

AP Stats Notes

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Contents

1	Data Analysis	5
1.1	What is Statistics?	5
1.2	Analyzing Categorical Data	5
1.2.1	One-Variable Categorical Data	5
1.2.2	Two-Variable Categorical Data	6
1.3	Analyzing Quantative Data with Graphs	7
1.4	Describing Quantative Data with Numbers	8
2	Modelling Distributions	10
2.1	Describing Location in a Distribution	10
2.1.1	Transforming Data	10
2.2	Density Curves	11
2.2.1	Normal Distributions	11
2.2.2	Assessing Normality	12
3	Two-Variable Data	13
3.1	Scatterplots and Correlation	13
3.2	Least-Squares Regression	14
3.2.1	Residuals	14
3.2.2	Least-Square Regression Lines	14
3.2.3	Problems with Least-Square Regression Lines	15
3.2.4	Strength of regression lines	15
3.3	Transforming to Achieve Linearity	16
3.3.1	Power Models	16
3.3.2	Transforming with Logarithms	16
4	Collecting Data	17
4.1	Sampling and Surveys	17
4.1.1	What is Bias?	17
4.1.2	Sources of Bias	17
4.1.3	How to Avoid Bias	18
4.2	Experiments	19
4.2.1	Principles of Experimental Design	20
4.3	Using Studies Wisely	20
4.3.1	Data Ethics*	21
5	Probability	22
5.1	Randomness	22
5.1.1	Simulation	22

5.1.2	Probability Models	22
5.2	Rules of Probability	23
5.3	Conditional Probability	23
5.4	Independence	24
6	Random Variables and Distributions	25
6.1	Random Variables	25
6.1.1	Discrete Random Variables	25
6.1.2	Continuous Random Variables	26
6.2	Transforming and Combining Random Variables	26
6.3	Binomial and Geometric Random Variables	27
6.3.1	Binomial Variables	27
6.3.2	Geometric Variables	28
7	Sampling Distributions	29
7.1	What is a Sampling Distribution	29
7.1.1	Biased and Unbiased Estimators	30
7.2	Sample Proportion Distributions	30
7.3	Sample Mean Distributions	31
8	Confidence Intervals	32
9	Significance Tests	33
9.1	Basics of Significance Tests	33
9.1.1	Hypotheses	33
9.1.2	P-values	33
9.1.3	Type I and Type II Errors	35
9.1.4	Power	35
9.1.5	Steps for Significance Tests	35
9.2	Tests About a Population Proportion	36
9.3	Tests About a Difference in Proportions	37
10	Estimating Means	38
10.1	One-Sample t intervals	38
10.2	Two-Sample t intervals for a Difference between Two Means	39
10.3	Paired t interval For a Mean Difference	39
11	Confidence with Means	40
11.1	Tests about a Population Mean	40

12 Inference for Distributions and Relationships	41
12.1 Chi-Square Tests for Goodness of Fit	41
12.2 Inference for Two-Way Tables	43
12.2.1 Chi-square tests for homogeneity	43
12.2.2 Chi-square tests for independence	44
12.2.3 Differences between Homogeneity and Independence . .	44
12.3 Inference for Slope	45

using *The Practice of Statistics for the AP Exam: 6th Edition* by Starnes and Tabor

1 Data Analysis

1.1 What is Statistics?

Definition 1 (Statistics). The science of collecting, analyzing, and drawing conclusions from data.

Data is collected from *individuals* about certain *variables*.

Definition 2 (Individual, Variable). **Individuals** are objects described in a dataset. Typically people, but not always.

Variables are attributes that can take different values for different individuals.

For example, *individuals* may be households, and *variables* may be region, number of people, household income, etc. It's important to distinguish between *categorical* and *quantitative* variables:

Definition 3 (Categorical and Quantitative Variables). **Categorical Variables** are variables whose values can be placed into distinct categories.

Quantitative Variables are variables whose values are quantities, typically counts or measurements.

For example, region would be categorical, while household income would be quantitative. *Not all numbers are quantitative*; eg. zip code.

1.2 Analyzing Categorical Data

1.2.1 One-Variable Categorical Data

Definition 4 (Frequency and Relative Frequency Tables). **Frequency Tables** shows the number of individuals that have values of a certain category. **Relative Frequency Tables** shows the proportion or percent of individuals in each category.

Note (relative) frequencies are not data; they summarize data. Bar graphs and Pie Graphs summarize relative frequency tables.

Beware of misleading graphs; we mainly react to the area of each bar, not the actual height.

	Like Skateboards	Do Not Like Skateboards	Totals
Like Snowmobiles	80	25	105
Do not like Snowmobiles	45	10	55
Totals	125	35	160

MathBits.com

Figure 1: An example two-way table with additional summary information.

1.2.2 Two-Variable Categorical Data

Use a two-way table to summarize data about two categorical variables. These tables can be used to answer questions about *marginal*, *joint*, and *conditional relative frequencies*.

Margial relative frequencies give the percent or proportion of individuals that have a given value for one categorical variable. For example, the marginal relative frequency of liking skateboards is $\frac{125}{160} \approx 78.125\%$.

Joint relative frequencies give the percent or proportion of individuals that have a specific value for both categorical variables. For example, the joint frequency of liking both skateboards and snowmobiles is $\frac{80}{160} = 50\%$.

Conditional relative frequencies give the percent or proportion of individuals that have a specific value for one categorical variable relative to other individuals with the same other categorical variable. For example, the conditional relative frequency of those who like snowmobiles out of all individuals that like skateboards is $\frac{80}{125} = 64\%$.

These frequencies can be summarized in *side by side bar graphs*, *segregated bar graphs*, or *mosaic plots*.

Graphs and these tables can be used to show **association** between two variables. There is association between two variables if knowing the value of one helps to predict the other. For example, knowing that an individual likes skateboards helps predict whether they like snowmobiles ($\frac{80}{125} = 64\%$ vs $\frac{25}{35} \approx 71.4\%$). **ASSOCIATION DOES NOT IMPLY CAUSATION!**

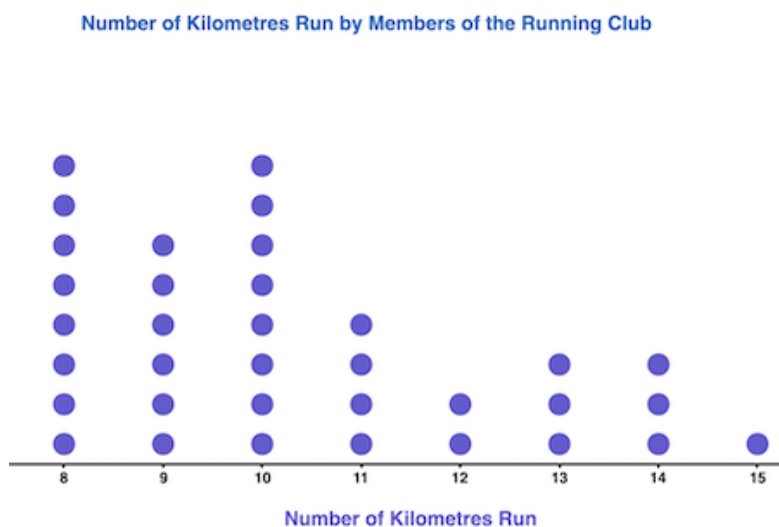


Figure 2: A dotplot showing the distribution of kilometers run by members of the running club.

1.3 Analyzing Quantative Data with Graphs

Dotplots (as shown above) show each individual as a dot above their quantitative data value.

When describing the shape of a dotplot (or other quantitative graphs), *focus on main features*: major peaks, clusters, or gaps. Especially note whether the distribution is roughly symmetric or skewed:

Definition 5 (Symmetric, Skewed). A distribution is roughly **symmetric** if the right side of the graph has roughly the same shape as the left side.

A distribution is **skewed to the right** if the right 'tail' has less values than the left; typically, the left has a peak whereas the right does not. **Left-skewed** definition are defined similarly to right-skewed distributions.

For example, the distribution of the number of kilometers run is right-skewed because the right 'tail' has less values.

Graphs with a single peak are considered *unimodal*, like the dotplot. Distributions with two peaks are considered *bimodal*, and beyond that is considered *multimodal*.

When describing a distribution of quantitative data, use the acronym ROCS: **R**ange (max - min), **O**utliers (clear departures from the data), **C**enter (mean or median), and **S**hape (symmetry, skew, gaps, peaks).

Leaf plots exist. Stem represents first few digits, leaf represents final digit.

