DS, ES, FS, and GS registers without causing another exception. (See the Program State Change description for "Interrupt 10—Invalid TSS Exception (#TS)" in this chapter for additional information on how to handle this situation.)

### General Protection Exception in 64-bit Mode

The following conditions cause general-protection exceptions in 64-bit mode:

- If the memory address is in a non-canonical form.
- If a segment descriptor memory address is in non-canonical form.
- If the target offset in a destination operand of a call or jmp is in a non-canonical form.
- If a code segment or 64-bit call gate overlaps non-canonical space.
- If the code segment descriptor pointed to by the selector in the 64-bit gate doesn't have the L-bit set and the D-bit clear.
- If the EFLAGS.NT bit is set in IRET.
- If the stack segment selector of IRET is null when going back to compatibility mode.
- If the stack segment selector of IRET is null going back to CPL3 and 64-bit mode.
- If a null stack segment selector RPL of IRET is not equal to CPL going back to non-CPL3 and 64-bit mode.
- If the proposed new code segment descriptor of IRET has both the D-bit and the L-bit set.

- If the segment descriptor pointed to by the segment selector in the destination operand is a code segment and it has both the D-bit and the L-bit set.
- If the segment descriptor from a 64-bit call gate is in non-canonical space.
- If the DPL from a 64-bit call-gate is less than the CPL or than the RPL of the 64-bit call-gate.
- If the type field of the upper 64 bits of a 64-bit call gate is not 0.
- If an attempt is made to load a null selector in the SS register in compatibility mode.
- If an attempt is made to load null selector in the SS register in CPL3 and 64-bit mode.
- If an attempt is made to load a null selector in the SS register in non-CPL3 and 64-bit mode where RPL is not equal to CPL.
- If an attempt is made to clear CR0.PG while IA-32e mode is enabled.
- If an attempt is made to set a reserved bit in CR3, CR4 or CR8.

## Interrupt 14—Page-Fault Exception (#PF)

**Exception Class**      **Fault.**

### Description

Indicates that, with paging enabled (the PG flag in the CR0 register is set), the processor detected one of the following conditions while using the page-translation mechanism to translate a linear address to a physical address:

- The P (present) flag in a page-directory or page-table entry needed for the address translation is clear, indicating that a page table or the page containing the operand is not present in physical memory.
- The procedure does not have sufficient privilege to access the indicated page (that is, a procedure running in user mode attempts to access a supervisor-mode page). If the SMAP flag is set in CR4, a page fault may also be triggered by code running in supervisor mode that tries to access data at a user-mode address. If either the PKE flag or the PKS flag is set in CR4, the protection-key rights registers may cause page faults on data accesses to linear addresses with certain protection keys.
- Code running in user mode attempts to write to a read-only page. If the WP flag is set in CR0, the page fault will also be triggered by code running in supervisor mode that tries to write to a read-only page.
- An instruction fetch to a linear address that translates to a physical address in a memory page with the execute-disable bit set (for information about the execute-disable bit, see Chapter 5, “Paging”). If the SMEP flag is set in CR4, a page fault will also be triggered by code running in supervisor mode that tries to fetch an instruction from a user-mode address.
- One or more reserved bits in paging-structure entry are set to 1. See description below of RSVD error code flag.
- A shadow-stack access is made to a page that is not a shadow-stack page. See Section 18.2, “Shadow Stacks,” in the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 1, and Section 5.6, “Access Rights.”
- An enclave access violates one of the specified access-control requirements. See Section 36.3, “Access-control Requirements,” and Section 36.20, “Enclave Page Cache Map (EPCM),” in Chapter 36, “Enclave Access Control and Data Structures.” In this case, the exception is called an **SGX-induced page fault**. The processor uses the error code (below) to distinguish SGX-induced page faults from ordinary page faults.

The exception handler can recover from page-not-present conditions and restart the program or task without any loss of program continuity. It can also restart the program or task after a privilege violation, but the problem that caused the privilege violation may be uncorrectable.

See also: Section 5.7, “Page-Fault Exceptions.”

### Exception Error Code

Yes (special format). The processor provides the page-fault handler with two items of information to aid in diagnosing the exception and recovering from it:

- An error code on the stack. The error code for a page fault has a format different from that for other exceptions (see Figure 7-11). The processor establishes the bits in the error code as follows:
  - P flag (bit 0).  
This flag is 0 if there is no translation for the linear address because the P flag was 0 in one of the paging-structure entries used to translate that address.
  - W/R (bit 1).  
If the access causing the page-fault exception was a write, this flag is 1; otherwise, it is 0. This flag describes the access causing the page-fault exception, not the access rights specified by paging.
  - U/S (bit 2).  
If a user-mode access caused the page-fault exception, this flag is 1; it is 0 if a supervisor-mode access did so. This flag describes the access causing the page-fault exception, not the access rights specified by paging.

