#### **LINEAR SIMULTANEOUS EQUATIONS**

#### **Input Test Case**

$$4x_1 + 2x_2 = 10$$

$$2x_1 + 4x_2 + x_3 = 11.5$$

$$x_2 + 5x_3 = 4.5$$

#### 1) Gauss Elimination (Without Pivoting)

**INPUT:** 

3

42010

2 4 1 11.5

0154.5

**OUTPUT:** 

X

1.500000

2.000000

0.500000

Gauss Elimination Method is good for finding roots of simultaneous equations but it diverges if matrix is not pivoted and completely different answers with high error can be obtained.

#### 2) Gauss Elimination (With Partial Pivoting)

**INPUT:** 

3

42010

2 4 1 11.5

0154.5

**OUTPUT:** 

X

1.500000

2.000000

0.500000

The partial pivoting technique is used to avoid round-off errors that could be caused when dividing every entry of a row by a pivot value that is relatively small in comparison to its remaining row entries.

3) LU Decomposition (Doolittle Method – Without

**Pivoting)** 

**INPUT:** 

3

42010

2 4 1 11.5

0154.5

OUTPUT:

Х

1.500000

2.000000

0.500000

L

1.000000 0.000000 0.000000

0.500000 1.000000 0.000000

0.000000 0.333333 1.000000

U

4.000000 2.000000 0.000000

0.000000 3.000000 1.000000

0.000000 0.000000 4.666667

n² equations and n² unknowns

**Equations are solved simultaneously in two steps:** 

1. UX = Y

2. LY = B

To solve AX = B where A=LU

4) LU Decomposition (Crout Method – Without

**Pivoting)** 

**INPUT:** 

3

42010

2 4 1 11.5

0154.5

OUTPUT:

Χ

1.500000

2.000000

0.500000

L

4.000000 0.000000 0.000000

2.000000 3.000000 0.000000

0.000000 1.000000 4.666667

U

1.000000 0.500000 0.000000

0.000000 1.000000 0.333333

0.000000 0.000000 1.000000

Complexity of the Crout Method is similar to Doolittle Method, involves the same procedure. It differ slightly in formulation of L and U.

# 5) LU Decomposition (Cholesky Method – Without Pivoting)

**INPUT:** 

3

42010

2 4 1 11.5

0 1 5 4.5

OUTPUT:

X

1.500000

2.000000

0.500000

ı

2.000000 0.000000 0.000000

1.000000 1.732051 0.000000

0.000000 0.577350 2.160247

n (n+1)/2 equations and n(n+1)/2 unknowns

**Equations are solved simultaneously in two steps:** 

1. UX = Y

2. LY = B

To solve AX = B where A=LU

**Effective for Symmetric Matrices** 

#### **EIGENVALUES**

### **Input Test Case**

$$A = \begin{bmatrix} 8 & -1 & -1 \\ -1 & 4 & -2 \\ -1 & -2 & 10 \end{bmatrix}$$

Maximum iterations: 50

Maximum relative approximate error: 0.001%

Find Eigenvalue closest to: 8

# 1) Power Method

INPUT:

3

8 -1 -1

-14-2

-1 -2 10

100

0.001

OUTPUT:

**Eigenvalue** 

10.7788

**Eigenvector** 

-0.267587

-0.255597

1.000000

**Iterations** 

32

Power Method works best when there is dominant eigenvalue.

No. of Eigenvalues = Dimension of Symmetric Matrix

But, with power method we are limited to finding only the maximum eigenvalue.

#### 2) Inverse Power Method

**INPUT:** 

3

8 -1 -1

-14-2

-1 -2 10

100

0.001

OUTPUT:

Eigenvalue

3.0749

**Eigenvector** 

0.269593

1.000000

0.327737

**Iterations** 

12

Inverse Power Method is for finding the smallest eigenvalues, works best when there is dominant eigenvalue.

Similar complexity as that of Power Method

# 3) Inverse Power Method with Shift

**INPUT:** 

3

8 -1 -1

-14-2

-1 -2 10

100

0.001

OUTPUT:

Eigenvalue

8.1461

Eigenvector

1.000000

-0.329774

0.183644

**Iterations** 

6

Inverse Power Method with Shift is for finding the eigenvalues that is close to given value, but still we can find one at a time

Similar complexity as that of Power Method

# 4) QR Method

INPUT:

3

8 -1 -1

-14-2

-1 -2 10

100

0.001

OUTPUT:

Eigenvalues

10.7789

8.1462

3.0749

Iterations

25