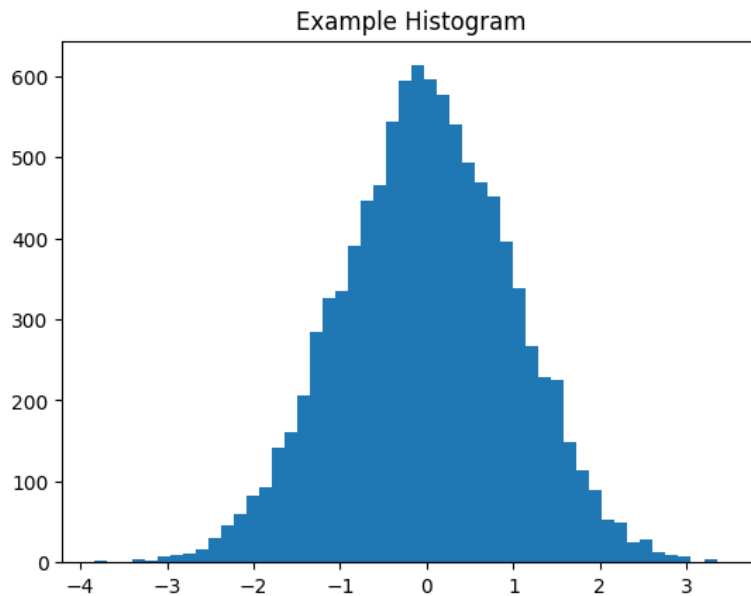


Figure 3: An example histogram with a normal distribution.

Histograms are a notable way of displaying quantative data, as they avoid showing individual data points. Histograms divide the variable into many 'bins' (bars), with the height representing the frequency. Smaller bins show more detail at the cost of a less clear pattern.

Don't confuse histograms and bar graphs. Histograms are used for quantative data, while bar graphs are used for qualatative data.

Use percentages when comapring to distributions in order to remove the effect of a larger sample.

1.4 Describing Quantative Data with Numbers

Definition 6 (Mean: \bar{x}, μ). The average of all individual data values. If there are n observations x_1, x_2, \dots, x_n , the sample mean is calculated by

$$\bar{x} = \frac{\sum x_i}{n}$$

The mean of a **sample** is referred to using \bar{x} , while the mean of a **population** is referred to using μ .

Statistics come from **samples** (small subset of population) and **parameters** come from **populations** (all possible samples of what's being tested).

The mean is not **resistant** as it is sensitive to strong outliers in a distribution. The median *is* a resistant measure of the center of the distribution.

Definition 7 (Median). The 'midpoint' of a distribution. Either the middle element (n is odd) or the average of the two middle elements (n is even) in a **SORTED** distribution.

Using both the mean and the median, one can predict the skew of the data. If a distribution is roughly symmetric without outliers, **the mean and median will be similar**. If a distribution is strongly skewed, **the mean will be pulled in the direction of the skew**. (Mean < Median for left-skewed, Mean > Median for right-skewed)

The **range** (max - min) is one way to show the variability of a distribution. Note that the range is *not* resistant.

Definition 8 (Standard Deviation). The **standard deviation** (s_x, σ) measures the 'average' distance of the values in a distribution from the mean. Standard deviation is calculated by

$$s_x = \sqrt{\frac{\sum (x_i - \bar{x})^2}{n - 1}}$$

The squared stdev is known as **variance** (s_x^2, σ^2). Remember, s_x refers to a sample while σ refers to a population. Larger stdev indicates greater variation, but is not a resistant measure of variability. **Stdev measures variance around the mean; if the mean is skewed, so will stdev!**

The **Interquartile Range (IQR)** is another way to measure variance, using $IQR = Q_3 - Q_1$ where Q represents the quartiles. IQR can be thought of as the range of the 'middle half' of the distribution. *IQR is a resistant measure.*

Lower Outliers < $Q_1 - 1.5 \times IQR$ or High Outliers > $Q_3 + 1.5 \times IQR$

boxplots and the five-number summary = min, Q1, median, Q3, and max exist. **Boxplots don't show gaps, clusters, or multiple peaks.**

be careful with language- 'skews' is a shape, IQR and range are single numbers (no 'in the middle of the IQR')

2 Modelling Distributions

2.1 Describing Location in a Distribution

Definition 9 (Percentile). The p th percentile of a distribution is the value with $p\%$ of observations less than (*or equal, depending on who you ask*) than it. Note that this distinction of whether or not to include "or equal" only matters for discrete variables.

For example, in a class of 25 students, if a student gets a score greater than or equal to 21 other students, then they would be at the 84th percentile in the class's test score distribution ($\frac{21}{25} \approx 84\%$). **An observation is never "in" a percentile; an observation is AT a percentile** (percentile is just a number; like IQR and range). Also, definition, $Q_1 \approx 25$ th percentile, Q_2 (median) ≈ 50 th percentile, and $Q_3 \approx 75$ th percentile. Percentiles can be graphically shown in a **cumulative relative frequency graph**, where the y-coordinates of points are graphed based on their percentile.

Definition 10 (Standardized Score (z-score)). How many standard deviations an individual value is from the mean. For a value p , mean μ , and stdev σ :

$$z = \frac{p - \mu}{\sigma}$$

z-scores provide a way to objectively compare measurements from two distributions while still considering means and variability.

2.1.1 Transforming Data

Effect of adding a constant a :

- Adds a to measures of center and location (mean, median, quartiles, min, max)
- Does not change measures of variability (range, IQR, stdev)
- Does not change the shape of the distribution (percentile; translation along axis)

Effect of multiplying by constant $b > 0$:

- Multiplies measures of center and location by b (mean, median, quartiles, min, max)
- Multiplies measures of variability by $|b|$ (range, IQR, stdev)

- Does not change the *overall* shape of the distribution (percentile; like squish or squash)

z-scores transform any distribution into one with mean 0 and stdev 1, but with the same original shape.

2.2 Density Curves

Definition 11 (Density Curves). A curve that models the distribution of a quantative variable with a curve that

- Is always on (or above) the horizontal axis
- Has an area of exactly 1 underneath

The area under the curve within any interval of values estimates the proportion of all observations that fall into this interval.

No set of quantative data is fully described by a density curve. Density curves are approximations that are easy to use by smoothing out small irregularities in the data. Similarly to finite distributions, distributions will have shapes, often with skews and peaks.

The median of the density curve splits the curve into two equal-area halves of area = 0.5. The mean of the density curve is harder to define. For a density curve described by a function $p(x)$, the mean is given as the below. (Intuitively, this is the idea of a 'weighted average'; weight being its relative density- $p(x)$, in this case- being extended to a continous distribution.)

$$\text{mean of } p(x) = \int_{-\infty}^{\infty} xp(x)dx$$

While the mean-median location principles still apply, they aren't too useful as it's relatively hard to locate the mean of a curve by simply looking at it.

2.2.1 Normal Distributions

As $\lim_{n \rightarrow \infty} n$, binomial distributions will approach a **Normal distribution** (see Chapter 6 or something), which are described using Normal curves.

Definition 12 (Normal Curve). Any normal distribution is described by a symmetric, single-peaked, bell-shaped density curve. Its center is equal to the mean and the median, and the stdev represents the 'width' of the curve. Any normal distribution is fully described by its mean and stdev. A normal

curve's mean is its peak, while the stdev are its inflection points (symmetric around the mean).

Normal distributions with $\mu = 0$ and $\sigma = 1$ is known as a **standard Normal distribution** (which is the same as any other Normal distribution normalized into z-scores). *Remember that mean and stdev only fully describe Normal distributions!*

All normal distributions follow the **empirical rule**: 68%, 95%, and 99.7% of all observations will fall within 1, 2, and 3 stdev around the mean respectively. `normalcdf(upper, lower, mean, stdev)` can be used to find the area under the normal curve (with a given mean and stdev) between upper and lower. Similarly, `invNorm(area to the left, mean, stdev)` calculates the area's percentile value given the mean and stdev. **When using calculator functions like normalcdf, make sure to 1) label what the inputs mean and 2) answer the question asked AS A SENTENCE!**

2.2.2 Assessing Normality

uhh i'll do it later

3 Two-Variable Data

3.1 Scatterplots and Correlation

When analyzing two sets of data, we usually hope to establish a cause-effect relationship between the **independent / explanatory variable** and the **dependent / response variable**. We want to show that knowing the value of the independent value will help predict the dependent variable's value. **Just because knowing the independent value helps us predict the dependent value does not imply direct causation; there may be some other variable influencing both!**

We can analyze two-variable using a scatterplot. To describe a scatterplot, consider the following:

- **DIRECTION:** Does the dependent variable increase (*positive association*) or decrease (*negative association*) with the independent variable? Or does it look like there's no relation between the two? (*no association*)
- **FORM:** Is the data linear or nonlinear? Nonlinear data still shows a pattern, although it's harder to describe.
- **STRENGTH:** How closely does data follow the predicted pattern? Not very much (*strong association*) or a lot (*weak association*)? Or somewhere between? (*moderate association*)
- **OUTLIERS:** Look at distinct departures from the described pattern and distinct clusters of points.

We can directly quantify correlation for linear relationships using the **(linear) correlation r** .

Definition 13 (Correlation r). A measure of the direction and strength of a linear association. Always between -1 and 1, with values closer to each extreme indicating stronger relationships ($r = \pm 1 \rightarrow$ perfectly linear relationship, $r = 0 \rightarrow$ no linear relationship). Positive r suggests positive association, while negative r suggests negative association.

$$r = \frac{1}{n-1} \sum \left(\frac{x_i - \bar{x}}{s_x} \right) \left(\frac{y_i - \bar{y}}{s_y} \right) = \frac{1}{n-1} \sum z_x z_y$$

On a surface level, the formula for r standardizes each variable to avoid the issue of different linear slopes. Other than that, don't ask why this formula works; it's wayyyy too much of a hassle to reasonably prove.