- RSVD flag (bit 3).  
This flag is 1 if there is no translation for the linear address because a reserved bit was set in one of the paging-structure entries used to translate that address.
- I/D flag (bit 4).  
This flag is 1 if the access causing the page-fault exception was an instruction fetch. This flag describes the access causing the page-fault exception, not the access rights specified by paging.
- PK flag (bit 5).  
This flag is 1 if the access causing the page-fault exception was a data access to a linear address with a protection key for which the protection-key rights registers disallow access.
- SS (bit 6).  
If the access causing the page-fault exception was a shadow-stack access (including shadow-stack accesses in enclave mode), this flag is 1; otherwise, it is 0. This flag describes the access causing the page-fault exception, not the access rights specified by paging.
- HLAT (bit 7).  
This flag is 1 if there is no translation for the linear address using HLAT paging because, in one of the paging-structure entries used to translate that address, either the P flag was 0 or a reserved bit was set. An error code will set this flag only if it clears bit 0 or sets bit 3. This flag will not be set by a page fault resulting from a violation of access rights, nor for one encountered during ordinary paging, including the case in which there has been a restart of HLAT paging.
- SGX flag (bit 15).  
This flag is 1 if the exception is unrelated to paging and resulted from violation of SGX-specific access-control requirements. Because such a violation can occur only if there is no ordinary page fault, this flag is set only if the P flag (bit 0) is 1 and the RSVD flag (bit 3) and the PK flag (bit 5) are both 0.

See Section 5.6, “Access Rights,” and Section 5.7, “Page-Fault Exceptions,” for more information about page-fault exceptions and the error codes that they produce.