Obviously, r only works if both variables are quantitative; use the word *association* if either variables are categorical. r doesn't differentiate between explanatory and response variables; r will be the same even if you swap the two sets. r also has no units; it's just a scalar.

The linear correlation should only be used when talking about LINEAR relationships: a perfectly quadratic relationship will not give $r = 1$. Linear correlation does not care about form; even if something is curved, linear correlation only measures its 'closeness' to a linear line. **Linear correlation is not resistant; it is GREATLY influenced by extreme points.**

3.2 Least-Squares Regression

Definition 14 (Regression Line). A line of form $\hat{y} = a + bx$ which models how the dependent variable y changes as the independent x changes. (\hat{y} = predicted value of y for given x) **Regression lines require that we consider the x as the independent variable.**

Alternatively, we can think of \hat{y} as the average price for a sample of individuals with the same x value (assuming that our pattern is true). Beware of **extrapolation**: using a regression line to predict outside of the interval of x -values used to obtain the line. The further the values are from the data used to generate the line, the less reliable the prediction is. *Just because regression lines can predict extreme values doesn't mean those values will ever happen!*

3.2.1 Residuals

To determine if a regression line is a good prediction, plot the **residuals** ($y - \hat{y}$ for all data points in the set). No pattern suggests that the regression model is accurate, while a leftover non-zero pattern suggests that this model isn't appropriate. (Close to the x -axis = strength)

Intuitively, we look at the remaining pattern because **form of residual plot = form of association - form of model**. As such, no residual plot form suggests that form of association = form of model (good), while a residual plot form suggests that form of association \neq form of model (bad!!!).

3.2.2 Least-Square Regression Lines

A good regression line minimizes the **sum of the squared residuals**. (Why not the residuals themselves? The sum of all the residuals = 0, so we square it to avoid sign- similar to stdev.) The line that minimizes the squared residuals is known as the **least squares regression line**.

The least-square regression line $\hat{y} = a + bx$ can be calculated as follows:

$$b = r \frac{s_y}{s_x}$$

$$a = \bar{y} - b\bar{x}$$

The formula for the slope can be thought of as "normalizing" the correlation to fit with the specific scenario using the coefficient $\frac{s_y}{s_x}$. (as far as i can tell there's no super intuitive way to think about this. sorry)

The formula for the y-intercept comes from the fact the least-squares regression line will always pass through (\bar{x}, \bar{y}) . Using simple algebra we rearrange for a.

This is called *regression to the mean* because something something predicted values "regress" to the mean somehow.

3.2.3 Problems with Least-Square Regression Lines

Similar to correlation, least-square regression lines are 1) only used to describe linear relationships, 2) not resistant, and 3) only describe patterns in the data, not direct causation.

2 suggests that points with relatively high or low x-values have **high leverage** over the regression line versus other points in the data set. These **outliers** (original def + high residual) are **influential points**; if removed, they substantially change the regression line or measures of strength (see 3.2.4).

3.2.4 Strength of regression lines

To determine the strength of a regression line, we have two methods: the **standard deviation of the residuals** or the **coefficient of determination** r^2 .

The standard deviation of the residuals (s) is pretty obvious: calculate the stdev of the data relative to the prediction. (why $n - 2$? idk it looks rllly complicated)

$$s = \sqrt{\frac{\sum (y_i - \hat{y}_i)^2}{n - 2}}$$

On the other hand, the coefficient of determination measures the percent reduction in the sum of squared residuals when using the regression line vs. using $\hat{y} = \bar{y}$. In other words, it represents the percent of variability in the response variable that is accounted for by the least squares regression line. ($1 - r^2$ can be thought of as the % of variability that's caused by other factors)

than the independent variable.) (It's also equal to the square of the linear correlation, hence the symbol r^2 . why? idk)

$$r^2 = \frac{\sum(y_i - \bar{y})^2 - \sum(y_i - \hat{y})^2}{\sum(y_i - \bar{y})^2}$$

3.3 Transforming to Achieve Linearity

The techniques discussed in 3.1 and 3.2 (obviously) only apply to purely linear relationships. In some special cases, we may be able to **transform the data** from a non-linear pattern into a linear pattern to apply our techniques.

3.3.1 Power Models

Definition 15 (Power Model). Any regression model that takes the form $\hat{y} = ax^p$. Scenarios modeled by these regression models should be expected to do so by geometry (eg. area proportional to square, volume proportional to cube) or some other factor like physics.

While power models (by definition) describe a non-linear relationship between x and y , there will always be a linear relationship between x^p and y . As such, if we raise x to the p th power or take the p th root of y there should be a linear relationship between x^p and y (or x and $\sqrt[p]{y}$).

However, this all assumes p is known. If p isn't known, you could either guess and check (cringe) or use logarithms.

3.3.2 Transforming with Logarithms

If a scenario is modeled by $y = ax^p$, then $\ln(y) = \ln(ax^p) \rightarrow \ln(y) = \ln(a) + p\ln(x)$. Thus, there is a linear relationship between $\ln(x)$ and $\ln(y)$. (*Note that the power p now becomes the slope of the line!*) If the resulting graph turns out to be linear, we can fit a linear regression line to the graph and then use the relation $\hat{y} = e^{a+b\ln(x)}$ to predict values. (This relationship is the same as the power model: $\hat{y} = e^a \times e^{b\ln(x)} = e^a x^b$; e^a is a constant.)

If a scenario is modeled by $y = ab^x$ (an **exponential model**), then $\ln(y) = \ln(ab^x) \rightarrow \ln(y) = \ln(a) + \ln(b)x$. Thus, there is a linear relationship between x and $\ln(y)$. If the resulting graph turns out to be linear, we can fit a linear regression line to the graph and use the relation $\hat{y} = e^{a+bx}$. (This relationship is the same as the exponential model: $\hat{y} = e^a \times e^{bx} = e^a \times (e^b)^x$; e^a and e^b are constants.)

If unsure if an exponential or power model is better, consider their residual plots. If both models have similarly random residual plots, choose the model with the largest r^2 .

4 Collecting Data

most yap based chapter. almost no math :/

4.1 Sampling and Surveys

In statistics, we often want to discover things about a large group of people (the **population**). While we could survey *everybody* in a **census**, this is often incredibly impractical for obvious reasons. Instead, we often consider only a small **sample** (subset) of people to represent the population, in a **sample survey** (a study of a sample to predict things about the population). From the data we observe in the sample, we can make predictions about the population as a whole. *Surveys include but aren't restricted to just questions.* They can include asking people to do something, and observing how they go around doing it.

4.1.1 What is Bias?

Definition 16 (Bias). The design shows bias if it is very likely to underestimate or overestimate the value you're trying to predict. (Remember, the statistical analyses discussed in Chapters 8-12 don't consider bias!)

Bias is not bad luck in one sample- Bias will consistently miss the truth in the same way. When asked to describe how a statistical study shows bias:

- Describe how members of the sample might respond differently vs. the population
- Explain how this difference might lead to an overestimate or underestimate
- **Don't overthink it-** it should be a "common sense" explanation.

4.1.2 Sources of Bias

Definition 17 (Convenience Sampling). Selecting individuals from a population that are easy to reach. May cause bias due to nearby individuals sharing some characteristics (like a club or class) Eg. asking about sports in a library.

Definition 18 (Voluntary Response Sampling). Allowing people to *choose* whether or not they are part of a sample. Often causes bias due to attracting

people who feel strongly about an issue, share some common opinion, or who are more confident.

Definition 19 (Undercoverage). When some members of a population are less likely or unable to be chosen in a sample. Eg. selecting a sample from a list of houses ignores dormitory students, homeless people, and prisoners.

Definition 20 (Nonresponse). When an individual chosen for the sample can't participate (voluntary or involuntary). May lead to bias as those who don't respond may respond differently vs. those who do participate. Eg. landline calling people to ask if they go on runs- people unable to pick up may be on a run and thus run more.

Definition 21 (Response Bias). A systematic pattern of inaccurate answers to a survey question. Often due to **question wording bias**: the wording of the question causes some confusion or leads individual to one specific conclusion.

Voluntary response does not explain why certain people don't respond in an individual survey. Nonresponse can only happen after a sample has been selected. In a voluntary response sample, every individual has *opted* to take part, so there won't be any nonresponse.

4.1.3 How to Avoid Bias

Definition 22 (Random Sampling). Using some sort of chance process to determine which members of a population are included in a sample. **Chance process specifically- not just "arbitrary!"**

Definition 23 (Simple Random Sample (SRS)). A sample size n selected by random sampling such that every group of n individuals in a population has a equal chance of being selected as part of the sample. Should be done using **sampling without replacement**.

When using technology: label all people in the population $1 \dots N$, use a rng to generate n *different* integers $1-N$, then use the people corresponding to the rng. When using a table, **make sure to choose a system s.t. every number has an equal chance of occurring!**

Definition 24 (Sampling with(out) replacement). An individual from a population may only be selected once (without replacement) or multiple times (with replacement).

Definition 25 (Stratified Random Sampling). Dividing a populations into groups that share certain characteristics (**strata**), selecting SRSEs from the strata, then combining them into one random sample. Yield more accurate results **IF** individuals within each strata are **homogenous** (similar).

Definition 26 (Cluster Sampling). Dividing a population into groups in the population into non-overlapping groups (**clusters**) that *don't* share common characteristics, picking some clusters, and then combining them into one random sample. Less accurate than stratification, but obviously more practical-much easier to access clusters vs. strata. Yields more accurate results **IF** individuals within each strata are **heterogenous** (different).

Definition 27 (Systematic Random Sampling). Selecting a sample from an ordered arrangement of the population by randomly selecting one of the first k individuals, then picking every kth individual after for a sample. Very useful for continous streams of people, where the number of people isn't known before hand; eg. voting booths. **If there are patterns in the way the population is ordered that coincide with the pattern being chosen, then the sample likely isn't representative of the population.** (Eg. some people are late, take up more of the sample)

4.2 Experiments

Surveys are one kind of **observational studies**: studies that observe individuals and measures variables of interest, but does not attempt to influence the responses. Split into *retrospective* (look at the past) and *prospective* (look into the future). Prospective studies are more useful than retrospective studies, as other influences on certain variables are much easier to track.

Definition 28 (Experiment). Deliberately imposes conditions (**treatments**) on **experimental units** (the object the treatment is being applied to: if human, use **subjects**) to measure their responses. Treatments are sometimes known as **factors**; **explanatory variables** whose different **levels** may cause different changes in the **response variable**. Surveys show correlation between two variables exist, experiments show cause and effect between two variables.

Experiments should be designed to avoid **confounding**: two or more variables can be shown to possibly be an independent variable without direct conformation (better definition?). One notable type of confounding to consider is the **placebo effect**: some subjects will genuinely improve because they think they will, not due to the treatment. To counteract this, one treatment should typically be a **control group**; a group not given treatment

(whether completely no treatment or fake treatment) in order to compare whether the treatment causes some change.

The placebo effect also applies to the experiment designers, too! Experiments should ideally be **double blind** (neither the subject nor the interviewer knows what treatment the patient is receiving). Obviously, this might not be possible for some experiments. For this case, experiments should still attempt to be **single blind** (either the subjects or the interviewers don't know which treatment a patient is receiving).

There are two discussed types of experiment designs: **Completely Randomized Design**, where experimental units are assigned to treatments completely at random, and **Randomized Block Design**, where experimental units are divided into similar groups (**blocks**; like strata) and then tested using completely randomized testing individually. **Matched Pair design** is one specific type of experimental design for comparing treatments of block size 2. Typically, two very similar experimental units (some type of pair) are made into a block and are given the treatment randomly.

4.2.1 Principles of Experimental Design

- **Comparison:** use a design that compares two or more treatments (at least a Control Group)
- **Random Assignment:** use a chance process to assign experimental units avoids confounding
- **Control:** keep other variables same for all groups, especially other confounders
- **Replication:** more sample size = less likely variation in the effects is due to random chance

4.3 Using Studies Wisely

Obviously, a sample isn't a population, so there's going to be some variation in the data you observe in the sample versus the population. This is known as **sampling variability**. Bigger sample size = less variability. Duh.

When the observed results of a study are too unusual to be explained by chance alone, the results are **statistically significant**. *Statistical significance does not account for bias!*

When inferring from data, keep in mind **what population individuals come from**, and **random assignment to groups allows inference on**

cause and effect. Observational studies should **almost** never be used to demonstrate cause and effect. Unless:

- Association ($R^2?$) is very strong
- Association is consistent (does not vary between different populations)
- Larger values of explanatory = stronger response (stopping = lese response)
- Cause always preceeds effect in time (not something else)
- Alleged cause makes intuitive sense (or has some other history that makes it plausible)

4.3.1 Data Ethics*

i'm not doin allat

5 Probability

Two-way tables and tree diagrams exist, but won't be covered here (cause I'm lazy). Also, they should be pretty intuitive anyways.

5.1 Randomness

Definition 29 (Random Process, Probability, Events). A process that generates outcomes purely determined by chance. The proportion of times a given outcome would occur out of an infinitely long series of trials is the probability of that outcome. By definition as a ratio, probabilities range between 0 and 1, with 0 and 1 representing the outcome never and always happening respectively. The probability of a specific set of outcomes (an event) A is denoted $P(A)$.

By definition, as the number of observed trials of a random outcome approaches infinity, the more the ratio of its occurrence vs. total trials approaches the outcome's probability. **This only applies as the number of observed trials approach infinity.** This does NOT apply to short term situations; randomness is practically never predictable in the short-term.

5.1.1 Simulation

Definition 30 (Simulation). An imitation of a random process in a way that reflects a real-life process.

To use a simulation:

1. Describe how to use an artificial random process (eg. rolling dice, using a random number generator) to perform one trial of the simulation, including what to record at the end of each trial.
2. Using the description, perform many trials of the simulation.
3. Use the results of your simulation to answer the question of interest.

5.1.2 Probability Models

Definition 31 (Probability Model, Sample Space). A probability model is a description of a random process, consisting of the set of the possible outcomes- the sample space- and their respective probabilities.

Definition 32 (Event). A specific set of outcomes from some random process.

5.2 Rules of Probability

Assuming uniform probability, the probability of some event A is

$$P(A) = \frac{\text{number of outcomes in event } A}{\text{total number of possible outcomes}}$$

As discussed in Section 5.1, the probability of any specific is between 0 and 1. For a random process, the probabilities of each event should add up to 1. This implies that *the probability that an event does not occur is 1 - the probability that the event does occur*. The probability that an event does not occur is known as the **compliment** of that event, denoted $P(A^C)$ for some event A .

The symbols \cup and \cap are the **union** and **intersection** between two events. \cup and \cap are logically equivalent to OR and AND respectively.

Definition 33 (Mutually Exclusive (Disjoint) Events). Two events A and B are mutually exclusive or disjoint if they share no outcomes in common: $P(A \cap B) = 0$.

Definition 34 (General Addition Rule). For all events A and B ,

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

5.3 Conditional Probability

Definition 35 (Conditional Probability). The probability that one event occurs given that another event has occurred. The conditional probability that event A occurs given that event B has occurred is denoted $P(A|B)$.

Conditional probability can be calculated as follows:

$$P(A|B) = \frac{\text{number of outcomes where } A \text{ and } B \text{ occur}}{\text{number of outcomes where } B \text{ occurs}} = \frac{P(A \cap B)}{P(B)}$$

Definition 36 (General Multiplication Rule).

$$P(A \cap B) = P(B) \times P(A|B) = P(A) \times P(B|A) = P(A) + P(B) - P(A \cup B)$$

The general multiplication rule can be obtained by multiplying the formula for $P(A|B)$ by $P(B)$ on both sides. Intuitively, the probability of both A and B occurring is equal to the probability that B occurs times the probability that A occurs, given that B occurs, and vice versa.

5.4 Independence

Definition 37 (Independence). Two events A and B are independent if knowing one does not help predict the other. Mathematically:

$$P(B|A) = P(B|A^C) = P(B), P(A|B) = P(A|B^C) = P(A)$$

It can be observed that for independent events, $P(A \cap B) = P(A) \times P(B|A) = P(A) \times P(B)$.

6 Random Variables and Distributions

6.1 Random Variables

Definition 38 (Random Variable). A "variable" that takes on numerical values based on a random process. Typically notated with capital letters, with specific values notated with lowercase letters.

Definition 39 (Probability Distribution). A description of a random variable's possible values and corresponding probabilities. For discrete random variables, often takes the form of a table.

The *median* of a random variable is the 50th percentile of its distribution.

6.1.1 Discrete Random Variables

Definition 40 (Discrete Random Variable DRV). A random variable which has a finite set of distinct possible values. For example, the random variable X = the number of heads when flipping a coin 3 times is discrete.

The probability that a random variable X takes on the value x is notated $P(X = x)$. Using the above definition of X , $P(X = 2) = 3/8$. Similarly, we can notate the probability that a random variable takes on a value greater than or less than a certain value: $P(X > x)$ or $P(X \leq x)$.

Using the same techniques as discussed in Section 1, we can analyze the shapes and features of distributions of random variables. Typically, graphing the random variable's values with respect to the probabilities should indicate most of its features.

To analyze a random variable's center and variability, we use a weighted mean and standard deviation.