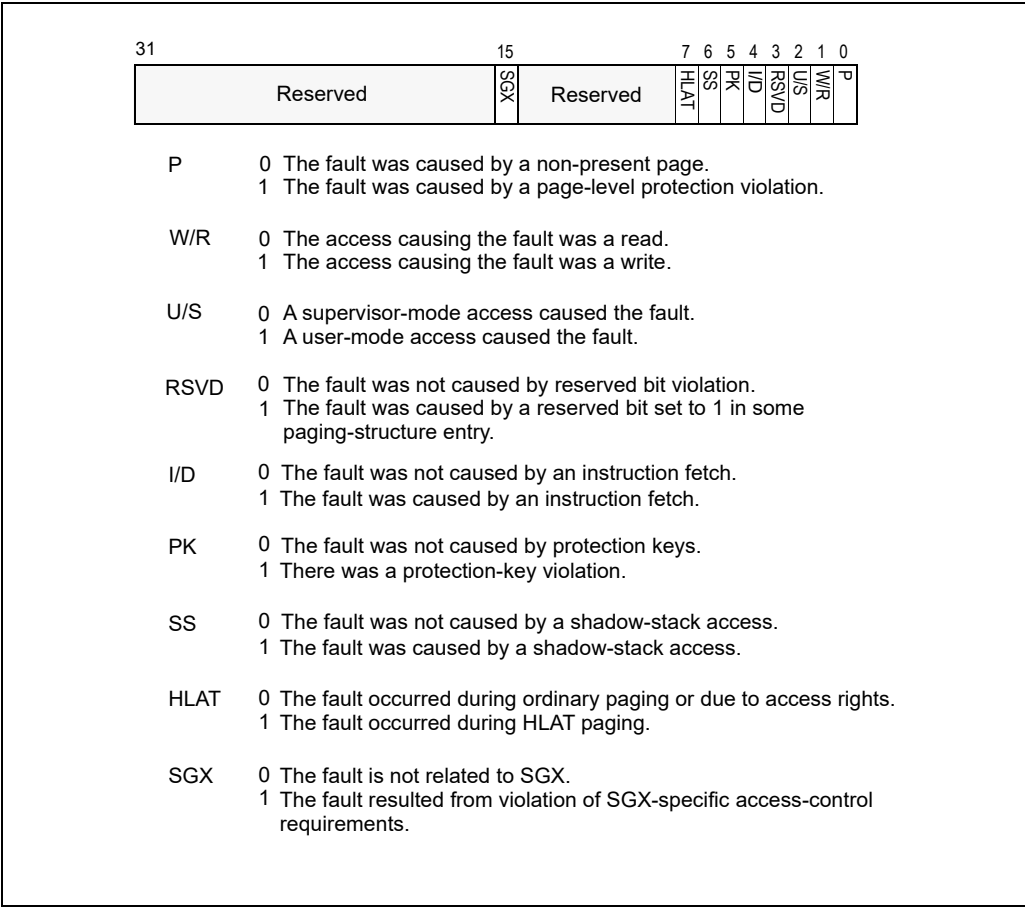


Figure 7-11. Page-Fault Error Code

- The contents of the CR2 register. The processor loads the CR2 register with the linear address that generated the exception. If linear-address masking had been in effect (Section 4.4), the address recorded reflects the result of that masking and does not contain any masked metadata. If the page-fault exception occurred during execution of an instruction in enclave mode (and not during delivery of an event incident to enclave mode), bits 11:0 of the address are cleared.  
The page-fault handler can use this address to locate the corresponding paging-structure entries. Another page fault can potentially occur during execution of the page-fault handler; the handler should save the contents of the CR2 register before a second page fault can occur.<sup>1</sup> If a page fault is caused by a page-level protection violation, the accessed flags in paging-structure entries may be set when the fault occurs (behavior is model-specific and not architecturally defined).

Saved Instruction Pointer

The saved contents of CS and EIP registers generally point to the instruction that generated the exception. If the page-fault exception occurred during a task switch, the CS and EIP registers may point to the first instruction of the new task (as described in the following “Program State Change” section).

1. Processors update CR2 whenever a page fault is detected. If a second page fault occurs while an earlier page fault is being delivered, the faulting linear address of the second fault will overwrite the contents of CR2 (replacing the previous address). These updates to CR2 occur even if the page fault results in a double fault or occurs during the delivery of a double fault.

## Program State Change

A program-state change does not normally accompany a page-fault exception, because the instruction that causes the exception to be generated is not executed. After the page-fault exception handler has corrected the violation (for example, loaded the missing page into memory), execution of the program or task can be resumed.

When a page-fault exception is generated during a task switch, the program-state may change, as follows. During a task switch, a page-fault exception can occur during any of following operations:

- While writing the state of the original task into the TSS of that task.
- While reading the GDT to locate the TSS descriptor of the new task.
- While reading the TSS of the new task.
- While reading segment descriptors associated with segment selectors from the new task.
- While reading the LDT of the new task to verify the segment registers stored in the new TSS.

In the last two cases the exception occurs in the context of the new task. The instruction pointer refers to the first instruction of the new task, not to the instruction which caused the task switch (or the last instruction to be executed, in the case of an interrupt). If the design of the operating system permits page faults to occur during task-switches, the page-fault handler should be called through a task gate.

If a page fault occurs during a task switch, the processor will load all the state information from the new TSS (without performing any additional limit, present, or type checks) before it generates the exception. The page-fault handler should thus not rely on being able to use the segment selectors found in the CS, SS, DS, ES, FS, and GS registers without causing another exception. (See the Program State Change description for “Interrupt 10—Invalid TSS Exception (#TS)” in this chapter for additional information on how to handle this situation.)

## Additional Exception-Handling Information

Special care should be taken to ensure that an exception that occurs during an explicit stack switch does not cause the processor to use an invalid stack pointer (SS:ESP). Software written for 16-bit IA-32 processors often use a pair of instructions to change to a new stack, for example:

```
MOV SS, AX
MOV SP, StackTop
```

When executing this code on one of the 32-bit IA-32 processors, it is possible to get a page fault, general-protection fault (#GP), or alignment check fault (#AC) after the segment selector has been loaded into the SS register but before the ESP register has been loaded. At this point, the two parts of the stack pointer (SS and ESP) are inconsistent. The new stack segment is being used with the old stack pointer.

The processor does not use the inconsistent stack pointer if the exception handler switches to a well defined stack (that is, the handler is a task or a more privileged procedure). However, if the exception handler is called at the same privilege level and from the same task, the processor will attempt to use the inconsistent stack pointer.

In systems that handle page-fault, general-protection, or alignment check exceptions within the faulting task (with trap or interrupt gates), software executing at the same privilege level as the exception handler should initialize a new stack by using the LSS instruction rather than a pair of MOV instructions, as described earlier in this note.

When the exception handler is running at privilege level 0 (the normal case), the problem is limited to procedures or tasks that run at privilege level 0, typically the kernel of the operating system.

## Interrupt 16—x87 FPU Floating-Point Error (#MF)

**Exception Class**      **Fault.**

### Description

Indicates that the x87 FPU has detected a floating-point error. The NE flag in the register CR0 must be set for an interrupt 16 (floating-point error exception) to be generated. (See Section 2.5, “Control Registers,” for a detailed description of the NE flag.)

### NOTE

SIMD floating-point exceptions (#XM) are signaled through interrupt 19.

While executing x87 FPU instructions, the x87 FPU detects and reports six types of floating-point error conditions:

- Invalid operation (#I)
  - Stack overflow or underflow (#IS)
  - Invalid arithmetic operation (#IA)
- Divide-by-zero (#Z)
- Denormalized operand (#D)
- Numeric overflow (#O)
- Numeric underflow (#U)
- Inexact result (precision) (#P)

Each of these error conditions represents an x87 FPU exception type, and for each of exception type, the x87 FPU provides a flag in the x87 FPU status register and a mask bit in the x87 FPU control register. If the x87 FPU detects a floating-point error and the mask bit for the exception type is set, the x87 FPU handles the exception automatically by generating a predefined (default) response and continuing program execution. The default responses have been designed to provide a reasonable result for most floating-point applications.

If the mask for the exception is clear and the NE flag in register CR0 is set, the x87 FPU does the following:

1. Sets the necessary flag in the FPU status register.
2. Waits until the next “waiting” x87 FPU instruction or WAIT/FWAIT instruction is encountered in the program’s instruction stream.
3. Generates an internal error signal that cause the processor to generate a floating-point exception (#MF).

Prior to executing a waiting x87 FPU instruction or the WAIT/FWAIT instruction, the x87 FPU checks for pending x87 FPU floating-point exceptions (as described in step 2 above). Pending x87 FPU floating-point exceptions are ignored for “non-waiting” x87 FPU instructions, which include the FNINIT, FNCLEX, FNSTSW, FNSTSW AX, FNSTCW, FNSTENV, and FNSAVE instructions. Pending x87 FPU exceptions are also ignored when executing the state management instructions FXSAVE and FXRSTOR.

All of the x87 FPU floating-point error conditions can be recovered from. The x87 FPU floating-point-error exception handler can determine the error condition that caused the exception from the settings of the flags in the x87 FPU status word. See “Software Exception Handling” in Chapter 8 of the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 1, for more information on handling x87 FPU floating-point exceptions.

### Exception Error Code

None. The x87 FPU provides its own error information.

### Saved Instruction Pointer

The saved contents of CS and EIP registers point to the floating-point or WAIT/FWAIT instruction that was about to be executed when the floating-point-error exception was generated. This is not the faulting instruction in which the error condition was detected. The address of the faulting instruction is contained in the x87 FPU instruction pointer

register. See Section 8.1.8, “x87 FPU Instruction and Data (Operand) Pointers,” in Chapter 8 of the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 1, for more information about information the FPU saves for use in handling floating-point-error exceptions.

### Program State Change

A program-state change generally accompanies an x87 FPU floating-point exception because the handling of the exception is delayed until the next waiting x87 FPU floating-point or WAIT/FWAIT instruction following the faulting instruction. The x87 FPU, however, saves sufficient information about the error condition to allow recovery from the error and re-execution of the faulting instruction if needed.

In situations where non- x87 FPU floating-point instructions depend on the results of an x87 FPU floating-point instruction, a WAIT or FWAIT instruction can be inserted in front of a dependent instruction to force a pending x87 FPU floating-point exception to be handled before the dependent instruction is executed. See “x87 FPU Exception Synchronization” in Chapter 8 of the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 1, for more information about synchronization of x87 floating-point-error exceptions.

Interrupt 17—Alignment Check Exception (#AC)

Exception Class      **Fault.**

Description

There are two causes of alignment-check exceptions: alignment violations and bus-lock violations.

Alignment Violations

An **alignment violation** occurs when the processor detects an unaligned memory operand when alignment checking was enabled. Alignment checks are only carried out in data (or stack) accesses (not in code fetches or system segment accesses). An example of an alignment violation is a word stored at an odd byte address, or a doubleword stored at an address that is not an integer multiple of 4. Table 7-7 lists the alignment requirements various data types recognized by the processor.

Table 7-7. Alignment Requirements by Data Type

Data Type	Address Must Be Divisible By
Word	2
Doubleword	4
Single precision floating-point (32-bits)	4
Double precision floating-point (64-bits)	8
Double extended precision floating-point (80-bits)	8
Quadword	8
Double quadword	16
Segment Selector	2
32-bit Far Pointer	2
48-bit Far Pointer	4
32-bit Pointer	4
GDTR, IDTR, LDTR, or Task Register Contents	4
FSTENV/FLDENV Save Area	4 or 2, depending on operand size
FSAVE/FRSTOR Save Area	4 or 2, depending on operand size
Bit String	2 or 4 depending on the operand-size attribute.

Note that an alignment violation occurs only for data types that must be aligned on word, doubleword, and quadword boundaries. A general-protection exception (#GP) is generated 128-bit data types that are not aligned on a 16-byte boundary.

To enable alignment checking, the following conditions must be true:

- AM flag in CR0 register is set.
- AC flag in the EFLAGS register is set.
- The CPL is 3 (including virtual-8086 mode).