Definition 41 (Mean and Expected Value of a DRV). The mean or expected value of a discrete random variable X is its average value over many trials of the same process.

$$\mu_X = E(X) = \sum x_i p_i$$

Definition 42 (Standard Deviation of a DRV). How much the values of a random variable typically vary from the mean over many trials. The standard deviation of DRV X is the square root of the variance of X :

$$\sigma_X = \sqrt{\sigma_x^2} = \sqrt{\sum (x_i - \mu_X)^2 p_i}$$

6.1.2 Continuous Random Variables

Definition 43 (Continuous Random Variable CRV). A random variable which has an unbounded set of possible values. For example, X = the height of a randomly selected student in centimeters.

The probability distribution of a CRV is described using a density curve. The probability of a CRV equalling a specific value is zero: its distribution can only be described in intervals (as the area underneath the probability density curve).

$$P(a \leq X \leq b) = P(a < X < b) = \int_a^b P_X(x)dx$$

The mean and standard deviation can be found by considering the distribution itself, as in Chapters 1 and 2.

6.2 Transforming and Combining Random Variables

Adding and multiplying constants to random variables has literally the same effects as described in Section 2.1.1. To the word.

For any two random variables X and Y :

$$\mu_{X+Y} = \mu_X + \mu_Y$$

$$\mu_{X-Y} = \mu_X - \mu_Y$$

The standard deviation of a sum or difference can only be calculated if the variables are **independent**: knowing one value does not help predict the other. This allows us to apply the probability multiplication of independent events, which can be used to prove (provided here without further proof):

$$\sigma_{X+Y} = \sigma_{X-Y} = \sqrt{\sigma_X^2 + \sigma_Y^2}$$

In words, the variance of $X + Y$ and $X - Y$ are the sum of X and Y 's variances individually, given that they are independent. This logic extends to any number of random variables.

Note that if variables are Normally distributed, then any sum or difference of them will also be Normally distributed. The equations for the mean and stdev discussed here still apply. Use `normalcdf` to find the probability of an event between two bounds.

6.3 Binomial and Geometric Random Variables

6.3.1 Binomial Variables

Definition 44 (Binomial Variable and Distribution). A random variable that describes the number of one particular outcome out of n independent trials of the same random binary process. Binary variables have 4 conditions, **BINS**:

- **Binary**: the possible outcomes can be classified as either "success" or "failure."
- **Independent**: trials are independent- one trial doesn't depend on any of the others.
- **Number**: n is fixed in advance.
- **Same probability**: each trial has the same success rate p .

The probability distribution of a binary variable is known as a **binomial distribution**, and is completely described by n and p .

For a binomial variable B:

$$P(B = x) = \binom{n}{x} p^x (1 - p)^{n-x}$$

$\binom{n}{x}$ is the *binomial coefficient*, and describes the number of ways to arrange x successes among n trials.

$$\binom{n}{x} = \frac{n!}{x!(n-x)!}$$

`binompdf(n, p, x)` and `binomcdf(n, p, x)` can be used to calculate $P(B = x)$ and $P(B \leq x)$ respectively. *Make sure to clearly check whether BINS is satisfied before using binomcdf and binompdf!*

The skew of a binomial distribution is determined by p : $p > 0.5$ results in a left-skewed distribution, $p < 0.5$ results in a right-skewed distribution, with $p \approx 0.5$ resulting in a roughly symmetric distribution.

The peak of the distribution occurs at the mean of the distribution, $\mu_B = E(B) = np$. Intuitively, over many trials, each individual trial will result in a success with a p proportion.

The stdev of a binomial random variable is harder to prove, but can be shown as $\sigma_B = \sqrt{np(1-p)}$. (Intuitively, consider the binomial variable with

1 trial, prob p , success = 1 and failure = 0. The general binomial distribution can be described as the sum of n of these binomial variables).

For the purposes of AP Statistics, when taking a random sample of size n from a population size N , we treat individual observations as "independent" as long as $n < 0.10N$. Beyond 10%, we can no longer treat individual observations as independent.

As stated in Section 2.2, as $\lim n \rightarrow \infty$, approaches the normal distribution with the same mean and stdev. For the purposes of AP Statistics, when the expected number of successes and failures are at least 10 ($np \geq 10$ and $n(1 - p) \geq 10$), approximations of the binomial distribution as Normal are allowed. Intuitively, this ensures that the tails of the distribution are roughly large enough to make up for the missing area in the normal distribution.

6.3.2 Geometric Variables

Definition 45 (Geometric Random Variables and the Geometric Distribution). A random variable that describes the number of trials needed for a constant-probability independent random process to produce at least one "success." The distribution of a geometric random variable is the geometric distribution, which is fully described by the probability p . The possible values for a geometric random variable is \mathbb{N} .

Let G represent a random geometric variable for the rest of this section. It should be fairly obvious that $P(G = x) = (1 - p)^{x-1}p$. (you get failures for 1, 2, ... $n - 1$, then succeed on n).

Similar to `binompdf` and `binomcdf`, `geometpdf` and `geometcdf` (arguments x and p) can be used to calculate $P(G = x)$ and $P(G \leq x)$ respectively.

$\mu_G = \frac{1}{p}$. Intuitively, it takes roughly $\frac{1}{p}$ to roll p at least once, per the definition of probability. The formula for the stdev of a geometric distribution is significantly more annoying to think about, and is provided here without proof:

$$\sigma_G = \frac{\sqrt{1 - p}}{p}$$

The distribution of a geometric random variable is always skewed to the right, as the probability of each successive value decreases by $(1 - p)$. The distribution itself roughly looks like $y \sim \frac{1}{x}$.

7 Sampling Distributions

In statistics, we often want to answer questions about the *parameters* entire population. However, for obvious reasons, this is incredibly impractical. Instead, we take a sample of the population, and use the sample's *statistics* to approximate the parameters. This chapter discusses what we can say about sample statistics *given* the population parameters. Chapters 8 - 11 use this to answer questions about population parameters given sample statistics.

7.1 What is a Sampling Distribution

Definition 46 (Sampling Variability). The idea that different samples of the same population may produce different values for a statistic. If you take 50 samples of $n = 5$ people from a random population, most likely, the average age among the samples will be different.

Definition 47 (Sampling Distribution). The distribution of values taken by a given statistic among all possible samples of the same size from the same population. In other words, the graphical representation of sampling variability.

For small populations, sampling distributions can be generated by considering every possible sample and graphing the sample's corresponding statistics. For large populations, we *approximate* sampling distributions by taking many fixed-size samples, and graphing the corresponding statistics.

There are three distinct distributions involved in obtaining a sampling distribution:

- The **population distribution** describes the value of the variable for all individuals in the population. This has the parameter that we want to know.
- The **distribution of sampling data** describes the value of the variable within a sample. This contains one possible statistic value.
- The **sampling distribution (of the given statistic)** displays the value of the statistic over all samples taken.

Generally, larger sample sizes lead to smaller *sample variability*, and reduce the probability of error. Interestingly, sample variability is NOT dependent on population size, given the 10% condition is upheld. (A cup of corn doesn't care whether it's being scooped from a truck or a bag.)

7.1.1 Biased and Unbiased Estimators

From this distribution, we may see *how trustworthy a sample statistic is as an approximate for a parameter*.

Definition 48 (Unbiased Estimator). A statistic used to estimate a parameter is an **unbiased estimator** if the mean of its sampling distribution is equal to the value of the parameter being estimated. It can be observed that sample proportions and means are unbiased estimators.

Definition 49 (Biased Estimator). A statistic used to estimate a parameter is an **biased estimator** if the mean of its sampling distribution is NOT equal to the value of the parameter being estimated. It can be observed that sample range and variance are biased estimators. (Interestingly, while $\text{Var}(X)$ is a biased estimator, $\text{Var}(X - 1)$ is not: which is why we divide by $n - 1$ in calculating sample standard deviation.)

Just because a statistic is an unbiased estimator does not mean that it is perfectly accurate, just that it will not consistently under or overestimate the parameter. Similarly, these tests do not account for bias within the test itself.

7.2 Sample Proportion Distributions

For the sampling distribution of \hat{p} , it is observed:

- **Shape:** When p is close to zero, the sampling distribution of \hat{p} is skewed to the right. Similarly, when p is close to 1, the sampling distribution is skewed to the right. The sampling distribution becomes more Normal as n gets larger and/or p is closer to 0.5.
- **Center:** Because \hat{p} is an unbiased estimator, $\mu_{\hat{p}} = p$.
- **Variability:** Stdev is low around $p = 0$ or 1, but high around $p = 0.5$. Stdev is inversely proportional to the square root of sample size.

The standard deviation of the sampling distribution of \hat{p} can be found by considering a binomial random variable X . Because $\hat{p} = X/n = (1/n)X$, the mean and the stdev of the sampling distribution is equal to multiplying the binomial mean and stdev by $1/n$:

$$\mu_{\hat{p}} = \frac{np}{n} = p$$

$$\sigma_{\hat{p}} = \frac{1}{n} \sqrt{np(1-p)} = \sqrt{\frac{np(1-p)}{n^2}} = \sqrt{\frac{p(1-p)}{n}}$$

Keep in mind the 10% condition (for roughly consistent stdev) and large counts condition for Normality when using these formulas.

7.3 Sample Mean Distributions

8 Confidence Intervals

9 Significance Tests

Significance Tests are like the opposite of confidence intervals. Instead of using a statistic to find a parameter, significance tests use statistics to test claims about a parameter.

Definition 50 (Significance Test). A formal procedure for using observed statistics in order to decide between two competing claims (*hypotheses*) about parameters.

9.1 Basics of Significance Tests

9.1.1 Hypotheses

Definition 51 (Null Hypothesis, H_0). A claim about a parameter that we weigh evidence **against** in a significance test. Usually a statement of 'no difference' (as claimed).

Definition 52 (Alternative Hypothesis, H_a). The claim that we are trying to find evidence for. Directly contradicts the null hypothesis.

This "Null Hypothesis" and "Alternative Hypothesis" can be thought as trying to prove someone "guilty" or "not guilty."

For example, if a player claims they're a 80% free throw player, the null hypothesis would be $H_0 : p = 0.80$, and the alternative hypothesis would be $H_a : p < 0.80$.

The alternative hypothesis is **one-sided** because we suspect that the player makes less than 80% of his free throws. If we believe that it's equally plausible that they make more than 80% of their free throws, then we would use a **two-sided hypothesis**- $H_a : p \neq 0.80$.

Hypotheses express our beliefs before looking at the data. Modeling a hypothesis around data shows nothing. (11.1) **Just because a test is statistically significant does NOT mean that it is PRACTICALLY significant.** Focus on the P-value and better yet, the data itself. Graph your data and see if differences or outliers are significant, or if there's another pattern emerging. Generally, for practical importance, it's much better to give a confidence interval versus a significance test.

9.1.2 P-values

Definition 53 (P-value). The probability of getting the values observed in the data under the assumption that the null hypothesis H_0 is true.

Small P-values provide convincing evidence for the alternative hypothesis because small values suggest the observed result is unlikely to happen when the null hypothesis is true. Similarly, large P-values provide convincing evidence for the null hypothesis because large values suggest the observed result is likely to happen due to chance if the null hypothesis is true.

In terms of probability notation: P-value = $P(\text{observed data} \mid \text{null hypothesis is true})$.

For two-sided tests, we look at the distance between the null hypothesis and the observed data. For example, if $H_0 : p = 0.5$, $H_a : p \neq 0.5$ and $\hat{p} = 0.65$ (observed proportion), then the P-value = $P(\hat{p} \leq 0.35 \text{ or } \hat{p} \geq 0.6 \mid p = 0.5)$. We look at $\hat{p} \leq 0.35$ because $|p - 0.35| = |p - 0.65|$.

Based on the P-value, we make a conclusion about data:

- If the P-value is small (unlikely to happen by chance), then we "reject H_0 " and conclude that there is convincing evidence for H_a (in context).
- If the P-value is large (likely to happen by chance), then we "fail to reject H_0 " and conclude that there is not convincing evidence for H_a (in context).

How small does a P-value have to be in order to reject H_0 ? We use a given **significance value** for this boundary.

Definition 54 (Significance Level, α). The value that we use as a boundary for deciding whether a P-value is significant enough to disqualify the null hypothesis. α should be stated before data is produced (*cherry-picking*).

$\text{P-value} < \alpha \Rightarrow \text{reject } H_0 \Rightarrow \text{convincing evidence for } H_a \text{ in context}$

$\text{P-value} > \alpha \Rightarrow \text{fail to reject } H_0 \Rightarrow \text{not convincing evidence for } H_a \text{ in context}$

If P is less than the significance level, we say that the result is "statistically significant at the $\alpha = \text{----}$ level." Alternatively, "the results were significant ($P = 0.03 < \alpha = 0.05$)."
Keep in mind a P-value is more informative than a statement of significance!

NEVER "accept H_0 " or conclude that H_0 is true! Always use 'reject' or 'fail to reject'!

(11.1) **Beware of multiple analyses.** A significance test of $\alpha = 0.05$ is reasonable enough to prove something on its own. But if you take 20 tests of $\alpha = 0.05$ and record if any of them show your conclusion- well, that doesn't really show anything! "Searching for patterns is fine. But performing every conceivable significance test on a data set until you obtain a statistically significant result is not." (This is known as *P-hacking* or *data dredging*.)

9.1.3 Type I and Type II Errors

When drawing a conclusion from a significance test, our conclusion may be wrong. There are two types we can make with the conclusion process, helpfully named "Type I" and "Type II" errors. Only one type of error is possible at once.

Definition 55 (Type I and II errors). A **Type I error** occurs when we reject H_0 when H_0 is true; the data gives convincing evidence that H_a is true despite being false.

A **Type II error** occurs when we fail to reject H_0 when H_a is true; the data fails to give convincing evidence that H_a is true despite it being true.

Note $P(\text{Type I error}) = \alpha$. However, significance is inversely proportional to Type II error: as significance decreases, $P(\text{Type II error})$ increases.

9.1.4 Power

Definition 56 (Power). The **power** of a test is the probability that the test finds convincing evidence for H_a given that the parameter is a specific value that does follow H_a . In other words:

$$\text{power} = P(\text{reject } H_0 \mid H_0 \text{ is false})$$

Power depends on a specific value. For example, if the power of a test to detect $p = 0.08$ is 0.29 given $H_0 : p = 0.10$, if the true proportion in the population is $p = 0.08$, there is a 0.29 probability that researchers will find convincing evidence for H_a .

Note $\text{Power} = 1 - P(\text{Type II Error})$, or written alternatively, $P(\text{Type II Error}) = 1 - \text{Power}$. Also note that the power of a test increases with higher sample number, higher significance level, further null and alternative parameter values, and 'wise choices when collecting data' (reducing variability). *Larger significance values reduce the chance for Type II error, but increase the chance for Type I error.*

9.1.5 Steps for Significance Tests

Overall, significance tests can be summarized in four steps:

1. **STATE** the hypotheses, significance level, and parameters.
2. **PLAN** the appropriate inference method and check conditions.
3. **DO** the significance test (see Section 7.2):

- Give the sample statistic(s)
 - Calculate the standardized test statistic
 - Find the P-value.
4. **CONCLUDE** whether or not you believe in the null or alternate hypotheses, with reference to P-values, in the context of the problem. Make sure to reference the parameter, not the sample statistic!

9.2 Tests About a Population Proportion

Like confidence intervals, significance tests should satisfy several conditions; random sampling, no bias, 10% if applicable ($n < 0.10N$), and large counts ($np_0 \geq 10$ and $n(1 - p_0) \geq 10$). Note that the large counts condition uses p_0 : the number of successes and failures *assuming the null hypothesis is true* are both greater than or equal to 10.

To conduct a **one-sample z test for a proportion** (CITE THIS WHEN FOLLOWING THE SIGNIFIANCE TEST STEPS) about a proportion, look at the normal distribution *assuming the null hypothesis is true*.

From Section 7.2 (add ref later), $\mu_{\hat{p}} = p_0$ and $\sigma_{\hat{p}} = \sqrt{\frac{p_0(1-p_0)}{n}}$.

Using this, we standardize the statistic with respect to the null value to get the **standardized test statistic**; how many stdev units away the sample statistic is from what we would expect, assuming the null hypothesis is true. **YOU HAVE TO PUT THE STANDARDIZED TEST STATISTIC ON THE TEST!**

$$\text{standardized test statistic} = z_{sts} = \frac{\hat{p} - \mu_{\hat{p}}}{\sigma_{\hat{p}}}$$

Using this, we can directly find the P-value using `normalcdf` with the appropriate values:

- $P(z > z_{sts})$ if $H_a : p > p_0$
- $P(z < z_{sts})$ if $H_a : p < p_0$
- $P(z > |z_{sts}|) + P(z < -|z_{sts}|)$ if $H_a : p \neq p_0$

Keep in mind that just because the P-value is low *does not prove that H_0 is false*; sample proportions may be small due to sampling variability, or we have made a Type I error somehow. **AVOID JUMPING TO CONCLUSIONS**: just because a sample statistic looks unlikely, doesn't mean its P-value is!

It should be noted there is a link between *two-sided tests* and confidence intervals: a K% confidence interval gives an approximate set of p_0 's that would not be rejected by a two-sided test at the $\alpha = \frac{K}{100}$ level, with all other values being rejected.

Intuitively, if a confidence interval for p using *the same* \hat{p} does not include p_0 , as the distribution (test) about p_0 has a similar stdev (due to the same α) the distribution is unlikely to include the actual value of p .