Alignment violations are generated only when operating at privilege level 3 (user mode). Memory references that default to privilege level 0, such as segment descriptor loads, do not generate alignment violations, even when caused by a memory reference made from privilege level 3.

Storing the contents of the GDTR, IDTR, LDTR, or task register in memory while at privilege level 3 can generate an alignment violation. Although application programs do not normally store these registers, the fault can be avoided by aligning the information stored on an even word-address.

The FXSAVE/XSAVE and FXRSTOR/XRSTOR instructions save and restore a 512-byte data structure, the first byte of which must be aligned on a 16-byte boundary. If alignment violations are enabled when executing these instruc-

tions (and CPL is 3), a misaligned memory operand can cause either an alignment violation or a general-protection exception (#GP) depending on the processor implementation (see “FXSAVE—Save x87 FPU, MMX, SSE, and SSE2 State” and “FXRSTOR—Restore x87 FPU, MMX, SSE, and SSE2 State” in Chapter 3 of the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 2A; see “XSAVE—Save Processor Extended States” and “XRSTOR—Restore Processor Extended States” in Chapter 6 of the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 2D).

The MOVDQU, MOVUPS, and MOVUPD instructions perform 128-bit unaligned loads or stores. The LDDQU instructions loads 128-bit unaligned data. They do not generate general-protection exceptions (#GP) when operands are not aligned on a 16-byte boundary. If alignment checking is enabled, alignment violations may or may not be generated depending on processor implementation when data addresses are not aligned on an 8-byte boundary.

FSAVE and FRSTOR instructions can generate unaligned references, which can cause alignment violations. These instructions are rarely needed by application programs.

### Bus -Lock Violations

Some processors include features that disable bus locks. Section 10.1.2.3 provides details. When these features are enabled, occurrence of a bus lock causes a bus-lock violation, leading to a fault. In some cases, the fault is delivered as an alignment-check exception (#AC). The following are the cases in which bus-lock violation leads to an #AC:

- Split-lock disable is enabled (because MSR\_MEMORY\_CTRL[29] = 1) and locked access to multiple cache lines occurs (a split lock).
- Bus-lock disabled is enabled (because MSR\_MEMORY\_CTRL[28] = 1), CPUID.(EAX=07H, ECX=2):EDX[bit 6] is enumerated as 1 (indicating support for the architectural form of bus-lock disable), and a locked access using a memory type other than WB occurs (a UC lock).<sup>1</sup>

### Exception Error Code

Yes. For alignment violations and bus-lock violations due to split locks, the error code is null, meaning that bits 31:2 of the error code are clear. For bus-lock violations due to UC locks, the error code has value 4, meaning that bit 2 is set.

In either case, bit 0 (EXT) is set if the violation is recognized during delivery of an event other than a software interrupt. (See Section 7.13, “Error Code” and “INT n/INTO/INT3/INT1—Call to Interrupt Procedure” in Chapter 3 of the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 2A.) In such cases, the actual error code delivered will have value 1 or value 5.

### Saved Instruction Pointer

The saved contents of CS and EIP registers point to the instruction that generated the exception.

### Program State Change

A program-state change does not accompany an alignment-check fault, because the instruction is not executed.

---

1. If CPUID.(EAX=07H, ECX=2):EDX[bit 6] is enumerated as 0, the processor may support an older model-specific form of bus-lock disable. That form generates a general-protection exception (#GP) and not an alignment-check exception.

## Interrupt 18—Machine-Check Exception (#MC)

**Exception Class**     **Abort.**

### Description

Indicates that the processor detected an internal machine error or a bus error, or that an external agent detected a bus error. The machine-check exception is model-specific, available on the Pentium and later generations of processors. The implementation of the machine-check exception is different between different processor families, and these implementations may not be compatible with future Intel 64 or IA-32 processors. (Use the CPUID instruction to determine whether this feature is present.)

Bus errors detected by external agents are signaled to the processor on dedicated pins: the BINIT# and MCERR# pins on the Pentium 4, Intel Xeon, and P6 family processors and the BUSCHK# pin on the Pentium processor. When one of these pins is enabled, asserting the pin causes error information to be loaded into machine-check registers and a machine-check exception is generated.

The machine-check exception and machine-check architecture are discussed in detail in Chapter 17, “Machine-Check Architecture.” Also, see the data books for the individual processors for processor-specific hardware information.

### Exception Error Code

None. Error information is provided by machine-check MSRs.

### Saved Instruction Pointer

For the Pentium 4 and Intel Xeon processors, the saved contents of extended machine-check state registers are directly associated with the error that caused the machine-check exception to be generated (see Section 17.3.1.2, “IA32\_MCG\_STATUS MSR,” and Section 17.3.2.6, “IA32\_MCG Extended Machine Check State MSRs”).

For the P6 family processors, if the EIPV flag in the MCG\_STATUS MSR is set, the saved contents of CS and EIP registers are directly associated with the error that caused the machine-check exception to be generated; if the flag is clear, the saved instruction pointer may not be associated with the error (see Section 17.3.1.2, “IA32\_MCG\_STATUS MSR”).

For the Pentium processor, contents of the CS and EIP registers may not be associated with the error.

### Program State Change

The machine-check mechanism is enabled by setting the MCE flag in control register CR4.

For the Pentium 4, Intel Xeon, P6 family, and Pentium processors, a program-state change always accompanies a machine-check exception, and an abort class exception is generated. For abort exceptions, information about the exception can be collected from the machine-check MSRs, but the program cannot generally be restarted.

If the machine-check mechanism is not enabled (the MCE flag in control register CR4 is clear), a machine-check exception causes the processor to enter the shutdown state.

## Interrupt 19—SIMD Floating-Point Exception (#XM)

**Exception Class**     **Fault.**

### Description

Indicates the processor has detected an SSE/SSE2/SSE3 SIMD floating-point exception. The appropriate status flag in the MXCSR register must be set and the particular exception unmasked for this interrupt to be generated.

There are six classes of numeric exception conditions that can occur while executing an SSE/ SSE2/SSE3 SIMD floating-point instruction:

- Invalid operation (#I)
- Divide-by-zero (#Z)
- Denormal operand (#D)
- Numeric overflow (#O)
- Numeric underflow (#U)
- Inexact result (Precision) (#P)

The invalid operation, divide-by-zero, and denormal-operand exceptions are pre-computation exceptions; that is, they are detected before any arithmetic operation occurs. The numeric underflow, numeric overflow, and inexact result exceptions are post-computational exceptions.

See “SIMD Floating-Point Exceptions” in Chapter 11 of the Intel® 64 and IA-32 Architectures Software Developer’s Manual, Volume 1, for additional information about the SIMD floating-point exception classes.

When a SIMD floating-point exception occurs, the processor does either of the following things:

- It handles the exception automatically by producing the most reasonable result and allowing program execution to continue undisturbed. This is the response to masked exceptions.
- It generates a SIMD floating-point exception, which in turn invokes a software exception handler. This is the response to unmasked exceptions.

Each of the six SIMD floating-point exception conditions has a corresponding flag bit and mask bit in the MXCSR register. If an exception is masked (the corresponding mask bit in the MXCSR register is set), the processor takes an appropriate automatic default action and continues with the computation. If the exception is unmasked (the corresponding mask bit is clear) and the operating system supports SIMD floating-point exceptions (the OSXM-MEXCPT flag in control register CR4 is set), a software exception handler is invoked through a SIMD floating-point exception. If the exception is unmasked and the OSXMMEXCPT bit is clear (indicating that the operating system does not support unmasked SIMD floating-point exceptions), an invalid opcode exception (#UD) is signaled instead of a SIMD floating-point exception.

Note that because SIMD floating-point exceptions are precise and occur immediately, the situation does not arise where an x87 FPU instruction, a WAIT/FWAIT instruction, or another SSE/SSE2/SSE3 instruction will catch a pending unmasked SIMD floating-point exception.

In situations where a SIMD floating-point exception occurred while the SIMD floating-point exceptions were masked (causing the corresponding exception flag to be set) and the SIMD floating-point exception was subsequently unmasked, then no exception is generated when the exception is unmasked.

When SSE/SSE2/SSE3 SIMD floating-point instructions operate on packed operands (made up of two or four sub-operands), multiple SIMD floating-point exception conditions may be detected. If no more than one exception condition is detected for one or more sets of sub-operands, the exception flags are set for each exception condition detected. For example, an invalid exception detected for one sub-operand will not prevent the reporting of a divide-by-zero exception for another sub-operand. However, when two or more exceptions conditions are generated for one sub-operand, only one exception condition is reported, according to the precedences shown in Table 7-8. This exception precedence sometimes results in the higher priority exception condition being reported and the lower priority exception conditions being ignored.



**Table 7-8. SIMD Floating-Point Exceptions Priority**

Priority	Description
1 (Highest)	Invalid operation exception due to SNaN operand (or any NaN operand for maximum, minimum, or certain compare and convert operations).
2	QNaN operand <sup>1</sup> .
3	Any other invalid operation exception not mentioned above or a divide-by-zero exception <sup>2</sup> .
4	Denormal operand exception <sup>2</sup> .
5	Numeric overflow and underflow exceptions possibly in conjunction with the inexact result exception <sup>2</sup> .
6 (Lowest)	Inexact result exception.