9.3 Tests About a Difference in Proportions

Tests about difference in proportions work very similarly to tests about single proportions. For null hypothesis $H_0 : p_1 - p_2 = 0$, large counts can't directly be applied; we need estimate the true difference in proportions p using a weighted average of the two proportions:

$$\hat{p}_C = \frac{\text{number of successes in both samples combined}}{\text{number of individuals in both samples combined}} = \frac{n_1\hat{p}_1 + n_2\hat{p}_2}{n_1 + n_2}$$

We use this pooled proportion (*even for non-zero differences*, although the given formulas have to be changed) because the combined proportion provides *the best estimation of the true difference in proportions*. In the one-sample z test for a proportion, we used p_0 because we're looking at the distribution relative to it. For **two-sample z tests for the difference between two proportions**, we look at the distribution 'relative' to the true proportion; which our best guess is \hat{p}_C . (something something using each individual \hat{p}_i causes too much error + causes some error in the underlying math when we're testing for 0 diff)

In this case, we use the combined proportion for large counts *for both samples*: that is, $n_1\hat{p}_C, n_1(1 - \hat{p}_C), n_2\hat{p}_C, n_2(1 - \hat{p}_C)$ all need to be greater or equal than 10. Using the combined proportion works for a non-zero difference in the null hypothesis, although is not strictly necessary (large counts for each individual distribution can be used).

The standardized test statistic also uses the combined estimate (for both proportions are equal; otherwise, each individual statistic can be used):

$$z = \frac{(\hat{p}_1 - \hat{p}_2) - 0}{\sqrt{\frac{\hat{p}_C(1-\hat{p}_C)}{n_1} + \frac{\hat{p}_C(1-\hat{p}_C)}{n_2}}}$$

10 Estimating Means

10.1 One-Sample t intervals

To create a confidence interval for a mean, we can use the same point estimate \pm margin of error = (critical value)(SE of statistic) idea. However, this is slightly flipped, as (from Section 7) the stdev of a sample distribution relies on the stdev of the population itself. If we know the stdev of the population, we can the familiar *one-sample z interval for a population interval*:

$$\hat{\mu} = \bar{x} \pm z^* \frac{\sigma}{\sqrt{n}}$$

Using the sample stdev alone is not a good enough approximation. For an example, using the sample stdev to estimate a 99% confidence interval would result in a $\approx 92.5\%$ confidence interval. This is because there is significant variation in the sample stdev itself.

To account for this, we use the larger *t-distribution* instead. The t -distribution is like the z -distribution (measures how many stdevs needed for desired confidence), but has higher area in the tails to compensate for the errors in the sample stdev. Notably, t -distributions vary depending on the sample size; that is, they have a specific *degree of freedom df* . (Use `invT` to calculate the specific t^* value needed.) When using t -distributions, make sure to set $df = n - 1$. Thus, for the *one-sample t interval for a population mean*,

$$\hat{\mu} = \bar{x} \pm t^* \frac{s_x}{\sqrt{n}}$$

The random (and 10%) clauses still apply, although the Large Counts condition is slightly modified due to the central limit theorem:

- If the sample size is small ($n < 30$), then graph the sample data (dotplot is preferred, although boxplot works it's kinda funky) and consider whether the data plausibly comes from a normal population. No strong outliers or skew indicates yes. *You will have to show your graph when assesing the normality of the data.*
- If the sample size is big ($n \geq 30$), then you can still use a one-sample t interval for a population mean (although the true confidence level will be lower than presented).

The `TInterval` function on the calculator can be used to simulate a one-sample t interval for a population mean if the above are satisfied.

As $df \rightarrow \infty$, the t -distribution approaches the normal distribution. Intuitively, as sample size increases, the sample stdev will get closer to the population stdev. The quantity $\frac{s_{\bar{x}}}{\sqrt{n}}$ is known as the *standard error of the sample mean* ($s_{\bar{x}}$).

10.2 Two-Sample t intervals for a Difference between Two Means

Like two-sample z intervals, these require the one-sample requirements to be fulfilled for the populations, and follow the same idea (sqrt the variance):

$$\hat{\mu}_{x_1-x_2} = (\bar{x}_1 - \bar{x}_2) \pm t^* \sqrt{\frac{s_1^2}{n_1} + \frac{s_2^2}{n_2}}$$

However, the degrees of freedom are significantly more confusing to decide. There are two practical options to decide the df to use:

- **Technology:** Use the formula below to calculate df . Note that in this case, df is usually not a whole number. Results in confidence intervals that are approximately the stated confidence levels.

$$df = \frac{\left(\frac{s_1^2}{n_1} + \frac{s_2^2}{n_2}\right)^2}{\frac{1}{n_1-1}\left(\frac{s_1^2}{n_1}\right)^2 + \frac{1}{n_2-1}\left(\frac{s_2^2}{n_2}\right)^2}$$

- **Conservative:** $df = \min(n_1 - 1, n_2 - 1)$. Note this method causes a margin of error as large if not larger than is needed for the desired confidence level.

10.3 Paired t interval For a Mean Difference

(also known as a one-sample t interval for a mean difference)

For comparing data which interviews the "same" (or highly related) individuals (known as **paired data**), "combine" the data into one dataset by subtracting each individuals' values, and analyze that using the tactics from section 10.1. (n = the number of pairs)

The requirements are the same as the 1-sample t interval, although the meaning of 10% ($n_{diff} < 0.10N_{diff}$) is different: we suspect that the data is not independent, so 10% guarantees that the differences are independent.

11 Confidence with Means

tl;dr the same thing as Section 9 but with means this time (it works how you think it does)

11.1 Tests about a Population Mean

Null hypotheses, alternative hypotheses, and significance levels exist and mean the same thing as they did in Section 9. Yipee!

While the random and 10% conditions still apply, the large counts condition is modified to account for the Central Limit Theorem, like described in Section 10.1. To reiterate; if the $n < 30$, check whether the data is approximately Normal (no major skew or outliers) before performing tests; otherwise, everything proceeds as normal (haha). Dotplots are recommended to check for Normality due to ease, but other graphs work too.

As before, we need to calculate a standardized test statistic and a P-value.

$$\text{standardized test statistic} = z = \frac{\bar{x} - \mu_0}{\sigma_{\bar{x}}} = \frac{\bar{x} - \mu_0}{\frac{\sigma}{\sqrt{n}}}$$

Obviously, σ for the population is rarely known. So we use the *standard error of \bar{x}* once again:

$$t = \frac{\bar{x} - \mu_0}{\frac{s_x}{\sqrt{n}}}$$

Instead of using the Normal distribution (like you would when σ is known), you will need to use a *t-distribution*, like Section 10 describes. Same **tcdf**, $df = n - 1$, etc. Remember, if you're lazy: $P(t \geq k) = P(t \leq -k)$ for both Normal and t distributions. No calculator for t-distribution? Use the tables, but be wary to give a range between the floor and ceil of the df.

The same link between two-sided confidence intervals and confidence intervals exist. Interestingly, there's also a relation between one-sided tests and confidence intervals for a population mean.- a one sided test is the same as a confidence interval with $C = 1 - 2\alpha$.

Difference in means and paired means work exactly like you think they do. Remember to use \bar{x}_{diff} and s_{diff} for paired data. Remember to use $df = \min(n_1 - 1, n_2 - 1)$ or technology; don't use the sum.

(idk put this somewhere else) **Use one-sample t procedures when testing data collected in pairs. Use two-sample difference t procedures when testing data collected from two populations independently.**

12 Inference for Distributions and Relationships

12.1 Chi-Square Tests for Goodness of Fit

Obviously, the significance tests and confidence intervals discussed in sections 7 - 11 only apply to single continuous variables. This obviously raises the question: *what if you want to consider multiple variables at once?*

Say, for example, several mutually exclusive proportions, like dice rolls. Of course, you could run a single-variable test on every single sample proportion to see if it matches up with what you expect.

Besides the obvious problem of being fairly inefficient, this also raises the problem of multiple tests indirectly leading to **P-hacking** (running several tests until you get a statistically significant result). Additionally, it doesn't tell you how likely it is to get a random sample with the given sample distribution assuming the claimed proportions are true. Instead, we need to consider all proportions at once, using a *chi-square test for goodness of fit*.

For our null hypothesis, we assume that the claimed distribution is true. This leads to the obvious alternate hypothesis: the true distribution is not the same the claimed distribution. For example, dice rolls:

- H_0 : The distribution of dice rolls is the same as the claimed distribution. In other words: $p_i = \frac{1}{6}$ where p_i represents the proportion of dice rolls that land i th side up.
- H_a : The distribution of dice rolls is not the same as the claimed distribution. At least two of these proportions differ than the values stated in the null hypothesis (2 cause $\sum p_i = 1$)

Like other significance tests, we compare our *expected values* (assuming the null hypothesis is true) to our experimental data. Say we roll a dice 60 times. Then, our expected count for categorical variable i in the distribution is $np_i = (60)(\frac{1}{6}) = 10$ rolls to come up for each side of the die. (*np_i may not be an integer, and shouldn't be rounded to one.*)

To quantify how far our experimental data is compared to our expected data, we calculate the *chi-square test statistic*.