**NOTES:**

1. Though a QNaN this is not an exception, the handling of a QNaN operand has precedence over lower priority exceptions. For example, a QNaN divided by zero results in a QNaN, not a divide-by-zero- exception.
2. If masked, then instruction execution continues, and a lower priority exception can occur as well.

**Exception Error Code**

None.

**Saved Instruction Pointer**

The saved contents of CS and EIP registers point to the SSE/SSE2/SSE3 instruction that was executed when the SIMD floating-point exception was generated. This is the faulting instruction in which the error condition was detected.

**Program State Change**

A program-state change does not accompany a SIMD floating-point exception because the handling of the exception is immediate unless the particular exception is masked. The available state information is often sufficient to allow recovery from the error and re-execution of the faulting instruction if needed.

## Interrupt 20—Virtualization Exception (#VE)

**Exception Class**      **Fault.**

### Description

Indicates that the processor detected an EPT violation in VMX non-root operation. Not all EPT violations cause virtualization exceptions. See Section 27.5.7.2 for details.

The exception handler can recover from EPT violations and restart the program or task without any loss of program continuity. In some cases, however, the problem that caused the EPT violation may be uncorrectable.

### Exception Error Code

None.

### Saved Instruction Pointer

The saved contents of CS and EIP registers generally point to the instruction that generated the exception.

### Program State Change

A program-state change does not normally accompany a virtualization exception, because the instruction that causes the exception to be generated is not executed. After the virtualization exception handler has corrected the violation (for example, by executing the EPTP-switching VM function), execution of the program or task can be resumed.

### Additional Exception-Handling Information

The processor saves information about virtualization exceptions in the virtualization-exception information area. See Section 27.5.7.2 for details.

## Interrupt 21—Control Protection Exception (#CP)

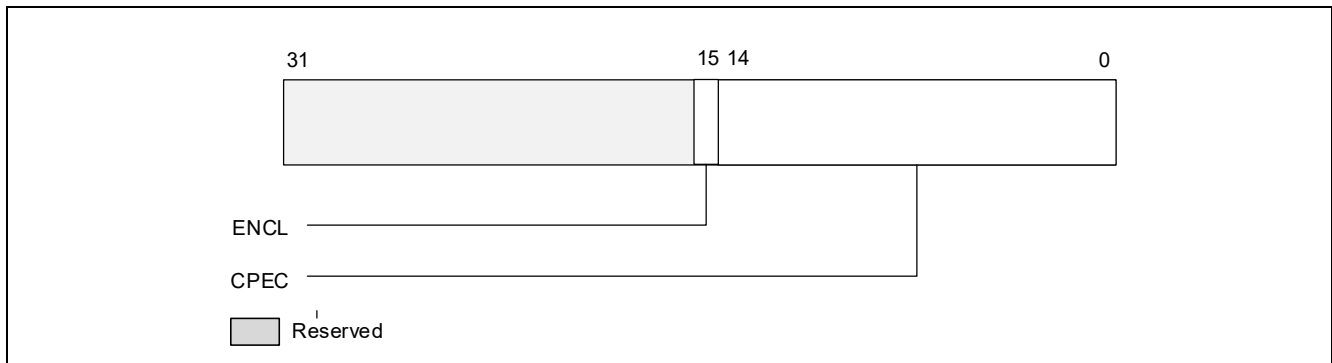
**Exception Class**     **Fault.**

### Description

Indicates a control flow transfer attempt violated the control flow enforcement technology constraints.

### Exception Error Code

Yes (special format). The processor provides the control protection exception handler with following information through the error code on the stack.



**Figure 7-12. Exception Error Code Information**

- Bit 14:0 - CPEC
  - 1 - NEAR-RET: Indicates the #CP was caused by a near RET instruction.
  - 2 - FAR-RET/IRET: Indicates the #CP was caused by a FAR RET or IRET instruction.
  - 3 - ENDBRANCH: indicates the #CP was due to missing ENDBRANCH at target of an indirect call or jump instruction.
  - 4 - RSTORSSP: Indicates the #CP was caused by a shadow-stack-restore token check failure in the RSTORSSP instruction.
  - 5- SETSSBSY: Indicates #CP was caused by a supervisor shadow stack token check failure in the SETSSBSY instruction.
- Bit 15 (ENCL) of the error code, if set to 1, indicates the #CP occurred during enclave execution.

### Saved Instruction Pointer

The saved contents of the CS and EIP registers generally point to the instruction that generated the exception.

### Program State Change

A program-state change does not normally accompany a control protection exception, because the instruction that causes the exception to be generated is not executed.