Definition 57 (Chi-square test statistic, χ^2). A measure of how far each experimental count differs from the expected count for each categorical variable. (Summed over all possible values for the categorical variable, k .)

$$\chi^2 = \sum \frac{(\text{Observed Count} - \text{Expected Count})^2}{\text{Expected Count}} = \sum_{i=0}^k \frac{(n\hat{p}_i - np_i)^2}{np_i}$$

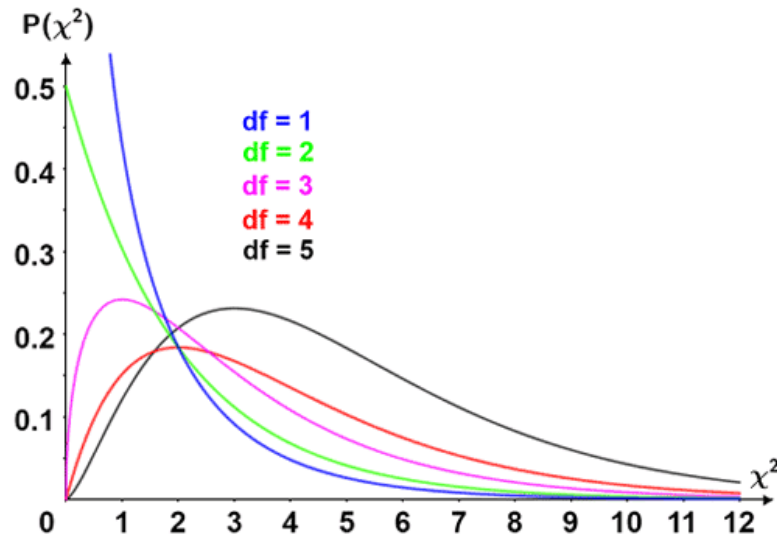


Figure 4: A probability density plot showing chi-square distributions with $df = 1, 2, 3, 4, 5$.

Make sure to use the COUNTS, and not the PROPORTIONS when calculating χ^2 . We square the difference for similar reasons to σ : to get rid of sign (i think). We divide by the expected count to encode its relative significance, instead of prioritizing extremely high differences.

Similar to previous significance tests, we look at the *chi-square distribution* to generate a P-value. Chi-square distributions are right-skewed non-negative distributions (due to the square) that also take in degrees of freedom (df) = number of categorical variables - 1. The mean of a chi-squared distribution is equal to df and has a singular peak at $df - 2$ ($df > 2$).

Similar to previous significance tests, the random and 10% conditions still apply. Large counts is slightly modified; all *expected* counts should at least be 5.

Use the chi-squared cdf function on your calculator to generate a P-value. (Remember, your P-value is the area to the RIGHT of your χ^2 value; your lower value should be your test statistic, not the upper!) From there, use the stated significance level to either reject or fail to reject the null hypothesis. Remember that just because we fail to reject the null hypothesis does NOT mean that it is true. We simply don't have data to reject the null hypothesis.

If you are asked how the distribution is different than the predicted distribution, note which categories that contribute the most to χ^2 . Then, describe how the observed and predicted counts for these categories differ, with reference to direction. (less or more?)

Gender	Union Member	Represented by Union	Non-Union	Total
Male	76	84	527	687
Female	67	75	493	635
Total	143	159	1,020	1,322

Figure 5: A two-way table comparing gender and union participation.

12.2 Inference for Two-Way Tables

Two-sample z tests (discussed in section 9.3) allow us to compare proportions in two populations or two treatments. *Chi-square tests for homogeneity* allow us to compare distributions of a single categorical variable across several populations or treatments. *Chi-square tests for independence* allow us to analyze whether there's evidence of an association between two variables.

12.2.1 Chi-square tests for homogeneity

To begin, create a two-way table like shown in Figure 5. Generally, our null hypothesis says that there is *no difference* in the true distribution of a categorical variable in the populations of interest (or treatments in an experiment). In this case, our null hypothesis would be H_0 : There is no difference in the true distributions of union participation if the worker is male or female. Similarly, the alternate hypothesis says that *there is a difference, but does not specify what that difference is*. (H_a works for ANY difference in distribution.) In this case, H_a : There is a difference in the true distributions of union participation if the worker is male or female.

(doesn't really belong here) **Performing multiple tests on the same data increases the probability of making a Type I error in at least one test. This is P-hacking.**

This test has similar requirements to that of chi-squares for goodness of fit: random, 10%, and large counts- all expected values are greater than five. How expected values are calculated is slightly different, as we need to account for different sample sizes. For example, from the table, 687 out of 1322 workers are male. If gender has no impact on union participation, then the proportion of each category of union participation should be the same $\frac{687}{1322} \approx 0.520$. Because 143 workers are union members, we would expect $143 \times \frac{687}{1322} \approx 74.31$ union members to be male, on average. Generally, the expected value for any given cell is equal to $\frac{\text{row total} \times \text{col total}}{\text{table total}}$.

	Union Member	Represented by Union	Non-Union	Total
Male	74.312	82.627	530.061	687
Female	68.688	76.373	489.939	635
Total	143	159	1020	1322

Figure 6: The compliment to Figure 5, showing the expected value for each cell. why doesn't matplotlib allow me to export a higher quality image istfg

Note that in the expected value table, the row and column sums are still the same, by design. From here, you can calculate the test statistic χ^2 and P-value (using $df = (\text{number of rows} - 1) * (\text{number of cols} - 1)$) as discussed in section 12.1. **Remember to cite the name of the test (χ^2 test for homogeneity), the test statistic, df, and P-value when conducting the test!**

12.2.2 Chi-square tests for independence

While chi-square tests for homogeneity test *if the distributions of two different populations are the same*, chi-square tests for independence test *if knowing one variable helps predict the value of the other*. The only functional difference between tests for independence versus homogeneity is the hypotheses. Instead of testing for difference between *two separate distributions*, tests for independence test for difference between *two separate variables in the same population*. That is:

- H_0 : There is no association between x and y in the population.
- H_a : There is an association between x and y in the population.

Other than this, *chi-square tests for independence are calculated exactly the same way as chi-square tests for homogeneity*. There are some differences in the interpretation of each step, but the general process is exactly the same.

12.2.3 Differences between Homogeneity and Independence

- Homogeneity tests for if the distribution of *one* categorical variable is the same for *multiple distributions*. Independence tests whether *two* categorical variables are associated in a *single* distribution.
- Homogeneity tests use data for which *the total sample size for each population is known before the data is collected*. Independence tests use data for which *only the total sample size is known- the size of each population is not known before the data is collected*.

12.3 Inference for Slope

When a scatterplot shows a linear relationship between two quantitative variables x and y , we can use least-squares as discussed in Section 3. However, if the data comes from a larger population, we cannot immediately say that there is a linear relationship between the two. For this, we can use statistical inference to (statistically) find **if there is a linear relationship between x and y and a confidence interval for the slope.**

Definition 58 (Population and Sample Regression). The population (or true) regression line calculated using *all* values in the population. Written $\mu_y = \alpha + \beta x$, where μ_y is the mean y -value for the given x .

Similarly, the sample (or estimated) regression line is calculated using a sample of the population. Written $\hat{y} = a + bx$, where \hat{y} is the estimated mean y -value for a given val of x .

It can be shown the sampling distribution of the sample slope b has the following properties:

1. approximately Normal
2. $\mu_b = \beta$ (b is an unbiased estimator of β)
3. $\sigma_b = \frac{\sigma}{\sigma_x \sqrt{n}}$ (σ = the stdev of the residuals for the population regression line)

When σ is larger, we should expect more variability in σ_b .

More variability in the explanatory variable (larger σ_x , more values to draw from)

\sqrt{n} from more sample size = more accurate predict.

The conditions for regression inference (LINER) are as follows:

1. **Linear:** the true relationship between x and y is linear (the data should look *roughly* linear)
2. **Independent:** observations independent of one another, sampling without replacement needs 10%
3. **Normal:** $\forall x$ the response y varies according to a normal distribution (make graph of residuals and check for skew or outliers)
4. **Equal SD:** $\forall x$ the stdev of y σ is the same (make plot of residual plot, check for no patterns)

5. **Random:** data comes from a random sample or randomized experiment

Once LINER is met, we can calculate the sample regression line via the methods discussed in Section 3. Because the sample regression line estimates the population regression line, it makes sense that the stdev of the residuals (s) is estimated by the stdev of the sample residuals. (Because s is estimated from the data itself, sometimes it's called the *regression standard error* or *root mean squared (RMS) error*.)

$$s = \sqrt{\frac{(y_i - \hat{y}_i)^2}{n - 2}}$$

With this, we can estimate the variability of the sampling distribution of b with the *standard error of the slope* SE_b . (For reasons I don't fully understand, we replace the denominator with $n - 1$.)

$$SE_b = \frac{s}{s_x \sqrt{n - 1}}$$

SE_b behaves like other standard errors. Using it, you can generate a **t-interval for the slope** ($df = n - 2$):

$$\beta \in (b \pm t^* SE_b)$$

Using the interval, estimates for larger changes in x can be obtained by multiplying the critical values by the larger change. For example, if you wanted to calculate the interval for x increasing in steps of 1000, you would multiply the critical values by 1000.

Similarly, the standardized test statistic can be calculated for the **t test for slope** ($df = n - 2$):

$$t = \frac{b - \beta_0}{SE_b}$$

(nice lil trick) Testing for no association ($r = 0$) is the same as testing for 0 slope ($H_0 : \beta_0 = 0$).