When a control protection exception is generated during a task switch, the program-state may change as follows. During a task switch, a control protection exception can occur during any of following operations:

- If task switch is initiated by IRET, CS and LIP stored on old task shadow stack do not match CS and LIP of new task (where LIP is the linear address of the return address).
- If task switch is initiated by IRET and SSP of new task loaded from shadow stack of old task (if new task CPL is < 3), OR the SSP from IA32\_PL3\_SSP (if new task CPL = 3) is not aligned to 4 bytes or is a value beyond 4GB.

In these cases the exception occurs in the context of the new task. The instruction pointer refers to the first instruction of the new task, not to the instruction which caused the task switch (or the last instruction to be executed, in the case of an interrupt). If the design of the operating system permits control protection faults to occur during task-switches, the control protection fault handler should be called through a task gate.

## Interrupts 32 to 255—User Defined Interrupts

**Exception Class**      **Not applicable.**

### Description

Indicates that the processor did one of the following things:

- Executed an INT *n* instruction where the instruction operand is one of the vector numbers from 32 through 255.
- Responded to an interrupt request at the INTR pin or from the local APIC when the interrupt vector number associated with the request is from 32 through 255.

### Exception Error Code

Not applicable.

### Saved Instruction Pointer

The saved contents of CS and EIP registers point to the instruction that follows the INT *n* instruction or instruction following the instruction on which the INTR signal occurred.

### Program State Change

A program-state change does not accompany interrupts generated by the INT *n* instruction or the INTR signal. The INT *n* instruction generates the interrupt within the instruction stream. When the processor receives an INTR signal, it commits all state changes for all previous instructions before it responds to the interrupt; so, program execution can resume upon returning from the interrupt handler.

## 8.1 INTRODUCTION

This chapter provides details of an architectural feature called **user interrupts**.

This feature defines user interrupts as new events in the architecture. User interrupts are delivered to software operating in 64-bit mode with CPL = 3 without any change to segmentation state. An individual user interrupt is identified by a 6-bit user-interrupt vector, which is pushed on the stack as part of user-interrupt delivery. The UIRET (user-interrupt return) instruction reverses user-interrupt delivery.

System software configures the user-interrupt architecture with MSRs. An operating system (OS) may update the content of some of these MSRs when switching between OS-managed threads.

One of these MSRs references a data structure called the **user posted-interrupt descriptor (UPID)**. User interrupts for an OS-managed thread can be posted in the UPID associated with that thread. Such user interrupts will be delivered after receipt of an ordinary interrupt (identified in the UPID) called a **user-interrupt notification**.<sup>1</sup>

System software can define operations to post user interrupts and to send user-interrupt notifications. In addition, the user-interrupt feature defines the SENDUIPI instruction, by which application software can send interprocessor user interrupts (user IPIs). An execution of SENDUIPI posts a user interrupt in a UPID and may send a user-interrupt notification.

(Platforms may include mechanisms to process external interrupts as either ordinary interrupts or user interrupts. Those processed as user interrupts would be posted in UPIDs and may result in user-interrupt notifications. Specifics of such mechanisms are outside of the scope of this manual.)

Section 8.2 explains how a processor enumerates support for user interrupts and how they are enabled by system software. Section 8.3 identifies the new processor state defined for user interrupts. Section 8.4 explains how a processor identifies and delivers user interrupts. Section 8.5 describes how a processor identifies and processes user-interrupt notifications. Section 8.6 enumerates new instructions that support management of user interrupts. Section 8.8 defines new support for user inter-processor interrupts (user IPIs).

## 8.2 ENUMERATION AND ENABLING

Software enables user interrupts by setting bit 25 (UINTR) in control register CR4. Setting CR4.UINTR enables user-interrupt delivery (Section 8.4.2), user-interrupt notification identification (Section 8.5.1), and the user-interrupt instructions (Section 8.6). It does not affect the accessibility of the user-interrupt MSRs (Section 8.3) by RDMSR, WRMSR or the XSAVE feature set.

Processor support for user interrupts is enumerated by CPUID.(EAX=7,ECX=0):EDX[5]. If this bit is set, software can set CR4.UINTR to 1 and can access the user-interrupt MSRs using RDMSR and WRMSR (see Section 8.3).

The user-interrupt feature is XSAVE-managed (see Section 13.5). This implies that aspects of the feature are enumerated as part of enumeration of the XSAVE feature set. See Section 13.5.11 in the Intel® 64 and IA-32 Architectures Software Developer's Manual, Volume 1, for details.

## 8.3 USER-INTERRUPT STATE AND USER-INTERRUPT MSRS

The user-interrupt architecture defines the following new state. Some of this state can be accessed via the RDMSR and WRMSR instructions (through new user-interrupt MSRs detailed in Section 8.3.2) and some can be accessed using instructions described in Section 8.6.

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1. For clarity, this chapter uses the term **ordinary interrupts** to refer to those events in the existing interrupt architecture, which are typically delivered to system software operating with CPL = 0.